



SBAS187 - SEPTEMBER 2001

# 8-Channel, 24-Bit ANALOG-TO-DIGITAL CONVERTER with FLASH Memory

# FEATURES

- 24 BITS NO MISSING CODES
- 0.0015% INL
- 22 BITS EFFECTIVE RESOLUTION (PGA = 1), 19 BITS (PGA = 128)
- 4K BYTES OF FLASH MEMORY PROGRAMMABLE FROM 2.7V TO 5.25V
- PGA FROM 1 TO 128
- SINGLE CYCLE SETTLING MODE
- PROGRAMMABLE DATA OUTPUT RATES UP TO 1kHz
- PRECISION ON-CHIP 1.25V/2.5V REFERENCE: ACCURACY: 0.2% DRIFT: 5ppm/°C
- EXTERNAL DIFFERENTIAL REFERENCE OF 0.1V TO 2.5V
- ON-CHIP CALIBRATION
- PIN COMPATIBLE WITH ADS1216
- SPI™ COMPATIBLE
- 2.7V TO 5.25V
- < 1mW POWER CONSUMPTION

# APPLICATIONS

- INDUSTRIAL PROCESS CONTROL
- LIQUID/GAS CHROMATOGRAPHY
- BLOOD ANALYSIS
- SMART TRANSMITTERS
- PORTABLE INSTRUMENTATION
- WEIGHT SCALES
- PRESSURE TRANSDUCERS

SPI is a registered trademark of Motorola.

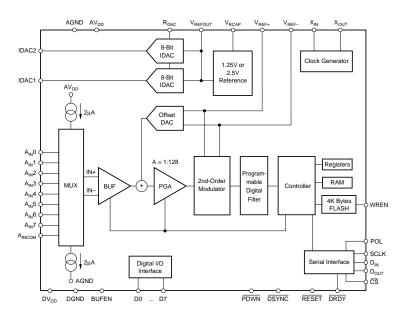
# DESCRIPTION

The ADS1218 is a precision, wide dynamic range, delta-sigma, Analog-to-Digital (A/D) converter with 24-bit resolution and FLASH memory operating from 2.7V to 5.25V supplies. The delta-sigma, A/D converter provides up to 24 bits of no missing code performance and effective resolution of 22 bits.

The eight input channels are multiplexed. Internal buffering can be selected to provide a very high input impedance for direct connection to transducers or low-level voltage signals. Burn out current sources are provided that allow for the detection of an open or shorted sensor. An 8-bit Digital-to-Analog (D/A) converter provides an offset correction with a range of 50% of the FSR (Full-Scale Range).

The PGA (Programmable Gain Amplifier) provides selectable gains of 1 to 128 with an effective resolution of 19 bits at a gain of 128. The A/D conversion is accomplished with a second-order delta-sigma modulator and programmable sinc filter. The reference input is differential and can be used for ratiometric conversion. The on-board current DACs (Digital-to-Analog Converters) operate independently with the maximum current set by an external resistor.

The serial interface is SPI compatible. Eight bits of digital I/O are also provided that can be used for input or output. The ADS1218 is designed for high-resolution measurement applications in smart transmitters, industrial process control, weight scales, chromatography, and portable instrumentation.





Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

### ABSOLUTE MAXIMUM RATINGS<sup>(1)</sup>

AV <sub>DD</sub> to AGND DV <sub>DD</sub> to DGND	
Input Current	
Input Current	
A <sub>IN</sub>	GND –0.5V to AV <sub>DD</sub> + 0.5V
AV <sub>DD</sub> to DV <sub>DD</sub>	–6V to +6V
AGND to DGND	–0.3V to +0.3V
Digital Input Voltage to GND	0.3V to DV <sub>DD</sub> + 0.3V
Digital Output Voltage to GND	–0.3V to DV <sub>DD</sub> + 0.3V
Maximum Junction Temperature	+150°C
Operating Temperature Range	–40°C to +85°C
Storage Temperature Range	–60°C to +100°C
Lead Temperature (soldering, 10s)	+300°C

NOTE: (1) Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. Exposure to absolute maximum conditions for extended periods may affect device reliability.

# PACKAGE/ORDERING INFORMATION



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

Electrostatic discharge can cause damage ranging from performance degradation to complete device failure. Texas Instruments recommends that all integrated circuits be handled and stored using appropriate ESD protection methods.

PRODUCT	PACKAGE-LEAD	PACKAGE DESIGNATOR	SPECIFIED TEMPERATURE RANGE	PACKAGE MARKING	ORDERING NUMBER	TRANSPORT MEDIA, QUANTITY
ADS1218Y	TQFP-48	PFB	–40°C to +85°C	ADS1218Y	ADS1218Y/250	Tape and Reel, 250
"	"	"	"	"	ADS1218Y/2K	Tape and Reel, 2000

NOTE: (1) Models with a slash (/) are available only in Tape and Reel in the quantities indicated (e.g., /2K indicates 2000 devices per reel). Ordering 2000 pieces of "ADS1218Y/2K" will get a single 2000-piece Tape and Reel.

# ELECTRICAL CHARACTERISTICS: AV<sub>DD</sub> = 5V

All specifications  $T_{MIN}$  to  $T_{MAX}$ ,  $AV_{DD} = +5V$ ,  $DV_{DD} = +2.7V$  to 5.25V,  $f_{MOD} = 19.2$ kHz,  $f_{OSC} = 2.4576$ MHz, PGA = 1, Buffer ON,  $R_{DAC} = 150$ k $\Omega$ ,  $f_{DATA} = 10$ Hz,  $V_{REF} \equiv (REF IN+) - (REF IN-) = +2.5V$ , unless otherwise specified.

			ADS1218		
PARAMETER	CONDITIONS	MIN	ТҮР	MAX	UNITS
ANALOG INPUT (A <sub>IN</sub> 0 – A <sub>IN</sub> 7, A <sub>INCOM</sub> ) Analog Input Range Full-Scale Input Voltage Range Differential Input Impedance Input Current	Buffer OFF Buffer ON (In+) – (In–), See Block Diagram Buffer OFF Buffer ON	AGND – 0.1 AGND + 0.05	5/PGA 0.5	$AV_{DD}$ + 0.1 $AV_{DD}$ - 1.5 $\pm V_{REF}$ /PGA	V V V MΩ nA
Bandwidth Fast Settling Filter Sinc <sup>2</sup> Filter Programmable Gain Amplifier Input Capacitance Input Leakage Current Burnout Current Sources	−3dB −3dB −3dB User Selectable Gain Ranges Modulator OFF, T = 25°C	1	0.469 • f <sub>DATA</sub> 0.318 • f <sub>DATA</sub> 0.262 • f <sub>DATA</sub> 9 5 2	128	Hz Hz Hz pF pA μA
OFFSET DAC Offset DAC Range Offset DAC Monotonicity Offset DAC Gain Error Offset DAC Gain Error Drift		8	±V <sub>REF</sub> /(2 • PGA) ±10 1		V Bits % ppm/°C
SYSTEM PERFORMANCE Resolution No Missing Codes Integral Non-Linearity Offset Error <sup>(1)</sup> Offset Drift <sup>(1)</sup> Gain Error Gain Error Drift <sup>(1)</sup> Common-Mode Rejection Normal-Mode Rejection	$\begin{array}{c} \text{sinc}^{3}\\ \text{End Point Fit}\\ \text{Before Calibration}\\ \text{After Calibration}\\ \text{at DC}\\ f_{CM} = 60\text{Hz}, f_{DATA} = 10\text{Hz}\\ f_{CM} = 50\text{Hz}, f_{DATA} = 50\text{Hz}\\ f_{CM} = 60\text{Hz}, f_{DATA} = 60\text{Hz}\\ f_{SIG} = 50\text{Hz}, f_{DATA} = 50\text{Hz}\\ f_{SIG} = 60\text{Hz}, f_{DATA} = 60\text{Hz}\\ f_{SIG} = 60\text{Hz}, f_{DATA} = 60\text{Hz}\\ \end{array}$	24	7.5 0.02 0.005 0.5 130 120 120 120 100 100 Typical Characteri	24 ±0.0015	Bits Bits % of FS ppm of FS/°C % ppm/°C dB dB dB dB dB dB dB
Output Noise Power-Supply Rejection	at DC, dB = -20 log( $\Delta V_{OUT} / \Delta V_{DD}$ ) <sup>(2)</sup>	80	95		dB



# ELECTRICAL CHARACTERISTICS: AV<sub>DD</sub> = 5V (Cont.)

All specifications  $T_{MIN}$  to  $T_{MAX}$ ,  $AV_{DD} = +5V$ ,  $DV_{DD} = +2.7V$  to 5.25V,  $f_{MOD} = 19.2$ kHz,  $f_{OSC} = 2.4576$ MHz, PGA = 1, Buffer ON,  $R_{DAC} = 150$ k $\Omega$ ,  $f_{DATA} = 10$ Hz,  $V_{REF} \equiv (REF IN+) - (REF IN-) = +2.5V$ , unless otherwise specified.

			ADS1218		
PARAMETER	CONDITIONS	MIN	ТҮР	МАХ	UNITS
VOLTAGE REFERENCE INPUT					
Reference Input Range	REF IN+, REF IN-	0		AV <sub>DD</sub>	V
V <sub>REF</sub>	$V_{REF} \equiv (REF IN+) - (REF IN-)$	0.1	2.5	2.6	V
Common-Mode Rejection	at DC		120		dB
Common-Mode Rejection	$f_{VREFCM} = 60Hz, f_{DATA} = 60Hz$		120		dB
Bias Current <sup>(3)</sup>	$V_{\text{REF}} = 2.5 \text{V}$		1.3		μΑ
ON-CHIP VOLTAGE REFERENCE					
Output Voltage	REF HI = 1 at 25°C	2.495	2.50	2.505	V
	REF HI = $0$		1.25		V
Short-Circuit Current Source			8		mA
Short-Circuit Current Sink			50		μA
Short-Circuit Duration	Sink or Source		Indefinite		·
Drift			5		ppm/°C
Noise	BW = 0.1Hz to 100Hz		10		μVp-p
Output Impedance	Sourcing 100µA		3		Ω
Startup Time			50		 μs
IDAC					
Full-Scale Output Current	$R_{DAC} = 150 k\Omega$ , Range = 1		0.5		mA
	$R_{DAC} = 150k\Omega$ , Range = 2		1		mA
	$R_{DAC} = 150k\Omega$ , Range = 3		2		mA
	$R_{DAC} = 15k\Omega$ , Range = 3		20		mA
Maximum Short-Circuit Current Duration	$R_{DAC} = 10k\Omega_2$ , runge = 0 $R_{DAC} = 10k\Omega$		Indefinite		110.3
Maximum Short-Circuit Current Duration	$R_{DAC} = 10R22$ $R_{DAC} = 0\Omega$		Indennite	10	Minutes
Manadaniaita		0		10	
Monotonicity	$R_{DAC} = 150 k\Omega$	8			Bits
Compliance Voltage		0	 Turning  Objects start	AV <sub>DD</sub> – 1	V
Output Impedance		se	e Typical Characteri	STICS	
PSRR	$V_{OUT} = AV_{DD}/2$		400		ppm/V
Absolute Error	Individual IDAC		5		%
Absolute Drift			75		ppm/°C
Mismatch Error	Between IDACs, Same Range and Code		0.25		%
Mismatch Drift	Between IDACs, Same Range and Code		15		ppm/°C
	A) (	4 75		5.05	V
Power-Supply Voltage		4.75		5.25	-
Analog Current $(I_{ADC} + I_{VREF} + I_{DAC})$	PDWN = 0, or SLEEP		1	075	nA
ADC Current (I <sub>ADC</sub> )	PGA = 1, Buffer OFF		175	275	μA
	PGA = 128, Buffer OFF		500	750	μA
	PGA = 1, Buffer ON		250	350	μA
	PGA = 128, Buffer ON		900	1375	μΑ
V <sub>REF</sub> Current (I <sub>VREF</sub> )			250	375	μΑ
I <sub>DAC</sub> Current (I <sub>DAC</sub> )	Excludes Load Current		480	675	μΑ
Digital Current	Normal Mode, $DV_{DD} = 5V$		180	275	μΑ
	SLEEP Mode, $DV_{DD} = 5V$		150		μA
	Read Data Continuous Mode, DV <sub>DD</sub> = 5V		230		μΑ
	PDWN= LOW		1		nA
Power Dissipation	PGA = 1, Buffer OFF, REFEN = 0,		1.8	2.8	mW
	$I_{DACS}$ OFF, $DV_{DD} = 5V$				
TEMPERATURE RANGE					
Operating		-40		+85	°C
Storage		-60		+100	°C

NOTES: (1) Calibration can minimize these errors. (2)  $\Delta$  V<sub>OUT</sub> is change in digital result. (3) 12pF switched capacitor at f<sub>SAMP</sub> clock frequency.



