

## **AAT2822/2823/2824/2825**

### *TFT-LCD DC/DC Converter with WLED Driver and VCOM Buffer*

### **General Description**

The AAT2822-AAT2825 family of integrated panel power solutions provides the regulated voltages required by an active-matrix thin-film transistor (TFT) liquid-crystal display (LCD). The AAT2822 includes a triple-output DC-DC converter, a LED backlight driver, and a VCOM buffer in a 4 mm x 4mm TQFN package. The primary 1.3MHz DC-DC boost converter uses an ultra-small inductor and ceramic capacitor to generate output voltage  $(V_{AVDD})$  of up to 14.5V for the charge pumps. The low on-resistance of the integrated power MOSFET allows for efficiency up to 93%.

The two charge pumps independently regulate a positive output (VGH) and a negative output (VGL). These lowpower outputs use external diode and capacitor stages to regulate output voltages up to +30V and down to -30V. A proprietary regulation algorithm minimizes output ripple when using small capacitors.

The high efficiency backlight driver provides a constant current output capable of boosting up to 28V. The driver is an ideal power solution for backlight applications with up to seven white LEDs in series or up to 39 white LEDs in a parallel and series configuration. LED brightness is PWM controlled up to 1kHz. Filtered PWM is supported for higher frequencies.

The high slew rate operational amplifier is suitable for VCOM buffering and gain adjustment.

The sequencing of the power supplies ensures proper panel startup and avoid damage to the device.

The AAT2822 family is available in a Pb-free, 24-pin 4 x 4mm TQFN package and operates over the -40°C to +85°C temperature range.

#### **Features**

#### **LCD Bias Power**

- 2.5V to 5.5V Input Supply Range
- 1.3MHz Fixed Frequency Current-Mode Step-Up Regulator
- Fast Transient Response
- Adjustable Voltage up to 14.5V
	- $\pm 1\%$  Typical Accuracy
- Small External Inductor and Capacitors
- Integrated Soft Start and Sequencing of All Rails
- Short-Circuit, Over-Voltage, and Over-Temperature Protection

#### **Positive Output, VGH**

- Up to 13.2V Input Supply  $(V_{DD})$
- Adjustable Voltage up to 30V @ 20mA
	- $\pm$  ±3% Typical Accuracy

#### **Negative Output, VGL**

- Up to 13.2V Input Supply  $(V_{DD})$
- Adjustable Voltage down to -30V @ 20mA
- $\pm$  3% Typical Accuracy

#### **WLED Driver**

- Input Voltage Range: 2.5V to 25V
- Maximum Continuous Output:
	- 12V @ 260mA
	- 28V @ 50mA
- Panel sizes from 5" 10"
	- 5.0" 3S5P
	- 5.6" 3S6P
	- 7.0" 3S9P
	- 8.0" 3S10P/11P
	- 10" 3S13P
- Constant LED Current with 6% Accuracy
- PWM Dimming Control
	- Up to 1kHz
- 1.3MHz Switching Fixed Frequency
	- Up to 90% Efficiency

#### **VCOM Buffer**

- High-Performance
	- 13V/µs Slew Rate
	- **12MHz, -3dB Bandwidth**
- ±75mA Output Short-Circuit Current
- Low 1.5mA Quiescent Current

### **Applications**

- Automotive Displays
- Digital Photo Frames
- Netbooks
- PNDs

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## **Typical Application**



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### **Pin Descriptions**

Pinout is preliminary and subject to change during development.



1. Future products. Please contact factory for availability.

## **AAT2822/2823/2824/2825**

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### **Pin Configurations**

**TQFN44-24 (Top View)**







 **AAT2824 AAT2825** 



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### **Part Number Descriptions**



### **Absolute Maximum Ratings<sup>1</sup>**



### **Thermal Information<sup>2</sup>**



1. Stresses above those listed in Absolute Maximum Ratings may cause permanent damage to the device. Functional operation at conditions other than the operating conditions specified is not implied. Only one Absolute Maximum Rating should be applied at any one time.

2. Mounted on an FR4 board.

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## **Electrical Characteristics**

 $V_{IN}$  = 5V, EN = WEN = WDIM =  $V_{IN}$ ,  $V_{AVDD}$  =  $V_{DD}$  = 12V,  $T_A$  = -40°C to 85°C unless otherwise noted. Typical values are at  $T_A = 25$ °C.



