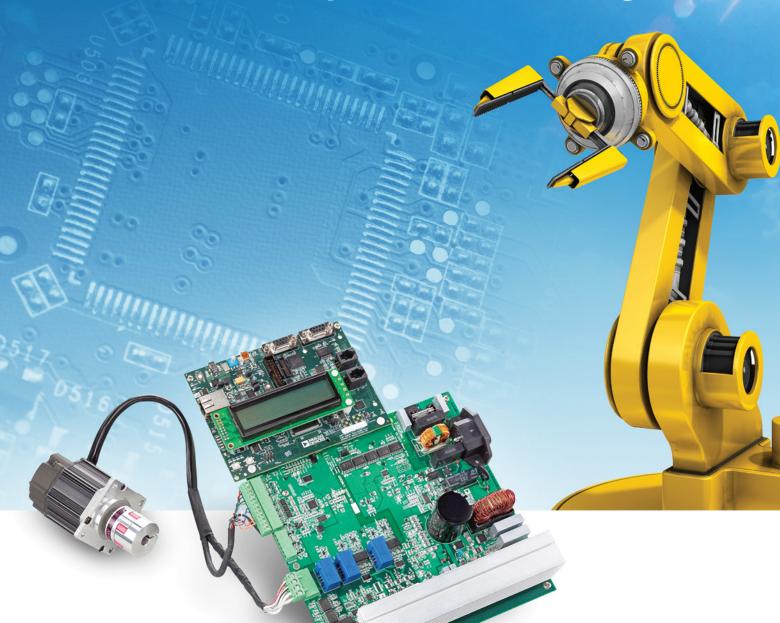


Analog Devices Products and Signal Chain Solutions for **Motor Control Systems and Design**



Analog Devices' Motor Control Mission Statement

ADI is positioned to deliver the most innovative motor control market solutions that offer the best in system efficiency, reliability, and connectivity by focusing its efforts on the highest system performance and industry-leading integration. With ADI's extensive motor control system-level knowledge and strategic technology partner alliances, ADI will be able to provide customers with unique system services and products leading the way to becoming a long-term technology partner.



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Introduction

More Stringent Energy Regulations Drive Motor Control Innovations

In today's expanding industrial marketplace, the demand for electrical power is growing at an unprecedented rate. More than 40% of that electrical demand comes from industrial electric motors of all sizes. Because of that phenomenon, governments and certification agencies worldwide are introducing new regulatory legislation and more stringent energy efficiency requirements on electric motor OEMs and end users. Like many great technological innovations, there needs to be a pressing demand in the market for change.

Analog Devices recognized years ago that this new era of smarter and highly efficient motor control systems would be the new standard for the motor control industry. As part of that recognition, ADI embarked on an integrated and comprehensive motor control design program in collaboration with our strategic partners, who are experts in their respective fields (MathWorks,® ARM,® Boston Engineering,® IAR® systems, and Xilinx®), aimed at addressing the entire system architecture to achieve the greatest level of efficiency while improving system accuracy and reliability.

By taking a system-level view (see Figure 1) of these new challenges, ADI was able to develop products that not only exceeded the individual performance specifications but also represented the optimal interface between other functional blocks of the circuit. This system solution approach enables ADI to offer industrial-based customers a completely integrated solution that fits their specific needs while helping them meet the new, more stringent energy regulations.

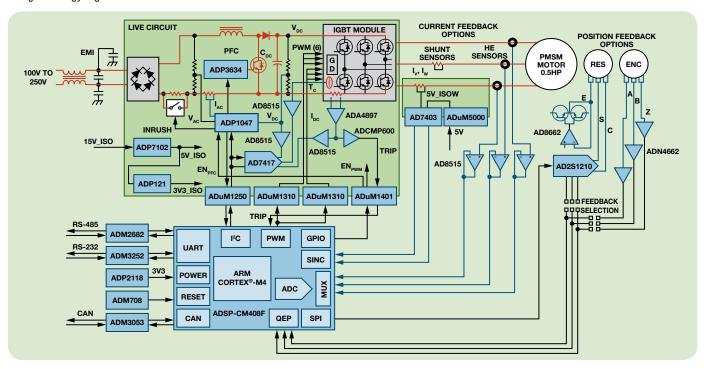


Figure 1. Complete system-level motor control solution capabilities.



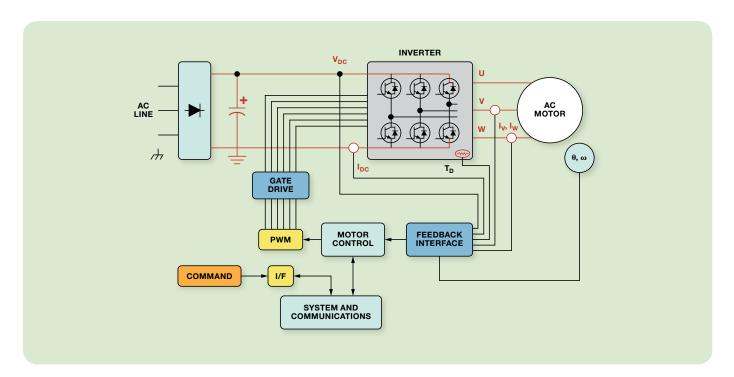


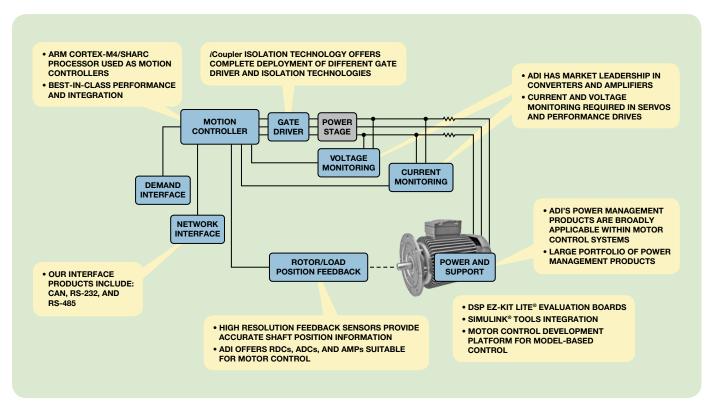


Motor drive power board.

For additional information go to www.analog.com/motorHV.

