

# MP1497S High-Efficiency, 3A, 16V, 500kHz Synchronous, Step-Down Converter

The Future of Analog IC Technology

# DESCRIPTION

The MP1497S is a high-frequency, synchronous, rectified, step-down switch mode converter with built in internal power MOSFETs. It offers a very compact solution to achieve 3A continuous output current with excellent load and line regulation over a wide input supply range. The MP1497S has synchronous mode operation for higher efficiency over the output current load range.

Current-mode operation provides a fast transient response and eases loop stabilization.

Protective features include over-current protection, thermal shutdown, and external SS control.

The MP1497S requires a minimal number of readily-available external components and is available in a space-saving 8-pin TSOT23 package.

### FEATURES

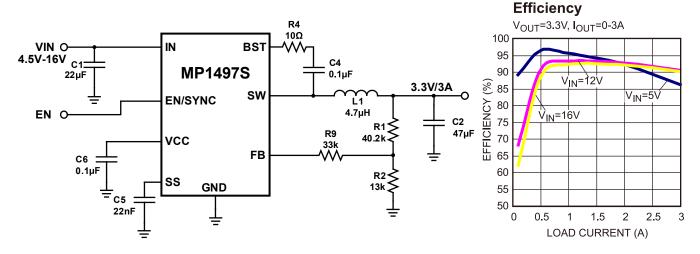
- Wide 4.5V-to-16V Operating Input Range
- 120m $\Omega$ /50m $\Omega$  Low R<sub>DS(ON)</sub> Internal Power MOSFETs
- Proprietary Switching-Loss–Reduction Technique
- High-Efficiency Synchronous Mode
  Operation
- Fixed 500kHz Switching Frequency
- Can Synchronize to a 300kHz-to-2MHz External Clock
- Externally-Programmable Soft-Start
- OCP and Hiccup
- Thermal Shutdown
- Output Adjustable from 0.8V
- Available in an 8-pin TSOT23 Package

### **APPLICATIONS**

- Notebook Systems and I/O Power
- Digital Set-Top Boxes
- Flat-Panel Televisions and Monitors
- Distributed Power Systems

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### TYPICAL APPLICATION



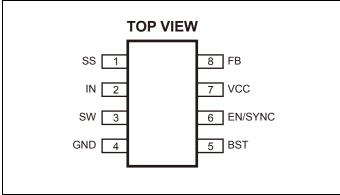


#### **ORDERING INFORMATION**

Part Number*	Package	Top Marking
MP1497SGJ	TSOT23-8	AJT

\* For Tape & Reel, add suffix –Z (e.g. MP1497SGJ–Z).

### .PACKAGE REFERENCE



### ABSOLUTE MAXIMUM RATINGS (1)

V <sub>IN</sub> 0.3V to	17\/
V <sub>SW</sub> 0.3V (-5V for <10ns) to 17V (19V for 5	5ns)
V <sub>BST</sub> V <sub>SW</sub>	+6V
All Other Pins0.3V to 6V	√ <sup>(2)</sup>
Continuous Power Dissipation ( $T_A = +25^{\circ}C$ )	(3)
	25W
Junction Temperature15	0°C
Lead Temperature26	0°C
Storage Temperature65°C to 15	0°C

#### Recommended Operating Conditions <sup>(4)</sup>

Supply Voltage V <sub>IN</sub>	4.5V to 16V
Output Voltage Vout	$\dots$ 0.8V to V <sub>IN</sub> x D <sub>MAX</sub>
Operating Junction Temp.	(T <sub>J</sub> )40°C to +125°C

# Thermal Resistance <sup>(5)</sup> $\theta_{JA}$ $\theta_{JC}$

TSOT23-8...... 100..... 55... °C/W

#### Notes:

- 1) Exceeding these ratings may damage the device.
- 2) About the details of the EN pin's ABS MAX rating, please refer to Page 9, Enable section.
- 3) The maximum allowable power dissipation is a function of the maximum junction temperature T<sub>J</sub> (MAX), the junction-toambient thermal resistance  $\theta_{JA}$ , and the ambient temperature T<sub>A</sub>. The maximum allowable continuous power dissipation at any ambient temperature is calculated by P<sub>D</sub> (MAX) = (T<sub>J</sub> (MAX)-T<sub>A</sub>)/ $\theta_{JA}$ . Exceeding the maximum allowable power dissipation will cause excessive die temperature, and the regulator will go into thermal shutdown. Internal thermal shutdown circuitry protects the device from permanent damage.
- The device is not guaranteed to function outside of its operating conditions.
- 5) Measured on JESD51-7, 4-layer PCB.