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## **AAT2822/2823/2824/2825**

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## **Typical Characteristics**

#### **Oscillator Frequency vs. Temperature**



**Power Up Sequencing (VAVDD->VGL->VGH; VIN = 5.0V)**



**Time (1ms/div)**

**Main Boost Load Transient**  $(V_{IN} = 5.0V)$ 



**Time (500µs/div)**

**(VAVDD→VGH→VGL; VIN = 5.0V) EN/SET (5V/div) VAVDD (5V/div) VGL (20V/div) VGH (20V/div)**

**Time (500µs/div)**

**Power Up Sequencing**



**Line Regulation**



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## **Typical Characteristics**

#### **VGH vs. Temperature**



**VGL vs. Temperature**





**VGH Load Regulation**



**VGL Load Regulation**



**WLED Operation at 300mA Load**  $(V_{IN} = 5.0V, 3S13P)$ 



**Time (200µs/div)**

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## **Typical Characteristics**





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### **Functional Block Diagram**



### **Functional Description**

#### **Main Boost Converter**

The main boost regulator contains a current-mode, fixed-frequency PWM architecture to maximize loop bandwidth and provide fast transient response to pulsed loads typical of TFT-LCD panel source drivers. The 1.3MHz switching frequency allows the use of low profile, low value inductors and ceramic capacitors to minimize the thickness of LCD panel designs.

#### **Dual Charge-Pump Regulator**

The AAT2822 provides low-power regulated output voltages from two individual charge pumps to provide the VGH and VGL supplies. Using a single stage, the VGL

charge pump inverts the supply voltage  $(V_{DD})$  and provides a regulated negative output voltage. The VGH charge pump doubles  $V_{DD}$  and provides a regulated positive output voltage. These outputs use external Schottky diodes and capacitor multiplier stages (dependent upon the required output voltage) to regulate up to  $\pm 30V$ . Integrated soft-start circuitry minimizes the start-up inrush current and eliminates output voltage overshoot across the full input voltage range and all load conditions. A constant switching frequency of 1.3MHz minimizes output ripple and capacitor size.

#### **White LED Backlight Applications**

The AAT2822 consists of a 1.3MHz fixed-frequency DC/ DC boost controller, and an integrated high voltage MOSFET power switch. A high-voltage rectifier, power

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inductor, output capacitor, and sense resistors are required to implement a DC/DC constant current boost converter. Integrated soft-start circuitry minimizes the start-up inrush current and eliminates output voltage overshoot across the full input voltage range and all load conditions. The backlight current is set by an external ballast resistor up to a maximum of 260mA at 12V or 50mA at 28V output. Brightness control is via PWM dimming at up to 1kHz. Higher frequencies are achieved by filtered PWM. The AAT2822 can drive from 3 LEDs in series up to a maximum of 7 LEDs, making it suitable for screen sizes from 5" up to 10". Depending upon the number of LEDs required, up to 9 parallel strings can be successfully driven.

If the OVP input voltage is exceeded the WLED driver continues to regulate at the OVP threshold.



**Figure 1: WLED Driver Operation.**

#### **VCOM Buffer: Operational Amplifier**

The operational amplifier drives the LCD backplane VCOM. The operational amplifier features +/- 75mA(min) output short-circuit current, 13V/μs slew rate, and 12MHz bandwidth. Internal short-circuit protection limits the short circuit current while the output is directly shorted.

### **Power Supply Sequencing**

The AAT2822 family has integrated power supply sequencing to prevent damage to the LCD screen. Two sequences are available to swap the startup of the positive and negative gate drive voltages. The startup sequence for the "-1" option establishes main boost supply  $(V_{AVDD})$ first, followed by the gate voltages VGL then VGH. The sequence for the plain option is to establish  $V_{AVDD}$  first followed by VGH then VGL. The WLED backlight driver is independently controlled by WEN and WDIM.

### **Operating Faults**

The AAT2822 family continuously monitors for fault conditions on the main boost converter and charge pumps according to defined fault trip levels. During operation if any fault conditions persist the controller will shut down all supplies. After removing the fault conditions, recycle the enables to start up the supplies.

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#### **Figure 2: Startup Sequence for AAT282X-11.**

1. For AAT282x the startup sequence is positive charge pump followed by the negative charge pump.

### **Application Information**

#### **Main Step-Up Converter**

#### **Output Capacitor**

The high output ripple inherent in the boost converter necessitates low impedance output filtering. Multi-layer ceramic (MLC) capacitors provide small size and adequate capacitance, low parasitic equivalent series resistance (ESR) and equivalent series inductance (ESL), and are well suited for use with the primary step-up converter. MLCs of type X7R or X5R are recommended to ensure good capacitance stability over the full operating temperature range.