Typical Motor Control System Offering





Digital Isolation with iCoupler Technology

The iCoupler Transformer Isolation Advantage

- Smaller size
- Integrate with other functions
- Lower cost at high performance

- isoPower
- Lower power consumption
- · Higher reliability

Safety and Standards

- Basic and functional safety
 - IEC60664, IEC61800-5-x
- Reinforced isolation
 - VDE-0884-10, IEC60747-5-5
 - UL1577

- 1200 V_{PEAK} working voltage
- Guaranteed 8 mm creepage

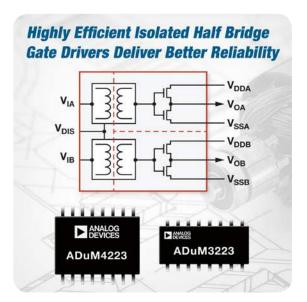
Isolated Gate Drivers

Overcoming Limitations of Optocouplers and High Voltage Gate Driver Solutions

Isolated gate drivers provide electrical isolation as well as strong gate drive capability, which is often required for safety and robustness in many system architectures. The isolated gate driver portfolio from Analog Devices offers designers performance and reliability advantages over designs utilizing optocouplers or pulse transformers. Utilizing ADI's proven iCoupler® technology, the isolated gate driver family offers the advantage of a maximum propagation delay of 50 ns, less than 5 ns channel-tochannel matching, a 50-year lifetime for 400 V rms working voltage, and galvanic isolation in a single package.

| Part Number | Insulation Rating (kV rms) | Max Operating Temperature (°C) | Isolated Output (V) Max | Isolated Output (V) Min |
|----------------|-------------------------------|-----------------------------------|----------------------------|----------------------------|
| ADuM7223 | 2.5 | 125 | 18 | 4.5 |
| ADuM3223 | 3 | 125 | 18 | 4.5 |
| ADuM4223 | 5 | 125 | 18 | 4.5 |
| ADuM3221 | 2.5 | 125 | 18 | 4.5 |
| ADuM3220 | 2.5 | 125 | 18 | 4.5 |
| ADuM7234 | 1 | 105 | 18 | 12 |

INVERTER ISOLATED GATE DRIVE GATE DRIVE ISOLATED FEEDBACK PWM I/F DATA ISOLATION SYSTEM AND COMMUNICATIONS FEEDBACK INTERFACE Tx/Rx ISOLATED COMMUNICATION INTERFACES isoPower



Isolated Σ - Δ Modulators—Voltage and Current Sensing

The AD7403 is the industry's highest performance isolated Σ - Δ modulator enabling even more accurate current and voltage sense feedback. Wider dynamic range enables the use of smaller shunts, improving system efficiency and motor to drive matching. Superior modulator performance coupled with an external clock of 20 MHz provides flexibility in performance/latency trade-offs in applications such as robotics where dynamic response is important. The AD7403 also features an isolation scheme with a higher continuous working voltage (V_{IORM}) than the previous generation and is offered in packages providing 8.3 mm creepage and clearance.

| Part Number | Clock (MHz) | V _{IORM} (V _{PEAK}) | Package |
|-------------|---------------|--|-------------------------------------|
| AD7400A | 10 (int) | 848 | 16-lead SOIC_W |
| AD7401A | 20 (ext) | 848 | 16-lead SOIC_W |
| AD7403 | 20 (ext) | 1250 | 16-lead SOIC_IC, 8-lead SOIC_IC, |
| AD7402 | 10 (int) | 1250 | 16-lead SOIC_IC, 8-lead SOIC_IC, |
| AD7405 | 20 (ext) LVDS | 1250 | 16-lead SOIC_IC |

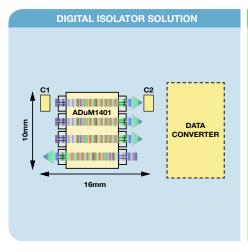


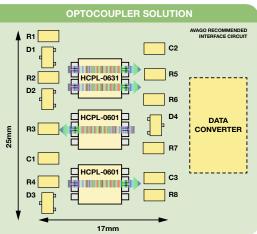
Standard Data Isolators

Digital Isolators Deliver Peak Performance Without Compromise

Digital isolators with iCoupler technology enable designers to implement isolation in designs without the cost, size, power, performance, and reliability constraints found with optocouplers. With more than one billion channels shipped into the field, these magnetically isolated products are a safe, reliable, and easy to use alternative to optocouplers.

| Channel Count | Insulation Rating (kV rms) | Max Data Rate (Mbps) | Max Operating Temperature (°C) |
|---------------|-------------------------------|-------------------------|-----------------------------------|
| 1 | 2.5 | Up to 100 | Up to 125 |
| 2 | 2.5, 3.75, 5 | Up to 100 | Up to 125 |
| 3 | 2.5 | Up to 90 | Up to 125 |
| 4 | 2.5, 3.75, 5 | Up to 150 | Up to 125 |
| 5 | 1, 2.5 | 10 | 105 |
| 6 | 1 | 25 | 105 |



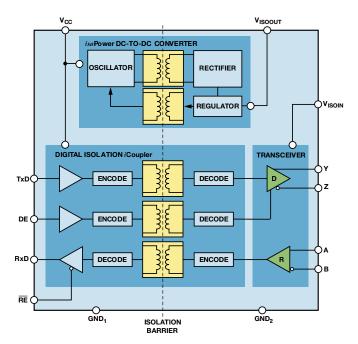


Isolated RS-485 Transceivers for Intersystem Communication in Motor Control

 $These isolated transceivers integrate Analog \ Devices \ i Coupler \ technology \ to \ combine \ a \ 3-channel \ isolator, \ a \ three-state \ differential \ line \ driver, \ a \ differential \ line \ driver, \ a \ differential \ line \ driver, \ a \ d$

differential input receiver, and Analog Devices *iso* Power dc-to-dc converter into a single package. The devices are powered by a single 5 V or 3.3 V supply, realizing a fully integrated signal and power isolated RS-485 solution. The parts are fully specified over the industrial temperature range and are available in a highly integrated, 16-lead, wide-body SOIC package with >8 mm creepage and clearance. These devices enable designers to isolate communications in design without the cost, size, power, and reliability constraints found with traditional isolation products.

| Part Number | Insulation Rating (kV rms) | ESD Protection (kV) | Data Rate RS-485 | Power Supply (V _{NOM}) |
|----------------|-------------------------------|------------------------|---------------------|----------------------------------|
| ADM2682E | 5 | 15 | 16 Mbps | 3.3, 5 |
| ADM2687E | 5 | 15 | 500 kbps | 3.3, 5 |
| ADM2582E | 2.5 | 15 | 16 Mbps | 3.3, 5 |
| ADM2587E | 2.5 | 15 | 500 kbps | 3.3, 5 |



isoPower Integrated, Isolated DC-to-DC Converters

These isolated dc-to-dc converters expand ADI's isolated power portfolio by providing designers with a compact, easy to implement, cost-effective approach to meeting both isolated power and data requirements. The combination of size and output power also addresses the growing space and power constraints engineers must consider when designing motor drives.