# **ELECTRICAL CHARACTERISTICS**

 $V_{IN}$  = 12V,  $T_A$  = 25°C, unless otherwise noted.

Parameter	Symbol	Condition	Min	Тур	Max	Units
Supply Current (Shutdown)	I <sub>IN</sub>	V <sub>EN</sub> = 0V			1	μA
Supply Current (Quiescent)	l <sub>q</sub>	V <sub>EN</sub> = 2V, V <sub>FB</sub> = 1V		0.7	1	mA
HS-Switch ON Resistance	$HS_{RDS-ON}$	V <sub>BST-SW</sub> =5V		120		mΩ
LS-Switch ON Resistance	LS <sub>RDS-ON</sub>	V <sub>CC</sub> =5V		50		mΩ
Switch Leakage	SWLKG	V <sub>EN</sub> = 0V, V <sub>SW</sub> =12V			1	μA
Current Limit <sup>(6)</sup>	I <sub>LIMIT</sub>	Under 40% Duty Cycle	4.2	5		A
Oscillator Frequency	f <sub>SW</sub>	V <sub>FB</sub> =750mV	410	500	600	kHz
Fold-back Frequency	f <sub>FB</sub>	V <sub>FB</sub> <400mV		0.5		f <sub>SW</sub>
Maximum Duty Cycle	D <sub>MAX</sub>	V <sub>FB</sub> =700mV	90	95		%
Minimum ON Time <sup>(7)</sup>	T <sub>ON_MIN</sub>			60		ns
Sync Frequency Range	f <sub>SYNC</sub>		0.3		2	MHz
Feedback Voltage	V <sub>FB</sub>	T <sub>A</sub> =25°C	791	807	823	mV
I CEUDACK VOILAGE		-40°C <t<sub>A&lt;85°C<sup>(8)</sup></t<sub>	787	807	827	
Feedback Current	I <sub>FB</sub>	V <sub>FB</sub> =820mV		10	50	nA
EN Rising Threshold	$V_{\text{EN}_{\text{RISING}}}$		1.1	1.4	1.75	V
EN Falling Threshold	$V_{\text{EN}_{\text{FALLING}}}$		1	1.25	1.55	V
EN Input Current	I <sub>EN</sub>	V <sub>EN</sub> =2V		2		μA
		V <sub>EN</sub> =0		0		μA
EN Turn Off Delay	$EN_{Td-off}$			8		μs
V <sub>IN</sub> Under-Voltage Lockout Threshold-Rising	$INUV_{Vth}$		3.6	3.9	4.2	V
V <sub>IN</sub> Under-Voltage Lockout Threshold-Hysteresis	INUV <sub>HYS</sub>			650		mV
VCC Regulator	V <sub>CC</sub>			5		V
VCC Load Regulation		I <sub>cc</sub> =5mA		3		%
Soft-Start Current	I <sub>SS</sub>		5	11	17	μA
Thermal Shutdown <sup>(7)</sup>				150		°C
Thermal Hysteresis <sup>(7)</sup>				20		°C

Notes:

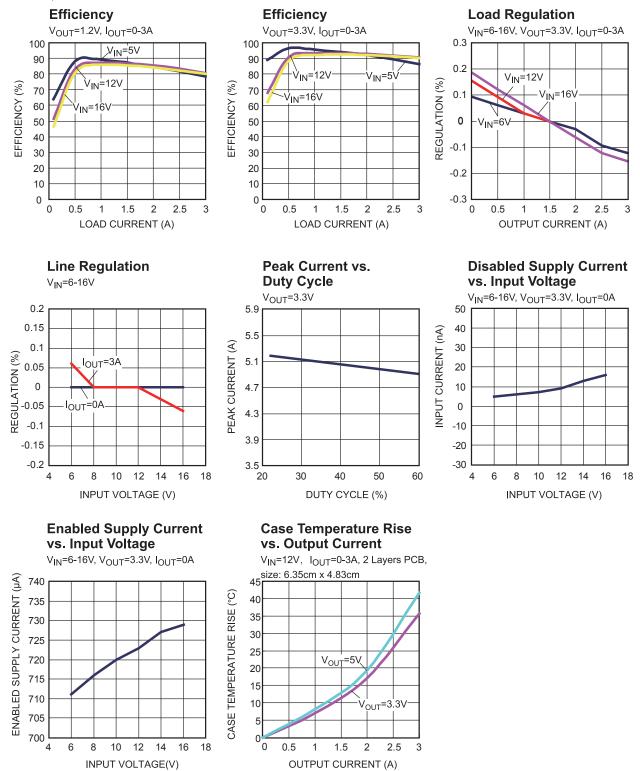
6) Guaranteed by characterization.