The output capacitor is sized to maintain the output load without significant voltage droop during the power switch ON interval, when the output diode is not conducting. And because the VGH, VGL also have their input power from the main step-up converter output, the output capacitor may also decrease the inrush current during VGH and VGL start up. A ceramic output capacitor with a minimum value of 22µF is recommended. For inrush current sensitive applications, two 22µF are recommended. Typically, 25V rated ceramic capacitors are required for the 24V boost output. Ceramic capacitors sized as small as 0805 are available which meet these requirements. MLCs exhibit significant capacitance reduction with applied voltage. Output ripple measurements should confirm that output voltage droop is acceptable.

#### **Input Capacitor**

The boost converter input current flows during both ON and OFF switching intervals. The input ripple current is less than the output ripple and, as a result, less input capacitance is required. However, the AAT2822 input voltage is shared among other channels; a ceramic input capacitor from 4.7µF to 10µF is recommended. Minimum 6.3V rated ceramic capacitors are required at the input. Ceramic capacitors sized as small as 0603 are available which meet these requirements.

Large capacitance tantalum or solid-electrolytic capacitors may be necessary to meet stringent output ripple and transient load requirements. These can replace (or be used in parallel with) ceramic capacitors. Both tantalum and OSCON-type capacitors are suitable due to their low ESR and excellent temperature stability (although they exhibit much higher ESR than MLCs). Aluminumelectrolytic types are less suitable due to their high ESR

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characteristics and temperature drift. Unlike MLCs, these types are polarized and proper orientation on input and output pins is required. 30% to 70% voltage derating is recommended for tantalum capacitors.

#### **Selecting the Schottky Diode**

To ensure minimum forward voltage drop and no recovery, high voltage Schottky diodes are the best choice for the primary step-up converter. The output diode is sized to maintain acceptable efficiency and reasonable operating junction temperature under full load operating conditions. Forward voltage  $(V_F)$  and package thermal resistance  $(\theta_{1A})$  are the dominant factors to consider in selecting a diode. The diode's published current rating may not reflect actual operating conditions and should be used only as a comparative measure between similarly rated devices. 20V rated Schottky diodes are recommended for outputs less than 15V, while 30V rated Schottky diodes are recommended for outputs greater than 15V.

The average diode current is equal to the output current:

 $I_{AVG} < I_{OUT}$ 

The average output current multiplied by the forward diode voltage determines the loss of the output diode.

$$
P_{\text{Loss\_DIODE}} = I_{\text{AVG}} \cdot V_{F} = I_{\text{OUT}} \cdot V_{F}
$$

Diode junction temperature can be estimated:

$$
T_{J} = T_{A} + \theta_{JA} \cdot P_{Loss\_DIODE}
$$

The junction temperature should be maintained below 110°C, but may vary depending on application and/or system guidelines. The diode  $\theta_{JA}$  can be minimized with additional PCB area on the cathode. PCB heat sinking the anode may degrade EMI performance.

The reverse leakage current of the rectifier must be considered to maintain low quiescent (input) current and high efficiency under light load. The rectifier's reversed current increases dramatically at high temperatures.

#### **Selecting the Main Step-Up Inductor**

The primary step-up converter is designed to operate with a 2.2μH inductor for all input and output voltage combinations. The inductor saturation current rating should be greater than the NMOS current limit. If necessary, the peak inductor current can exceed the saturation level by a small amount with no significant effect on performance. The maximum duty cycle can be estimated from the relationship for a continuous mode boost converter. Maximum duty cycle  $(D_{MAX})$  is the duty cycle at minimum input voltage  $(V_{IN(MIN)})$ .

$$
D_{MAX} = \frac{(V_{OUT} + V_F - V_{IN(MIN)})}{V_{OUT} + V_F}
$$

Where  $V_F$  is the Schottky diode forward voltage and can be estimated at 0.5V. Manufacturer's specifications list both the inductor DC current rating, which is a thermal limitation, and peak inductor current rating, which is determined by the saturation characteristics. Measurements at full load and high ambient temperature should be completed to ensure that the inductor does not saturate or exhibit excessive temperature rise.

