

Important notice

Dear Customer,

On 7 February 2017 the former NXP Standard Product business became a new company with the tradename **Nexperia**. Nexperia is an industry leading supplier of Discrete, Logic and PowerMOS semiconductors with its focus on the automotive, industrial, computing, consumer and wearable application markets

In data sheets and application notes which still contain NXP or Philips Semiconductors references, use the references to Nexperia, as shown below.

Instead of http://www.nxp.com, http://www.nxp.com, http://www.nexperia.com, http://www.nexperia.com)

Instead of sales.addresses@www.nxp.com or sales.addresses@www.semiconductors.philips.com, use salesaddresses@nexperia.com (email)

Replace the copyright notice at the bottom of each page or elsewhere in the document, depending on the version, as shown below:

- © NXP N.V. (year). All rights reserved or © Koninklijke Philips Electronics N.V. (year). All rights reserved

Should be replaced with:

- © Nexperia B.V. (year). All rights reserved.

If you have any questions related to the data sheet, please contact our nearest sales office via e-mail or telephone (details via **salesaddresses@nexperia.com**). Thank you for your cooperation and understanding,

Kind regards,

Team Nexperia

INTEGRATED CIRCUITS

DATA SHEET

74AVC16334A

16-bit registered driver with inverted register enable and Dynamic Controlled Outputs™ (3-State)

Product specification Supersedes data of 2000 May 02





16-bit registered driver with inverted register enable and Dynamic Controlled Outputs™ (3-State)

74AVC16334A

FEATURES

- Wide supply voltage range of 1.2 V to 3.6 V
- Complies with JEDEC standard no. 8-1A/5/7.
- CMOS low power consumption
- Input/output tolerant up to 3.6 V
- DCO (Dynamic Controlled Output) circuit dynamically changes output impedance, resulting in noise reduction without speed degradation
- Low inductance multiple V_{CC} and GND pins for minimum noise and ground bounce
- Power off disables 74AVC16334A outputs, permitting Live Insertion
- Integrated input diodes to minimize input overshoot and undershoot
- Full PC133 solution provided when used with PCK2509S or PCK2510S and CBT16292

DESCRIPTION

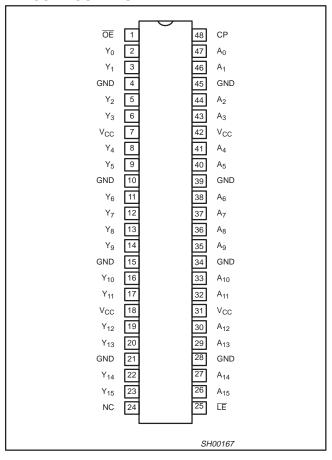
The 74AVC16334A is a 16-bit universal bus driver. Data flow is controlled by output enable (\overline{OE}) , latch enable (\overline{LE}) and clock inputs (CP).

This product is designed to have an extremely fast propagation delay and a minimum amount of power consumption.

To ensure the high-impedance state during power up or power down, \overline{OE} should be tied to V_{CC} through a pullup resistor (Live Insertion).

A Dynamic Controlled Output (DCO) circuitry is implemented to support termination line drive during transient. See the graphs on page 8 for typical curves.

PIN CONFIGURATION



QUICK REFERENCE DATA

GND = 0 V; $T_{amb} = 25^{\circ}C$; $t_r = t_f \le 2.0 \text{ ns}$; $C_L = 30 \text{ pF}$.

SYMBOL	PARAMETER	CONDITION	NS	TYPICAL	UNIT	
t _{PHL} /t _{PLH}	Propagation delay An to Yn	V _{CC} = 1.8 V V _{CC} = 2.5 V V _{CC} = 3.3 V	2.5 1.7 1.5	ns		
t _{PHL} /t _{PLH}	Propagation delay LE to Yn; CP to Yn	V _{CC} = 1.8 V V _{CC} = 2.5 V V _{CC} = 3.3 V	2.7 2.0 1.6	ns		
C _I	Input capacitance			3.8	pF	
	Power dissipation capacitance per buffer	$V_{L} = GND \text{ to } V_{CC}^{-1}$	Outputs enabled	25	pF	
C _{PD}	Power dissipation capacitance per buller	$\Lambda^{I} = Q M D \text{ fo } \Lambda^{CC}$.	Output disabled	6	l ht	

