



General Description

The XR3072X and XR3078X high performance RS-485 / RS-422 devices are designed for improved performance in noisy industrial environments and increased tolerance to system faults.

The analog bus pins can withstand direct shorts up to $\pm 18V$, and are protected against ESD events up to $\pm 15kV$. The differential high output driver delivers 10% higher SNR than standard RS-485 / RS-422 devices, affording additional noise margin or extended cable lengths.

The receivers include full fail-safe circuitry, guaranteeing a logic-high receiver output when the receiver inputs are open, shorted or undriven. The receiver input impedance is at minimum $96k\Omega$ (1/8 unit load), allowing up to 256 devices on the bus while preserving the full signal margin.

The drivers are protected by short circuit detection as well as thermal shutdown, and maintain high impedance in shutdown or when powered off. The XR3072X drivers are slew limited for reduced EMI and error-free communication over long or unterminated data cables.

The devices with DE and \overline{RE} pins include hot swap circuitry to prevent false transitions on the bus during powerup or live insertion, and can enter a 1nA low current shutdown mode for extreme power savings.

The transceivers draw less than $600\mu A$ from a 3.3V supply, and typically only $300\mu A$ when idling with the receivers active.

Features

- 10% higher SNR (Signal-to-Noise Ratio) compared to other RS-485 devices (1.65V vs. 1.5V)
- $\pm 18V$ fault tolerance on analog bus pins
- Robust ESD (ElectroStatic Discharge) protection:
 - $\pm 15kV$ IEC 61000-4-2 Air Gap Discharge
 - $\pm 8kV$ IEC 61000-4-2 Contact Discharge
 - $\pm 15kV$ Human Body Model
 - $\pm 4kV$ Human Body Model on non-bus pins
- 3.0V to 3.6V operation ($3.3V \pm 10\%$)
- $300\mu A$ idle current, 1nA shutdown current
- Enhanced receiver fail-safe protection for open, shorted or terminated but idle data lines
- Hot-swap glitch protection on DE and \overline{RE} pins
- Driver short circuit current limit and thermal shutdown for overload protection
- $1/8^{th}$ unit load allows up to 256 devices on bus
- Industrial operating temperature range ($-40^{\circ}C$ to $85^{\circ}C$)
- Industry standard 8- and 14 -pin NSOIC packages

Applications

- Motor control
- Security systems
- Building and process automation
- Remote utility meter reading
- Energy monitoring and control
- Long or unterminated transmission lines

Ordering Information - [page 15](#)

Product Selector Guide

Table 1: Selector Guide

| Part Number | Duplex | Data Rate | Shutdown | Receiver and Driver Enable | Transceivers on Bus | Footprint |
|---------------|--------|-----------|----------|----------------------------|---------------------|-----------|
| XR3072XIDTR-F | Half | 250kbps | Yes | Yes | 256 | SN75176 |
| XR3078XIDTR-F | Half | 20Mbps | Yes | Yes | 256 | SN75176 |

Revision History

| Document No. | Release Date | Change Description |
|--------------|--------------|---|
| 1.0.0 | Sept 2013 | Production release. |
| 1.0.1 | Dec 2013 | Updated typical driver differential rise / fall time, page 7. |
| 1.0.2 | May 2015 | Added extended temp range -40°C to 125°C part numbers, updated I _{SHDN} for industrial and extended temp range, updated ordering information table and table #7. ECN# 1525-07. |
| 1.0.3 | 8/30/19 | Update to MaxLinear format, update Ordering Information and move to page 15. Move ESD Ratings to below Absolute Maximum Ratings section, Pinout and Block Diagram to Pin Information section, and Product Selector Guide to first page. Remove obsolete products: XR3070X, XR3071X, XR3073X, XR3074X, XR3075X, XR3076X and XR3077X. |

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Specifications

Absolute Maximum Ratings

Important: These are stress ratings only and functional operation of the device at these ratings or any other above those indicated in the operation sections of the specifications below is not implied. Exposure to absolute maximum rating conditions for extended periods of time may affect reliability and cause permanent damage to the device.

Table 1: Absolute Maximum Ratings

| Parameter | Minimum | Maximum | Units |
|--|---|----------------|--------------------|
| V_{CC} | -0.3 | 7.0 | V |
| Input voltage at control and driver input (\overline{RE} , DE and DI) | -0.3 | 7.0 | V |
| Receiver output voltage (RO) | -0.3 | $V_{CC} + 0.3$ | V |
| Driver output voltage (A, B, Y & Z) | -18 | 18 | V |
| Receiver input voltage (A, B) | -18 | 18 | V |
| Transient voltage pulse, through 100 Ω , Figure 5 | -70 | 70 | V |
| Driver output current | -250 | 250 | mA |
| Storage temperature range | -65 | 150 | $^{\circ}\text{C}$ |
| Lead temperature (soldering, 10s) | | 300 | $^{\circ}\text{C}$ |
| Package Power Dissipation | | | |
| 8-pin SO, $\Theta_{JA} = 128.4^{\circ}\text{C}/\text{W}$ | Maximum junction temperature = 150 $^{\circ}\text{C}$ | | |
| 14-pin SO, $\Theta_{JA} = 86^{\circ}\text{C}/\text{W}$ | | | |

ESD Ratings

Table 2: ESD Ratings

| Parameter | Limit | Units |
|---|----------|-------|
| HBM - Human Body Model (pins A, B, Y & Z) | ± 15 | kV |
| HBM - Human Body Model (all other pins) | ± 4 | kV |
| IEC 1000-4-2 Airgap Discharge (pins A, B, Y & Z) | ± 15 | kV |
| IEC 1000-4-2 Contact Discharge (pins A, B, Y & Z) | ± 8 | kV |

Caution:

ESD (Electrostatic Discharge) sensitive device. Permanent damage may occur on unconnected devices subject to high energy electrostatic fields. Unused devices must be stored in conductive foam or shunts. Personnel should be properly grounded prior to handling this device. The protective foam should be discharged to the destination socket before devices are removed.