The output inductor (L) is selected to avoid saturation at minimum input voltage, maximum output load conditions. Peak current may be calculated from the following equation, again assuming continuous conduction mode. Worst-case peak current occurs at minimum input voltage (maximum duty cycle) and maximum load. Switching frequency  $(F_s)$  is at 1.3MHz with a 2.2 $\mu$ H inductor.

$$
I_{\text{PEAK}} = \frac{I_{\text{OUT}}}{1 - D_{\text{MAX}}} + \frac{D_{\text{MAX}} \cdot V_{\text{IN(MIN)}}}{2 \cdot F_s \cdot L}
$$

The RMS current flowing through the boost inductor is equal to the DC plus AC ripple components.

Under worst-case RMS conditions, the current waveform is critically continuous. The resulting RMS calculation yields worst-case inductor loss. The RMS value should be compared against the manufacturer's temperature rise or thermal derating guidelines.

$$
I_{\rm RMS}=\frac{I_{\rm PEAK}}{\sqrt{3}}
$$

For a given inductor type, smaller inductor size leads to an increase in DCR winding resistance and, in most cases, increased thermal impedance. Winding resistance degrades boost converter efficiency and increases the inductor operating temperature.

$$
P_{\text{Loss\_INDUCTOR}} = I_{\text{RMS}}^2 \cdot DCR
$$

#### **Setting the Output Voltage**

The resistive divider network R2 and R3 of Figure 7 programs the output to regulate at a voltage higher than 0.6V as shown in Table 1. To limit the bias current required for the external feedback resistor string while maintaining good noise immunity, the minimum sug-

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gested value for R3 is 6.04kΩ. The resistive divider can be calculated in the following equation:

$$
R_3 = R_2 \cdot \left(\frac{V_{\text{AVDD}}}{V_{\text{FB}}} - 1\right) = R_2 \cdot \left(\frac{V_{\text{AVDD}}}{0.6V} - 1\right)
$$



#### **Table 1: Setting the Output Voltage for the Main Step-Up Converter.**

#### **Selecting Compensation Components**

The AAT2822 main boost architecture uses peak current mode control to eliminate the double pole effect of the output L&C filter and simplifies compensation loop design. The current mode control architecture simplifies the transfer function of the control loop to a one-pole, one left plane zero and one right half plane (RHP) system in frequency domain. The dominant pole can be calculated by:

$$
f_{\text{p}} = \ \frac{1}{2\pi \cdot R_{\text{O}} \cdot C_6}
$$

The ESR zero of the output capacitor can be calculated by:

$$
\mathsf{f}_{Z\_ESR} = \frac{1}{2\pi \cdot \mathsf{R}_{ESR} \cdot \mathsf{C}_6}
$$

Where:

 $C_6$  is the output filter capacitor

 $R<sub>o</sub>$  is the load resistor value

 $R_{ESR}$  is the equivalent series resistance of the output capacitor.

The right half plane (RHP) zero can be determined by:

$$
f_{Z\_RHP} = \frac{V_{IN}^2}{2\pi \cdot L_1 \cdot I_{AVDD} \cdot V_{AVDD}}
$$

It is recommended to design the bandwidth to one

decade lower than the frequency of RHP zero to guarantee the loop stability. A series capacitor and resistor network (R11 and C8) connected to the COMP pin sets the pole and zero which are given by:

$$
f_{P\_COM} = \frac{1}{2\pi \cdot R_{EA} \cdot C_8}
$$

$$
f_{Z\_COM} = \frac{1}{2\pi \cdot R_{11} \cdot C_8}
$$

Where:

 $C_8$  is the compensation capacitor

 $R_{11}$  is the compensation resistor

 $R_{EA}$  is the output resistance of the error amplifier (M $\Omega$ ).

A 100pF capacitor and a 200kΩ resistor in series are chosen for optimum phase margin and fast transient response.

#### **Charge Pump**

The number of charge pump stages required for a given output ( $V_{GH}$ ) varies with the input voltage applied ( $V_{AVDD}$ ) from the main boost. A lower input voltage requires more stages for a given output. If the numbers of stages increases, the maximum load current limitation of the charge pump would be decreased to maintain output voltage regulation.

The number of stages required can be estimated by:

$$
n_{\rm P} = \frac{V_{\rm GH} \cdot V_{\rm AVDD(MIN)}}{V_{\rm AVDD(MIN)} \cdot 2V_{\rm F}}
$$

for the positive output and

$$
n_N = \frac{V_{GL}}{2V_F - V_{AVDD(MIN)}}
$$

for the negative output where  $V_F = 0.31V$  is the forward voltage of the BAT54 Schottky diode at 4mA forward current.