# ELECTRICAL CHARACTERISTICS: $AV_{DD} = 3V$

All specifications T<sub>MIN</sub> to T<sub>MAX</sub>,  $AV_{DD}$  = +3V,  $DV_{DD}$  = +2.7V to 5.25V,  $f_{MOD}$  = 19.2kHz,  $f_{OSC}$  = 2.4576MHz, PGA = 1, Buffer ON,  $R_{DAC}$  = 75k $\Omega$ ,  $f_{DATA}$ =10Hz,  $V_{REF} \equiv (REF IN+) - (REF IN-) = +1.25V$  unless otherwise specified.

		ADS1218				
PARAMETER	CONDITIONS	MIN	TYP	МАХ	UNITS	
ANALOG INPUT (A <sub>IN</sub> 0 – A <sub>IN</sub> 7, A <sub>INCOM</sub> ) Analog Input Range Full-Scale Input Voltage Range Input Impedance Input Current	nalog Input Range Buffer OFF Buffer ON ull-Scale Input Voltage Range (In+) – (In–) See Block Diagram put Impedance Buffer OFF		5/PGA 0.5	AV <sub>DD</sub> + 0.1 AV <sub>DD</sub> - 1.5 ±V <sub>REF</sub> /PGA	V V V MΩ nA	
Bandwidth Fast Settling Filter Sinc <sup>2</sup> Filter Sinc <sup>3</sup> Filter Programmable Gain Amplifier Input Capacitance Input Leakage Current Burnout Current Sources	-3dB -3dB -3dB User Selectable Gain Ranges Modulator OFF, T = 25°C	1	0.469 • f <sub>DATA</sub> 0.318 • f <sub>DATA</sub> 0.262 • f <sub>DATA</sub> 9 5 2	128	Hz Hz Hz pF pA μA	
OFFSET DAC Offset DAC Range Offset DAC Monotonicity Offset DAC Gain Error Offset DAC Gain Error Drift		8	±V <sub>REF</sub> /(2 • PGA) ±10 2		V Bits % ppm/°C	
SYSTEM PERFORMANCE Resolution No Missing Codes Integral Non-Linearity Offset Error <sup>(1)</sup> Offset Drift <sup>(1)</sup> Gain Error Gain Error Drift <sup>(1)</sup> Common-Mode Rejection	End Point Fit Before Calibration After Calibration at DC	24	15 0.04 0.010 1.0	24 ±0.0015	Bits Bits % of FS ppm of FS ppm of FS/°C % ppm/°C dB	
Normal-Mode Rejection Output Noise Power-Supply Rejection	Mode Rejection		130 120 120 120 100 100 see Typical Characterist 75 90		dB dB dB dB dB	
VOLTAGE REFERENCE INPUT Reference Input Range V <sub>REF</sub> Common-Mode Rejection Common-Mode Rejection Bias Current <sup>(3)</sup>	$\begin{array}{l} \text{REF IN+, REF IN-} \\ \text{V}_{\text{REF}} = (\text{REF IN+}) - (\text{REF IN-}) \\ & \text{at DC} \\ \text{f}_{\text{VREFCM}} = 60\text{Hz}, \text{f}_{\text{DATA}} = 60\text{Hz} \\ & \text{V}_{\text{REF}} = 1.25\text{V} \end{array}$	0 0.1	120 120 0.65	AV <sub>DD</sub> 1.25	V V dB dB μA	
ON-CHIP VOLTAGE REFERENCE Output Voltage Short-Circuit Current Source Short-Circuit Current Sink Short-Circuit Duration Drift Noise Output Impedance Startup Time	REF HI = 0 at 25°C Sink or Source BW = 0.1Hz to 100Hz Sourcing 100μA	1.245	1.25 3 50 Indefinite 5 10 3 50	1.255	V mA μA ppm/°C μVp-p Ω μs	
IDAC Full-Scale Output Current Maximum Short-Circuit Current Duration	$R_{DAC} = 75k\Omega, \text{ Range} = 1$ $R_{DAC} = 75k\Omega, \text{ Range} = 2$ $R_{DAC} = 75k\Omega, \text{ Range} = 3$ $R_{DAC} = 15k\Omega, \text{ Range} = 3$ $R_{DAC} = 10k\Omega$ $R_{DAC} = 0\Omega$ $R_{DAC} = 0\Omega$	٥	0.5 1 2 20 Indefinite	10	mA mA mA Minute Bite	
Monotonicity Compliance Voltage Output Impedance PSRR Absolute Error Absolute Drift Mismatch Error Mismatch Drift	R <sub>DAC</sub> = 75kΩ V <sub>OUT</sub> = AV <sub>DD</sub> /2 Individual IDAC Individual IDAC Between IDACs, Same Range and Code Between IDACs, Same Range and Code	8 0 see	Typical Characteri 600 5 75 0.25 15	AV <sub>DD</sub> – 1 stics	Bits V ppm/V % ppm/°C % ppm/°C	





# ELECTRICAL CHARACTERISTICS: AV<sub>DD</sub> = 3V (Cont.)

All specifications  $T_{MIN}$  to  $T_{MAX}$ ,  $AV_{DD} = +3V$ ,  $DV_{DD} = +2.7V$  to 5.25V,  $f_{MOD} = 19.2$ kHz,  $f_{OSC} = 2.4576$ MHz, PGA = 1, Buffer ON,  $R_{DAC} = 75$ k $\Omega$ ,  $f_{DATA} = 10$ Hz,  $V_{REF} \equiv (REF IN+) - (REF IN-) = +1.25V$  unless otherwise specified.

		ADS1218			
PARAMETER	CONDITIONS	MIN	ТҮР	МАХ	UNITS
POWER-SUPPLY REQUIREMENTS					
Power-Supply Voltage	-Supply Voltage AV <sub>DD</sub>			3.3	V
Analog Current (I <sub>ADC</sub> + I <sub>VREF</sub> + I <sub>DAC</sub> )	$\overline{PDWN} = 0$ , or SLEEP		1		nA
ADC Current (I <sub>ADC</sub> )	PGA = 1, Buffer OFF		160	250	μΑ
	PGA = 128, Buffer OFF		450	700	μΑ
	PGA = 1, Buffer ON		230	325	μΑ
	PGA = 128, Buffer ON		850	1325	μΑ
V <sub>REF</sub> Current (I <sub>VREF</sub> )			250	375	μΑ
I <sub>DAC</sub> Current (I <sub>DAC</sub> )	Excludes Load Current		480	675	μΑ
Digital Current	Normal Mode, DV <sub>DD</sub> = 3V		90	200	μΑ
	SLEEP Mode, $DV_{DD} = 3V$		75		μA
	Read Data Continuous Mode, DV <sub>DD</sub> = 3V		113		μΑ
	$\overline{PDWN} = 0$		1		nA
Power Dissipation	PGA = 1, Buffer OFF, REFEN = 0,		0.8	1.4	mW
	$I_{DACS}$ OFF, $DV_{DD} = 3V$				
TEMPERATURE RANGE					
Operating		-40		+85	°C
Storage		-60		+100	°C

NOTES: (1) Calibration can minimize these errors. (2)  $\Delta$  V<sub>OUT</sub> is change in digital result. (3) 12pF switched capacitor at  $f_{SAMP}$  clock frequency.

#### DIGITAL CHARACTERISTICS: $T_{MIN}$ to $T_{MAX}$ , $DV_{DD} = 2.7V$ to 5.25V

PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
Digital Input/Output					
Logic Family			CMOS		
Logic Level: V <sub>IH</sub>		0.8 • DV <sub>DD</sub>		DV <sub>DD</sub>	V
V <sub>IL</sub>		DGND		0.2 • DV <sub>DD</sub>	V
V <sub>OH</sub>	I <sub>OH</sub> = 1mA	DV <sub>DD</sub> - 0.4			V
V <sub>OL</sub>	$I_{OL} = 1mA$	DGND		DGND + 0.4	V
Input Leakage: I <sub>IH</sub>	$V_{I} = DV_{DD}$			10	μA
IIL	$V_1 = 0$	-10			μA
Master Clock Rate: f <sub>OSC</sub> <sup>(1)</sup>		1		5	MHz
Master Clock Period: tosc(1)	1/f <sub>OSC</sub>	200		1000	ns

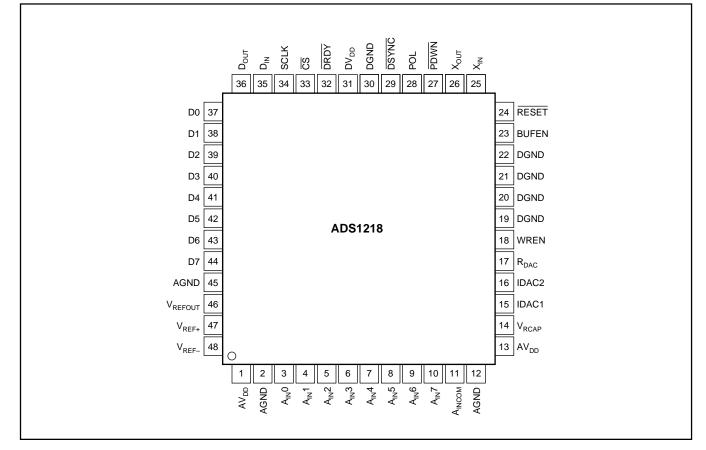
NOTE: (1) For FLASH E/W operations, the SPEED bit in the SETUP register must be set appropriately and the device operating frequency must be:  $2.3MHz < F_{OSC} < 4.13MHz$ .

### FLASH CHARACTERISTICS: $T_{MIN}$ to $T_{MAX}$ , $DV_{DD}$ = 2.7V to 5.25V, unless otherwise specified.

PARAMETER	CONDITIONS	MIN	ТҮР	MAX	UNITS
Operating Current					
Page Write	$DV_{DD} = 5V$ , During WR2F Command		6.5		mA
-	DV <sub>DD</sub> = 3V, During WR2F Command		3.75		mA
Page Read	DV <sub>DD</sub> = 5V, During RF2R Command		4.0		mA
	DV <sub>DD</sub> = 3V, During RF2R Command		1.2		mA
Endurance			100,000		E/W Cycles
Data Retention	at 25°C	100			Years
DV <sub>DD</sub> for Erase/Write		2.7		5.25	V