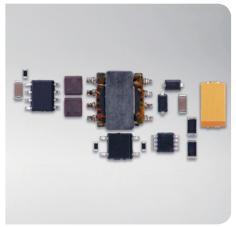


| Part Number | Insulation Rating (kV rms) | Max Data Rate (Mbps) | Propagation Delay (ns) | Isolated Output Supply (mA) | Isolated Output (V) Min |
|----------------|-------------------------------|-------------------------|---------------------------|--------------------------------|----------------------------|
| ADM3260 | 2.5 | 1 | 95 | 30 | 4.5 |
| ADuM5000 | 2.5 | _ | _ | 100 | 3.3 |
| ADuM5200 | 2.5 | 25 | 60 | 100 | 3.3 |
| ADuM5400 | 2.5 | 25 | 60 | 100 | 3.3 |
| ADuM6000 | 5 | _ | _ | 100 | 3.3 |
| ADuM6200 | 5 | 25 | 60 | 100 | 3.3 |
| ADuM6400 | 5 | 25 | 60 | 100 | 3.3 |

The iso Power Difference







DC-to-DC module.

isoPower solution.

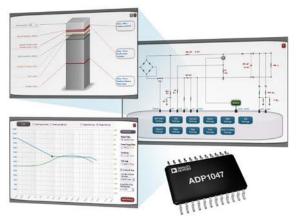
Optocoupler design.

Power Management

Digital Power Factor Correction with PMBus for Motor Control Systems

Motor control systems are increasingly migrating from passive harmonic correction inductors to active power factor correction (PFC) systems to improve total harmonic distortion (THD), reduce system size and weight, and improve efficiency of single-phase and 3-phase designs.

The ADP1047 and ADP1048 digital power factor correction series offer versatile controllers with input power metering capability to $\pm 1\%$ accuracy. The ADP1047 is a single-phase device, while the ADP1048 is an interleaved controller that can also be configured as a bridgeless PFC for high system efficiency. The ADP1047/ADP1048 can be programmed using the easy to use graphic user interface (GUI) with programming implementation in hardware state machine for robust and reliable motor control PFC solutions. The PMBus interface allows parameters to be adjusted and reported, including the accurate measurement of input voltage, current, power, and temperature. The ADP1047/ADP1048 PFC family can communicate with motor controllers, such as ADSP-CM408F, to optimize efficiency and motor control system performance.



Intuitive graphical user interface simplifies programming.

| Part Number | Description | Key Features | V _{IN} (V) | Interface | EEPROM | PWM Outputs | Housekeeping I/O | Protection | Package |
|----------------|--|--|---------------------|------------------------|--------|----------------|---|--|--------------|
| ADP1047 | Single-phase PFC controller with accurate power metering | Inrush control, real-time efficiency optimization, enhanced dynamic response, synchronization, and spread spectrum | 3.3 | I ² C/PMBus | Yes | 2 | PSON, inrush control, ACOK, PGOOD | Programmable ac fault detection, OCP, OVP, OTP | 24-lead QSOP |
| ADP1048 | Interleaved PFC controller with accurate power metering; capable of supporting high efficiency bridgeless topology | Inrush control, real-time efficiency optimization, enhanced dynamic response, synchronization, spread spectrum, and light load shedding | 3.3 | I ² C/PMBus | Yes | 2 | PSON, inrush control, ACOK, PGOOD | Programmable ac fault detection, OCP, OVP, OTP | 24-lead QSOP |

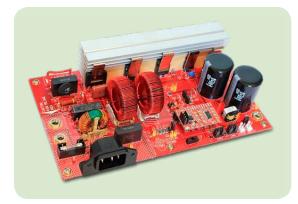
PFC Evaluation Tools and Software

Evaluation boards can be ordered and the GUI can be downloaded free of charge from *analog.com*. There are a number of reference designs, applications notes, and video guides to get started:

- ADP1047 300 W interleaved evaluation board—ADP1048_600_EVALZ
- ADP1048 600 W interleaved evaluation board—ADP1047_300_EVALZ
- ADP1048 bridgeless reference design
- GUI and user guides available from analog.com

High Speed MOSFET Drivers

The ADP36xx family of 2 A and 4 A high speed FET drivers complement the ADP1047/ADP1048 digital PFC controllers. These devices use a standard industry footprint but add faster switching performance and advanced protection features.



ADP1048 600 W interleaved evaluation board.

| Part Number | Description | V _{IN} (V) | Peak Drive Current (A) | Precision Enable/Shutdown | OT Protection | OT Warning Signal | Package |
|--|--|------------------------|---------------------------|------------------------------|---------------|-------------------|------------------------------------|
| ADP3654 | Dual noninverting | 4.5 to 18 | 4 | No | No | No | 8-lead MSOP_EP 8-lead SOIC_N_EP |
| ADP3633/ADP3634/ADP3635 ADP3623/ADP3624/ADP3625 | Dual inverting (33), dual noninverting (34), invert/noninvert (35) | 9.5 to 18 4.5 to 18 | 4 | Yes | Yes | Yes | 8-lead MSOP_EP 8-lead SOIC_N_EP |
| ADP3629/ADP3630/ADP3631 | Dual inverting (29), dual noninverting (30), invert/noninvert (31) | 9.5 to 18 | 2 | Yes | Yes | Yes | 8-lead MSOP_EP 8-lead SOIC_N |

Integrated Regulators Devices Delivering Best-in-Class Efficiency, System Performance, and Size

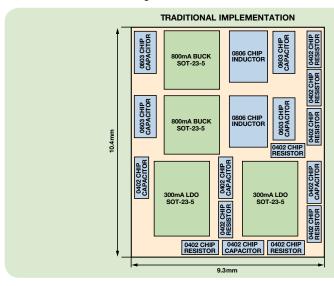
ADI regulator products for motor control offer a selection of power integrated point of load (POL) devices supporting a wide range of power distribution options. This includes standalone switch regulators with 5 V, 12 V, and 24 V process to multirail solutions that support load requirements from the milliamperes to multiple ampere loads while maintaining effective efficiency and performance; to linear regulators offering low noise solutions that help increase precision in fine position sensing applications.