When solving for  $n_p$  and  $n_p$ , round up the solution to the next highest integer to determine the number of stages required.

#### **Negative Output Voltage (V<sub>GL</sub>)**

The negative output voltage is adjusted by a resistive divider from the output ( $V_{ON}$ ) to the FBN and REF pins. The maximum reference voltage current is 200µA; therefore, the minimum allowable value for  $R_{10}$  of Figure

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6 is 6.04kΩ. It is best to select the smallest value possible for  $R_{10}$ , as this will keep the value of  $R_9$  to a minimum. With  $R_{10}$  selected,  $R_9$  can be determined:

$$
R_9 = \frac{V_{GL}}{V_{REF}} \cdot R_{10} = \frac{V_{GL}}{1.2V} \cdot R_{10}
$$

#### **Positive Output Voltage (V<sub>GH</sub>)**

The positive output voltage is set by a resistive divider from the output  $(V_{GH})$  to the FBP and ground pins. Limiting the value of  $R_7$  to 6.04kΩ or lower reduces noise in the feedback circuit.

Once  $R_7$  has been determined, solve for  $R_6$ :

$$
R_6 = R_7 \cdot \left(\frac{V_{GH}}{V_{FBP}} - 1\right) = R_7 \cdot \left(\frac{V_{GH}}{0.6V} - 1\right)
$$

#### **Flying and Output Capacitors**

The minimum value for the flying capacitor is limited by the output power requirement, while the maximum value is set by the bandwidth of the power supply. If  $C_{FLY}$  is too small, the output may not be able to deliver the power demanded, while too large of a capacitor may limit the bandwidth and time required to recover from load and line transients. A 0.1µF X7R or X5R ceramic capacitor is typically used. The voltage rating of the flying and reservoir output capacitors varies with the number of charge pump stages. The reservoir output capacitor value should be roughly 10 times the value of the flying capacitor. Use larger capacitors for reduced output ripple.

#### **Input Capacitor**

The primary function of the input capacitor is to provide a low impedance loop for the edges of pulsed current drawn by the IC. A low ESL X7R or X5R type ceramic capacitor is ideal for this function. The size required will vary depending on the load, output voltage, and input voltage characteristics. Typically, the input capacitor value should be 5 to 10 times the value of the flying capacitor. If the source impedance of the input supply is high, a larger capacitor may be required. To minimize stray inductance, the capacitor should be placed as closely as possible to the IC. This keeps the high frequency content of the input current localized, minimizing radiated and conducted EMI.

#### **Rectifier Diodes**

For the rectifiers, use Schottky diodes with a voltage rating of 1.5 times the input voltage. The maximum steadystate voltage seen by the rectifier diodes for both the positive and negative charge pumps (regardless of the number of stages) is:

$$
V_{REVERSE} = V_{IN} - V_{F}
$$

The BAT54SDW quad Schottky diode in a SOT363 (2x2mm) package is a good choice for multiple-stage charge pump configuration.

#### **White LED Driver**

The white LED backlight driver can be enabled when input supply rises above under voltage lockout threshold. To reduce inrush current it is recommended that the main boost and white LED driver are not enabled concurrently.

#### **Over-Voltage Protection (OVP) with Open Circuit Failure**

The OVP protection circuit consists of a resistor network tied from the output voltage to the OVP pin (see Figure 3). To protect the device from open circuit failure, the resistor divider can be selected such that the over-voltage threshold occurs prior to the output reaching  $V_{LED+(MAX)}$ . The value of R<sub>5</sub> should be selected from 10kΩ to 20kΩ to minimize losses without degrading noise immunity.



**Figure 3: Over-Voltage Protection Circuit.**

#### **OVP Constant Voltage Operation**

Under closed loop constant current conditions, the output voltage is determined by the operating current, LED forward voltage characteristics  $(V_{F(FD)})$ , quantity of series connected LEDs (N), and the feedback pin voltage ( $V_{FB}$ ).

$$
V_{\text{OUT}} = V_{\text{FB}} + N \cdot V_{\text{FLED}}
$$

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When the rising OVP threshold is exceeded, switching is stopped and the output voltage decays. Switching automatically restarts when the output drops below the lower OVP hysteresis voltage (100mV typical), and as a result the output voltage increases. The cycle repeats, maintaining an average DC output voltage proportional to the average of the rising and falling OVP levels (multiplied by the resistor divider scaling factor). High operating frequency and low output voltage ripple ensure DC current and negligible flicker in the LED string(s).