7)

Guaranteed by design. Not tested in production and guaranteed by over-temperature correlation. 8)

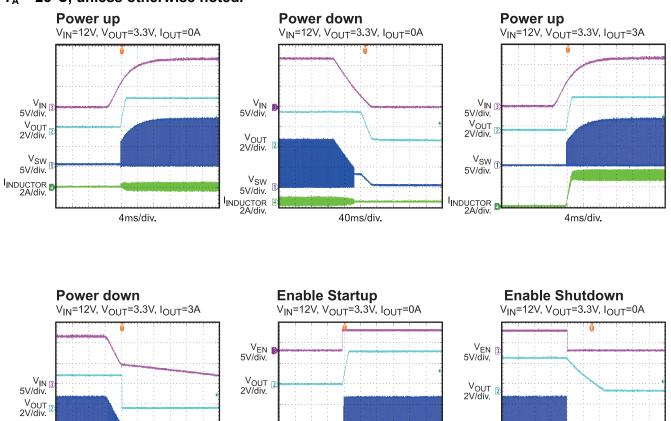
# **TYPICAL PERFORMANCE CHARACTERISTICS**

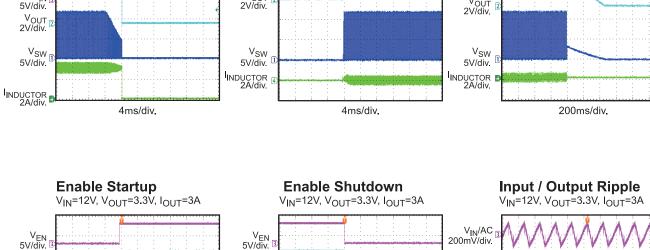
Performance waveforms are tested on the evaluation board.  $T_A = 25^{\circ}C$ , unless otherwise noted.



# **TYPICAL PERFORMANCE CHARACTERISTICS** (continued)

Performance waveforms are tested on the evaluation board.  $T_A = 25^{\circ}C$ , unless otherwise noted.





V<sub>OUT</sub>/AC 20mV/div.

VSW

10V/div

INDUCTOR 2A/div.



4ms/div.

V<sub>OUT</sub>

V<sub>SW</sub>

5V/div.

INDUCTOR 2A/div.

V<sub>OUT</sub>

 $V_{SW}$ 

4ms/div.

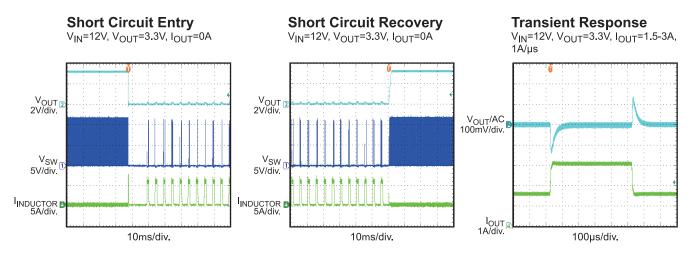
5V/div.

I<sub>INDUCTOR</sub> 2A/div.

2µs/div.

# TYPICAL PERFORMANCE CHARACTERISTICS (continued)

Performance waveforms are tested on the evaluation board.  $T_A = 25^{\circ}C$ , unless otherwise noted.