NOTE:

1. C_{PD} is used to determine the dynamic power dissipation (P_{D} in μW):

 $P_D = C_{PD} \times V_{CC}^2 \times f_i + \Sigma (C_L \times V_{CC}^2 \times f_o)$ where: f_i = input frequency in MHz; C_L = output load capacitance in pF; f_o = output frequency in MHz; V_{CC} = supply voltage in V; $\Sigma (C_L \times V_{CC}^2 \times f_o)$ = sum of outputs.

ORDERING INFORMATION

PACKAGES	TEMPERATURE RANGE	OUTSIDE NORTH AMERICA	NORTH AMERICA	DRAWING NUMBER
48-Pin Plastic Thin Shrink Small Outline (TSSOP) Type II	–40°C to +85°C	AVC16334A DGG		SOT362-1

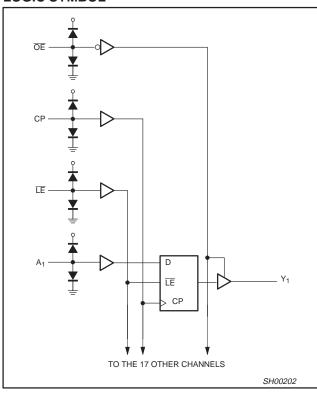
16-bit registered driver with inverted register enable and Dynamic Controlled Outputs™ (3-State)

74AVC16334A

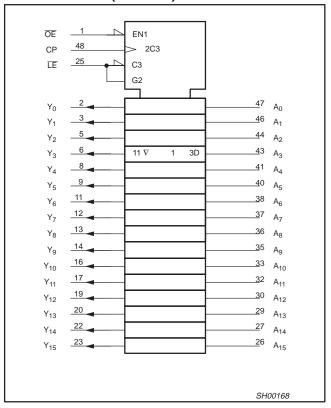
PIN DESCRIPTION

PIN NUMBER	SYMBOL	NAME AND FUNCTION			
24	NC	No connection			
2, 3, 5, 6, 8, 9, 11, 12, 13, 14, 16, 17, 19, 20, 22, 23	Y ₀ to Y ₁₅	Data outputs			
4, 10, 15, 21, 28, 34, 39, 45	GND	Ground (0 V)			
7, 18, 31, 42	V _{CC}	Positive supply voltage			
1	ŌĒ	Output enable input (active LOW)			
25	LE	Latch enable input (active LOW)			
48	CLK	Clock input			
47, 46, 44, 43, 41, 40, 38, 37, 36, 35, 33, 32, 30, 29, 27, 26	A ₀ to A ₁₅	Data inputs			

LOGIC SYMBOL



LOGIC SYMBOL (IEEE/IEC)



FUNCTION TABLE

	INP	INPUTS						
ŌĒ	LE	CLK	Α	OUTPUTS				
Н	Х	Х	Х	Z				
L	L	Х	L	L				
L	L	Х	Н	Н				
L	Н	1	L	L				
L	Н	\uparrow	Н	Н				
L	Н	L or H	Х	Y ₀ ¹				

HIGH voltage level LOW voltage level

Don't care

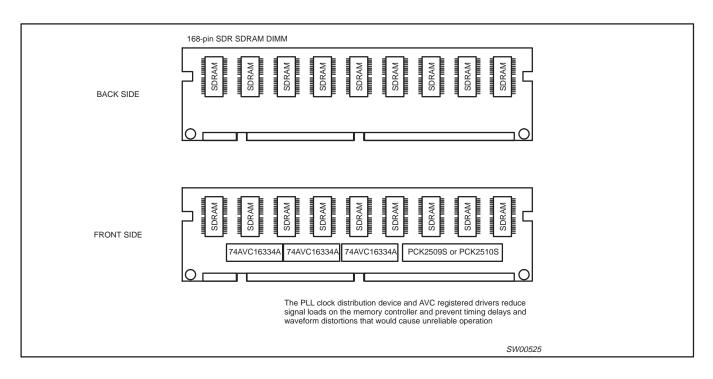
X Z ↑ High impedance "off" state LOW-to-HIGH level transition