While OVP is active, the maximum LED current programming error  $(\Delta I_{LED})$  is proportional to voltage error across an individual LED (ΔV<sub>FLED</sub>).

$$
\Delta V_{\text{FLED}} = \frac{N \cdot V_{\text{FLED(TYP)}} - V_{\text{OVP(MIN)}} - V_{\text{WFB}}}{N}
$$

To minimize the  $\Delta I_{LED}$  error, the minimum OVP voltage  $(V_{\text{OVP(MIN)}})$  may be increased, yielding a corresponding increase in the maximum OVP voltage  $(V_{\text{OVP(MAX)}})$ .

Measurements should confirm that the maximum switching node voltage ( $V_{WLX(MAX)}$ ) is less than 30V under worst case operating conditions.

$$
V_{\text{WLX(MAX)}} = V_{\text{OVP(MAX)}} \cdot \left(\frac{R_2}{R_1} + 1\right) + V_{\text{F}} + V_{\text{RING}}
$$

 $V_F$  is the Schottky diode D<sub>2</sub> forward voltage at turn-OFF.

 $V_{RING}$  is the voltage ring occurring at turn-OFF.

#### **White LED Selection and Current Setting**

The WLED current is controlled by the WFB voltage and the ballast resistor  $(R_8)$ . For maximum accuracy, a 1% tolerance resistor is recommended.

The ballast resistor  $(R_8)$  value can be calculated as follows:

$$
R_8 = \left(\frac{V_{WFB(MAX)}}{I_{LED(MAX)}}\right)
$$

Where  $V_{WFB} = 0.3V$ 

For example, if the maximum current for each string of 3 series LEDs is 20mA, the maximum current for a 10 inch panel (3S13P) is 260mA (20mA  $x$  13), which corresponds to a minimum resistor value of  $1.15\Omega$ 

$$
R_8 = \left(\frac{0.3V}{260mA}\right) = 1.15\Omega
$$



**Table 2: Maximum LED Current and Ballast Resistor (R8) Values for 10" Panel Size.**

Typical white LEDs are driven at maximum continuous currents of 15mA to 20mA. The maximum number of series-connected LEDs is determined by the minimum output voltage of the boost converter  $(V_{LED})$ , minus the maximum feedback voltage ( $V_{WFB(MAX)}$ ) divided by the maximum LED forward voltage ( $V_{FLED(MAX)}$ ) which can be estimated from the manufacturers' datasheet at the maximum LED operating current.

$$
V_{LED} = V_{\text{OVP(TYP)}} \cdot \left(\frac{R_{5}}{R_{4}} + 1\right)
$$

$$
N = \left(\frac{V_{\text{OVP(MIN)}} - V_{\text{WFB(MAX)}}}{V_{\text{FLED(MAX)}}}\right)
$$

For example, the typical forward voltage of the white LED is 3.5V at 20mA.

$$
V_{LED} = V_{\text{OVP(TYP)}} \cdot \left(\frac{R_5}{R_4} + 1\right) = 0.6 \cdot \left(\frac{464k\Omega}{10k\Omega} + 1\right) = 27.8 \cdot \text{V}
$$

$$
N = \left(\frac{V_{\text{OVP(MIN)}} - V_{\text{WFB(MAX)}}}{V_{\text{FLED(MAX)}}}\right) = \left(\frac{27.8 \cdot 0.6 \cdot \text{V}}{3.5 \cdot \text{V}}\right) = 7.8 \cdot \text{LEDS}
$$

Therefore, under these typical operating conditions, 7 LEDs can be used in series for each string.

#### **PWM Dimming Control**

The dimming of the white LED can be controlled using a PWM or a filter PWM signal. By connecting a PWM signal to the WDIM pin and adjusting the duty cycle of the PWM signal, the dimming of the white LED changes proportionally to the percentage of the duty cycle as shown in Figure 4. However, the dimming control using PWM connected to the WDIM pin can operate at a frequency up to 1kHz.

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**Figure 4: PWM Dimming Control.**



**Figure 5: Low-Pass Filter PWM Dimming Control.**

When the PWM duty cycle is adjusted, the DC voltage across the ballast resistor  $(R_8)$  changes, resulting in change of the white LED current. Apply the KCL at the feedback node (WFB). The voltage across the  $R_8$  resistor can be expressed:

$$
V_{R8} = 0.3V - \frac{R_{21}}{R_{22}} \cdot (V_{C25} - 0.3V)
$$

For minimum dimming,  $V_{R8} = 0V$ .