Electrical Characteristics

Unless otherwise noted, $V_{CC} = 3.3V \pm 10\%$, $T_A = T_{MIN}$ to T_{MAX} . Typical values are at $V_{CC} = 3.3V$, $T_A = 25^\circ C$.

Table 3: Electrical Characteristics

| Parameter | Symbol | Test Condition | Minimum | Typical | Maximum | Units |
|---|-----------|---|----------------|------------|-----------|------------|
| Driver DC Characteristics | | | | | | |
| Supply voltage range | V_{CC} | | 3.0 | | 3.6 | V |
| Differential Driver Output | V_{OD} | No load | 3 | | V_{CC} | V |
| | | $R_L = 100$ (RS-422), Figure 2 | 2 | | V_{CC} | |
| | | $R_L = 54$ (RS-485), Figure 2 | 1.65 | | V_{CC} | |
| | | $-7V \leq V_{CM} \leq 12V$, Figure 3 | 1.5 | | V_{CC} | |
| Change in magnitude of differential output voltage | DV_{OD} | | | | ± 0.2 | V |
| Driver common mode output voltage (steady state) | V_{CM} | $R_L = 54\Omega$ (RS-485) or $R_L = 100\Omega$ (RS-422), Figure 2 ⁽¹⁾ | | $V_{CC}/2$ | 3 | V |
| Change in magnitude of common-mode output voltage | DV_{CM} | | | | ± 0.2 | V |
| Logic input thresholds (DI, DE, \overline{RE}) | V_{IH} | Logic input high | 2 | | | V |
| | V_{IL} | Logic input low | | | 0.8 | V |
| Input hysteresis (DI, DE, \overline{RE}) | V_{HYS} | | | 100 | | mV |
| Logic input current (DI, DE, \overline{RE}) | I_{IN} | $0V \leq V_{IN} \leq V_{CC}$, after first transition ⁽²⁾ | | | ± 1 | μA |
| Logic input current (DE and \overline{RE}) | | Until first transition ⁽²⁾ | | 100 | ± 200 | μA |
| Input Current (A and B) | $I_{A,B}$ | $V_{OUT} = 12V$, $DE = 0V$, $V_{CC} = 0V$ or $5.5V$ | | | 125 | μA |
| | | $V_{OUT} = -7V$, $DE = 0V$, $V_{CC} = 0V$ or $5.5V$ | -100 | | | |
| Driver short-circuit output current | I_{OSD} | $-7V \leq V_{OUT} \leq 12V$, Figure 4 | | | ± 250 | mA |
| Driver Thermal Characteristics | | | | | | |
| Thermal shutdown threshold | T_{TS} | Junction temperature ⁽⁴⁾ | | 175 | | $^\circ C$ |
| Thermal shutdown hysteresis ⁽⁴⁾ | T_{TSH} | | | 15 | | $^\circ C$ |
| Receiver DC Characteristics | | | | | | |
| Receiver differential threshold voltage ($V_A - V_B$) | V_{TH} | $-7V \leq V_{CM} \leq 12V$ | -200 | -125 | -50 | mV |
| Receiver input hysteresis | DV_{OH} | $V_{CM} = 0V$ | | 25 | | mV |
| Receiver output high voltage (RO) | V_{OH} | $I_O = -1mA$ | $V_{CC} - 0.6$ | | | V |
| Receiver output low voltage (RO) | V_{OL} | $I_O = 1mA$ | | | 0.4 | V |
| High-Z receiver output current | I_{OZR} | $0 \leq V_{OUT} \leq V_{CC}$ | | | ± 1 | μA |
| Receiver input resistance | R_{IN} | $-7V \leq V_{CM} \leq 12V$ | 96 | | | k Ω |
| Receiver output short-circuit current | I_{OSC} | $0V \leq V_{RO} \leq V_{CC}$ | | | ± 80 | mA |

Table 3: Electrical Characteristics (Continued)

| Parameter | Symbol | Test Condition | Minimum | Typical | Maximum | Units |
|---|-------------------------|---|---------|---------|---------|---------|
| Supply Current | | | | | | |
| Supply current | I_{CC} | No load, $\overline{RE} = 0V$, $DE = V_{CC}$, $DI = 0V$ | | 425 | 600 | μA |
| | | No load, $\overline{RE} = V_{CC}$, $DE = V_{CC}$, $DI = 0V$ | | 330 | 600 | |
| | | No load, $\overline{RE} = 0V$, $DE = 0V$ Receiver A and B inputs open | | 300 | 500 | |
| Supply current in shutdown mode | I_{SHDN} | $\overline{RE} = V_{CC}$, $DE = 0V$ | | 0.001 | 1 | μA |
| Driver AC Characteristics - XR3072X (250kbps) | | | | | | |
| Driver propagation delay (low to high) | t_{DPLH} | $C_L = 50pF$, $R_L = 54\Omega$, Figure 6 | 250 | | 1500 | ns |
| Driver propagation delay (high to low) | t_{DPHL} | | 250 | | 1500 | ns |
| Differential driver output skew | $ t_{DPLH} - t_{DPHL} $ | | | 20 | 200 | ns |
| Driver differential output rise or fall time | t_{DR} , t_{DF} | | 350 | | 1600 | ns |
| Maximum data rate | | $1/t_{UI}$, duty cycle 40% to 60% | 250 | | | kbps |
| Driver enable to output high | t_{DZH} | $C_L = 50pF$, $R_L = 500\Omega$, Figure 7 | | 200 | 2500 | ns |
| Driver enable to output low | t_{DZL} | | | 200 | 2500 | ns |
| Driver disable from output high | t_{DZH} | | | 6 | 100 | ns |
| Driver disable from output low | t_{DLZ} | | | 6 | 100 | ns |
| Driver enable from shutdown to output high | $t_{DZH(SHDN)}$ | $C_L = 50pF$, $R_L = 500\Omega$, Figure 7 | | | 5500 | ns |
| Driver enable from shutdown to output low | $t_{DZL(SHDN)}$ | | | | 5500 | ns |
| Time to shutdown ^(3, 4) | t_{SHDN} | | 50 | 200 | 600 | ns |
| Receiver AC Characteristics - XR3072X (250kbps) | | | | | | |
| Receiver propagation delay (low to high) | t_{RPLH} | $C_L = 15pF$, $V_{ID} = \pm 2V$, V_{ID} rise and fall times < 15ns Figure 8 | | | 200 | ns |
| Receiver propagation delay (high to low) | t_{RPHL} | | | | 200 | ns |
| Propagation delay skew | $t_{RPLH} - t_{RPHL}$ | | | | 30 | ns |
| Maximum data rate | | $1/t_{UI}$, duty cycle 40% to 60% | 250 | | | kbps |
| Receiver enable to output high | t_{RZH} | $C_L = 15pF$, $R_L = 1k\Omega$, Figure 9 | | | 50 | ns |
| Receiver enable to output low | t_{RZL} | | | | 50 | ns |
| Receiver disable from output high | t_{RHZ} | | | | 50 | ns |
| Receiver disable from output low | t_{RLZ} | | | | 50 | ns |
| Receiver enable from shutdown to output high | $t_{RZH(SHDN)}$ | $C_L = 15pF$, $R_L = 1k\Omega$, Figure 9 | | | 3500 | ns |
| Receiver enable from shutdown to output low | $t_{RZL(SHDN)}$ | | | | 3500 | ns |
| Time to shutdown ^(3, 4) | t_{SHDN} | | 50 | 200 | 600 | ns |