NOTE:

1. Output level before the indicated steady-state input conditions were established.

16-bit registered driver with inverted register enable and Dynamic Controlled Outputs™ (3-State)

74AVC16334A



RECOMMENDED OPERATING CONDITIONS

SYMBOL	PARAMETER	CONDITIONS	MIN	MAX	UNIT	
V _{CC}	DC supply voltage (according to JEDEC Low Voltage Standards)		1.65 2.3 3.0	1.95 2.7 3.6	V	
V _{CC}	DC supply voltage (for low voltage applications)		1.2	3.6	V	
VI	DC Input voltage range		0	3.6	V	
V	DC output voltage range; output 3-State		0	3.6	V	
Vo	DC output voltage range; output HIGH or LOW state		0	V _{CC}	1 ^v	
T _{amb}	Operating free-air temperature range		-40	+85	°C	
		$V_{CC} = 1.65 \text{ to } 2.3 \text{ V}$	0	30		
t _r , t _f	Input rise and fall times	$V_{CC} = 2.3 \text{ to } 3.0 \text{ V}$	0	20	ns/V	
		$V_{CC} = 3.0 \text{ to } 3.6 \text{ V}$	0	10		

ABSOLUTE MAXIMUM RATINGS

In accordance with the Absolute Maximum Rating System (IEC 134). Voltages are referenced to GND (ground = 0 V).

SYMBOL	PARAMETER	CONDITIONS	RATING	UNIT
V _{CC}	DC supply voltage		-0.5 to +4.6	V
I _{IK}	DC input diode current	V ₁ < 0	-50	mA
V _I	DC input voltage	For data inputs ¹	-0.5 to 4.6	V
I _{OK}	DC output diode current	$V_{O} > V_{CC}$ or $V_{O} < 0$	±50	mA
Vo	DC output voltage; output 3-State	Note 1	-0.5 to 4.6	V
Vo	DC output voltage; output HIGH or LOW state	Note 1	–0.5 to V _{CC} +0.5	V
Io	DC output source or sink current	$V_{O} = 0$ to V_{CC}	±50	mA
I _{GND} , I _{CC}	DC V _{CC} or GND current		±100	mA
T _{stg}	Storage temperature range		-65 to +150	°C
P _{TOT}	Power dissipation per package –plastic thin-medium-shrink (TSSOP)	For temperature range: –40 to +125 °C above +55°C derate linearly with 8 mW/K	600	mW

NOTE:

^{1.} The input and output voltage ratings may be exceeded if the input and output current ratings are observed.

16-bit registered driver with inverted register enable and Dynamic Controlled Outputs™ (3-State)

74AVC16334A

DC ELECTRICAL CHARACTERISTICS

Over recommended operating conditions. Voltage are referenced to GND (ground = 0 V).