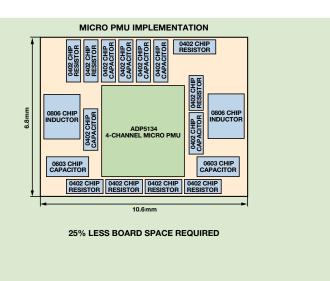
Switching/Multirail Regulators

| Part Number | Product Description | V _{IN} Range (V) | I _{out} Max (A) | | | |
|-------------|---|------------------------------|--|--|--|--|
| ADP2119 | 1.2 MHz synchronous step- down dc-to-dc regulator | 2.3 to 5.5 | 2 | | | |
| ADP2120 | 1.2 MHz synchronous step- down dc-to-dc regulator | 2.3 to 5.5 | 1.25 | | | |
| ADP2164 | High efficiency synchronous step-down dc-to-dc regulator with selectable switching frequency (600 kHz or 1.2 MHz) | 2.7 to 6.5 | 4 | | | |
| ADP230x | Nonsynchronous step-down switching regulator | 3.0 to 20 | ADP2300/ ADP2301: 1.2, ADP2302: 2, ADP2303: 3 | | | |
| ADP2370 | 1.2 MHz/600 kHz low quiescent current step-down dc-to-dc regulator | 3.2 to 15 | 0.8 | | | |
| ADP2384 | Synchronous step-down dc-to-dc regulator with programmable switching frequency | 4.5 to 20 | 4 | | | |

| Part Number | Product Description | V _{IN} Range (V) | I _{out} Max (A) |
|-------------|--|---|---|
| ADP2386 | Synchronous step-down dc-to-dc regulator with programmable switching frequency | 4.5 to 20 | 6 |
| ADP2441 | Synchronous step-down dc-to-dc regulator with adjustable switching frequency 300 kHz to 1 MHz | 4.5 to 36 | 1 |
| ADP5024 | 3-channel regulator with dual 3 MHz switching regulator and one LDO | Switches: 2.3 to 5.5, LDO: 1.7 to 5.5 | Switches: 1.2 each, LDO: 0.300 |
| ADP5134 | 4-channel regulator with dual 3 MHz switching regulator and dual LDO | Switches: 2.3 to 5.5, LDOs: 1.7 to 5.5 | Switches: 1.2 each, LDOs: 0.300 |
| ADP5052 | 5-channel integrated power solution with quad step- down synchronous switching regulators and one LDO | Switches: 4.5 to 15, LD0s: 1.7 to 5.5 | Switches: 4, 4/1.2, 1.2, LDO: 0.200 |

ADP5134 Micro PMU Advantages





Linear Regulators

| Part Number | Product Description | V _™ Range (V) | I _{out} Max (A) |
|-----------------|--------------------------------------|-----------------------------|----------------------------------|
| ADP151 | Ultralow noise CMOS linear regulator | 2.2 to 5.5 | 0.2 |
| ADP7102/ADP7104 | Low noise CMOS LDO | 3.3 to 20 | ADP7102: 0.300 ADP7104: 0.500 |
| ADP7105 | Low noise CMOS LDO with soft start | 3.3 to 20 | 0.5 |
| ADP7118 | Low noise CMOS LDO | 2.7 to 20 | 0.2 |
| ADP7142 | Low noise, high PSRR CMOS LDO | 2.7 to 40 | 0.2 |
| ADM7150 | Ultralow noise, high PSRR LDO | 4.5 to 16 | 0.8 |

| Part Number | Product Description | V _{IN} Range (V) | I _{out} Max (A) |
|---------------------------------|--|------------------------------|--------------------------|
| ADM7170/ADM7171/ ADM7172 | Low noise, high PSRR LDO | 2.3 to 6.5 | 0.5/1.0/2.0 |
| ADP124/ADP125 | Low quiescent current CMOS linear regulator | 2.3 to 5.5 | 0.5 |
| ADP222/ADP223/ ADP224/ADP225 | Dual, low noise, high PSRR linear regulators | 2.5 to 5.5 | 0.300 each |
| ADP322/ADP323 | Triple, low noise, high PSRR linear regulators | 2.5 to 5.5 | 0.200 each |
| ADP7182 | Low noise, negative linear regulator | -2.7 to -28 | -0.200 |

Position and Current Sense Feedback

Simultaneous Sampling ADCs

Current, Voltage, and Position Sensing Products

ADI offers an extensive portfolio of simultaneous sampling ADCs incorporating high performance, resolution, and accuracy with multiple channel combinations that serve a variety of motor control feedback and sensing needs. Small packaged dual devices are ideal for position sensing applications such as robotics or for current sensing in space constrained IDMs. Bipolar input devices suit current and voltage feedback in high power applications. Multichannel devices suit the topologies of multiaxis designs while fast conversion times offer low latency resulting in fast dynamic response.

| Part Number | No. Simultaneous Channels | Total Channel Count | Sample Rate/Sim Channel | Resolution (Bits) |
|--------------------------------|------------------------------|------------------------|-----------------------------|----------------------|
| AD7265/AD7266 | 2 | 12 | 1 MSPS/2 MSPS | 12 |
| AD7262/AD7264 | 2 | 2 | 1 MSPS | 12/14 |
| AD7352/AD7356/ AD7357 | 2 | 2 | 3 MSPS/ 5 MSPS/4.75 MSPS | 10 to 16 |
| AD7656-1/AD7657-1/ AD7658-1 | 6 | 6 | 250 kSPS | 16/14/12 |
| AD7606/AD7606-6/ AD7606-4 | 8/6/4 | 8/6/4 | 200 kSPS | 16 |
| AD7607/AD7608/ AD7609 | 8 | 8 | 200 kSPS | 14/18/18 |
| AD7366/AD7367 | 2 | 4 | 1 MSPS | 12/14 |
| ADAS3023 | 8–8 | 8 | 500 kSPS to 125 kSPS | 16 |
| AD7902/AD7903 | 2 | 2 | 1 MSPS | 16 |



Resolver-to-Digital Converters

Many motor control systems operate at variable shaft rotation speeds. To provide the most accurate position information, a system with flexible resolution is required. The resolver-to-digital converter that provides resolution change on-the-fly is the AD2S1210. This converter delivers an integrated solution including an excitation oscillator with programmable frequency, programmable threshold levels, very wide analog input range, and information indicating the exact nature of detected faults. The AD2S1210 provides a high level of functionality required to interface to resolvers with a reduced number of external components.

| Part Number | Resolution (Bits) | Accuracy (Arcmin) | Max Tracking Rate (rps) |
|-------------|-------------------|-------------------|-------------------------|
| AD2S1200 | 12 | 11 | 1000 |
| AD2S1205 | 12 | 11 | 1250 |
| AD2S1210 | 10 to 16 | 2.5 | 3125 |



Processors

Processor Value

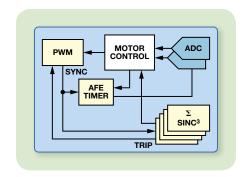
- ARM and DSP cores
- Strong DMA capability
- Real-time Ethernet (1588)
- High performance/cost ratio

System Value

- Embedded sinc filters for isolated Σ-Δ
- High amount of local RAM and flash
- · Fast embedded 16-bit ADCs