# **PIN FUNCTIONS**

Package Pin #	Name	Description
1	SS	Soft-Start. Connect an external capacitor to program the soft start time for the switch-mode regulator.
2	IN	Supply Voltage. The MP1497S operates from a 4.5V-to-16V input rail. Use C1 to decouple the input rail. Connect using a wide PCB trace.
3	SW	Switch Output. Connect using a wide PCB trace.
4	GND	System Ground. The regulated output voltage reference ground. Connect to GND with copper and vias.
5	BST	Bootstrap. Connect a capacitor between SW and BST pins to form a floating supply across the high-side switch driver. A $10\Omega$ resistor placed between SW and BST cap is strongly recommended to reduce SW spike voltage.
6	EN/SYNC	Enable/Synchronize. EN high to enable the MP1497S. Apply an external clock to change the switching frequency.
7	VCC	Bias Supply. Decouple with a $0.1\mu$ F-to- $0.22\mu$ F capacitor. Avoid a capacitance that exceeds $0.22\mu$ F. VCC capacitor should be put closely to VCC pin and GND pin.
8	FB	Feedback. Connect to the tap of an external resistor divider from the output to GND to set the output voltage. The comparator lowers the oscillator frequency when the FB voltage drops below 400mV to prevent current-limit run-away during a short-circuit fault.

### **BLOCK DIAGRAM**

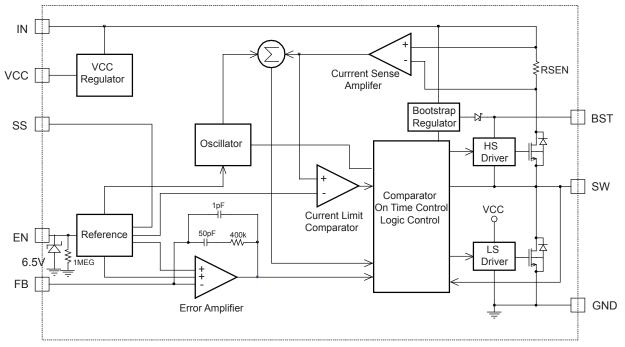


Figure 1: Functional Block Diagram

# **OPERATION**

The MP1497S is a high-frequency, synchronous, rectified, step-down, switch-mode converter with built-in power MOSFETs. It offers a very compact solution to achieve 3A continuous output current with excellent load and line regulation over a wide input supply range.

The MP1497S operates in a fixed-frequency, peak-current-control mode to regulate the output voltage. The internal clock initiates a PWM cycle. The integrated high-side power MOSFET turns on and remains on until its current reaches the value set by the COMP voltage. When the power switch is off, it remains off until the next clock cycle starts. If the current in the power MOSFET does not reach the COMP set current value within 95% of one PWM period, the power MOSFET will be forced to turn off.

#### **Internal Regulator**

The 5V internal regulator powers most of the internal circuitries. This regulator takes the  $V_{IN}$  input and operates in the full  $V_{IN}$  range. When  $V_{IN}$  exceeds 5.0V, the output of the regulator is in full regulation. When  $V_{IN}$  is below 5.0V, the output decreases and requires a 0.1µF ceramic decoupling capacitor.

#### **Error Amplifier**

The error amplifier compares the FB pin voltage against the internal 0.8V reference (REF) and outputs a COMP voltage that controls the power MOSFET current. The optimized internal compensation network minimizes the external component counts and simplifies the control loop design.

#### **Enable/SYNC Control**

EN is a digital control pin that turns the regulator on and off. Drive EN high to turn on the regulator, drive it low to turn it off. An internal  $1M\Omega$  resistor from EN to GND allows EN to float to shut down the chip.

The EN pin is clamped internally using a 6.5V series-Zener-diode as shown in Figure 2. Connecting the EN pin through a pullup resistor to any voltage connected to  $V_{IN}$  limits the EN input current to less than 100µA.

For example, when connecting V<sub>IN</sub> to a 12V source,  $R_{PULLUP} \ge [(12V - 6.5V) \div 100\mu A = 55k\Omega]$ . Connecting the EN pin directly to a voltage source without any pullup resistor requires limiting the amplitude of the voltage source to below 6.5V to prevent damaging the Zener diode.

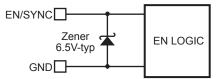


Figure 2: Zener Diode Circuit

For external clock synchronization, connect a clock with a frequency range of 300kHz and 2MHz 2ms after the output voltage is set: The internal clock rising edge will synchronize with the external clock rising edge. Select an external clock signal with a pulse-width less than  $1.7\mu$ s.