				LIMITS				
SYMBOL	PARAMETER	TEST CONDITIONS	Temp	= -40°C to +8	5°C	UNIT		
			MIN	TYP ¹	MAX	1		
		V _{CC} = 1.2 V	V _{CC}	-	-			
	LUCI Lieval leavet valte as	V _{CC} = 1.65 to 1.95 V	0.65 V _{CC}	0.9	-	V		
V_{IH}	HIGH level Input voltage	V _{CC} = 2.3 to 2.7 V	1.7	-	\ \			
		V _{CC} = 3.0 to 3.6 V	2.0	1.5	_			
		V _{CC} = 1.2 V	-	-	GND			
V	LOW lovel lanut voltage	V _{CC} = 1.65 to 1.95 V	-	0.9	0.35 V _{CC}	V		
V_{IL}	LOW level Input voltage	V _{CC} = 2.3 to 2.7 V	-	1.2	0.7	1 °		
		V _{CC} = 3.0 to 3.6 V	-	1.5	0.8	1		
	HIGH level output voltage	V_{CC} = 1.65 to 3.6 V; V_I = V_{IH} or V_{IL} ; I_O = -100 μA	V _{CC} -0.20 V _{CC} -		_			
V_{OH}		$V_{CC} = 1.65 \text{ V}; V_I = V_{IH} \text{ or } V_{IL}; I_O = -4 \text{ mA}$	V _{CC} - 0.45	V _{CC} _0.10	_	V		
U		$V_{CC} = 2.3 \text{ V}; V_I = V_{IH} \text{ or } V_{IL}; I_O = -8 \text{ mA}$	V _{CC} - 0.55	V _{CC} _0.28	_			
		$V_{CC} = 3.0 \text{ V}; V_I = V_{IH} \text{ or } V_{IL}; I_O = -12 \text{ mA}$	V _{CC} -0.70	V _{CC} -0.32	-	1		
		$V_{CC} = 1.65 \text{ to } 3.6 \text{ V}; \ V_I = V_{IH} \text{ or } V_{IL}; \ I_O = 100 \ \mu\text{A}$	-	GND	0.20			
V_{OL}	LOW level output voltage	$V_{CC} = 1.65 \text{ V}; V_I = V_{IH} \text{ or } V_{IL}; I_O = 4 \text{ mA}$	-	0.10	0.45	.45 V		
		$V_{CC} = 2.3 \text{ V}; V_I = V_{IH} \text{ or } V_{IL}; I_O = 8 \text{ mA}$	-	0.26	0.55	1		
		$V_{CC} = 3.0 \text{ V}; V_I = V_{IH} \text{ or } V_{IL}; I_O = 12 \text{ mA}$	-	0.36	0.70	1		
lį	Input leakage current	$V_{CC} = 3.6 \text{ V};$ $V_{I} = V_{CC} \text{ or GND}$	-	0.1	2.5	μА		
I _{OFF}	3-State output OFF-state current	$V_{CC} = 0 \text{ V}; V_{I} \text{ or } V_{O} = 3.6 \text{ V}$	-	0.1	±10	μΑ		
	2 State output OFF state surrent	V_{CC} = 1.65 to 2.7 V; V_I = V_{IH} or V_{IL} ; V_O = V_{CC} or GND	-	0.1	5			
l _{OZ}	3-State output OFF-state current	V_{CC} = 3.0 to 3.6 V; V_I = V_{IH} or V_{IL} ; V_O = V_{CC} or GND	-	0.1	10	μΑ		
1	Quicecent aupply aurrent	$V_{CC} = 1.65 \text{ to } 2.7 \text{ V}; V_I = V_{CC} \text{ or GND}; I_O = 0$	-	0.1	20			
Icc	Quiescent supply current	$V_{CC} = 3.0 \text{ to } 3.6 \text{ V}; V_I = V_{CC} \text{ or GND}; I_O = 0$	_	0.2	40	μΑ		

NOTE:

2000 Aug 03 5

^{1.} All typical values are at $T_{amb} = 25^{\circ}C$.

16-bit registered driver with inverted register enable and Dynamic Controlled Outputs™ (3-State)