Table 3: Electrical Characteristics (Continued)

| Parameter | Symbol | Test Condition | Minimum | Typical | Maximum | Units |
|--|-------------------------|---|---------|---------|---------|-------|
| Driver AC Characteristics - XR3078X (20Mbps) | | | | | | |
| Driver propagation delay (low to high) | t_{DPLH} | $C_L = 50\text{pF}$, $R_L = 54\Omega$, Figure 6 | | | 25 | ns |
| Driver propagation delay (high to low) | t_{DPHL} | | | | 25 | ns |
| Differential driver output skew | $ t_{DPLH} - t_{DPHL} $ | | | | 5 | ns |
| Driver differential output rise or fall time | t_{DR} , t_{DF} | | | 12 | | ns |
| Maximum data rate | | $1/t_{UI}$, duty cycle 40% to 60% | 20 | | | Mbps |
| Driver enable to output high | t_{DZH} | $C_L = 50\text{pF}$, $R_L = 500\Omega$, Figure 7 | | | 45 | ns |
| Driver enable to output low | t_{DZL} | | | | 45 | ns |
| Driver disable from output high | t_{DHZ} | | | | 40 | ns |
| Driver disable from output low | t_{DLZ} | | | | 40 | ns |
| Driver enable from shutdown to output high | $t_{DZH(SHDN)}$ | $C_L = 50\text{pF}$, $R_L = 500\Omega$, Figure 7 | | | 250 | ns |
| Driver enable from shutdown to output low | $t_{DZL(SHDN)}$ | | | | 250 | ns |
| Time to shutdown ^(3, 4) | t_{SHDN} | | 50 | 200 | 600 | ns |
| Receiver AC Characteristics - XR3078X (20Mbps) | | | | | | |
| Receiver propagation delay (low to high) | t_{RPLH} | $C_L = 15\text{pF}$, $V_{ID} = \pm 2\text{V}$, V_{ID} rise and fall times < 15ns Figure 8 | | | 50 | ns |
| Receiver propagation delay (high to low) | t_{RPHL} | | | | 50 | ns |
| Propagation delay skew | $ t_{RPLH} - t_{RPHL} $ | | | | 5 | ns |
| Maximum data rate | | $1/t_{UI}$, duty cycle 40% to 60% | 20 | | | Mbps |
| Receiver enable to output high | t_{RZH} | $C_L = 15\text{pF}$, $R_L = 1\text{k}\Omega$, Figure 9 | | | 30 | ns |
| Receiver enable to output low | t_{RZL} | | | | 30 | ns |
| Receiver disable from output high | t_{RHZ} | | | | 30 | ns |
| Receiver disable from output low | t_{RLZ} | | | | 30 | ns |
| Receiver enable from shutdown to output high | $t_{RZH(SHDN)}$ | $C_L = 15\text{pF}$, $R_L = 1\text{k}\Omega$, Figure 9 | | | 1800 | ns |
| Receiver enable from shutdown to output low | $t_{RZL(SHDN)}$ | | | | 1800 | ns |
| Time to shutdown ^(3, 4) | t_{SHDN} | | 50 | 200 | 600 | ns |

1. Change in magnitude of differential output voltage and change in magnitude of common mode output voltage are the changes in output voltage when DI input changes state.

2. The hot swap feature disables the DE and \overline{RE} inputs for the first 10 μs after power is applied. Following this time period these inputs are weakly pulled to their disabled state (low for DE, high for \overline{RE}) until the first transition, after which they become high impedance inputs.

3. The transceivers are put into shutdown by bringing \overline{RE} high and DE low simultaneously for at least 600ns. If the control inputs are in this state for less than 50ns, the device is guaranteed to not enter shutdown. If the enable inputs are held in this state for at least 600ns, the device is assured to be in shutdown. Note that the receiver and driver enable times increase significantly when coming out of shutdown.