Out of Box Experience

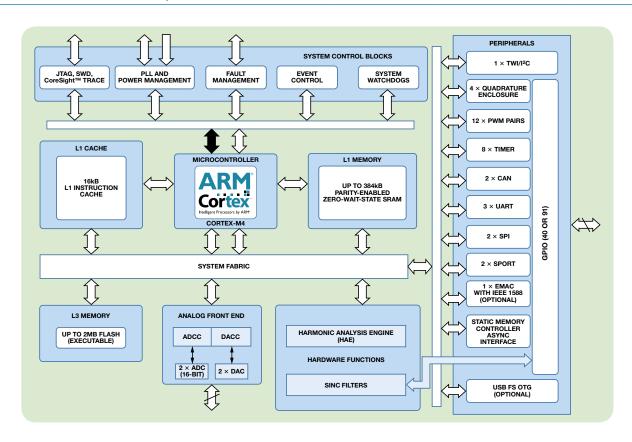
- · Support of MATLAB® and model-based design
- 230 V_{AC} and 48 V_{DC} development platforms
- · Strong local support team



Motor Control ASSPs—ADSP-CM40x Mixed-Signal Processors for High End Drive and Servo Control

ADSP-CM40x mixed-signal processors offer control processing performance combined with high speed, high accuracy analog-to-digital conversion aimed at the needs of next-generation industrial motor drives and servos. Based on the ARM Cortex-M4, the ADSP-CM40x combines industry-leading 240 MHz core clock speed, large 384 kB SRAM, and 2 MB flash memories with industry-leading dual 16-bit ADCs. In addition to its raw digital and analog performance capabilities, the ADSP-CM40x offers a number of features including sinc filters for glueless connection to AD740x Σ - Δ modulators and a harmonic analysis engine for power spectrum analysis.

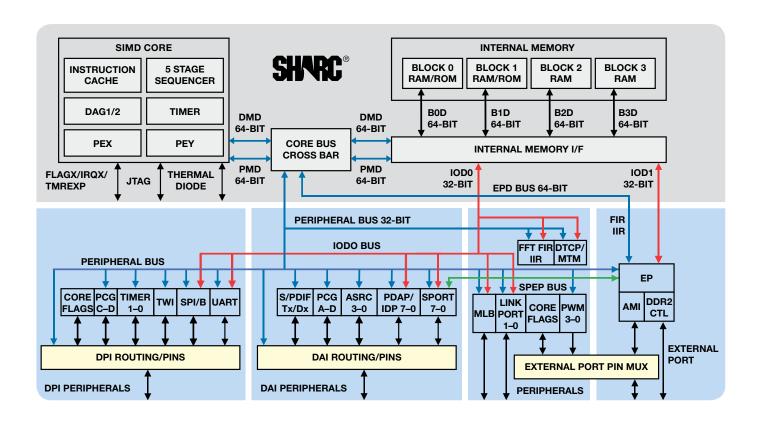
| Model | Package | Speed (MHz) | SRAM/Flash | Dual ADC Accuracy (ENOB) | Comms |
|-------------------|-------------------------------------|-------------|---------------|--------------------------|---------------|
| ADSP-CM408BSWZ-AF | 24 mm $	imes$ 24 mm, 176-lead LQFP | 240 | 384 kB/2 MB | 13 | USB, Ethernet |
| ADSP-CM408BSWZ-BF | 24 mm \times 24 mm, 176-lead LQFP | 240 | 384 kB/2 MB | 13 | USB |
| ADSP-CM407BSWZ-AF | 24 mm \times 24 mm, 176-lead LQFP | 240 | 384 kB/2 MB | 11 | USB, Ethernet |
| ADSP-CM407BSWZ-BF | 24 mm $	imes$ 24 mm, 176-lead LQFP | 240 | 384 kB/2 MB | 11 | USB |
| ADSP-CM403BSWZ-CF | 14 mm $	imes$ 14 mm, 120-lead LQFP | 240 | 384 kB/2 MB | 13 | None |
| ADSP-CM403BSWZ-EF | 14 mm $	imes$ 14 mm, 120-lead LQFP | 150 | 128 kB/512 kB | 13 | None |
| ADSP-CM403BSWZ-FF | 14 mm $	imes$ 14 mm, 120-lead LQFP | 100 | 128 kB/256 kB | 13 | None |
| ADSP-CM402BSWZ-EF | 14 mm $	imes$ 14 mm, 120-lead LQFP | 150 | 128 kB/512 kB | 11 | None |
| ADSP-CM402BSWZ-FF | 14 mm $	imes$ 14 mm, 120-lead LQFP | 100 | 128 kB/256 kB | 11 | None |



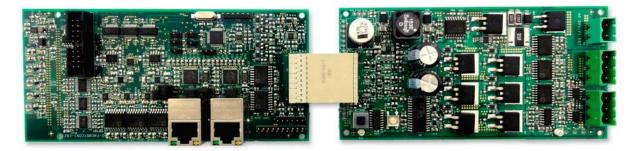
ADSP-214xx SHARC Floating-Point DSPs for Motion Controllers and High End Drive and Servo Control

The SHARC® processor family dominates the floating-point DSP market with exceptional core performance, memory size, memory performance, and cost per MFLOP. As the fourth generation of SHARC 32-bit floating-point DSPs, the ADSP-214xx continues the legacy with unparalleled performance and features. The ADSP-214xx processors incorporate up to 800 MMACs of performance, 5 MB of on chip memory, FFT/FIR/IIR accelerators, and a host of external memory interfaces and peripherals that make these processors well suited for motion controllers and high end motor drive and servo systems.

| Model | Package | Speed (MHz) | On-Chip SRAM (MB) | GPI0s | Parallel Interfaces | Accelerators |
|-------------------|-------------------------------------|-------------|-------------------|-------|-----------------------|--------------|
| ADSP-21469BBCZ-3 | 24 mm \times 24 mm, 176-lead LQFP | 450 | 5 | 34 | DDR2, AMI, link ports | FFT/FIR/IIR |
| ADSP-21489BSWZ-3A | 14 mm \times 14 mm, 100-lead LQFP | 350 | 5 | 32 | _ | FFT/FIR/IIR |
| ADSP-21489BSWZ-3B | 24 mm \times 24 mm, 176-lead LQFP | 350 | 5 | 34 | SDRAM | FFT/FIR/IIR |
| ADSP-21489BSWZ-4A | 14 mm \times 14 mm, 100-lead LQFP | 400 | 5 | 32 | _ | FFT/FIR/IIR |
| ADSP-21489BSWZ-4B | 24 mm \times 24 mm, 176-lead LQFP | 400 | 5 | 34 | SDRAM | FFT/FIR/IIR |
| ADSP-21488BSWZ-3A | 14 mm $	imes$ 14 mm, 100-lead LQFP | 350 | 3 | 32 | _ | FFT/FIR/IIR |
| ADSP-21488BSWZ-3B | 24 mm \times 24 mm, 176-lead LQFP | 350 | 3 | 34 | SDRAM | FFT/FIR/IIR |
| ADSP-21488BSWZ-4A | 14 mm \times 14 mm, 100-lead LQFP | 400 | 3 | 32 | _ | FFT/FIR/IIR |
| ADSP-21488BSWZ-4B | 24 mm $	imes$ 24 mm, 176-lead LQFP | 400 | 3 | 34 | SDRAM | FFT/FIR/IIR |



FPGA Motor Control Solutions



AD-FMCMOTCON1 evaluation board kit.