74AVC16334A

AC CHARACTERISTICS

GND = 0 V; $t_r = t_f \le 2.0 \text{ ns}$; $C_L = 30 \text{ pF}$

								LIN	IITS						
SYMBOL	PARAMETER	WAVEFORM	Vcc	= 3.3 ±	0.3 V	Vcc	= 2.5 ± (0.2 V	Vcc	= 1.8 ± 0	.15 V	V _C 1.5 ±	c = 0.1 V	V _{CC} = 1.2 V	UNIT
			MIN	TYP ¹	MAX	MIN	TYP ¹	MAX	MIN	TYP ¹	MAX	MIN	MAX	TYP	1
	Propagation delay An to Yn	1	0.7	1.5	2.6	0.8	1.7	3.0	1.0	2.5	4.4	1.7	5.3	5.0	
t _{PHL} /t _{PLH}	Propagation delay LE to Yn	2	0.7	1.6	3.2	1.0	2.0	3.3	1.2	2.7	4.8	1.7	6.0	5.3	ns
	Propagation delay CP to Yn	3	0.7	1.6	2.8	0.8	1.7	3.0	1.0	2.3	3.9	1.4	4.6	4.1	
t _{PZH} /t _{PZL}	3-State output enable time OE to Yn	6	0.7	1.7	3.4	1.0	2.2	3.8	1.5	3.1	5.3	2.0	6.7	6.0	ns
t _{PHZ} /t _{PLZ}	3-State output disable time OE to Yn	6	1.0	2.1	3.7	0.9	2.0	3.9	1.5	3.7	6.5	1.7	7.1	6.1	ns
4	CP pulse width HIGH or LOW	3	1.0	-	_	1.2	_	_	2.0	-	_	-	_	-	ns
t _W	LE pulse width LOW	2	1.0	-	_	1.2	_	_	2.0	-	_	-	_	-	TIS
4	Set-up time An to CP	5	0.2	-0.1	_	0.1	-0.1	_	0.1	-0.1	_	0.1	_	0.0	ns
t _{SU}	Set-up time An to LE	4	0.4	0.1	_	0.5	0.1	_	0.8	0.3	_	1.2	_	1.0	115
	Hold time An to CP	5	0.6	0.2	_	0.6	0.2	_	0.6	0.2	_	0.6	_	0.1	
t _h	Hold time An to LE	4	0.4	0.1	_	0.4	0.1	_	0.3	0.1	_	0.3	_	-0.4	ns
f _{max}	Maximum clock pulse frequency	3	500	-	_	400	_	_	250	-	_	_	_	_	MHz

NOTE:

2000 Aug 03 6

^{1.} All typical values are measured at T_{amb} = 25°C and at V_{CC} = 1.8 V, 2.5 V, 3.3 V.

16-bit registered driver with inverted register enable and Dynamic Controlled Outputs™ (3-State)

74AVC16334A

AC WAVEFORMS FOR $V_{CC} = 3.0 \text{ V}$ TO 3.6 V RANGE

 $V_{M} = 0.5 V_{CC}$ $V_{X} = V_{OL} + 0.300 V$ $V_{Y} = V_{OH} - 0.300 V$

 $V_Y = V_{OH} - 0.300 \text{ V}$ V_{OL} and V_{OH} are the typical output voltage drop that occur with the output load.

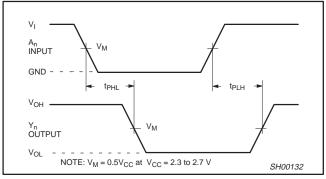
 $V_I = V_{CC}$

AC WAVEFORMS FOR $V_{CC} = 2.3 \text{ V TO } 2.7 \text{ V AND } V_{CC} < 2.3 \text{ V RANGE}$

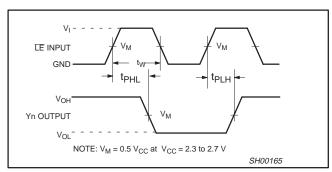
 $V_{M} = 0.5 V_{CC}$ $V_{X} = V_{OL} + 0.15 V$ $V_{Y} = V_{OL} - 0.15 V$

 $V_Y = V_{OH} - 0.15$ V V_{OL} and V_{OH} are the typical output voltage drop that occur with the output load.

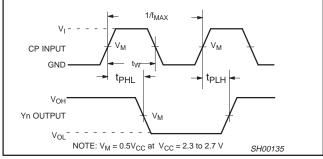
 $V_I = V_{CC}$



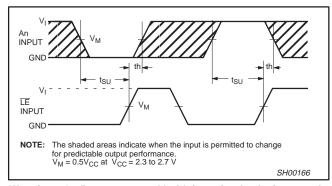
Waveform 1. Input (An) to output (Yn) propagation delay



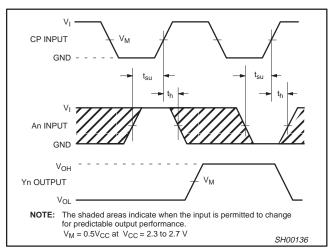
Waveform 2. Latch enable input (LE) pulse width, the latch enable input to output (Yn) propagation delays.