4. This spec is guaranteed by design and bench characterization.

Test Circuits and Timing Diagrams

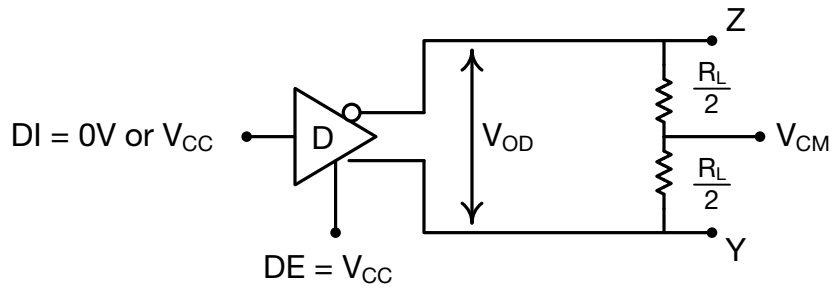


Figure 2: Differential Driver Output Voltage

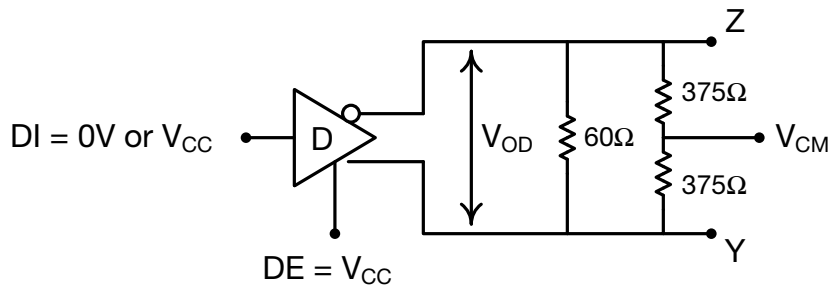


Figure 3: Differential Driver Output Voltage Over Common Mode

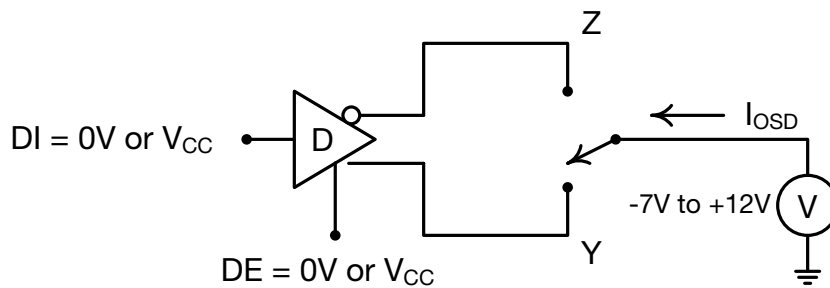


Figure 4: Driver Output Short Circuit Current