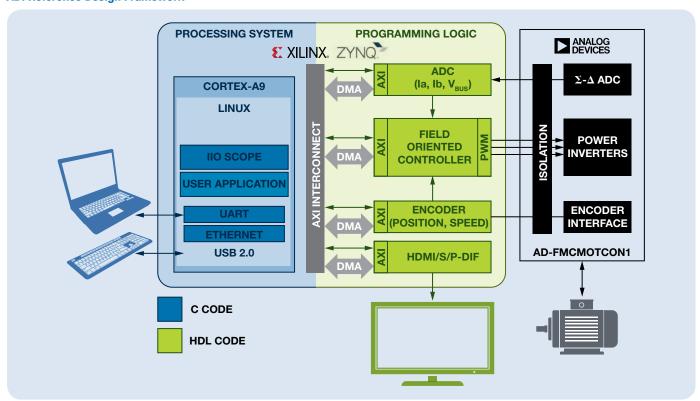
The AD-FMCMOTCON1-EBZ evaluation board kit offers designers a complete motor drive system demonstrating efficient and high dynamic control of 3-phase PMSM and induction motors. The kit consists of two boards: a controller board, designed to connect to any Xilinx FPGA or SoC platforms with FPGA mezzanine card (FMC) connectors, and a drive board as shown above.

Complete drive system demonstrating efficient control of multiple motor types:

- High quality power sources
- · Reliable power, control, and feedback signals isolation
- Accurate measurement of motor current and voltage signals
- · High speed interfaces for control signals to allow fast controller response
- Industrial Ethernet high speed interfaces suitable for communication protocols like PROFINET, EtherCAT, and Powerlink
- Flexible control with FPGA/SoC interface

The hardware is provided with example reference designs showing how to use the control solution with Xilinx FPGAs/SoCs and Simulink from MathWorks. Additionally, the system can be extended with the AD-DYNO1-EBZ Analog Devices dynamometer, which is a dynamically adjustable load that can be used to test real-time motor control performance.

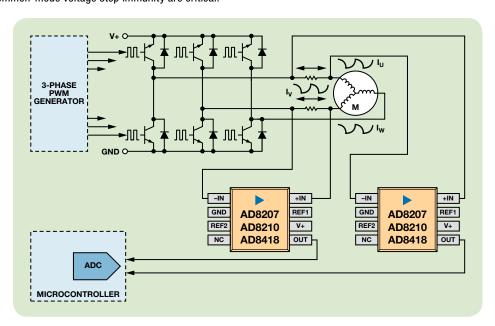
ADI Reference Design Framework



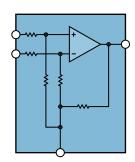
Standard Linear Products

Current Sense Amplifiers

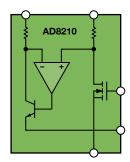
Current sense amplifiers are used when a shunt resistor is placed in the high side or low side and high accuracy over temperature is required in harsh environments. In motor control, normally the bidirectional capability will be needed. In order to build fast and accurate control loops, the step response time and common-mode voltage step immunity are critical.



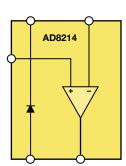
| Part Number | Input CMV (V) | Gain (V/V) | Bandwidth (kHz) | Max TCV _{os} (μV/°C) | Comments |
|---------------|---------------|------------|--------------------------------|-------------------------------|----------------------|
| AD8205/AD8206 | -2 to +65 | 50/20 | 50/100 | 15 | |
| AD8207 | -4 to +65 | 20 | 100 | 1 | Zero drift |
| AD8216 | 0 to 65 | 3 | 3000 | 20 | Fast output response |
| AD8218 | 4 to 80 | 20 | 500 | 0.5 | Zero drift, low cost |
| AD8417/AD8418 | -2 to +70 | 60/20 | 250 | 0.5 | Zero drift, low cost |
| AD8210 | -2 to +65 | 20 | 500 | 8 | High precision |
| AD8214 | 5 to 65 | Comparator | Propagation delay 90 ns typ | _ | Current output |







Current sense amplifier.



Threshold detector.

Difference Amplifiers

Difference amplifiers can be used for voltage and current sensing in motor control systems because they can reject very high common-mode voltage. They will enable the low voltage converters to interface with the high voltage industrial environment. This is especially true when functional isolation is needed. Excellent drift and CMRR are the advantages of ADI's difference amplifiers.

| Part Number | CMV (±V) | CMRR (dB) Min | Gain | Gain Drift (ppm/°C) Max | V _{os} Drift (μV/°C) Max |
|-------------|----------|---------------|----------------|-------------------------|-----------------------------------|
| AD8479 | 600 | 90 | 1 | 5 | 10 |
| AD629 | 270 | 86 | 1 | 10 | 10 |
| AD628 | 120 | 75 | 0.1 to 100 adj | 5 no external | 8 no external |

There are other cases that will need attenuation and/or level shifting in the signal conditioning. In industrial sites, anything higher than the power supply common-mode voltage will be seen by these difference amplifiers.

| Part Number | CMV (±V) | CMRR (dB) Min | Gain | Gain Drift (ppm/°C) Max | I ₀ /Amp (mA) | Comment |
|---------------|---|---------------|----------|-------------------------|--------------------------|--------------------|
| AD8275 | -12.3 to +12 | 86 | 0.2 | 1 | 2.3 | With level shifter |
| AD8276/AD8277 | $-2 (V_s + 0.1) \text{ to } +2 (V_s - 1.5)$ | 86 | 1 | 1 | 0.2 | AD8277 is dual |
| AD8278/AD8279 | $-3 (V_s + 0.1) \text{ to } +3 (V_s - 1.5)$ | 80 | 0.5 or 2 | 1 | 0.2 | AD8279 is dual |
| AD8273/AD8274 | $3 (-V_s) + 4.5 \text{ to } 3 (+V_s) - 4.5$ | 77 | 0.5 or 2 | 2 | 2.6 | AD8273 is dual |