#### Under-Voltage Lockout

Under-voltage lockout (UVLO) protects the chip from operating at an insufficient supply voltage. The MP1497S UVLO comparator monitors the output voltage of the internal regulator, VCC. The UVLO rising threshold is about 3.9V while its falling threshold is 3.25V.

#### **External Soft-Start**

Adjust the soft-start time by connecting a capacitor from the SS pin to ground. When the soft-start period starts, an internal  $11\mu$ A current source charges the external capacitor. The soft-start capacitor connects to the non-inverting input of the error amplifier. The soft-start period lasts until the voltage on the soft-start capacitor exceeds the reference voltage of 0.8V. At this point, the non-inverting amplifier uses the reference voltage. The soft-start time can be calculated as:

$$t_{SS}(ms) = \frac{0.8V \times C_{SS}(nF)}{11\mu A}$$

#### **Over-Current-Protection and Hiccup**

The MP1497S has a cycle-by-cycle overcurrent limit that protects against the inductor current peak value exceeding the set current

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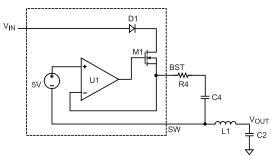
limit threshold. Under-voltage protection (UVP) triggers if the FB voltage drops below the under-voltage (UV) threshold—typically 50% below the reference. Once UVP triggers, the MP1497S enters hiccup mode to periodically restart the part. This protection mode is especially useful when the output is dead-shorted to ground. The average short-circuit current falls to alleviate thermal issues and to protect the regulator. The MP1497S exits hiccup mode once the over-current condition is removed.

#### **Thermal Shutdown**

Thermal shutdown prevents the chip from operating at exceedingly high temperatures. When the silicon die temperature exceeds  $150^{\circ}$ C, it shuts down the whole chip. When the temperature drops below its lower threshold (typically  $130^{\circ}$ C) the chip is enabled again.

#### **Floating Driver and Bootstrap Charging**

An external bootstrap capacitor powers the floating power MOSFET driver. This floating driver has its own UVLO protection with a rising threshold of 2.2V and a hysteresis of 150mV. The bootstrap capacitor voltage is regulated internally by V<sub>IN</sub> through D1, M1, C4, L1 and C2 (Figure 3). If (V<sub>IN</sub>-V<sub>SW</sub>) exceed 5V, U1 will regulate M1 to maintain a 5V BST voltage across C4. A 10 $\Omega$  resistor placed between SW and BST cap is strongly recommended to reduce SW spike voltage.



#### Figure 3: Internal Bootstrap Charging Circuit, Startup and Shutdown

If both  $V_{IN}$  and EN exceed their appropriate thresholds, the chip starts. The reference block starts first, generating stable reference voltage and currents, and then the internal regulator is enabled. The regulator provides stable supply for the remaining circuitries.

Three events can shut down the chip: EN low,  $V_{IN}$  low, and thermal shutdown. For the shutdown procedure, the signaling path is first blocked to avoid any fault triggering. The COMP voltage and the internal supply rail are then pulled down. The floating driver is not subject to this shutdown command.

### **APPLICATION INFORMATION**

#### Setting the Output Voltage

The external resistor divider sets the output voltage (see Typical Application on page 1). The feedback resistor R1 sets the feedback loop bandwidth. R2 is then given by:

$$R2 = \frac{R1}{\frac{V_{out}}{0.807V} - 1}$$

The T-type network shown in Figure 4 is highly recommended.

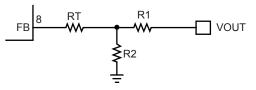


Figure 4: T-Type Network

Table 1 lists the recommended T-type resistors value for common output voltages.

**Table 1: Resistor Values for Common Output** Voltages

Voltages					
V <sub>OUT</sub> (V)	R1 (kΩ)	R2 (kΩ)	Rt (kΩ)		
1.0	20.5	82	82		
1.2	30.1	60.4	82		
1.8	40.2	32.4	56		
2.5	40.2	19.1	33		
3.3	40.2	13	33		
5	40.2	7.68	33		

#### Selecting the Inductor

Use a 1µH-to-10µH inductor with a DC current rating of at least 25% percent higher than the maximum load current for most applications. For highest efficiency, select an inductor with a DC resistance less than  $15m\Omega$ . For most designs, calculate the inductance value with:

$$L_{1} = \frac{V_{\text{OUT}} \times (V_{\text{IN}} - V_{\text{OUT}})}{V_{\text{IN}} \times \Delta I_{\text{L}} \times f_{\text{OSC}}}$$

Where  $\Delta I_{L}$  is the inductor ripple current.