## **PIN CONFIGURATION (TQFP-48)**



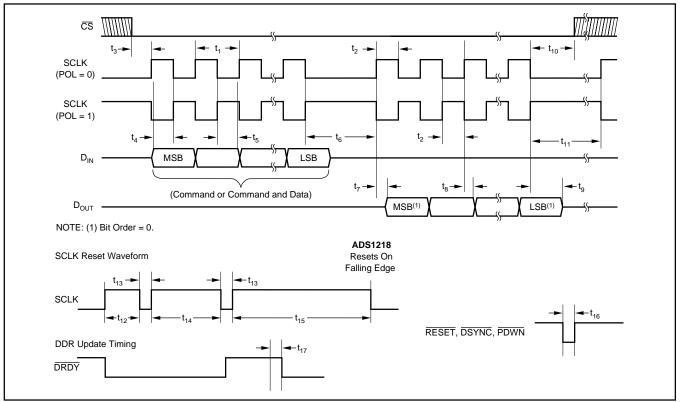
#### **PIN DESCRIPTIONS**

PIN NUMBER	NAME	DESCRIPTION	PIN NUMBER	NAME	DESCRIPTION
1	AV <sub>DD</sub>	Analog Power Supply	24	RESET	Active LOW, resets the entire chip.
2	AGND	Analog Ground	25	X <sub>IN</sub>	Clock Input
3	A <sub>IN</sub> 0	Analog Input 0	26	X <sub>OUT</sub>	Clock Output, used with crystal or resonator.
4	A <sub>IN</sub> 1	Analog Input 1	27	PDWN	Active LOW. Power Down. The power down
5	A <sub>IN</sub> 2	Analog Input 2			function shuts down the analog and digital
6	A <sub>IN</sub> 3	Analog Input 3			circuits.
7	A <sub>IN</sub> 4	Analog Input 4	28	POL	Serial Clock Polarity
8	A <sub>IN</sub> 5	Analog Input 5	29	DSYNC	Active LOW, Synchronization Control
9	A <sub>IN</sub> 6	Analog Input 6	30	DGND	Digital Ground
10	A <sub>IN</sub> 7	Analog Input 7	31	DV <sub>DD</sub>	Digital Power Supply
10	A <sub>INCOM</sub>	Analog Input Common	32	DRDY	Active LOW, Data Ready
12		Analog Ground	33	CS	Active LOW, Chip Select
12	AGND AV <sub>DD</sub>	Analog Power Supply	34	SCLK	Serial Clock, Schmitt Trigger
14		V <sub>RFF</sub> Bypass CAP	35	D <sub>IN</sub>	Serial Data Input, Schmitt Trigger
15	V <sub>RCAP</sub> IDAC1	Current DAC1 Output	36	D <sub>OUT</sub>	Serial Data Output
-	-		37-44	D0-D7	Digital I/O 0-7
16	IDAC2	Current DAC2 Output	45	AGND	Analog Ground
17	R <sub>DAC</sub>	Current DAC Resistor	46	V <sub>REFOUT</sub>	Voltage Reference Output
18	WREN	Active High, FLASH Write Enable	47	V <sub>REF+</sub>	Positive Differential Reference Input
19-22	DGND	Digital Ground	48		Negative Differential Reference Input
23	BUFEN	Buffer Enable	40	V <sub>REF-</sub>	





## TIMING SPECIFICATIONS



### TIMING SPECIFICATION TABLES

SPEC	DESCRIPTION	MIN	МАХ	UNITS
t <sub>1</sub>	SCLK Period	4		t <sub>osc</sub> Periods
			3	DRDY Periods
t <sub>2</sub>	SCLK Pulse Width, HIGH and LOW	200		ns
t <sub>3</sub>	CS LOW to first SCLK Edge; Setup Time	0		ns
t <sub>4</sub>	D <sub>IN</sub> Valid to SCLK Edge; Setup Time	50		ns
t <sub>5</sub>	Valid D <sub>IN</sub> to SCLK Edge; Hold Time	50		ns
t <sub>6</sub>	Delay between last SCLK edge for D <sub>IN</sub> and first SCLK			
	edge for D <sub>OUT</sub> : RDATA, RDATAC, RREG, WREG, RRAM, WRAM	50		t Doriodo
		200		t <sub>OSC</sub> Periods
	CSREG, CSRAMX, CSRAM CHKARAM, CHKARAMX	1100		t <sub>OSC</sub> Periods
<b>t</b> (1)		1100	50	t <sub>OSC</sub> Periods
$t_7^{(1)}$	SCLK Edge to Valid New D <sub>OUT</sub>		50	ns
t <sub>8</sub> <sup>(1)</sup>	SCLK Edge to D <sub>OUT</sub> , Hold Time	0	10	ns t Dariada
t <sub>9</sub>	Last SCLK Edge to D <sub>OUT</sub> Tri-State	6	10	t <sub>OSC</sub> Periods
	NOTE: D <sub>OUT</sub> goes tri-state immediately when CS goes HIGH. CS LOW time after final SCLK edge	0		
t <sub>10</sub>	Final SCLK edge of one op code until first edge SCLK	0		ns
t <sub>11</sub>	of next command:			
	RREG, WREG, RRAM, WRAM, CSRAMX, CSARAMX,			
	CSRAM, CSARAM, CSREG, SLEEP,			
	RDATA, RDATAC, STOPC	4		t <sub>OSC</sub> Periods
	DSYNC, RESET	16		t <sub>OSC</sub> Periods
	CSFL	33,000		t <sub>OSC</sub> Periods
	CREG, CRAM	220		t <sub>OSC</sub> Periods
	RF2R	1090		t <sub>OSC</sub> Periods
	CREGA	1600		t <sub>OSC</sub> Periods
	WR2F	76,850 (SPEED = 0)		t <sub>OSC</sub> Periods
		101,050 (SPEED = 1)	4	t <sub>osc</sub> Periods
	SELFGCAL, SELFOCAL, SYSOCAL, SYSGCAL	7	'	DRDY Periods
	SELFCAL	14		DRDY Periods
	RESET (Command, SCLK, or Pin)	16		t <sub>OSC</sub> Periods
t <sub>12</sub>	SCLK Reset, First HIGH Pulse	300	500	t <sub>OSC</sub> Periods
t <sub>12</sub>	SCLK Reset, LOW Pulse	5		t <sub>OSC</sub> Periods
t <sub>13</sub>	SCLK Reset, Second HIGH Pulse	550	750	t <sub>OSC</sub> Periods
t <sub>15</sub>	SCLK Reset, Third HIGH Pulse	1050	1250	t <sub>OSC</sub> Periods
t <sub>16</sub>	Pulse Width	4		t <sub>OSC</sub> Periods
t <sub>17</sub>	DOR Data Not Valid	4		t <sub>OSC</sub> Periods

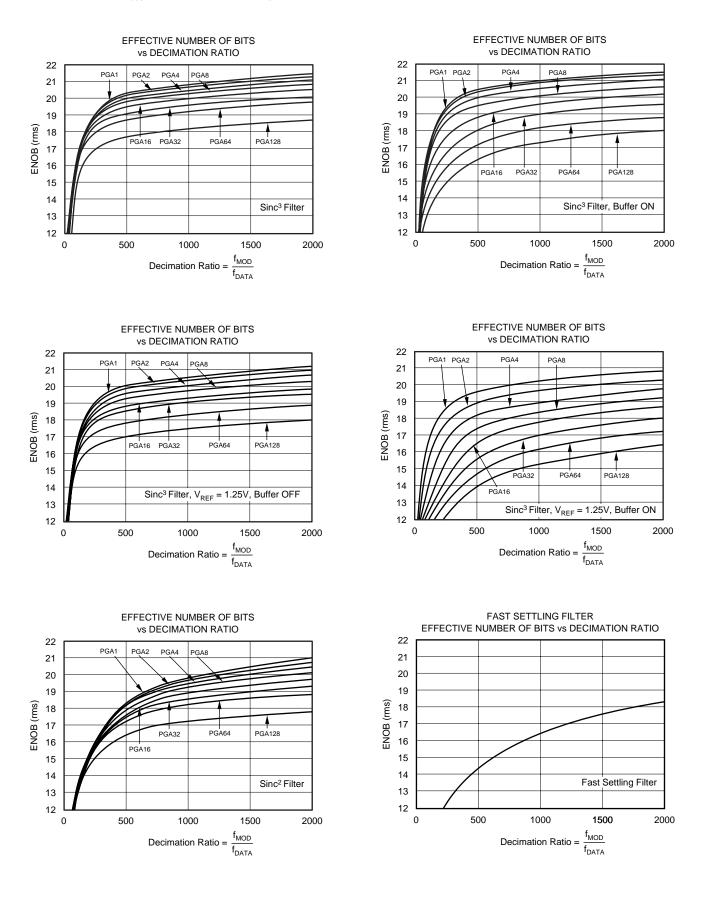
NOTE: (1) Load =  $20pF || 10k\Omega$  to DGND.





# **TYPICAL CHARACTERISTICS**

 $AV_{DD} = +5V, DV_{DD} = +5V, f_{OSC} = 2.4576MHz, PGA = 1, R_{DAC} = 150k\Omega, f_{DATA} = 10Hz, V_{REF} \equiv (REF IN+) - (REF IN-) = +2.5V, unless otherwise specified.$ 



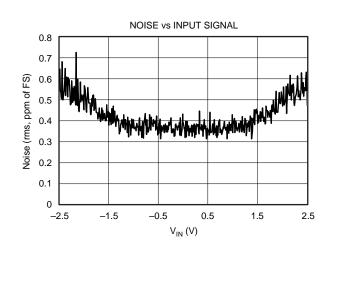
Texas

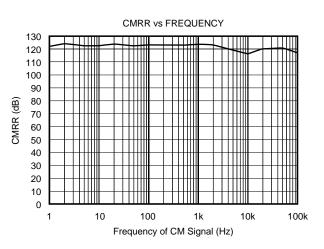
**ISTRUMENTS** 

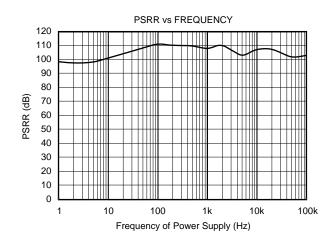


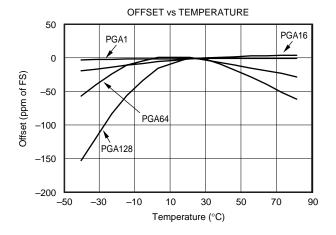
# **TYPICAL CHARACTERISTICS (Cont.)**

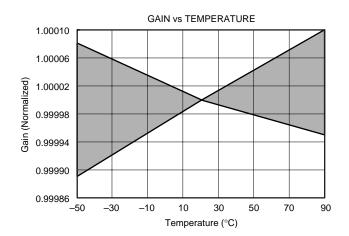
 $AV_{DD} = +5V, DV_{DD} = +5V, f_{OSC} = 2.4576MHz, PGA = 1, R_{DAC} = 150k\Omega, f_{DATA} = 10Hz, V_{REF} = (REF IN+) - (REF IN-) = +2.5V, unless otherwise specified.$ 

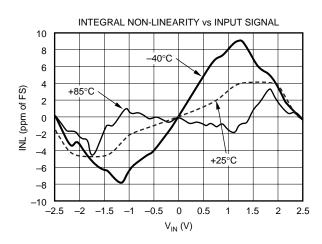










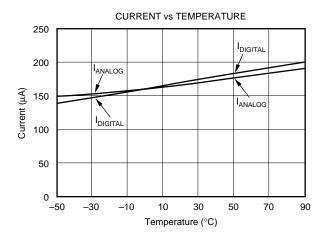


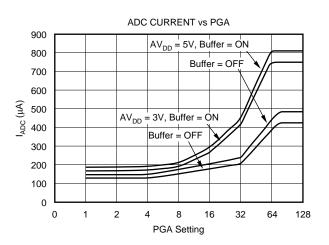


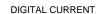


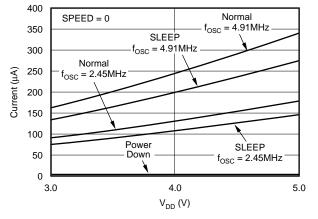
# **TYPICAL CHARACTERISTICS (Cont.)**

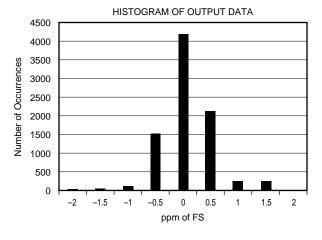
 $AV_{DD} = +5V, DV_{DD} = +5V, f_{OSC} = 2.4576MHz, PGA = 1, R_{DAC} = 150k\Omega, f_{DATA} = 10Hz, V_{REF} \equiv (REF IN+) - (REF IN-) = +2.5V, unless otherwise specified.$ 