Precision Op Amps

Precision op amps are used as signal conditioning in the motor control systems. They will be used as the sensor to ADC interface, thus the rail-to-rail input and output in high linearity will be needed. They can also be used between the resolver-to-digital converter (RDC) and the resolver to provide high current in high slew rate and accuracy. Wider bandwidth amplifiers will be used to detect the fast changing current in the system.

| Part Number | Power Supply (V) | Offset Voltage (μV) Max | TCV _{os} (μV/°C) Max | Short Circuit Current (mA) | Bandwidth (MHz) | Slew Rate (V/µs) | Comment |
|-------------|------------------|----------------------------|-------------------------------|-------------------------------|--------------------|---------------------|-----------------------------------|
| ADA4077 | 10 to 30 | 25 | 0.25 | 22 | 4 | 1 | General-purpose precision |
| ADA4096 | 3 to 30 | 300 | 1 | 10 | 0.8 | 0.4 | General-purpose RRIO |
| 0P279 | 4.5 to 12 | 4000 | 4 | 50 | 5 | 3 | RDC driver |
| ADA4661 | 3 to 18 | 150 | 3.1 | 220 | 4 | 2 | RDC driver |
| ADA4666 | 3 to 18 | 2200 | 3.1 | 220 | 4 | 2 | Low cost RDC driver |
| AD8662 | 5 to 16 | 1000 | 9 | 19 | 4 | 3.5 | RDC driver |
| ADA4500 | 2.7 to 5.5 | 120 | 5.5 | 26 | 10.1 | 5.5 | RRIO, zero crossover |
| AD8602 | 2.7 to 5.5 | 500 | 2 | 30 | 8 | 5 | Low cost |
| AD8515 | 1.8 to 5 | 6000 | 4 (typ) | 20 | 5 | 2.7 | Low cost, smaller package |
| AD8606 | 2.7 to 5.5 | 65 | 4.5 | 80 | 10 | 5 | Low cost, smaller package |
| ADA4897 | 3 to 10 | 500 | 0.2 (typ) | 135 | 230 | 120 | High speed current measurement |
| AD8027 | 2.7 to 12 | 800 | 1.5 (typ) | 120 | 190 | 90 | High speed current measurement |

Precision Voltage References

Voltage references are used as converter voltage reference or signal conditioning. Low drift and low cost parts are needed in motor control.

| Part Number | Power Supply (V) | Output Voltage (V) | Max Drift (ppm/°C) | Load Current (mA) | Comment |
|-------------|------------------|------------------------------|--------------------|-------------------|--|
| ADR43x | Up to 18 | 2.048, 2.5, 3, 4.5, 4.096, 5 | 3 | +30/–20 | Low noise |
| ADR34xx | Up to 5.5 | 1.2, 2.048, 2.5, 3, 4.096, 5 | 8 | +10/–3 | Low power, small size of 6-lead SOT-23, low cost |
| ADR1581 | 5 | 1.25 | 50 | N/A | Low cost, small size of 3-lead SOT-23 |

Reference Designs

Analog Devices reference designs enable design engineers to apply ADI's vast applications expertise quickly and with a high level of confidence toward their own design using circuits that are built and tested by the experts to ensure both performance and function. Low cost hardware allows for evaluation and rapid prototyping with several development platforms. Thorough documentation and design files ease application understanding and minimize system integration issues.



Hardware Enables

- A modular approach to system designs
- · Application ready software
- Fast prototyping with FPGA and MCU

Design and Integration Files Support

- Schematic, layout, BOM downloads
- · Linux code for driver development
- · Simplified application integration

Documentation Provides

- Expert applications knowledge
- Understanding of circuit capabilities
- · Tested and verified performance data

| Circuit Note Number | Title | Applications | Products Used in This Circuit |
|------------------------|--|---|--|
| CN0288 | LVDT Signal Conditioning Circuit | Servos and robotics | AD598, AD7992, AD8615 |
| CN0301 | Universal LVDT Signal Conditioning Circuit | Servos and robotics | AD698, AD7992, AD8615 |
| CN0303 | MEMS-Based Vibration Analyzer with Frequency Response Compensation | Servos and roboticsDrivesApplication specific motor control | AD7866, AD8227, AD8615 |
| CN0323 | Magnetoresistive Angle Measurement | Servos and roboticsDrivesApplication specific motor control | AD7866, AD8227, AD8615 |
| CN0196 | H-Bridge Driver Circuit Using Isolated Half-Bridge Drivers | Servos and roboticsDrivesApplication specific motor control | ADCMP350, ADG787, ADP1720, ADuC7061, ADuM3100, ADuM7234 |
| CN0313 | EMC Compliant RS-485 Transceiver Protection Circuits | Servos and roboticsDrivesApplication specific motor control | ADM3485E |
| CN0218 | 500 V Common-Mode Voltage Current Monitor | Servos and roboticsDrivesApplication specific motor control | AD7171, AD8212, AD8605, ADR381, ADuM5402 |
| CN0192 | High Current Driver for the AD2S1210 Resolver-to-Digital Reference Signal Output | Servos and roboticsApplication specific motor control | AD2S1210, AD8662 |
| CN0185 | A Novel Analog-to-Analog Isolator Using an Isolated Sigma-Delta Modulator Isolated DC-to-DC Converter and Active Filter | Application specific motor control | AD7400A, AD8646, ADP121, ADP3301, ADuM5000 |
| CN0116 | High Voltage High Precision Current Sensing with Output Level Shifting Using the AD8210 Current Sense Amplifier and the AD8274 Difference Amplifier | Application specific motor control | AD780, AD8210, AD8274 |
| CN0100 | Measuring –48 V High-Side Current Using the AD629 Difference Amplifier AD8603 Op Amp AD780 Reference and AD7453 12-Bit ADC Single-Supply Components | Application specific motor control | AD629, AD7453, AD780, AD8603 |



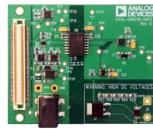
CN0301 circuit evaluation board.



CN0323 circuit evaluation board.



CN0313 circuit evaluation board.



CN0218 circuit evaluation board.

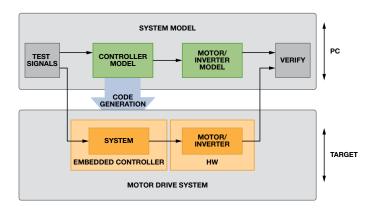


CN0185 circuit evaluation board.