Choose an inductor ripple current to be approximately 30% of the maximum load current. The maximum inductor peak current is:

$$I_{L(MAX)} = I_{LOAD} + \frac{\Delta I_{L}}{2}$$

Use a larger inductance for improved light-load efficiency.

#### Selecting the Input Capacitor

The input current to the step-down converter is discontinuous, therefore requires a capacitor supply the AC current to the step-down converter while maintaining the DC input voltage. Use low-ESR capacitors for the best performance, such as ceramic capacitors with X5R or X7R dielectrics that have low ESR and small temperature coefficients. For most applications, use a 22µF capacitor.

The input capacitor (C1) requires an adequate ripple current rating because it absorbs the input switching current. Estimate the RMS current in the input capacitor as:

$$I_{C1} = I_{LOAD} \times \sqrt{\frac{V_{OUT}}{V_{IN}}} \times \left(1 - \frac{V_{OUT}}{V_{IN}}\right)$$

The worst-case condition occurs at  $V_{IN}=2V_{OUT}$ , where:

$$I_{C1} = \frac{I_{LOAD}}{2}$$

For simplification, choose the input capacitor with an RMS current rating greater than half of the maximum load current.

The input capacitor can be electrolytic, tantalum or ceramic. When using electrolytic or tantalum capacitors, include a small, high-quality, ceramic capacitor-e.g. 0.1µF-as close to the IC as possible. When using ceramic capacitors, make sure that they have enough capacitance to prevent excessive input voltage ripple. Estimate the input voltage ripple caused by the capacitance as:

$$\Delta V_{IN} = \frac{I_{LOAD}}{f_{S} \times C1} \times \frac{V_{OUT}}{V_{IN}} \times \left(1 - \frac{V_{OUT}}{V_{IN}}\right)$$

#### Selecting the Output Capacitor

The output capacitor (C2) maintains the DC output voltage. Use ceramic, tantalum, or lowelectrolytic capacitors. ESR Low ESR capacitors are preferred to keep the output voltage ripple low. The output voltage ripple can be estimated by:

$$\Delta V_{\text{OUT}} = \frac{V_{\text{OUT}}}{f_{\text{S}} \times L_{1}} \times \left(1 - \frac{V_{\text{OUT}}}{V_{\text{IN}}}\right) \times \left(R_{\text{ESR}} + \frac{1}{8 \times f_{\text{S}} \times C2}\right)$$

Where  $L_1$  is the inductor value and  $R_{\text{ESR}}$  is the equivalent series resistance of the output capacitor.

For ceramic capacitors, the capacitance dominates the impedance at the switching frequency. The capacitance also causes the majority of the output voltage ripple. For simplification, estimate the output voltage ripple with:

$$\Delta V_{\text{OUT}} = \frac{V_{\text{OUT}}}{8 \times f_{\text{S}}^{2} \times L_{1} \times C2} \times \left(1 - \frac{V_{\text{OUT}}}{V_{\text{IN}}}\right)$$

For tantalum or electrolytic capacitors, the ESR dominates the impedance at the switching frequency. For simplification, the output ripple can be approximated to:

$$\Delta V_{\text{out}} = \frac{V_{\text{out}}}{f_{\text{s}} \times L_{1}} \times \left(1 - \frac{V_{\text{out}}}{V_{\text{IN}}}\right) \times R_{\text{esr}}$$

The characteristics of the output capacitor also affect the stability of the regulation system. The MP1497S can be optimized for a wide range of capacitance and ESR values.

#### **External Bootstrap Diode**

An external bootstrap diode can enhance the efficiency of the regulator, given the following conditions:

- V<sub>OUT</sub> is 5V or 3.3V; and
- Duty cycle is high:  $D = \frac{V_{OUT}}{V_{IN}} > 65\%$

In these cases, connect an external BST diode from the VCC pin to BST pin, as shown in Figure 5.