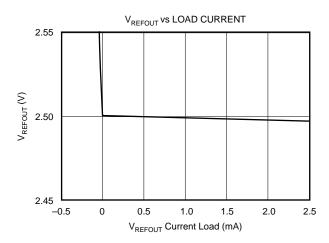


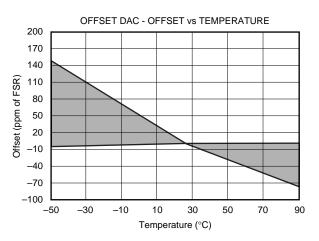










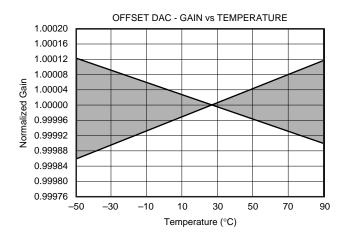


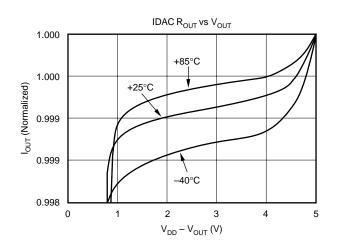


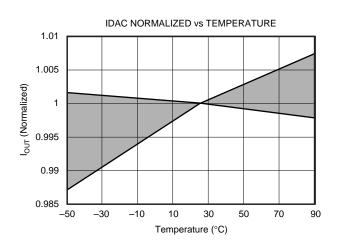


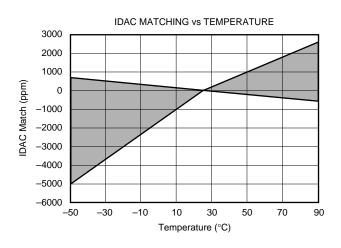
# **TYPICAL CHARACTERISTICS (Cont.)**

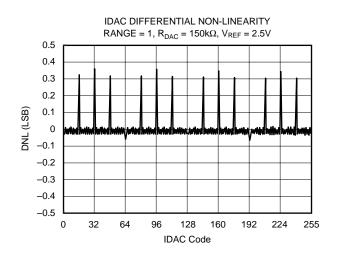
 $AV_{DD} = +5V, DV_{DD} = +5V, f_{OSC} = 2.4576MHz, PGA = 1, R_{DAC} = 150k\Omega, f_{DATA} = 10Hz, V_{REF} \equiv (REF IN+) - (REF IN-) = +2.5V, unless otherwise specified.$ 











IDAC INTEGRAL NON-LINEARITY  $\mathsf{RANGE} = \mathsf{1}, \, \mathsf{R}_{\mathsf{DAC}} = \mathsf{150k}\Omega, \, \mathsf{V}_{\mathsf{REF}} = \mathsf{2.5V}$ 0.5 0.4 0.3 0.2 INL (LSB) 0.1 0 -0.1 -0.2 -0.3 -0.4 -0.5 32 0 64 96 128 160 192 224 255 IDAC Code





# **OVERVIEW**

# INPUT MULTIPLEXER

The input multiplexer provides for any combination of differential inputs to be selected on any of the input channels, as shown in Figure 1. For example, if channel 1 is selected as the positive differential input channel, any other channel can be selected as the negative differential input channel. With this method, it is possible to have up to eight fully differential input channels.

In addition, current sources are supplied that will source or sink current to detect open or short circuits on the input pins.

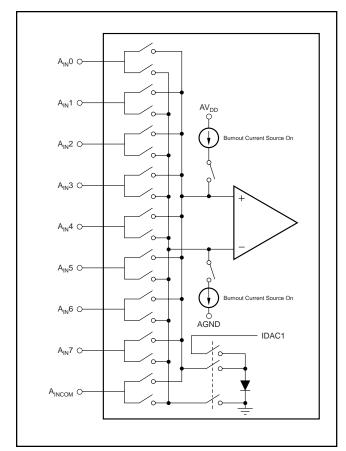


FIGURE 1. Input Multiplexer Configuration.

#### **TEMPERATURE SENSOR**

An on-chip diode provides temperature sensing capability. When the configuration register for the input MUX is set to all 1s, the diode is connected to the input of the A/D converter. All other channels are open. The anode of the diode is connected to the positive input of the A/D converter, and the cathode of the diode is connected to negative input of the A/D converter. The output of IDAC1 is connected to the anode to bias the diode and the cathode of the diode is also connected to ground to complete the circuit.

In this mode, the output of IDAC1 is also connected to the output pin, so some current may flow into an external load from IDAC1, rather than the diode.

## **BURNOUT CURRENT SOURCES**

When the Burnout bit is set in the ACR configuration register, two current sources are enabled. The current source on the positive input channel sources approximately  $2\mu$ A of current. The current source on the negative input channel sinks approximately  $2\mu$ A. This allows for the detection of an open circuit (full-scale reading) or short circuit (0V differential reading) on the selected input differential pair.

#### INPUT BUFFER

The input impedance of the ADS1218 without the buffer is  $5M\Omega/PGA$ . With the buffer enabled, the input voltage range is reduced and the analog power-supply current is higher. The buffer is controlled by ANDing the state of the BUFEN pin with the state of the BUFFER bit in the ACR register.

### **IDAC1 AND IDAC2**

The ADS1218 has two 8-bit current output DACs that can be controlled independently. The output current is set with  $R_{DAC}$ , the range select bits in the ACR register, and the 8-bit digital value in the IDAC register. The output current =  $V_{REF}/(8 \cdot R_{DAC})(2^{RANGE-1})(DAC CODE)$ . With  $V_{REFOUT}$  = 2.5V and  $R_{DAC}$  = 150k $\Omega$  to AGND the full-scale output can be selected to be 0.5, 1, or 2mA. The compliance voltage range is 0 to within 1V of AV<sub>DD</sub>. When the internal voltage reference of the ADS1218 is used, it is the reference for the IDAC. An external reference and tying the external reference input to the V<sub>REFOUT</sub> pin.

## PGA

The Programmable Gain Amplifier (PGA) can be set to gains of 1, 2, 4, 8, 16, 32, 64, or 128. Using the PGA can actually improve the effective resolution of the A/D converter. For instance, with a PGA of 1 on a 5V full-scale range, the A/D converter can resolve to 1 $\mu$ V. With a PGA of 128, on a 40mV full-scale range, the A/D converter can resolve to 75nV. With a PGA of 1 on a 5V full-scale range, it would require a 26-bit A/D converter to resolve 75nV.

# PGA OFFSET DAC

The input to the PGA can be shifted by half the full-scale input range of the PGA by using the ODAC register. The ODAC (Offset DAC) register is an 8-bit value; the MSB is the sign and the seven LSBs provide the magnitude of the offset. Using the ODAC register does not reduce the performance of the A/D converter.

# MODULATOR

The modulator is a single-loop second-order system. The modulator runs at a clock speed ( $f_{MOD}$ ) that is derived from the external clock ( $f_{OSC}$ ). The frequency division is determined by the SPEED bit in the SETUP register.

SPEED BIT	f <sub>MOD</sub>
0	f <sub>OSC</sub> /128
1	f <sub>OSC</sub> /256





#### CALIBRATION

The offset and gain errors in the ADS1218, or the complete system, can be reduced with calibration. Internal calibration of the ADS1218 is called self calibration. This is handled with three commands. One command does both offset and gain calibration. There is also a gain calibration command and an offset calibration command. Each calibration process takes seven  $t_{DATA}$  periods to complete. Therefore, it takes 14  $t_{DATA}$  periods to complete both an offset and gain calibration.

For system calibration, the appropriate signal must be applied to the inputs. The system offset command requires a "zero" differential input signal. It then computes an offset that will nullify offset in the system. The system gain command requires a positive "full-scale" differential input signal. It then computes a value to nullify gain errors in the system. Each of these calibrations will take seven  $t_{DATA}$  periods to complete.

Calibration should be performed after power on, a change in temperature, a change in decimation ratio, or a change in the PGA. Calibration will remove the offset in the ODAC register. Therefore, changes to the ODAC register must be done after calibration.

At the completion of calibration, the DRDY signal will go LOW to indicate that calibration is complete and valid data is available.

#### **DIGITAL FILTER**

The Digital Filter can use either the fast settling,  $sinc^2$ , or  $sinc^3$  filter, as shown in Figure 2. In addition, the Auto mode changes the sinc filter after the input channel or PGA is changed. When switching to a new channel, it will use the fast

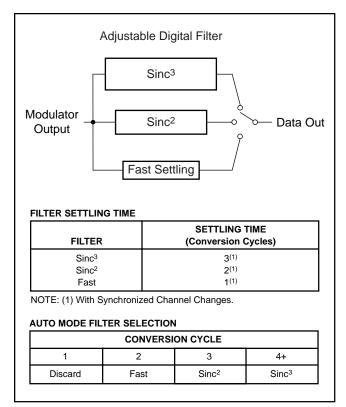


FIGURE 2. Filter Step Responses.

settling filter for the next two conversions, the first of which should be discarded. It will then use the sinc<sup>2</sup> followed by the sinc<sup>3</sup> filter to improve noise performance. This combines the low-noise advantage of the sinc<sup>3</sup> filter with the quick response of the fast settling time filter. The frequency response of each filter is shown in Figure 3.

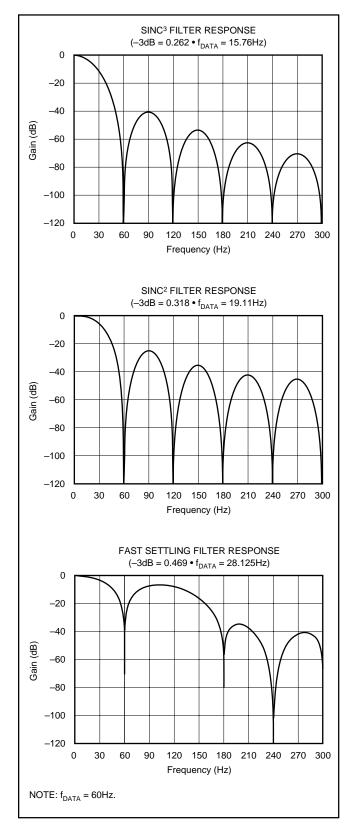


FIGURE 3. Filter Frequency Responses.





#### **VOLTAGE REFERENCE**

The voltage reference used for the ADS1218 can either be internal or external. The power-up configuration for the voltage reference is 2.5V internal. The selection for the voltage reference is made through the status configuration register.

The internal voltage reference is selectable as either 1.25V or 2.5V ( $AV_{DD} = 5V$  only). The  $V_{REFOUT}$  pin should have a 0.1µF capacitor to AGND.

The external voltage reference is differential and is represented by the voltage difference between the pins:  $+V_{REF}$  and  $-V_{REF}$ . The absolute voltage on either pin ( $+V_{REF}$  and  $-V_{REF}$ ) can range from AGND to  $AV_{DD}$ , however, the differential voltage must not exceed 2.5V. The differential voltage reference provides easy means of performing ratiometric measurement.

## V<sub>RCAP</sub> PIN

This pin provides a bypass cap for noise filtering on internal  $V_{REF}$  circuitry only. The recommended capacitor is a 0.001µF ceramic cap. If an external  $V_{REF}$  is used, this pin can be left unconnected.

### **CLOCK GENERATOR**

The clock source for the ADS1218 can be provided from a crystal, ceramic resonator, oscillator, or external clock. When the clock source is a crystal or ceramic resonator, external capacitors must be provided to ensure start-up and a stable clock frequency. This is shown in Figure 4 and Table I.

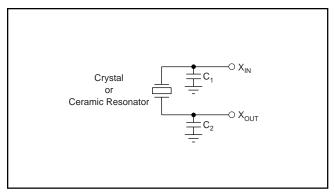


FIGURE 4. Crystal or Ceramic Resonator Connection.

CLOCK SOURCE	FREQUENCY	C <sub>1</sub>	C <sub>2</sub>	PART NUMBER
Crystal	2.4576	0-20pF	0-20pF	ECS, ECSD 2.45 - 32
Crystal	4.9152	0-20pF	0-20pF	ECS, ECSL 4.91
Crystal	4.9152	0-20pF	0-20pF	ECS, ECSD 4.91
Crystal	4.9152	0-20pF	0-20pF	CTS, MP 042 4M9182

TABLE I. Typical Clock Sources.

#### **DIGITAL I/O INTERFACE**

The ADS1218 has eight pins dedicated for digital I/O. The default power-up condition for the digital I/O pins are as inputs. All of the digital I/O pins are individually configurable as inputs or outputs. They are configured through the DIR control register. The DIR register defines whether the pin is an input or output, and the DIO register defines the state of the digital output. When the digital I/O are configured as inputs, DIO is used to read the state of the pin.

### SERIAL INTERFACE

The serial interface is standard four-wire SPI compatible ( $D_{IN}$ ,  $D_{OUT}$ , SCLK, and  $\overline{CS}$ ). The ADS1218 also offers the flexibility to select the polarity of the serial clock through the POL pin. The serial interface can be clocked up to  $f_{OSC}/4$ . If  $\overline{CS}$  goes HIGH, the serial interface is reset. When  $\overline{CS}$  goes LOW, a new command is expected.