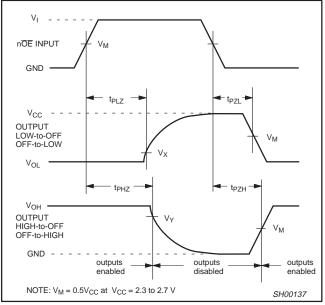
Waveform 3. The clock (CP) to Yn propagation delays, the clock pulse width and the maximum clock frequency.



Waveform 4. Data set-up and hold times for the An input to the LE input



Waveform 5. Data set-up and hold times for the An input to the clock CP input



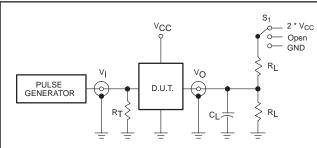
Waveform 6. 3-State enable and disable times

2000 Aug 03 7

16-bit registered driver with inverted register enable and Dynamic Controlled Outputs™ (3-State)

74AVC16334A

TEST CIRCUIT



Test Circuit for switching times

DEFINITIONS

R_L = Load resistor

C_L = Load capacitance includes jig and probe capacitance

 R_T = Termination resistance should be equal to Z_{OUT} of pulse generators.

SWITCH POSITION

TEST	S ₁
t _{PLH} /t _{PHL}	Open
t _{PLZ} /t _{PZL}	2 * V _{CC}
t _{PHZ} /t _{PZH}	GND

v _{cc}	VI	R _L		
< 2.3 V	V _{CC}	1000 Ω		
2.3–2.7 V	V _{CC}	500 Ω		
3.0 V	V _{CC}	500 Ω		

SV01018

Waveform 7. Load circuitry for switching times

GRAPHS

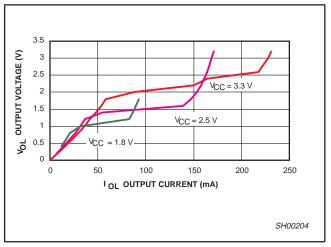


Figure 1. Output voltage (V_{OL}) vs. output current (I_{OL})

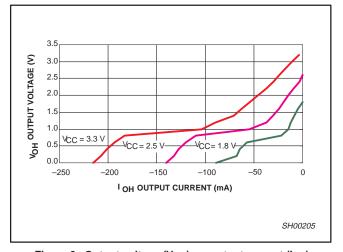


Figure 2. Output voltage (V_{OH}) vs. output current (I_{OH})

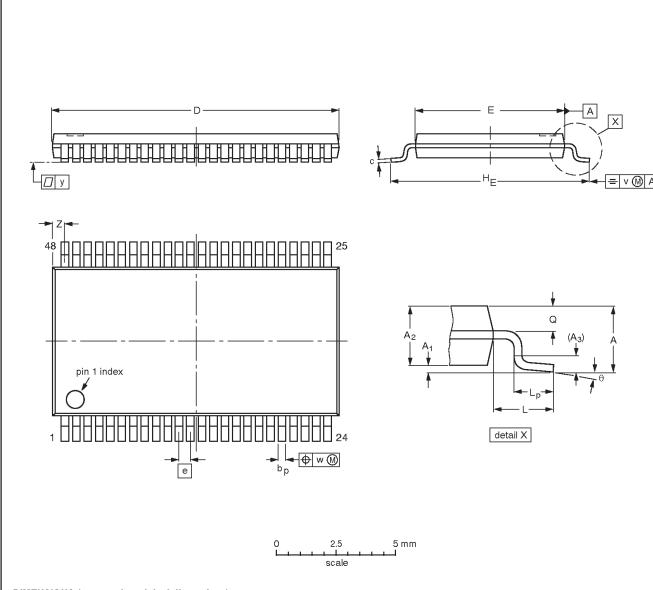
A Dynamic Controlled Output (DCO) circuit is designed in. During the transition, it initially lowers the output impedance to effectively drive the load and, subsequently, raises the impedance to reduce noise. Figures 1 and 2 show V_{OL} vs. I_{OL} and V_{OH} vs. I_{OH} curves to illustrate the output impedance and drive capability of the circuit. At the beginning of the signal transition, the DCO circuit provides a maximum dynamic drive that is equivalent to a high drive standard output device.