Device powered on or powered off

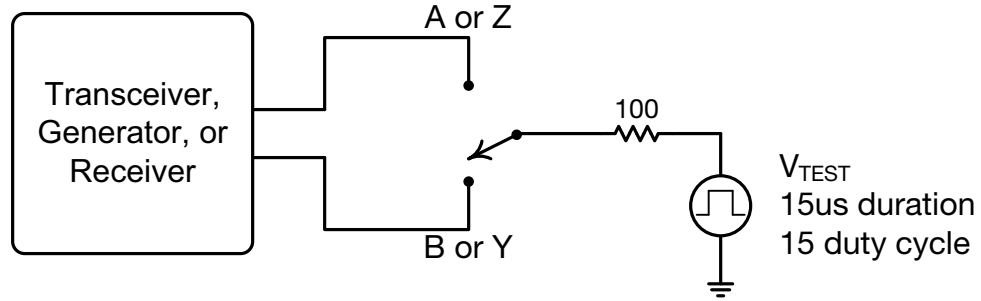


Figure 5: Transient Overvoltage Test Circuit

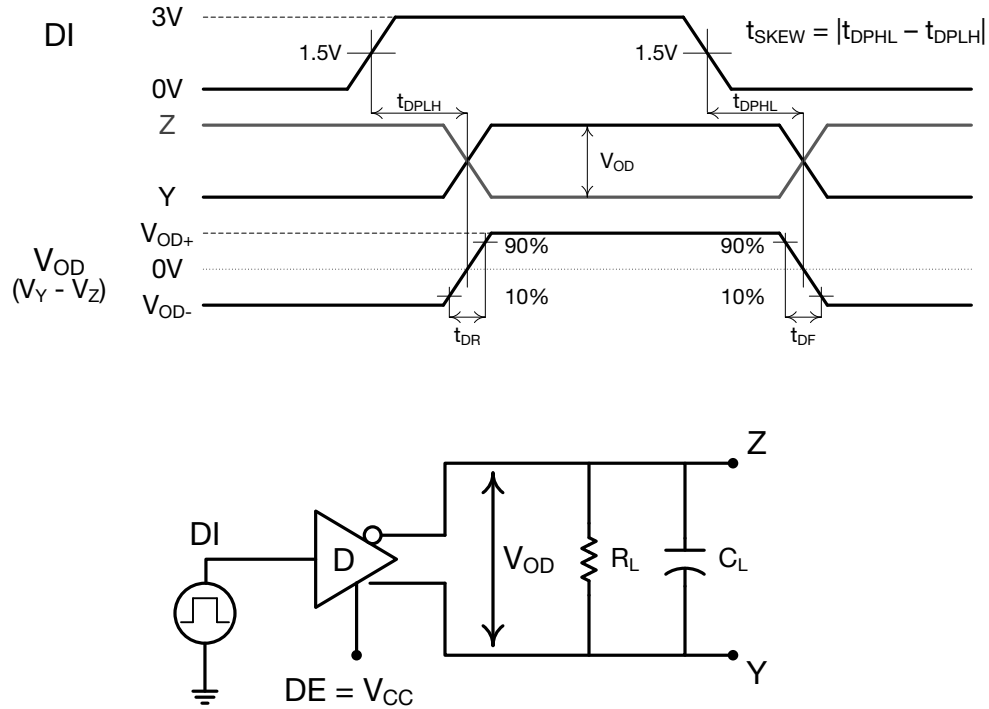


Figure 6: Driver Propagation Delay Test Circuit and Timing Diagram

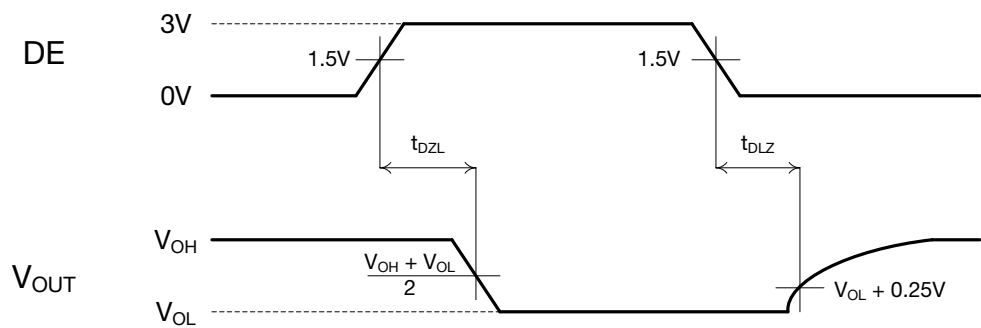
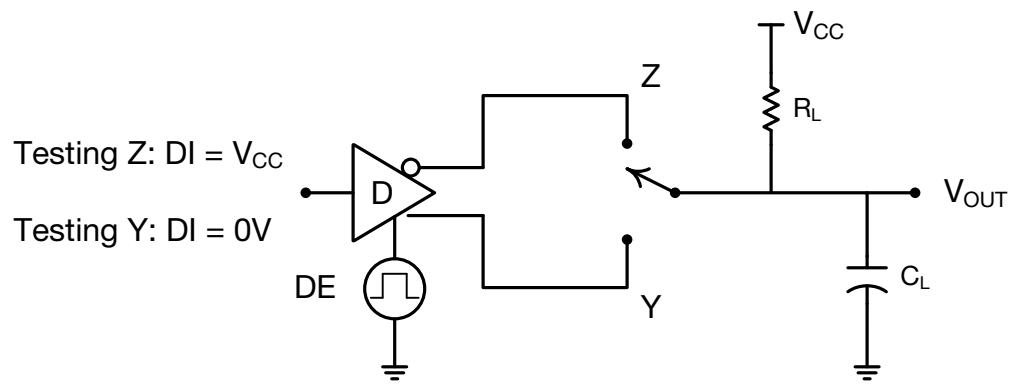
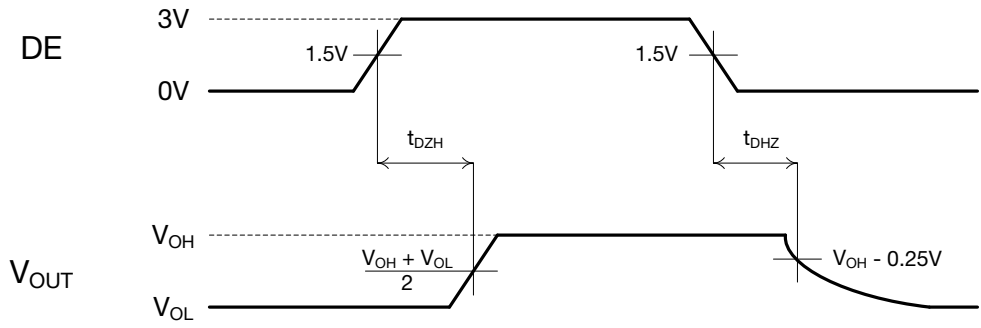
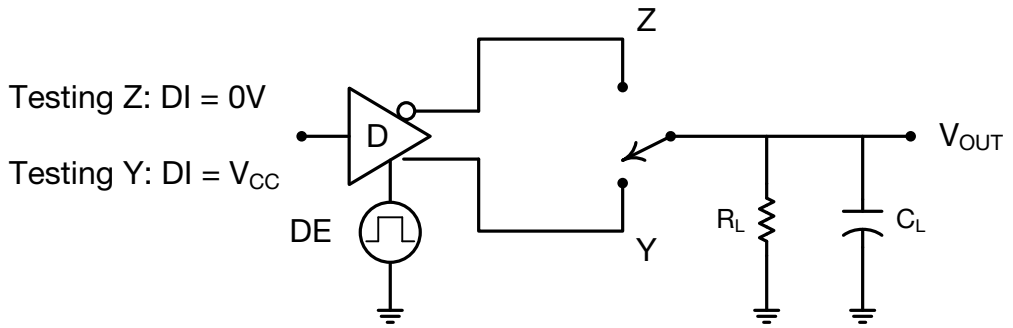