The serial interface operates independently of  $\overline{\text{DRDY}}$ .  $\overline{\text{DRDY}}$  is used to indicate availability of data in the DOR. In order to ensure the validity of the data being read, DOR timing requirements must be met.

# **DSYNC** OPERATION

 $\overline{\text{DSYNC}}$  is used to provide for synchronization of the A/D conversion with an external event. Synchronization can be achieved either through the DSYNC pin or the  $\overline{\text{DSYNC}}$  command. When the  $\overline{\text{DSYNC}}$  pin is used, the filter counter is reset on the falling edge of  $\overline{\text{DSYNC}}$ . The modulator is held in reset until  $\overline{\text{DSYNC}}$  is taken HIGH. Synchronization occurs on the next rising edge of the system clock after  $\overline{\text{DSYNC}}$  is taken HIGH.

When the DSYNC command is sent, the filter counter is reset after the last SCLK on the DSYNC command. The modulator is held in RESET until the next edge of SCLK is detected. Synchronization occurs on the next rising edge of the system clock after the first SCLK after the DSYNC command.

## POWER-UP—SUPPLY VOLTAGE RAMP RATE

The power-on reset circuitry was designed to accommodate digital supply ramp rates as slow as 1V/10ms. To ensure proper operation, the power supply should ramp monotonically. The POR issues the RESET command as described below.

## RESET

There are three methods of reset. The  $\overrightarrow{\text{RESET}}$  pin, the RESET command, and the SCLK Reset pattern. They all perform the same function. After a reset, the FLASH data values from Page 0 are loaded into RAM, subsequently data values from Bank 0 of RAM are loaded into the configuration registers.





#### MEMORY

Three types of memory are used on the ADS1218: registers, RAM, and FLASH. 16 registers directly control the various functions (PGA, DAC value, Decimation Ratio, etc.) and can be directly read or written to. Collectively, the registers contain all the information needed to configure the part, such as data format, mux settings, calibration settings, decimation ratio, etc. Additional registers, such as conversion data, are accessed through dedicated instructions.

The on-chip FLASH can be used to store non-volatile data. The FLASH data is separate from the configuration registers and therefore can be used for any purpose, in addition to device configuration. The FLASH page data is read and written in 128 byte blocks through the RAM banks, i.e. all RAM banks map to a single page of FLASH, as shown in Figure 5.

#### **REGISTER BANK TOPOLOGY**

The operation of the device is set up through individual registers. The set of the 16 registers required to configure the device is referred to as a Register Bank, as shown in Figure 5.

#### RAM

Reads and Writes to Registers and RAM occur on a byte basis. However, copies between registers and RAM occurs on a bank basis. The RAM is independent of the Registers, i.e.: the RAM can be used as general-purpose RAM.

The ADS1218 supports any combination of eight analog inputs. With this flexibility, the device could easily support eight unique configurations—one per input channel. In order to facilitate this type of usage, eight separate register banks are available. Therefore, each configuration could be written once and recalled as needed without having to serially retransmit all the configuration data. Checksum commands are also included, which can be used to verify the integrity of RAM.

The RAM provides eight "banks", with a bank consisting of 16 bytes. The total size of the RAM is 128 bytes. Copies between the registers and RAM are performed on a bank basis. Also, the RAM can be directly read or written through the serial interface on power-up. The banks allow separate storage of settings for each input.

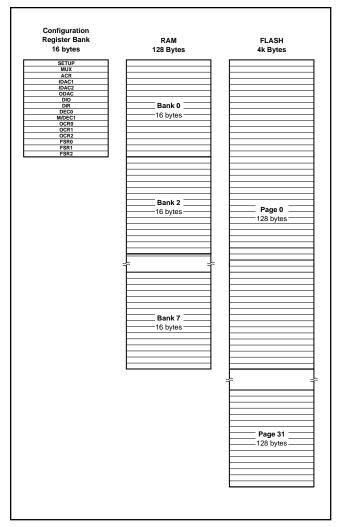


FIGURE 5. Memory Organization.

ADDRESS	REGISTER	BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
00 <sub>H</sub>	SETUP	ID	ID	ID	SPEED	REF EN	REF HI	BUF EN	BIT ORDER
01 <sub>H</sub>	MUX	PSEL3	PSEL2	PSEL1	PSEL0	NSEL3	NSEL2	NSEL1	NSEL0
02 <sub>H</sub>	ACR	BOCS	IDAC2R1	IDAC2R0	IDAC1R1	IDAC1R0	PGA2	PGA1	PGA0
03 <sub>H</sub>	IDAC1	IDAC1_7	IDAC1_6	IDAC1_5	IDAC1_4	IDAC1_3	IDAC1_2	IDAC1_1	IDAC1_0
04 <sub>H</sub>	IDAC2	IDAC2_7	IDAC2_6	IDAC2_5	IDAC2_4	IDAC2_3	IDAC2_2	IDAC2_1	IDAC2_0
05 <sub>H</sub>	ODAC	SIGN	OSET_6	OSET_5	OSET_4	OSET_3	OSET_2	OSET_1	OSET_0
06 <sub>H</sub>	DIO	DIO_7	DIO_6	DIO_5	DIO_4	DIO_3	DIO_2	DIO_1	DIO_0
07 <sub>H</sub>	DIR	DIR_7	DIR_6	DIR_5	DIR_4	DIR_3	DIR_2	DIR_1	DIR_0
08 <sub>H</sub>	DEC0	DEC07	DEC06	DEC05	DEC04	DEC03	DEC02	DEC01	DEC00
09 <sub>H</sub>	M/DEC1	DRDY	U/B	SMODE1	SMODE0	WREN	DEC10	DEC09	DEC08
0A <sub>H</sub>	OCR0	OCR07	OCR06	OCR05	OCR04	OCR03	OCR02	OCR01	OCR00
0B <sub>H</sub>	OCR1	OCR15	OCR14	OCR13	OCR12	OCR11	OCR10	OCR09	OCR08
0C <sub>H</sub>	OCR2	OCR23	OCR22	OCR21	OCR20	OCR19	OCR18	OCR17	OCR16
0D <sub>H</sub>	FSR0	FSR07	FSR06	FSR05	FSR04	FSR03	FSR02	FSR01	FSR00
0E <sub>H</sub>	FSR1	FSR15	FSR14	FSR13	FSR12	FSR11	FSR10	FSR09	FSR08
0F <sub>H</sub>	FSR2	FSR23	FSR22	FSR21	FSR20	FSR19	FSR18	FSR17	FSR16

TABLE II. Registers.



The RAM address space is linear, therefore accessing RAM is done using an auto-incrementing pointer. Access to RAM in the entire memory map can be done consecutively without having to address each bank individually. For example, if you were currently accessing bank 0 at offset 0xF (the last location of bank 0), the next access would be bank 1 and offset 0x0. Any access after bank 7 and offset 0xF will wrap around to bank 0 and Offset 0x0.

Although the Register Bank memory is linear, the concept of addressing the device can also be thought of in terms of bank and offset addressing. Looking at linear and bank addressing syntax, we have the following comparison: in the linear memory map, the address 0x14 is equivalent to bank 1 and offset 0x4. Simply stated, the most significant four bits represent the bank, and the least significant four bits represent the offset. The offset is equivalent to the register address for that bank of memory.

#### FLASH

Reads and Writes to FLASH occur on a Page basis. Therefore, the entire contents of RAM is used for both Read and Write operations. The FLASH is independent of the Registers, i.e., the FLASH can be used as generalpurpose FLASH.

Upon power-up or reset, the contents of FLASH Page 0 are loaded into RAM subsequently the contents of RAM Bank 0 are loaded into the configuration register. Therefore, the user can customize the power-up configuration for the device. Care should be taken to ensure that data for FLASH Page 0 is written correctly, in order to prevent unexpected operation upon power-up. The ADS1218 supports any combination of eight analog inputs and the FLASH memory supports up to 32 unique Page configurations. With this flexibility, the device could support 32 unique configurations for each of the eight analog input channels. For instance, the on-chip temperature sensor could be used to monitor temperature then different calibration coefficients could be recalled for each of the eight analog input channels based on the change in temperature. This would enable the user to recall calibration coefficients for every 4°C change in temperature over the industrial temperature range which could be used to correct for drift errors. Checksum commands are also included, which can be used to verify the integrity of FLASH.

The following two commands can be used to manipulate the FLASH. First, the contents of FLASH can be written to with the WR2F (write RAM to FLASH) command. This command first erases the designated FLASH page and then writes the entire content of RAM (all banks) into the designated FLASH page. Second, the contents of FLASH can be read with the RF2R (read FLASH to RAM) command. This command reads the designated FLASH page into the entire contents of RAM (all banks). In order to ensure maximum endurance and data retention, the SPEED bit in the SETUP register must be set for the appropriate  $f_{OSC}$  frequency.

Writing to or erasing FLASH can be disabled either through the WREN pin or the WREN register bit. If the WREN pin is LOW OR the WREN bit is cleared, then the WR2F command has no effect. This protects the integrity of the FLASH data from being inadvertently corrupted.

Accessing the FLASH data either through read, write, or erase may effect the accuracy of the conversion result. Therefore, the conversion result should be discarded when accesses to FLASH are done.



#### DETAILED REGISTER DEFINITIONS

**SETUP** (Address 00<sub>H</sub>) Setup Register

Reset Value = iii01110

_	bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
	ID	ID	ID	SPEED	REF EN	REF HI	BUF EN	BIT ORDER

- bit 7-5 Factory Programmed Bits
- bit 4 SPEED: FLASH Access Clock Speed  $0: 2.30MHz > f_{OSC} > 3.12MHz \text{ (default)} \\ 1: 3.12MHz > f_{OSC} > 4.13MHz$
- bit 3 REF EN: Internal Voltage Reference Enable 0 = Internal Voltage Reference Disabled 1 = Internal Voltage Reference Enabled (default)
- bit 2 REF HI: Internal Reference Voltage Select 0 = Internal Reference Voltage = 1.25V 1 = Internal Reference Voltage = 2.5V (default)
  - BUF EN: Buffer Enable 0 = Buffer Disabled

bit 1

- 1 = Buffer Enabled (default)
- bit 0 BIT ORDER: Set Order Bits are Transmitted 0 = Most Significant Bit Transmitted First (default) 1 = Least Significant Bit Transmitted First Data is always shifted into the part most significant bit first. Data is always shifted out of the part most significant byte first. This configuration bit only controls the bit order within the byte of data that is shifted out.

**MUX** (Address  $01_{\rm H}$ ) Multiplexer Control Register Reset Value =  $01_{\rm H}$ 

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
PSEL3	PSEL2	PSEL1	PSEL0	NSEL3	NSEL2	NSEL1	NSEL0

- bit 7-4 PSEL3: PSEL2: PSEL1: PSEL0: Positive Channel Select 0000 = AIN0 (default) 0001 = AIN10010 = AIN20011 = AIN30100 = AIN40101 = AIN50110 = AIN60111 = AIN71xxx = AINCOM (except when all bits are 1's) 1111 = Temperature Sensor Diode Anode bit 3-0 NSEL3: NSEL2: NSEL1: NSEL0: Negative Channel Select 0000 = AIN00001 = AIN1 (default)
  - 0001 = AIN10010 = AIN2
  - 0011 = AIN3
  - 0100 = AIN4
  - 0101 = AIN5
  - 0110 = AIN6
  - 0111 = AIN7

1xxx = AINCOM (except when all bits are 1's)

1111 = Temperature Sensor Diode Cathode Analog GND

## ACR (Address $02_{\rm H}$ ) Analog Control Register

Reset Value =  $00_{\rm H}$ 

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
BOCS	IDAC2R1	IDAC2R0	IDAC1R1	IDAC1R0	PGA2	PGA1	PGA0

- bit 7 BOCS: Burnout Current Source
  - 0 = Disabled (default)

1 = Enabled

IDAC Current = 
$$\left(\frac{V_{REF}}{8 \bullet R_{DAC}}\right) (2^{RANGE-1}) (DAC Code)$$

# bit 6-5 IDAC2R1: IDAC2R0: Full-Scale Range Select for IDAC2

- 00 = Off (default)
- 01 = Range 1
- 10 = Range 2
- 11 = Range 3
- bit 4-3 IDAC1R1: IDAC1R0: Full-Scale Range Select for IDAC1
  - 00 = Off (default)
  - 01 = Range 1
  - 10 = Range 2
  - 11 = Range 3

bit 2-0 PGA2: PGA1: PGA0: Programmable Gain Amplifier

> Gain Selection 000 = 1 (default)

000	=	I	(dera
001		0	

- 001 = 2010 = 4
- 010 4
- 011 = 8100 = 16
- 100 = 16101 = 32
- 101 = 52110 = 64
- 110 = 04111 = 128

## IDAC1 (Address 03<sub>H</sub>) Current DAC 1

Reset Value =  $00_{\rm H}$ 

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
IDAC1_7	IDAC1_6	IDAC1_5	IDAC1_4	IDAC1_3	IDAC1_2	IDAC1_1	IDAC1_0

The DAC code bits set the output of DAC1 from 0 to fullscale. The value of the full-scale current is set by this Byte,  $V_{REF}$ ,  $R_{DAC}$ , and the DAC1 range bits in the ACR register.