16-bit registered driver with inverted register enable and Dynamic Controlled Outputs™ (3-State)

74AVC16334A

TSSOP48: plastic thin shrink small outline package; 48 leads; body width 6.1mm

SOT362-1



DIMENSIONS (mm are the original dimensions).

UNIT	A max.	A ₁	A ₂	А3	bp	С	D ⁽¹⁾	E ⁽²⁾	е	HE	L	Lp	Q	v	w	у	z	θ
mm	1.2	0.15 0.05	1.05 0.85	0.25	0.28 0.17	0.2 0.1	12.6 12.4	6.2 6.0	0.5	8.3 7.9	1	0.8 0.4	0.50 0.35	0.25	0.08	0.1	0.8 0.4	8° 0°

Notes

- 1. Plastic or metal protrusions of 0.15 mm maximum per side are not included.
- 2. Plastic interlead protrusions of 0.25 mm maximum per side are not included.

OUTLINE		REFER	ENCES	EUROPEAN	ISSUE DATE	
VERSION	IEC	JEDEC	EIAJ		PROJECTION	ISSUE DATE
SOT362-1		MO-153ED				-93-02-03 95-02-10

16-bit registered driver with inverted register enable and Dynamic Controlled Outputs™ (3-State)

74AVC16334A

Data sheet status

Data sheet status	Product status	Definition [1]
Objective specification	Development	This data sheet contains the design target or goal specifications for product development. Specification may change in any manner without notice.
Preliminary specification	Qualification	This data sheet contains preliminary data, and supplementary data will be published at a later date. Philips Semiconductors reserves the right to make changes at any time without notice in order to improve design and supply the best possible product.
Product specification	Production	This data sheet contains final specifications. Philips Semiconductors reserves the right to make changes at any time without notice in order to improve design and supply the best possible product.

^[1] Please consult the most recently issued datasheet before initiating or completing a design.

Definitions

Short-form specification — The data in a short-form specification is extracted from a full data sheet with the same type number and title. For detailed information see the relevant data sheet or data handbook.

Limiting values definition — Limiting values given are in accordance with the Absolute Maximum Rating System (IEC 134). Stress above one or more of the limiting values may cause permanent damage to the device. These are stress ratings only and operation of the device at these or at any other conditions above those given in the Characteristics sections of the specification is not implied. Exposure to limiting values for extended periods may affect device reliability.

Application information — Applications that are described herein for any of these products are for illustrative purposes only. Philips Semiconductors make no representation or warranty that such applications will be suitable for the specified use without further testing or modification.

Disclaimers

Life support — These products are not designed for use in life support appliances, devices or systems where malfunction of these products can reasonably be expected to result in personal injury. Philips Semiconductors customers using or selling these products for use in such applications do so at their own risk and agree to fully indemnify Philips Semiconductors for any damages resulting from such application.

Right to make changes — Philips Semiconductors reserves the right to make changes, without notice, in the products, including circuits, standard cells, and/or software, described or contained herein in order to improve design and/or performance. Philips Semiconductors assumes no responsibility or liability for the use of any of these products, conveys no license or title under any patent, copyright, or mask work right to these products, and makes no representations or warranties that these products are free from patent, copyright, or mask work right infringement, unless otherwise specified.

Philips Semiconductors 811 East Arques Avenue P.O. Box 3409 Sunnyvale, California 94088–3409 Telephone 800-234-7381 © Copyright Philips Electronics North America Corporation 2000 All rights reserved. Printed in U.S.A.

Date of release: 08-00

Document order number: 9397-750 07394

Let's make things better.

Philips Semiconductors