Figure 7: Driver Enable and Disable Timing Test Circuits and Timing Diagrams

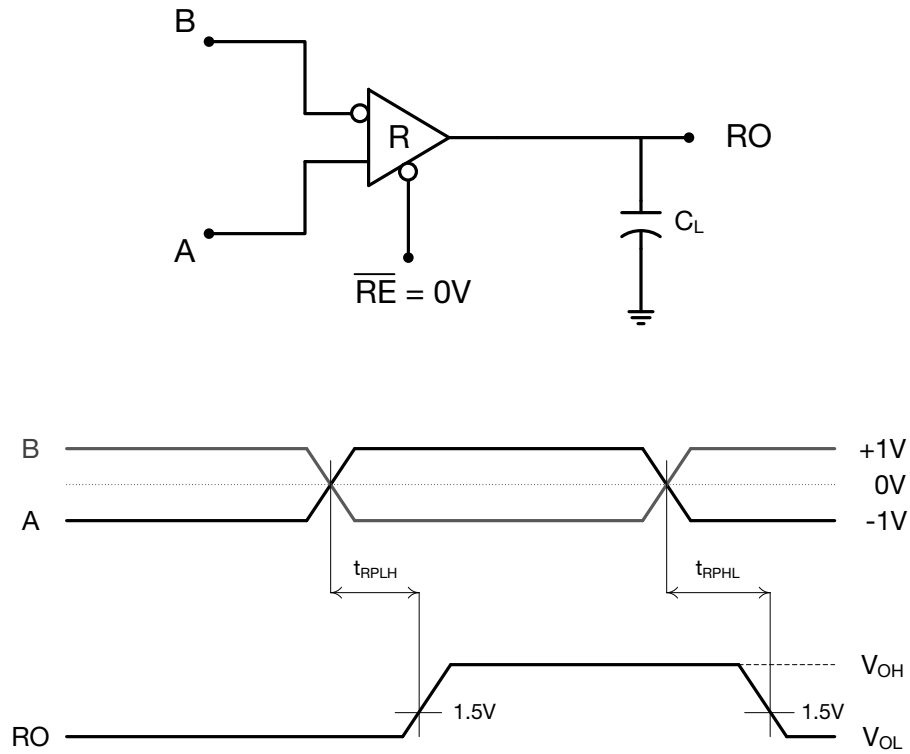


Figure 8: Receiver Propagation Delay Test Circuit and Timing Diagram

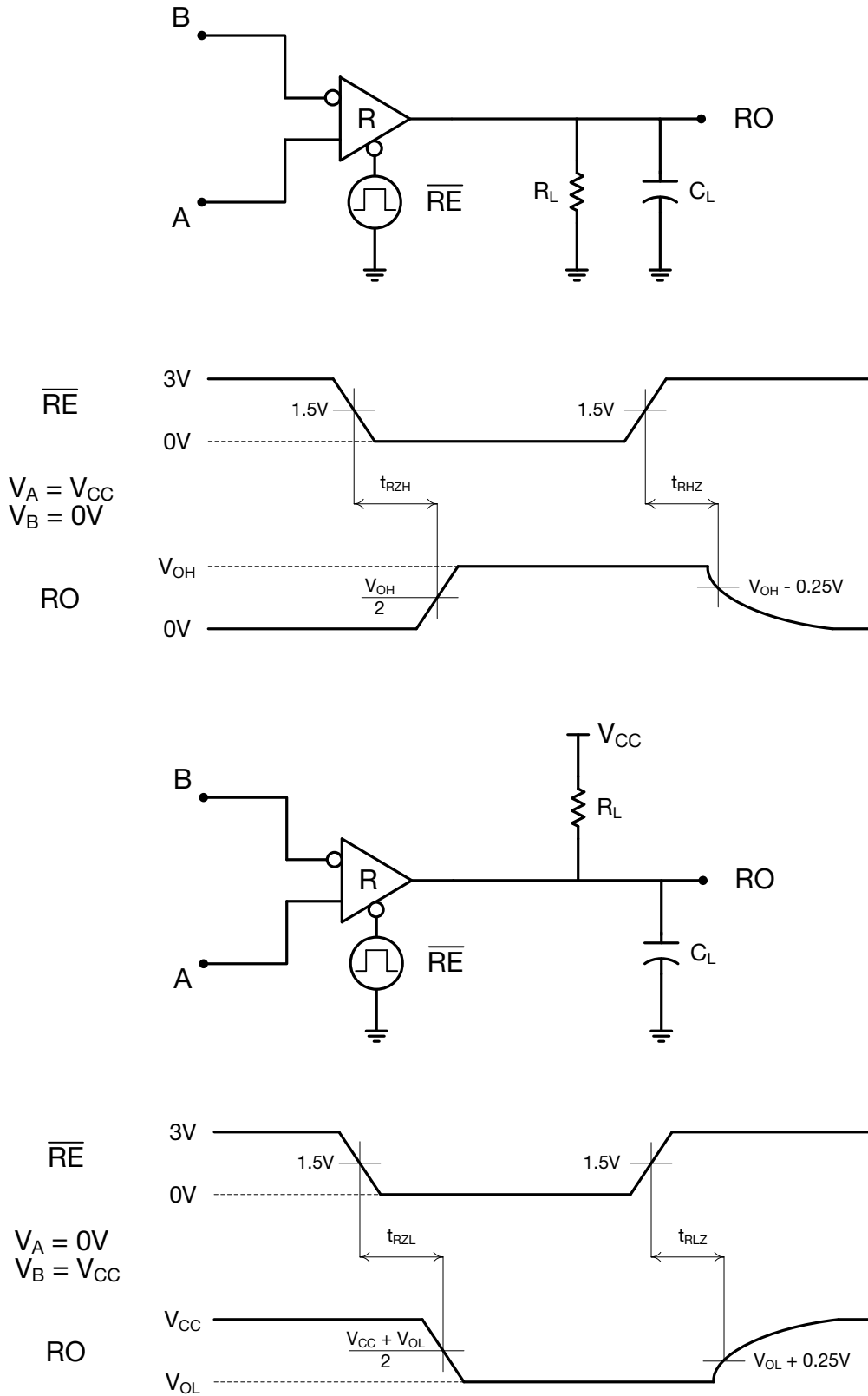


Figure 9: Receiver Enable and Disable Test Circuits and Timing Diagrams

Pin Information

Pin Configuration and Block Diagram

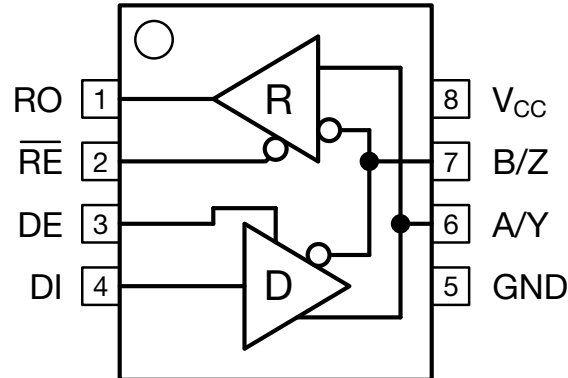


Figure 10: Pin Configuration and Half-Duplex Block Diagram

Pin Descriptions

Table 4: Pin Descriptions

| Pin Number | Pin Name | Type | Pin Function |
|------------|-----------------|-------|--|
| 1 | RO | Out | Receiver output. When \overline{RE} is low and if $(A-B) \leq -50\text{mV}$, RO is High. If $(A-B) \geq -200\text{mV}$, RO is low. |
| 2 | \overline{RE} | In | Receiver output enable (Hot swap). When \overline{RE} is low, RO is enabled. When \overline{RE} is high, RO is high impedance. \overline{RE} should be high and DE should be low to enter shutdown mode. |
| 3 | DE | In | Driver output enable (Hot swap). When DE is high, outputs are enabled. When DE is low, outputs are high impedance. DE should be low and \overline{RE} should be high to enter shutdown mode. |
| 4 | DI | In | Driver input. With DE high, a low level on DI forces non-inverting output low and inverting output high. Similarly, a high level on DI forces non-inverting output high and inverting output low. |
| 5 | GND | Pwr | Ground. |
| 6 | A | I / O | Non-inverting receiver input and non-inverting driver output. |
| 7 | B | I / O | Inverting receiver input and inverting driver output. |
| 8 | V _{CC} | Pwr | 3.3V positive supply input. Bypass to GND with a 0.1 μF capacitor. |

Product Description

The XR3072X and XR3078X RS-485 / RS-422 devices are part of MaxLinear's X Series high performance serial interface product line. The analog bus pins can survive direct shorts up to $\pm 18\text{V}$, and are protected against ESD events up to $\pm 15\text{kV}$. The high output differential driver delivers 10% higher SNR than other RS-485 / 422 devices, affording additional noise margin or extended cable lengths.

Enhanced Fail-Safe

Ordinary RS-485 differential receivers will be in an indeterminate state whenever the data bus is not being actively driven. The enhanced failsafe feature of the XR3072X and XR3078X guarantees a logic-high receiver output when the receiver inputs are open, shorted, or when they are connected to a terminated transmission line with all drivers disabled. In a terminated bus with all transmitters disabled, the receivers' differential input voltage is pulled to 0V by the termination. The XR3072X and XR3078X interpret 0V differential as a logic high with a minimum 50mV noise margin while maintaining compliance with the EIA / TIA-485 standard of $\pm 200\text{mV}$. Although the XR3072X and XR3078X do not need failsafe biasing resistors, they can operate without issue if biasing is used.

Receiver Input Filtering

The XR3072X receiver incorporates internal filtering in addition to input hysteresis. This filtering enhances noise immunity by ignoring signals that do not meet a minimum pulse width of 30ns. Receiver propagation delay increases slightly due to this filtering. The high speed XR3078X does not have this input filtering.

Hot-Swap Capability

When V_{CC} is first applied, the XR3072X and XR3078X hold the driver enable and receiver enable inactive for approximately 10 microseconds. During power ramp-up, other system ICs may drive unpredictable values, or tri-stated lines may be influenced by stray capacitance. The hot-swap feature prevents these devices from driving any output signal until power has stabilized. After the initial 10 μs , the driver and receiver enable pins are weakly pulled to their disabled states (low for DE, high for $\overline{\text{RE}}$) until the first transition. After the first transition, the DE and $\overline{\text{RE}}$ pins operate as high impedance inputs.