## IDAC2 (Address 04<sub>H</sub>) Current DAC 2

Reset Value =  $00_{\rm H}$ 

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
IDAC2_7	IDAC2_6	IDAC2_5	IDAC2_4	IDAC1_3	IDAC1_2	IDAC1_1	IDAC1_0

The DAC code bits set the output of DAC2 from 0 to fullscale. The value of the full-scale current is set by this Byte,  $V_{REF}$ ,  $R_{DAC}$ , and the DAC2 range bits in the ACR register.



ADS1218

**ODAC** (Address  $05_{\rm H}$ ) Offset DAC Setting Reset Value =  $00_{\rm H}$ 

	bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
	SIGN	OSET6	OSET5	OSET4	OSET3	OSET2	OSET1	OSET0
1	bit 7	Offset $0 = Pc$	t Sign ositive					

1 = Negative

bit 6-0 Offset =  $\frac{V_{REF}}{2 \bullet PGA} \bullet \left(\frac{Code}{127}\right)$ 

NOTE: Calibration will cancel the value in the ODAC register. Therefore, writing to the ODAC register should be done after calibration.

DIO (A	O (Address $06_{\rm H}$ ) Digital I/OReset Value = $00_{\rm H}$ 7bit 6bit 5bit 4bit 3bit 2bit 1bit 007DI06DI05DI04DI03DI02DI01DI00						
bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
DIO7	DIO6	DIO5	DIO4	DIO3	DIO2	DIO1	DIO0

A value written to this register will appear on the digital I/O pins if the pin is configured as an output in the DIR register. Reading this register will return the value of the digital I/O pins.

#### **DIR** (Address $07_{\rm H}$ ) Direction control for digital I/O Reset Value = FF<sub>H</sub>

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
DIR7	DIR6	DIR5	DIR4	DIR3	DIR2	DIR1	DIR0

Each bit controls whether the Digital I/O pin is an output (= 0) or input (= 1). The default power-up state is as inputs.

#### **DEC0** (Address 08<sub>H</sub>) Decimation Register

(Least Significant 8 bits)

Reset Value =  $80_{\rm H}$ 

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
DEC07	DEC06	DEC05	DEC04	DEC03	DEC02	DEC01	DEC00

The decimation value is defined with 11 bits for a range of 20 to 2047. This register is the least significant 8 bits. The 3 most significant bits are contained in the M/DEC1 register. The default data rate is 10Hz with a 2.4576MHz crystal.

**M/DEC1** (Address  $09_{\rm H}$ ) Mode and Decimation Register Reset Value =  $07_{\rm H}$ 

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
DRDY	U/B	SMODE1	SMODE0	WREN	DEC10	DEC09	DEC08

bit 7 DRDY: Data Ready (Read Only) This bit duplicates the state of the DRDY pin.

## bit 6 $U/\overline{B}$ : Data Format

0 = Bipolar (default)

1 = Unipolar

U/B	ANALOG INPUT	DIGITAL OUTPUT		
	+FSR	0x7FFFFF		
0	Zero	0x000000		
	–FSR	0x800000		
	+FSR	0xFFFFFF		
1	Zero	0x000000		
	–FSR	0x000000		

# bit 5-4 SMODE1: SMODE0: Settling Mode

- 00 = Auto (default)
- 01 = Fast Settling filter
- $10 = \text{Sinc}^2$  filter
- $11 = \text{Sinc}^3$  Flash filter
- bit 3 WREN: Write Enable
  - 0 = Flash Writing Disabled (default)
  - 1 = Flash Writing Enabled

This bit is AND'd with the WREN pin to enable or disable Flash Writing and Erasing

bit 2-0 DEC10: DEC09: DEC08: Most Significant Bits of the Decimation Value

**OCR0** (Address  $0A_H$ ) Offset Calibration Coefficient (Least Significant Byte)

Reset Value =  $00_{\rm H}$ 

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
OCR07	OCR06	OCR05	OCR04	OCR03	OCR02	OCR01	OCR00

# **OCR1** (Address $0B_H$ ) Offset Calibration Coefficient (Middle Byte)

Reset Value =  $00_{\rm H}$ 

 bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
OCR15	OCR14	OCR13	OCR12	OCR11	OCR10	OCR09	OCR08

# **OCR2** (Address 0C<sub>H</sub>) Offset Calibration Coefficient (Most Significant Byte)

Reset Value =  $00_{\rm H}$ 

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
OCR23	OCR22	OCR21	OCR20	OCR19	OCR18	OCR17	OCR16

#### FSR0 (Address 0D<sub>H</sub>) Full-Scale Register

(Least Significant Byte)

Reset Value =  $24_{\rm H}$ 

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
FSR07	FSR06	FSR05	FSR04	FSR03	FSR02	FSR01	FSR00

#### FSR1 (Address 0E<sub>H</sub>) Full-Scale Register

(Middle Byte)

Reset Value =  $90_{\rm H}$ 

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
FSR15	FSR14	FSR13	FSR12	FSR011	FSR10	FSR09	FSR08

## FSR2 (Address 0F<sub>H</sub>) Full-Scale Register

(Most Significant Byte)

Reset Value =  $67_{\rm H}$ 

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
FSR23	FSR22	FSR21	FSR20	FSR019	FSR18	FSR17	FSR16



# **COMMAND DEFINITIONS**

The commands listed below control the operation of the ADS1218. Some of the commands are stand-alone commands (e.g., RESET) while others require additional bytes (e.g., WREG requires command, count, and the data bytes). Commands that output data require a minimum of four  $f_{OSC}$  cycles before the data is ready (e.g., RDATA).

Operands:

- n = count (0 to 127)
- r = register (0 to 15)
- x = don't care
- a = RAM bank address (0 to 7)
- f = FLASH page address (0 to 31)

COMMANDS	DESCRIPTION	COMMAND BYTE	2ND COMMAND BYTE
RDATA	Read Data	0000 0001 (01 <sub>H</sub> )	_
RDATAC	Read Data Continuously	0000 0011 (03 <sub>H</sub> )	—
STOPC	Stop Read Data Continuously	0000 1111 (0F <sub>H</sub> )	—
RREG	Read from REG Bank "rrrr"	0001 rrrr (1x <sub>H</sub> )	xxxx_nnnn (# of reg-1)
RRAM	Read from RAM Bank "aaa"	0010 0aaa (2x <sub>H</sub> )	xnnn_nnnn (# of bytes-1)
CREG	Copy REGs to RAM Bank "aaa"	0100 0aaa (4x <sub>H</sub> )	—
CREGA	Copy REGS to all RAM Banks	0100 1000 (48 <sub>H</sub> )	_
WREG	Write to REG "rrrr"	0101 rrrr (5x <sub>H</sub> )	xxxx_nnnn (# of reg-1)
WRAM	Write to RAM Bank "aaa"	0110 0aaa (6x <sub>H</sub> )	xnnn_nnnn (# of bytes-1)
RF2R	Read FLASH page to RAM	100 ffff(8,9x <sub>H</sub> )	—
WR2F	Write RAM to FLASH page	101fffff(A,Bx <sub>н</sub> )	_
CRAM	Copy RAM Bank "aaa" to REG	1100 0aaa (Cx <sub>H</sub> )	—
CSRAMX	Calc RAM Bank "aaa" Checksum	1101 0aaa (Dx <sub>H</sub> )	—
CSARAMX	Calc all RAM Bank Checksum	1101 1000 (D8 <sub>H</sub> )	_
CSREG	Calc REG Checksum	1101 1111 (DF <sub>H</sub> )	_
CSRAM	Calc RAM Bank "aaa" Checksum	1110 0aaa (Ex <sub>H</sub> )	_
CSARAM	Calc all RAM Banks Checksum	1110 1000 (E8 <sub>H</sub> )	_
CSFL	Calc FLASH Checksum	1110 1100 (EC <sub>H</sub> )	_
SELFCAL	Self Cal Offset and Gain	1111 0000 (F0 <sub>H</sub> )	—
SELFOCAL	Self Cal Offset	1111 0001 (F1 <sub>H</sub> )	—
SELFGCAL	Self Cal Gain	1111 0010 (F2 <sub>H</sub> )	_
SYSOCAL	Sys Cal Offset	1111 0011 (F3 <sub>H</sub> )	—
SYSGCAL	Sys Cal Gain	1111 0100 (F4 <sub>H</sub> )	—
DSYNC	Sync DRDY	1111 1100 (FC <sub>H</sub> )	—
SLEEP	Put in SLEEP Mode	1111 1101 (FD <sub>H</sub> )	—
RESET	Reset to Power-Up Values	1111 1110 (FE <sub>H</sub> )	—

NOTE: (1) The data received by the A/D is always MSB First, the data out format is set by the BIT ORDER bit in ACR reg.

TABLE III. Command Summary.

# **RDATA** Read Data

**Description:** Read a single data value from the Data Output Register (DOR) which is the most recent conversion result. This is a 24-bit value.

Operands:NoneBytes:1Encoding:0000 0001Data Transfer Sequence:



NOTE: (1) For wait time, refer to timing specification.

# **RDATAC** Read Data Continuous

**Description:** Read Data Continuous mode enables the continuous output of new data on each  $\overline{\text{DRDY}}$ . This command eliminates the need to send the Read Data Command on each  $\overline{\text{DRDY}}$ . This mode may be terminated by either the STOP Read Continuous command or the RESET command.

Operands: None

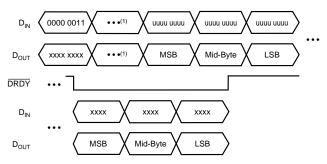
Bytes:

**Encoding:** 0000 0011

#### **Data Transfer Sequence:**

1

Command terminated when "uuuu uuuu" equals STOPC or RESET.

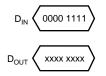


NOTE: (1) For wait time, refer to timing specification.



#### **STOPC** Stop Continuous

Description: Ends the continuous data output mode.Operands:NoneBytes:1Encoding:0000 1111Data Transfer Sequence:



## **RREG** Read from Registers

**Description:** Output the data from up to 16 registers starting with the register address specified as part of the instruction. The number of registers read will be one plus the second byte. If the count exceeds the remaining registers, the addresses will wrap back to the beginning.

Operands: r, n

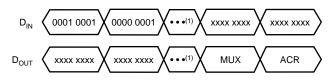
Bytes:

Encoding: 0001 rrrr xxxx nnnn

#### **Data Transfer Sequence:**

2

Read Two Registers Starting from Register 01<sub>H</sub> (MUX)



NOTE: (1) For wait time, refer to timing specification.

# RRAM Read from RAM

**Description:** Up to 128 bytes can be read from RAM starting at the bank specified in the op code. All reads start at the address for the beginning of the RAM bank. The number of bytes to read will be one plus the value of the second byte.

Operands: a, n

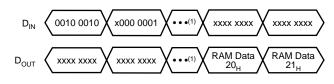
Bytes:

Encoding: 0010 0aaa xnnn nnnn

#### Data Transfer Sequence:

2

Read Two RAM Locations Starting from 20<sub>H</sub>



NOTE: (1) For wait time, refer to timing specification.

# CREG Copy Registers to RAM Bank

**Description:** Copy the 16 control registers to the RAM bank specified in the op code. Refer to timing specifications for command execution time.

Operands: a Bytes: 1

Encoding: 0100 0aaa

#### Data Transfer Sequence:

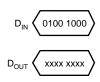
Copy Register Values to RAM Bank 3



## **CREGA** Copy Registers to All RAM Banks

**Description:** Duplicate the 16 control registers to all the RAM banks. Refer to timing specifications for command execution time.