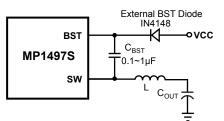


Figure 5: Optional External Bootstrap Diode to Enhance Efficiency

The recommended external BST diode is IN4148, and the BST capacitor is  $0.1\mu$ F to  $1\mu$ F.

#### PC Board Layout (9)

PCB layout is very important to achieve stable operation especially for VCC capacitor and input capacitor placement. For best results, follow these guidelines:

1) Use large ground plane directly connect to GND pin. Add vias near the GND pin if bottom layer is ground plane.

2) Place the VCC capacitor to VCC pin and GND pin as close as possible. Make the trace length of VCC pin-VCC capacitor anode-VCC capacitor cathode-chip GND pin as short as possible.

3) Place the ceramic input capacitor close to IN and GND pins. Keep the connection of input capacitor and IN pin as short and wide as possible.

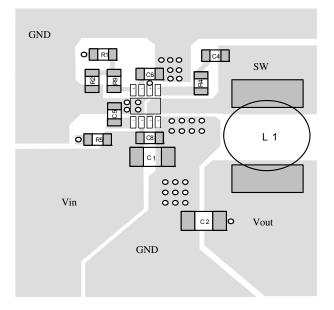
4) Route SW, BST away from sensitive analog areas such as FB. It's not recommended to route SW, BST trace under chip's bottom side.

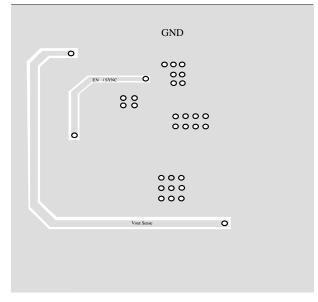
5) Place the T-type feedback resistor R9 close to chip to ensure the trace which connects to FB pin as short as possible

#### Notes:

9) The recommended layout is based on the Figure 6 Typical Application circuit on the next page.







# **TYPICAL APPLICATION CIRCUITS**

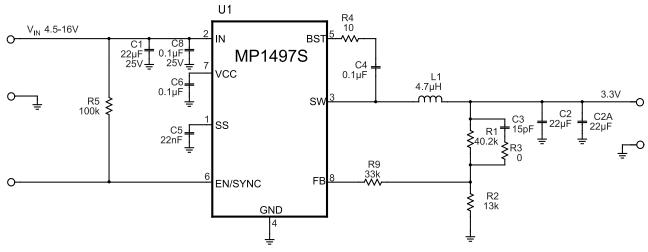
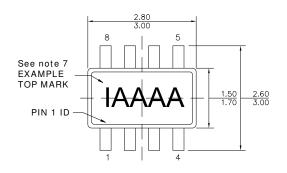


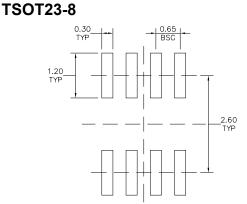
Figure 6: 12V<sub>IN</sub>, 3.3V/3A



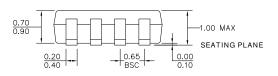
### **PACKAGE INFORMATION**



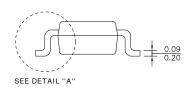
TOP VIEW



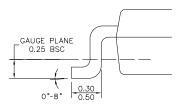
#### RECOMMENDED LAND PATTERN



FRONT VIEW



SIDE VIEW



DETAIL "A"

<u>NOTE:</u>

 ALL DIMENSIONS ARE IN MILLIMETERS.
 PACKAGE LENGTH DOES NOT INCLUDE MOLD FLASH, PROTRUSION OR GATE BURR.
 PACKAGE WIDTH DOES NOT INCLUDE INTERLEAD FLASH OR PROTRUSION.
 LEAD COPLANARITY (BOTTOM OF LEADS AFTER FORMING) SHALL BE 0.10 MILLIMETERS MAX.
 JEDEC REFERENCE IS MO-193, VARIATION BA.
 DRAWING IS NOT TO SCALE.
 PIN 1 IS LOWER LEFT PIN WHEN READING TOP MARK FROM LEFT TO RIGHT, (SEE EXAMPLE TOP MARK)

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