If circuit boards are inserted into an energized backplane (commonly called "live insertion" or "hot-swap"), power may suddenly be applied to all circuits. Without the hot-swap capability, this situation could improperly enable the transceiver's driver or receiver, driving invalid data onto shared buses and possibly causing driver contention or device damage.

Driver Output Protection

Two mechanisms prevent excessive output current and power dissipation caused by faults or by bus contention. First, a driver current limit on the output stage provides immediate protection against short circuits over the whole common-mode voltage range. Second, a thermal shutdown circuit forces the driver outputs into a high-impedance state if junction temperature becomes excessive.

Line Length

The RS-485 / RS-422 standard covers line lengths up to 4000ft. Maximum achievable line length is a function of signal attenuation and noise. Termination prevents signal reflections by eliminating the impedance mismatches on a transmission line. Line termination is generally used if rise and fall times are shorter than the round-trip signal propagation time. Higher output drivers may allow longer cables to be used.

±15kV ESD Protection

ESD-protection structures are incorporated on all pins to protect against electrostatic discharges encountered during handling and assembly. The driver output and receiver inputs of the XR3072X and XR3078X have extra protection against static electricity. MaxLinear's uses state of the art structures to protect these pins against ESD of ±15kV without damage. The ESD structures withstand high ESD in all states: normal operation, shutdown and powered down. After an ESD event, the XR3072X and XR3078X keep operating without latch-up or damage.

ESD protection can be tested in various ways. The transmitter outputs and receiver inputs of the XR3072X and XR3078X are characterized for protection to the following limits:

- ±15kV using the Human Body Model
- ±8kV using the Contact Discharge Model
- ±15kV Air-gap Discharge Model

ESD Test Conditions

ESD performance depends on a variety of conditions. Contact MaxLinear for a reliability report that documents test setup, methodology and results.

IEC 61000-4-2

The IEC 61000-4-2 standard covers ESD testing and performance of finished equipment. However, it does not specifically refer to integrated circuits. The XR3072X and XR3078X help you design equipment to meet IEC 61000-4-2, without sacrificing board space and cost for external ESD-protection components.

The major difference between tests done using the Human Body Model and IEC 61000-4-2 is higher peak current in IEC 61000-4-2. Series resistance is lower in the IEC 61000-4-2 model. Hence, the ESD withstand voltage measured to IEC 61000-4-2 is generally lower than that of the Human Body Model.

The air-gap test involves approaching the device with a charged probe. The contact discharge method connects the probe to the device before the probe is energized.

256 Transceivers on the Bus

The standard RS-485 receiver input impedance is 12kΩ (1 unit load). A standard driver can drive up to 32 unit loads. The XR3072X and XR3078X have a 1/8th unit load receiver input impedance (96kΩ), allowing up to 256 transceivers to be connected in parallel on a communication line. Any combination of these devices and other RS-485 transceivers up to a total of 32 unit loads may be connected to the line.