Operands:NoneBytes:1Encoding:0100 1000Data Transfer Sequence:



#### WREG Write to Register

**Description:** Write to the registers starting with the register specified as part of the instruction. The number of registers that will be written is one plus the value of the second byte.

Operands:r, nBytes:2Encoding:0101 rrrr xxxx nnnn

#### **Data Transfer Sequence:**

Write Two Registers Starting from 06<sub>H</sub> (DIO)





**Description:** Write up to 128 RAM locations starting at the beginning of the RAM bank specified as part of the instruction. The number of bytes written is RAM is one plus the value of the second byte.

**Operands:** a, n

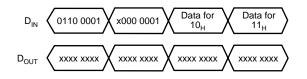
Bytes:

Encoding: 0110 0aaa xnnn nnnn

2

**Data Transfer Sequence:** 

Write to Two RAM Locations starting from  $10_{\rm H}$ 



## **RF2R Read FLASH Page to RAM**

Description: Read the selected FLASH page to the RAM.

**Operands:** f

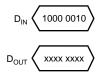
Bytes:

**Encoding:** 100f ffff

Data Transfer Sequence:

Read FLASH Page 2 to RAM

1



#### WR2F Write RAM to FLASH

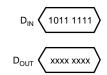
**Description:** Write the contents of RAM to the selected FLASH page.

**Operands:** f

Bytes: 1

**Encoding:** 101f ffff

**Data Transfer Sequence:** Write RAM to FLASH page 31



### **CRAM** Copy RAM Bank to Registers

**Description:** Copy the selected RAM Bank to the Configuration Registers. This will overwrite all of the registers with the data from the RAM bank.

Operands: a Bytes: 1 Encoding: 1100 0aaa Data Transfer Sequence: Copy RAM Bank 0 to the Registers



# CSRAMX Calculate RAM Bank Checksum

**Description:** Calculate the checksum of the selected RAM Bank. The checksum is calculated as a sum of all the bytes with the carry ignored. The ID, DRDY and DIO bits are masked so they are not included in the checksum.

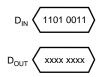
**Operands:** a

**Bytes:** 1

Encoding: 1101 Oaaa

**Data Transfer Sequence:** 

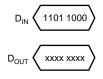
Calculate Checksum for RAM Bank 3



# CSARAMX Calculate the Checksum for all RAM Banks

**Description:** Calculate the checksum of all RAM Banks. The checksum is calculated as a sum of all the bytes with the carry ignored. The ID, DRDY and DIO bits are masked so they are not included in the checksum.

Operands:NoneBytes:1Encoding:1101 1000Data Transfer Sequence:



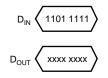


# CSREG Calculate the Checksum of Registers

**Description:** Calculate the checksum of all the registers. The checksum is calculated as a sum of all the bytes with the carry ignored. The ID, DRDY and DIO bits are masked so they are not included in the checksum.

Operands: None Bytes: 1 Encoding: 1101 1111

Data Transfer Sequence:



# CSRAM Calculate RAM Bank Checksum

**Description:** Calculate the checksum of the selected RAM Bank. The checksum is calculated as a sum of all the bytes with the carry ignored. All bits are included in the checksum calculation, there is no masking of bits.

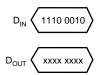
**Operands:** a

**Bytes:** 1

Encoding: 1110 Oaaa

**Data Transfer Sequence:** 

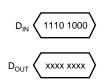
Calculate Checksum for RAM Bank 2



# CSARAM Calculate Checksum for all RAM Banks

**Description:** Calculate the checksum of all RAM Banks. The checksum is calculated as a sum of all the bytes with the carry ignored. All bits are included in the checksum calculation, there is no masking of bits.

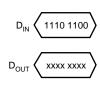
Operands: None Bytes: 1 Encoding: 1110 1000 Data Transfer Sequence:



# CSFL Calculate Checksum for all FLASH Pages

**Description:** Calculate the checksum for all FLASH pages. The checksum is calculated as a sum of all the bytes with the carry ignored. All bits are included in the checksum calculation, there is no masking of bits.

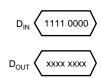
Operands:NoneBytes:1Encoding:1110 1100Data Transfer Sequence:



# SELFCAL Offset and Gain Self Calibration

**Description:** Starts the process of self calibration. The Offset Control Register (OCR) and the Full-Scale Register (FSR) are updated with new values after this operation.

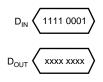
Operands:NoneBytes:1Encoding:1111 0000Data Transfer Sequence:



# SELFOCAL Offset Self Calibration

**Description:** Starts the process of self-calibration for offset. The Offset Control Register (OCR) is updated after this operation.

Operands:NoneBytes:1Encoding:1111 0001Data Transfer Sequence:



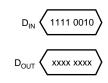




#### SELFGCAL Gain Self Calibration

**Description:** Starts the process of self-calibration for gain. The Full-Scale Register (FSR) is updated with new values after this operation.

Operands:NoneBytes:1Encoding:1111 0010Data Transfer Sequence:



## SYSOCAL System Offset Calibration

**Description:** Starts the system offset calibration process. For a system offset calibration the input should be set to 0V differential, and the ADS1218 computes the OCR register value that will compensate for offset errors. The Offset Control Register (OCR) is updated after this operation.

<b>Operands:</b>	None
Bytes:	1
Encoding:	1111 0011

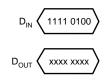
Data Transfer Sequence:



## SYSGCAL System Gain Calibration

**Description:** Starts the system gain calibration process. For a system gain calibration, the differential input should be set to the reference voltage and the ADS1218 computes the FSR register value that will compensate for gain errors. The FSR is updated after this operation.

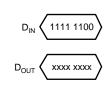
Operands:NoneBytes:1Encoding:1111 0100Data Transfer Sequence:



## DSYNC Sync DRDY

**Description:** Synchronizes the ADS1218 to the serial clock edge.

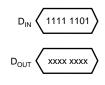
Operands:NoneBytes:1Encoding:1111 1100Data Transfer Sequence:



### SLEEP Sleep Mode

**Description:** Puts the ADS1218 into a low power sleep mode. To exit sleep mode strobe SCLK.

Operands:NoneBytes:1Encoding:1111 1101Data Transfer Sequence:

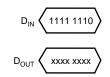


#### RESET

**Reset to Powerup Values** 

**Description:** Restore the registers to their power-up values. This command will also stop the Read Continuous mode. It does not affect the contents of RAM.

Operands:NoneBytes:1Encoding:1111 1110Data Transfer Sequence:





	LSB															
MSB	0000	0001	0010	0011	0100	0101	0110	0111	1000	1001	1010	1011	1100	1101	1110	1111
0000	х	rdata	х	rdatac	х	х	х	х	х	х	х	х	х	х	х	stopc
0001	rreg 0	rreg 1	rreg 2	rreg 3	rreg 4	rreg 5	rreg 6	rreg 7	rreg 8	rreg 9	rreg A	rreg B	rreg C	rreg D	rreg E	rreg F
0010	rram 0	rram 1	rram 2	rram 3	rram 4	rram 5	rram 6	rram 7	x	х	x	х	х	х	х	x
0011	х	х	х	х	х	х	х	х	х	х	х	х	х	х	х	х
0100	creg 0	creg 1	creg 2	creg 3	creg 4	creg 5	creg 6	creg 7	crega	х	х	х	х	х	х	x
0101	wreg 0	wreg 1	wreg 2	wreg 3	wreg 4	wreg 5	wreg 6	wreg 7	wreg 8	wreg 9	wreg A	wreg B	wreg C	wreg D	wreg E	wreg F
0110	wram 0	wram 1	wram 2	wram 3	wram 4	wram 5	wram 6	wram 7	x	х	х	х	х	х	х	x
0111	x	х	х	x	х	х	x	x	х	х	х	х	х	х	х	x
1000	rf2r 0	rf2r 1	rf2r 2	rf2r 3	rf2r 4	rf2r 5	rf2r 6	rf2r 7	rf2r 8	rf2r 9	rf2r A	rf2r B	rf2r C	rf2r D	rf2r E	rf2r F
1001	rf2r 10	rf2r 11	rf2r 12	rf2r 13	rf2r 14	rf2r 15	rf2r 16	rf2r 17	rf2r 18	rf2r 19	rf2r 1A	rf2r 1B	rf2r 1C	rf2r 1D	rf2r 1E	rf2r 1F
1010	wr2f 0	wr2f 1	wr2f 2	wr2f 3	wr2f 4	wr2f 5	wr2f 6	wr2f 7	wr2f 8	wr2f 9	wr2f A	wr2f B	wr2f C	wr2f D	wr2f E	wr2f F
1011	wr2f 10	wr2f 11	wr2f 12	wr2f 13	wr2f 14	wr2f 15	wr2f 16	wr2f 17	wr2f 18	wr2f 19	wr2f 1A	wr2f 1B	wr2f 1C	wr2f 1D	wr2f 1E	wr2f 1F
1100	cram 0	cram 1	cram 2	cram 3	cram 4	cram 5	cram 6	cram 7	х	х	x	х	х	х	x	х
1101	csramx 0	csramx 1	csramx 2	csramx 3	csramx 4	csramx 5	csramx 6	csramx 7	csramx	х	х	x	х	х	х	csreg
1110	csram 0	csram 1	csram2	csram 3	csram 4	csram 5	csram 6	csram 7	csram	х	х	х	csfl	х	х	x
1111	self cal	self ocal	self gcal	sys ocal	sys gcal	х	х	х	х	х	х	х	dsync	sleep	reset	x

x = Reserved

TABLE IV. ADS1218 Command Map.



#### SERIAL PERIPHERAL INTERFACE

The Serial Peripheral Interface (SPI), allows a controller to communicate synchronously with the ADS1218. The ADS1218 operates in slave only mode.

#### **SPI Transfer Formats**

During an SPI transfer, data is simultaneously transmitted and received. The SCLK signal synchronizes shifting and sampling of the information on the two serial data lines:  $D_{IN}$ and  $D_{OUT}$ . The  $\overline{CS}$  signal allows individual selection of an ADS1218 device; an ADS1218 with  $\overline{CS}$  HIGH is not active on the bus.

#### **Clock Phase and Polarity Controls (POL)**

The clock polarity is specified by the POL pin, which selects an active HIGH or active LOW clock, and has no effect on the transfer format.

#### Serial Clock (SCLK)

SCLK, a Schmitt Trigger input to the ADS1218, is generated by the master device and synchronizes data transfer on the  $D_{IN}$  and  $D_{OUT}$  lines. When transferring data to or from the ADS1218, burst mode may be used i.e., multiple bits of data may be transferred back-to-back with no delay in SCLKs or toggling of  $\overline{CS}$ .

#### Chip Select (CS)

The chip select  $(\overline{CS})$  input of the ADS1218 must be externally asserted before a master device can exchange data with the ADS1218.  $\overline{CS}$  must be LOW before data transactions and must stay LOW for the duration of the transaction.

#### DIGITAL INTERFACE

The ADS1218's programmable functions are controlled using a set of on-chip registers, as outlined previously. Data is written to these registers via the part's serial interface and read access to the on-chip registers is also provided by this interface.

The ADS1218's serial interface consists of four signals:  $\overline{CS}$ , SCLK, D<sub>IN</sub>, and D<sub>OUT</sub>. The D<sub>IN</sub> line is used for transferring data into the on-chip registers while the D<sub>OUT</sub> line is used for accessing data from the on-chip registers. SCLK is the serial clock input for the device and all data transfers (either on D<sub>IN</sub> or D<sub>OUT</sub>) take place with respect to this SCLK signal.

The  $\overline{\text{DRDY}}$  line is used as a status signal to indicate when data is ready to be read from the ADS1218's data register.  $\overline{\text{DRDY}}$  goes LOW when a new data word is available in the DOR register. It is reset HIGH when a read operation from the data register is complete. It also goes HIGH prior to the updating of the output register to indicate when not to read from the device to ensure that a data read is not attempted while the register is being updated.

 $\overline{\text{CS}}$  is used to select the device. It can be used to decode the ADS1218 in systems where a number of parts are connected to the serial bus.

The timing specification shows the timing diagram for interfacing to the ADS1218 with  $\overline{\text{CS}}$  used to decode the part.