For applications requiring a PWM frequency higher than 1KHz, an external filter PWM is connected to the WFB pin to control the dimming of the white LED. This low-pass filter ( $R_{23}/C_{25}$ ) integrates the high frequency PWM signal to produce a DC dimming control as shown in Figure 5.

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Choose  $R_{21}$  = 4.99k $\Omega$  and  $V_{C25}$  = 2V, and solve for  $R_{22}$ :

$$
R_{22} = \frac{R_{21}}{(0.3V - V_{R8}) \cdot (V_{C25} - 0.3V)} = 28k\Omega
$$

The low-pass filter should be chosen to produce an acceptable ripple for the DC dimming voltage and a small time constant. For application where the PWM frequency is greater than 10KHz, the optimum values for the low-pass filter are R<sub>23</sub> = 4.99kΩ and C<sub>25</sub> = 0.1μF.

#### **Selecting the Schottky Diode**

To ensure minimum forward voltage drop and no recovery, high-voltage Schottky diodes are considered the best choice for the WLED boost converter. The output diode is sized to maintain acceptable efficiency and reasonable operating junction temperature under full load operating conditions. Forward voltage  $(V_F)$  and package thermal resistance  $(\theta_{14})$  are the dominant factors to consider in selecting a diode. The diode's non-repetitive peak forward surge current rating  $(I_{FSM})$  should be considered for high pulsed load applications such as camera flash. The  $I_{FSM}$  rating drops with increasing conduction period. Manufacturers' datasheets should be consulted to verify reliability under peak load conditions. The diode's published current rating may not reflect actual operating conditions and should be used only as a comparative measure between similarly rated devices.

40V rated Schottky diodes are recommended for outputs less than 30V, while 60V rated Schottky diodes are recommended for outputs greater than 35V.

The average diode current is equal to the output current:

$$
I_{\text{AVG}}=I_{\text{OUT}}
$$

The average output current multiplied by the forward diode voltage determines the loss of the output diode.

$$
P_{\text{Loss\_DIODE}} = I_{\text{AVG}} \cdot V_{F} = I_{\text{OUT}} \cdot V_{F}
$$

Diode junction temperature can be estimated:

$$
T_{\text{J}} = T_{\text{A}} + \theta_{\text{JA}} \cdot P_{\text{Loss\_DIODE}}
$$

Output diode junction temperature should be maintained below 110°C, but may vary depending on application and/or system quidelines. The diode  $\theta_{14}$  can be minimized with additional PCB area on the cathode. PCB heat-sinking the anode may degrade EMI performance. The reverse leakage current of the rectifier must be considered to maintain low quiescent (input) current and

high efficiency under light load. The rectifier's reverse current increases dramatically at elevated temperatures.

#### **Selecting the WLED Step-Up Inductor**

The WLED step-up converter has the same topology as the main step-up converter. It is designed to operate with a 2.2μH inductor for all input and output voltage combinations. The inductor saturation current rating should be greater than the NMOS current limit.

$$
D_{MAX} = \frac{(V_{OUT} + V_F - V_{IN(MIN)})}{V_{OUT} + V_F}
$$

The output inductor (L) is selected to avoid saturation at minimum input voltage and maximum output load conditions. Peak current may be calculated from the following equation, again assuming continuous conduction mode. Worst-case peak current occurs at minimum input voltage (maximum duty cycle) and maximum load. Switching frequency is estimated at 1.3MHz with a 2.2µH inductor.

$$
I_{\text{PEAK}} = \frac{I_{\text{OUT}}}{1 - D_{\text{MAX}}} + \frac{D_{\text{MAX}} \cdot V_{\text{IN(MIN)}}}{2 \cdot F_s \cdot L}
$$

#### **Selecting the WLED Step-Up Capacitors**

The high output ripple inherent in the boost converter necessitates low impedance output filtering.

Multi-layer ceramic (MLC) capacitors provide small size and adequate capacitance, low parasitic equivalent series resistance (ESR) and equivalent series inductance (ESL), and are well suited for use with the WLED boost regulator. MLC capacitors of type X7R or X5R are recommended to ensure good capacitance stability over the full operating temperature range.

The output capacitor is sized to maintain the output load without significant voltage droop (ΔVoυτ) during the power switch ON interval, when the output diode is not conducting. A ceramic output capacitor with a value of 2.2μF to 4.7μF is recommended. Typically, 50V rated capacitors are required for the 28V maximum boost output. Ceramic capacitors sized as small as 0805 or 1206 are available which meet these requirements.