Low Power Shutdown Mode

Low-power shutdown mode is initiated by bringing both \overline{RE} high and DE low simultaneously. While in shutdown, devices draw less than 1μA of supply current. DE and \overline{RE} may be tied together and driven by a single control signal. Devices are guaranteed not to enter shutdown if \overline{RE} is high and DE is low for less than 50ns. If the inputs are in this state for at least 600ns, the parts will enter shutdown.

Enable times t_{ZH} and t_{ZL} apply when the part is not in a low-power shutdown state. Enable times $t_{ZH(SHDN)}$ and $t_{ZL(SHDN)}$ apply when the parts are shutdown. The drivers and receivers take longer to become enabled from low-power shutdown mode $t_{ZH(SHDN)}$ and $t_{ZL(SHDN)}$ than from driver /receiver-disable mode (t_{ZH} , t_{ZL}).

Function Tables

Table 5: Half Duplex Transmitting

| Transmitting | | | | |
|-----------------|----|----|----------|---|
| Inputs | | | Outputs | |
| \overline{RE} | DE | DI | Y | Z |
| X | 1 | 1 | 1 | 0 |
| X | 1 | 0 | 0 | 1 |
| 0 | 0 | X | High-Z | |
| 1 | 0 | X | Shutdown | |

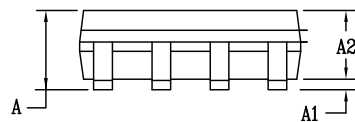
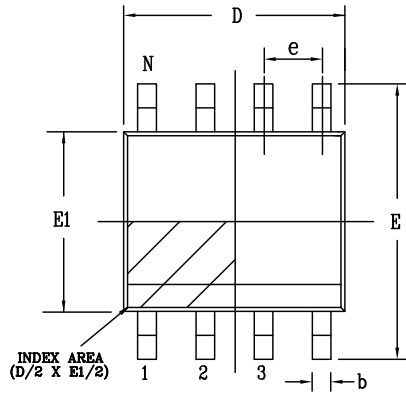
Table 6: Half Duplex Receiving

| Receiving | | | |
|-----------------|----|----------------------|----------|
| Inputs | | | Output |
| \overline{RE} | DE | $V_A - V_B$ | RO |
| 0 | X | $\geq -50\text{mV}$ | 1 |
| 0 | X | $\leq -200\text{mV}$ | 0 |
| 0 | X | Open / shorted | 1 |
| 1 | 1 | X | High-Z |
| 1 | 0 | X | Shutdown |

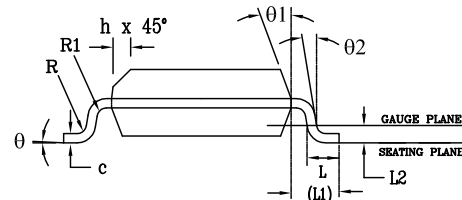
1. Receiver inputs $-200\text{mV} \leq V_A - V_B \leq -50\text{mV}$ are considered indeterminate.

Mechanical Dimensions

NSOIC8



Side View



Front View

| PACKAGE OUTLINE NSOIC .150" BODY JEDEC MS-012 VARIATION AA | | | | | | |
|---|---|-----|------|---|-----|-------|
| SYMBOLS | COMMON DIMENSIONS IN MM (Control Unit) | | | COMMON DIMENSIONS IN INCH (Reference Unit) | | |
| | MIN | NOM | MAX | MIN | NOM | MAX |
| A | 1.35 | — | 1.75 | 0.053 | — | 0.069 |
| A1 | 0.10 | — | 0.25 | 0.004 | — | 0.010 |
| A2 | 1.25 | — | 1.65 | 0.049 | — | 0.065 |
| b | 0.31 | — | 0.51 | 0.012 | — | 0.020 |
| c | 0.17 | — | 0.25 | 0.007 | — | 0.010 |
| E | 6.00 BSC | | | 0.236 BSC | | |
| E1 | 3.90 BSC | | | 0.154 BSC | | |
| e | 1.27 BSC | | | 0.050 BSC | | |
| h | 0.25 | — | 0.50 | 0.010 | — | 0.020 |
| L | 0.40 | — | 1.27 | 0.016 | — | 0.050 |
| L1 | 1.04 REF | | | 0.041 REF | | |
| L2 | 0.25 BSC | | | 0.010 BSC | | |
| R | 0.07 | — | — | 0.003 | — | — |
| R1 | 0.07 | — | — | 0.003 | — | — |
| q | 0° | — | 8° | 0° | — | 8° |
| q1 | 5° | — | 15° | 5° | — | 15° |
| q2 | 0° | — | — | 0° | — | — |
| D | 4.90 BSC | | | 0.193 BSC | | |
| N | 8 | | | 8 | | |

Drawing No: POD-00000108
Revision: A

Figure 11: Mechanical Dimension, NSOIC8

Ordering Information

Table 7: Ordering Information

| Ordering Part Number | Operating Temperature Range | Package | Packaging Method | Lead-Free ⁽²⁾ | Duplex / Data Rate |
|----------------------|-----------------------------|---------|------------------|--------------------------|--------------------|
| XR3072X | | | | | |
| XR3072XID-F | -40°C to 85°C | NSOIC8 | Tube | Yes | Half / 250kbps |
| XR3072XIDTR-F | -40°C to 85°C | NSOIC8 | Reel | Yes | Half / 250kbps |
| XR3078X | | | | | |
| XR3078XID-F | -40°C to 85°C | NSOIC8 | Tube | Yes | Half / 20Mbps |
| XR3078XIDTR-F | -40°C to 85°C | NSOIC8 | Reel | Yes | Half / 20Mbps |

1. Refer to www.maxlinear.com/XR3072X and www.maxlinear.com/XR3078X for most up-to-date Ordering Information.

2. Visit www.maxlinear.com for additional information on Environmental Rating.



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