The ADS1218 serial interface can operate in three-wire mode by tying the  $\overline{CS}$  input LOW. In this case, the SCLK,  $D_{IN}$ , and  $D_{OUT}$  lines are used to communicate with the ADS1218 and the status of  $\overline{DRDY}$  can be obtained by interrogating bit 7 of the M/DEC1 register. This scheme is suitable for interfacing to microcontrollers. If  $\overline{CS}$  is required as a decoding signal, it can be generated from a port pin.

#### **DEFINITION OF TERMS**

**Analog Input Voltage**—the voltage at any one analog input relative to AGND.

Analog Input Differential Voltage—given by the following equation: (IN+ - IN-). Thus, a positive digital output is produced whenever the analog input differential voltage is positive, while a negative digital output is produced whenever the differential is negative.

For example, when the converter is configured with a 2.5V reference and placed in a gain setting of 1, the positive full-scale output is produced when the analog input differential is 2.5V. The negative full-scale output is produced when the differential is -2.5V. In each case, the actual input voltages must remain within the AGND to AV<sub>DD</sub> range.

**Conversion Cycle**—the term "conversion cycle" usually refers to a discrete A/D conversion operation, such as that performed by a successive approximation converter. As used here, a conversion cycle refers to the  $t_{DATA}$  time period. However, each digital output is actually based on the modulator results from several  $t_{DATA}$  time periods.

FILTER SETTING	MODULATOR RESULTS
fast settling	1 t <sub>DATA</sub> time period
sinc <sup>2</sup>	2 t <sub>DATA</sub> time period
sinc <sup>3</sup>	3 t <sub>DATA</sub> time period

**Data Rate**—The rate at which conversions are completed. See definition for  $f_{DATA}$ .

**Decimation Ratio**—defines the ratio between the output of the modulator and the output Data Rate. Valid values for the Decimation Ratio are from 20 to 2047. Larger Decimation Ratios will have lower noise and vice-versa.



**Effective Resolution**—the effective resolution of the ADS1218 in a particular configuration can be expressed in two different units: bits rms (referenced to output) and Vrms (referenced to input). Computed directly from the converter's output data, each is a statistical calculation. The conversion from one to the other is shown below.

BITS rms	BIPOLAR Vrms	UNIPOLAR Vrms		
	$\frac{\left(\frac{2 \cdot V_{REF}}{PGA}\right)}{10^{\left(\frac{6.02 \cdot ER}{20}\right)}}$	$\frac{\left(\frac{V_{REF}}{PGA}\right)}{10^{\left(\frac{6.02 \cdot ER}{20}\right)}}$		
24	298nV	149nV		
22	1.19µV	597nV		
20	4.77μV	2.39µV		
18	19.1µV	9.55μV		
16	76.4µV	38.2µV		
14	505µV	152.7μV		
12	1.22mV	610μV		

**Filter Selection**—the ADS1218 uses a (sinx/x) filter or sinc filter. Actually there are three different sinc filters that can be selected. A fast settling filter will settle in one  $t_{DATA}$  cycle. The sinc<sup>2</sup> filter will settle in two cycles and have lower noise. The sinc<sup>3</sup> will achieve the lowest noise and highest number of effective bits, but requires three cycles to settle. The ADS1218 will operate with any one of these filters, or it can operate in an auto mode, where it will select the fast settling filter after a new channel is selected and will then switch to sinc<sup>2</sup> followed by sinc<sup>3</sup>. This allows fast settling response and still achieves low noise after the necessary number of  $t_{DATA}$  cycles.

 $f_{OSC}$ —the frequency of the crystal oscillator or CMOS compatible input signal at the X<sub>IN</sub> input of the ADS1218.

 $f_{MOD}$ —the frequency or speed at which the modulator of the ADS1218 is running. This depends on the SPEED bit as given by the following equation:

	SPEED = 0	SPEED = 1
mfactor	128	256

 $f_{MOD} = \frac{f_{OSC}}{mfactor}$ 

 $f_{SAMP}$ —the frequency, or switching speed, of the input sampling capacitor. The value is given by one of the following equations:

PGA SETTING	SAMPLING FREQUENCY
1, 2, 4, 8	$f_{SAMP} = \frac{f_{OSC}}{mfactor}$
16	$f_{SAMP} = \frac{f_{OSC} \bullet 2}{mfactor}$
32	$f_{SAMP} = \frac{f_{OSC} \bullet 4}{mfactor}$
64, 128	$f_{SAMP} = \frac{f_{OSC} \bullet 8}{mfactor}$

 $f_{DATA}$ —the frequency of the digital output data produced by the ADS1218,  $f_{DATA}$  is also referred to as the Data Rate.

$$f_{DATA} = \left(\frac{f_{MOD}}{\text{Decimation Ratio}}\right) = \left(\frac{f_{OSC}}{\text{mfactor} \bullet \text{Decimation Ratio}}\right)$$

**Full-Scale Range (FSR)**—as with most A/D converters, the full-scale range of the ADS1218 is defined as the "input", which produces the positive full-scale digital output minus the "input", which produces the negative full-scale digital output. The full-scale range changes with gain setting as shown in Table V.

For example, when the converter is configured with a 2.5V reference and is placed in a gain setting of 2, the full-scale range is: [1.25V (positive full-scale) minus -1.25V (negative full-scale)] = 2.5V.

Least Significant Bit (LSB) Weight—this is the theoretical amount of voltage that the differential voltage at the analog input would have to change in order to observe a change in the output data of one least significant bit. It is computed as follows:

LSB Weight = 
$$\frac{\text{Full-Scale Range}}{2^{N}}$$

where N is the number of bits in the digital output.

 $t_{DATA}$  —the inverse of  ${\rm f}_{\rm DATA},$  or the period between each data output.

	5V SUPPLY ANALOG INPUT <sup>(1)</sup>			GENERAL EQUATIONS			
GAIN SETTING	FULL-SCALE RANGE	DIFFERENTIAL INPUT VOLTAGES <sup>(2)</sup>	PGA OFFSET RANGE	FULL-SCALE RANGE	DIFFERENTIAL INPUT VOLTAGES <sup>(2)</sup>	PGA SHIFT RANGE	
1	5V	±2.5V	±1.25V	2 • V <sub>REF</sub>	±V <sub>REF</sub>	±V <sub>REF</sub>	
2	2.5V	±1.25V	±0.625V	PGA	PGA	2•PGA	
4	1.25V	±0.625V	±312.5mV				
8	0.625V	±312.5mV	±156.25mV				
16	312.5mV	±156.25mV	±78.125mV				
32	156.25mV	±78.125mV	±39.0625mV				
64	78.125mV	±39.0625mV	±19.531mV				
128	39.0625mV	±19.531mV	±9.766mV				

NOTES: (1) With a 2.5V reference. (2) The ADS1218 allows common-mode voltage as long as the absolute input voltage on  $A_{IN}P$  or  $A_{IN}N$  does not go below AGND or above  $AV_{DD}$ .

TABLE V. Full-Scale Range versus PGA Setting.



# **TOPIC INDEX**

# TOPIC

# PAGE

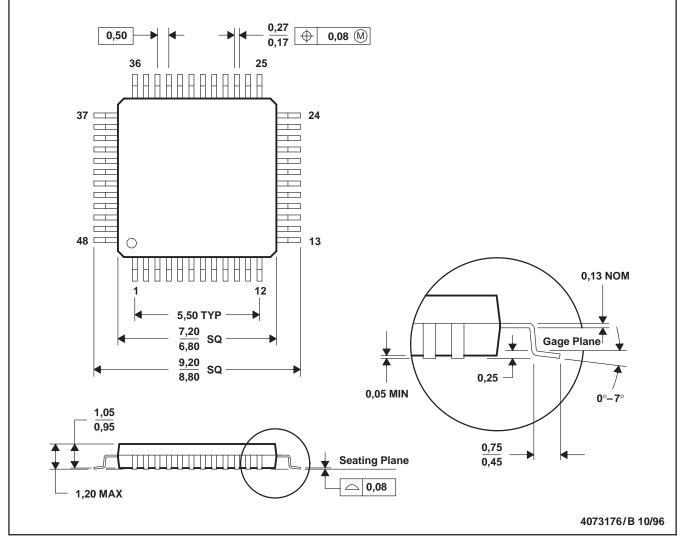
ABSOLUTE MAXIMUM RATINGS	2
PACKAGE AND ORDERING INFORMATION	
ELECTRICAL CHARACTERISTICS (AV <sub>DD</sub> = 5V)	2
ELECTRICAL CHARACTERISTICS (AV <sub>DD</sub> = 3V)	4
PIN CONFIGURATION	
TIMING SPECIFICATIONS	7
TYPICAL CHARACTERISTICS	8
DVERVIEW	
MEMORY	
REGISTER BANK TOPOLOGY	
DETAILED REGISTER DEFINITIONS	
COMMAND DEFINITIONS	
ADS1218 COMMAND MAP	
SERIAL PERIPHERAL INTERFACE	
DIGITAL INTERFACE	25
DEFINITION OF TERMS	25



#### PACKAGE DRAWING

#### PFB (S-PQFP-G48)

#### PLASTIC QUAD FLATPACK



NOTES: A. All linear dimensions are in millimeters.

B. This drawing is subject to change without notice.

C. Falls within JEDEC MS-026





## **PACKAGING INFORMATION**

ORDERABLE DEVICE	STATUS(1)	PACKAGE TYPE	PACKAGE DRAWING	PINS	PACKAGE QTY
ADS1218Y/250	ACTIVE	TQFP	PFB	48	250
ADS1218Y/2K	ACTIVE	TQFP	PFB	48	2000

(1) The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs. **LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

#### **IMPORTANT NOTICE**

Texas Instruments Incorporated and its subsidiaries (TI) reserve the right to make corrections, modifications, enhancements, improvements, and other changes to its products and services at any time and to discontinue any product or service without notice. Customers should obtain the latest relevant information before placing orders and should verify that such information is current and complete. All products are sold subject to TI's terms and conditions of sale supplied at the time of order acknowledgment.

TI warrants performance of its hardware products to the specifications applicable at the time of sale in accordance with TI's standard warranty. Testing and other quality control techniques are used to the extent TI deems necessary to support this warranty. Except where mandated by government requirements, testing of all parameters of each product is not necessarily performed.

TI assumes no liability for applications assistance or customer product design. Customers are responsible for their products and applications using TI components. To minimize the risks associated with customer products and applications, customers should provide adequate design and operating safeguards.

TI does not warrant or represent that any license, either express or implied, is granted under any TI patent right, copyright, mask work right, or other TI intellectual property right relating to any combination, machine, or process in which TI products or services are used. Information published by TI regarding third-party products or services does not constitute a license from TI to use such products or services or a warranty or endorsement thereof. Use of such information may require a license from a third party under the patents or other intellectual property of the third party, or a license from TI under the patents or other intellectual property of TI.

Reproduction of information in TI data books or data sheets is permissible only if reproduction is without alteration and is accompanied by all associated warranties, conditions, limitations, and notices. Reproduction of this information with alteration is an unfair and deceptive business practice. TI is not responsible or liable for such altered documentation.

Resale of TI products or services with statements different from or beyond the parameters stated by TI for that product or service voids all express and any implied warranties for the associated TI product or service and is an unfair and deceptive business practice. TI is not responsible or liable for any such statements.

Following are URLs where you can obtain information on other Texas Instruments products and application solutions:

Products		Applications	
Amplifiers	amplifier.ti.com	Audio	www.ti.com/audio
Data Converters	dataconverter.ti.com	Automotive	www.ti.com/automotive
DSP	dsp.ti.com	Broadband	www.ti.com/broadband
Interface	interface.ti.com	Digital Control	www.ti.com/digitalcontrol
Logic	logic.ti.com	Military	www.ti.com/military
Power Mgmt	power.ti.com	Optical Networking	www.ti.com/opticalnetwork
Microcontrollers	microcontroller.ti.com	Security	www.ti.com/security
		Telephony	www.ti.com/telephony
		Video & Imaging	www.ti.com/video
		Wireless	www.ti.com/wireless

Mailing Address:

Texas Instruments Post Office Box 655303 Dallas, Texas 75265

St Office Box 055505 Dallas, Texas 75205

Copyright © 2003, Texas Instruments Incorporated