MLC capacitors exhibit significant capacitance reduction with applied voltage. Output ripple measurements should confirm that output voltage droop and operating stability are acceptable. Voltage derating can minimize this factor, but results may vary with package size and among specific manufacturers.

### *TFT-LCD DC/DC Converter with WLED Driver and VCOM Buffer*

The output capacitor size can be estimated using the equation:

$$
C_{\text{OUT}} = \frac{I_{\text{OUT}} \cdot D_{\text{MAX}}}{F_{\text{s}} \cdot \Delta V_{\text{OUT}}}
$$

To maintain stable operation at full load, the output capacitor should be sized to maintain  $\Delta V_{\text{OUT}}$  between 100mV and 200mV.

The WLED boost converter input current flows during both ON and OFF switching intervals. The input ripple current is lower than the output ripple and, as a result, a lower input capacitance is required.

#### **LCD VCOM Buffer**

The VCOM buffer is designed to drive the voltage on the backplane of an LCD display. The buffer must be capable of sinking and sourcing capacitive pulse current at low frequency. A 10nF ceramic output capacitor in series with a 100Ω resistor is sufficient for buffer stability at high frequencies.

The VCOM output voltage is typically set to half of the main boost output voltage  $V_{ADD}$ . The maximum input bias voltage for the VCOM buffer  $(V_{\text{OPIN}})$  cannot exceed 13V. In applications where the main boost output voltage  $V_{VADD}$  is greater than 13V,  $V_{OPIN}$  should be connected to an external supply to prevent damage to the device; the jumper  $J_7$  should be left open to disconnect V<sub>AVDD</sub> from V<sub>OPIN</sub>.

## **AAT2822/2823/2824/2825**



**Figure 6: AAT2822IBK Evaluation Board Schematic.**

## **AAT2822/2823/2824/2825**

## *TFT-LCD DC/DC Converter with WLED Driver and VCOM Buffer*



#### **Table 3: AAT2822IBK Evaluation Board Bill Of Materials (BOM).**



**Table 4: Ballast Resistor Selection for Different Panel Sizes.**

**Eq. 1:** R<sub>2</sub> = R<sub>3</sub> · 
$$
\left(\frac{V_{AVDD}}{V_{FB}} - 1\right)
$$
 = 6.04kΩ ·  $\left(\frac{V_{AVDD}}{0.6V} - 1\right)$   
\n**Eq. 2:** R<sub>9</sub> =  $\frac{V_{GL}}{V_{FBN}}$  · R<sub>10</sub> =  $\frac{V_{GL}}{1.2V}$  · 6.04kΩ  
\n**Eq. 3:** R<sub>6</sub> = R<sub>7</sub> ·  $\left(\frac{V_{GH}}{V_{FBP}} - 1\right)$  = 6.04kΩ ·  $\left(\frac{V_{GH}}{0.6V} - 1\right)$ 

## **AAT2822/2823/2824/2825 DATA SHEET**



**Figure 7: AAT2823IBK Evaluation Board Schematic.**

## **AAT2822/2823/2824/2825**



**Figure 8: AAT2824IBK Evaluation Board Schematic.**

## **AAT2822/2823/2824/2825**



**Figure 9: AAT2825IBK Evaluation Board Schematic.**

## **AAT2822/2823/2824/2825**



 **Figure 10: AAT28XXIBK Evaluation Board Figure 11: AAT28XXIBK Evaluation Board** 



**Top Side Layout. Bottom Side Layout. Bottom Side Layout.** 

## **AAT2822/2823/2824/2825**

## *TFT-LCD DC/DC Converter with WLED Driver and VCOM Buffer*

## **Ordering Information1,2**





Skyworks Green™ products are compliant with all applicable legislation and are halogen-free. For additional information, refer to Skyworks Definition of Green™, document number SQ04-0074.

### **Package Information<sup>3</sup>**



**TQFN44-24**

All dimensions in millimeters.

1. XYY = assembly and date code.

- 2. Sample stock is generally held on part numbers listed in **BOLD**.
- 3. The leadless package family, which includes QFN, TQFN, DFN, TDFN and STDFN, has exposed copper (unplated) at the end of the lead terminals due to the manufacturing process. A solder fillet at the exposed copper edge cannot be guaranteed and is not required to ensure a proper bottom solder connection.

## **AAT2822/2823/2824/2825**

*TFT-LCD DC/DC Converter with WLED Driver and VCOM Buffer*

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