Model-Based Design—Making Design Easy

System Design Value for Any Motor Control System

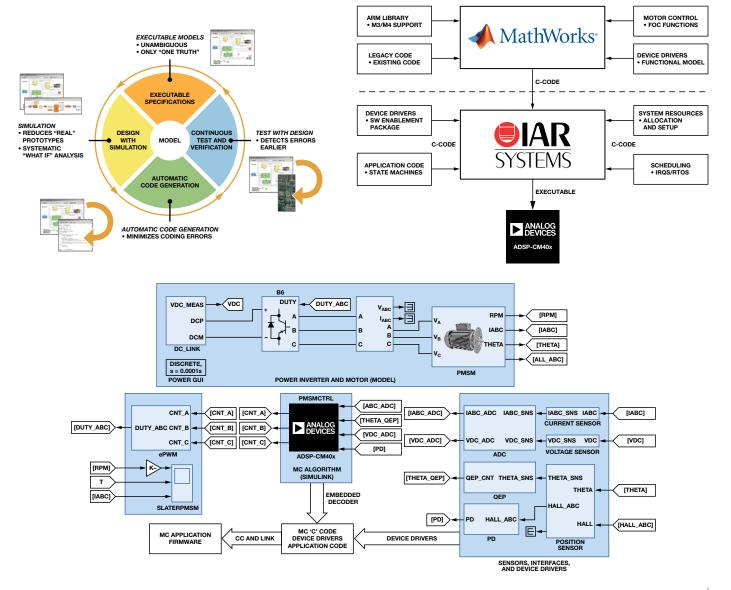
Model-based design was developed to help simplify the difficulties and complexities inherent in control systems designs using traditional non-automated methods. Model-based design provides the designer with a virtual design environment that enables developers to use a single model of their entire system for data analysis, model visualization, testing, validation, and eventually product deployment. Once the model is built and tested, accurate real-time software is automatically generated, saving time and reducing overall development costs as compared to traditional manual coding. Model-based design with automatic code generation can also be used in rapid prototyping, further reducing the design cycle. By its nature, model-based design provides a structure for software reuse that permits established designs to be effectively scaled up or down in complexity depending upon the desired application and reliably upgraded in a more simplistic and cost-effective manner.



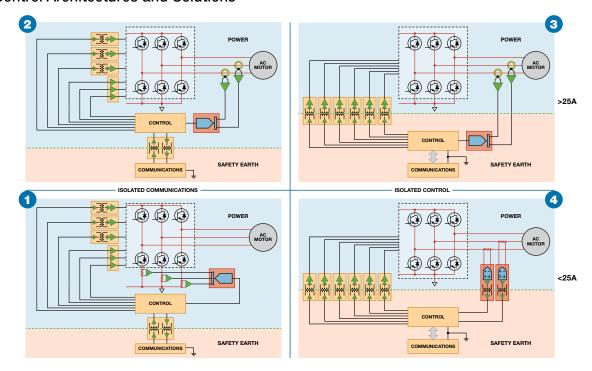
Model-based design saves valuable design resources by cutting design time and providing final designs that are more accurate and more closely approximate predesign expectations for performance, systems functionality, and features and schedule. It provides:

Benefits

- Faster design iterations that produce desired performance, functionality, and capabilities.
- Design cycles that are more predictable and result in faster product shipments
- Reduction in design, development, and implementation



Motor Control Architectures and Solutions



It is easy to become overwhelmed with the endless number of variations in motor control configurations. To help simplify things, Analog Devices has consolidated the number of possible motor control architectures into four fundamental categories that most systems would fall into. Depending on your selection, ADI can quickly identify and recommend the proper products and solutions for your specific design.

| Zone | Configuration Description | Typical Application | Recommended Solutions |
|------|---|---|--|
| 1 | This configuration is traditionally used in applications where the current flow is less than 25 A and the main isolation barrier is introduced at the interface between the controller path and communication interface (controller at motor potential) | Inverters | Digital isolationPower managementStandard linear |
| 2 | This configuration is traditionally used in applications where the current flow is greater than 25 A and the main isolation barrier is introduced at the interface between the controller path and communication interface (controller at motor potential) | Simple function servos and drives | Digital isolation Power management Standard linear Position and current sensing Embedded processors |
| 3 | This configuration is traditionally used in applications where the current flow is greater than 25 A and the main isolation barrier is introduced at the controller level supporting the highest isolated functionality of the control and communication boards (control at ground level) | Advanced functionality servos and drives | Digital isolation Power management Standard linear Position and current sensing Embedded processors |
| 4 | This configuration is traditionally used in applications where the current flow is less than 25 A and the main isolation barrier is introduced at the controller level supporting the highest isolated functionality of the control and communication boards (control at ground level) | Multiaxis servo designs, with real-time Ethernet and multiaxis processing capability provided by Xilinx FPGA. | Digital isolation Power management Standard linear Position and current sensing Embedded processors FPGAs |

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Analog Devices third-party developers network consists of companies all over the world that provide hardware products, software products, algorithms, and design services for a wide variety of applications and markets. To learn more about this program go to

www.analog.com/en/third-party-developers/processors-DSP/content/search.html

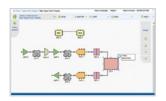
Online Tools And Resources

To learn more about products, signal chain solutions, and technical expertise offered by Analog Devices to help engineers meet today's motor control design challenges, visit www.analog.com/motorcontrol.

Signal Chain Designer-

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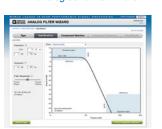
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product recommendations, tested application circuits, integrated Analog Filter Wizard™ and Photodiode Wizard,™ and connection to other Analog Devices engineering tools to provide an easy to use, one stop circuit builder for design engineers.

Analog Filter Wizard — www.analog.com/filterwizard

This online tool simplifies the filter design process with an intuitive user interface and easily accessible tutorials and help.



ADIsimPower—www.analog.com/adisimpower

ADIsimPower[™] is a collection of downloadable Excel spreadsheets that produce com-



plete power designs optimized to your design goals. Get a schematic, bill of materials, and performance data customized to your specific needs in minutes.

EngineerZone® Online Support Community

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Photodiode Wizard—www.analog.com/photodiode

The new Photodiode Wizard speeds up the process of selecting and designing the best circuit for your particular photodiode application.



Analog Devices Wiki-wiki.analog.com

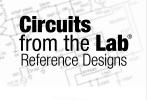
This wiki provides developers using Analog Devices products with software and documentation, including HDL interface code, software drivers, and reference



project examples for FPGA connectivity. It also contains user guides for some Analog Devices evaluation boards to help developers get up and running fast.

Circuits from the Lab Reference Designs

For a complete list of Analog Devices Circuits from the Lab® Reference Designs for motor control designs, visit



www.analog.com/circuits.

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I²C refers to a communications protocol originally developed by Philips Semiconductors (now NXP Semiconductors)

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