nRF9160

Product Specification

v2.1



nRF9160 features

Features:

Microcontroller:

- ARM Cortex -M33
 - 243 EEMBC CoreMark score running from flash memory
 - Data watchpoint and trace (DWT), embedded trace macrocell (ETM), and instrumentation trace macrocell (ITM)
 - · Serial wire debug (SWD)
 - Trace port
- 1 MB flash
- 256 kB low leakage RAM
- ARM Trustzone
- ARM Cryptocell 310
- Up to 4x SPI master/slave with EasyDMA
- Up to 4x I2C compatible two-wire master/slave with EasyDMA
- Up to 4x UART (CTS/RTS) with EasyDMA
- I2S with EasyDMA
- Digital microphone interface (PDM) with EasyDMA
- 4x pulse width modulator (PWM) unit with EasyDMA
- 12-bit, 200 ksps ADC with EasyDMA eight configurable channels with programmable gain
- 3x 32-bit timer with counter mode
- 2x real-time counter (RTC)
- Programmable peripheral interconnect (PPI)
- 32 general purpose I/O pins
- Single supply voltage: 3.0 5.5 V
- All necessary clock sources integrated
- Package: 10 × 16 x 1.04 mm LGA

LTE modem:

- Transceiver and baseband
- 3GPP LTE release 13 Cat-M1 and Cat-NB1 compliant
 - 3GPP release 13 coverage enhancement
- 3GPP LTE release 14 Cat-NB2 compliant
- GPS receiver
 - GPS L1 C/A supported
 - QZSS L1 C/A supported
- RF transceiver for global coverage
 - Up to 23 dBm output power
 - -108 dBm sensitivity (LTE-M) for low band, -107 dBm for mid hand
 - Single 50 Ω antenna interface
- LTE band support in hardware:
 - Cat-M1: B1, B2, B3, B4, B5, B8, B12, B13, B14, B18, B19, B20, B25, B26, B28, B66
 - Cat-NB1/NB2: B1, B2, B3, B4, B5, B8, B12, B13, B17, B19, B20, B25, B26, B28, B66
- Supports SIM and eSIM with an ETSI TS 102 221 compatible UICC interface
- Power saving features: DRX, eDRX, PSM
- IP v4/v6 stack
- Secure socket (TLS/DTLS) API

Current consumption @ 3.7 V:

- Power saving mode (PSM) floor current: 2.7 μA
- eDRX @ 82.91s: 18 μA in Cat-M1, 37 μA in Cat-NB1 (UICC included)

Applications:

- Sensor networks
- Logistics and asset tracking
- Smart energy
- Smart building automation
- Smart agriculture

- Industrial
- Retail and monitor devices
- Medical devices
- Wearables



4418_1315 v2.1 ii

Contents

	nRF9160 features.	. ii
1	Revision history.	10
2	About this document.	13
	2.1 Document status	13
	2.2 Peripheral chapters	13
	2.3 Register tables	14
	2.3.1 Fields and values	14
	2.3.2 Permissions	. 14
	2.4 Registers	. 14
	2.4.1 DUMMY	15
3	Product overview	16
	3.1 Block diagram	16
	3.2 Peripheral interface	17
	3.2.1 Peripheral ID	18
	3.2.2 Peripherals with shared ID	19
	3.2.3 Peripheral registers	19
	3.2.4 Bit set and clear	. 19
	3.2.5 Tasks	20
	3.2.6 Events	. 20
	3.2.7 Publish and subscribe	20
	3.2.8 Shortcuts	. 20
	3.2.9 Interrupts	20
	3.2.10 Secure/non-secure peripherals	21
4	Application core	22
	4.1 CPU	. 22
	4.1.1 Floating-point interrupt	
	4.1.2 CPU and support module configuration	
	4.1.3 Electrical specification	
	4.2 Memory	22
	4.2.1 Memory map	. 25
	4.2.2 Instantiation	26
	4.2.3 Peripheral access control capabilities	29
	4.3 VMC — Volatile memory controller	29
	4.3.1 Registers	. 30
	4.4 NVMC — Non-volatile memory controller	. 31
	4.4.1 Writing to flash	31
	4.4.2 Erasing a secure page in flash	32
	4.4.3 Erasing a non-secure page in flash	32
	4.4.4 Writing to user information configuration registers (UICR)	32
	4.4.5 Erase all	32
	4.4.6 NVMC protection mechanisms	
	4.4.7 Cache	33
	4.4.8 Registers	. 34
	4.4.9 Electrical specification	37
	4.5 FICR — Factory information configuration registers	37



4418_1315 v2.1 iii

4.5.1 Registers	
6 UICR — User information configuration registers	
4.6.1 Registers	
7 EasyDMA	
4.7.1 EasyDMA error handling	
4.7.2 EasyDMA array list	
8 AHB multilayer interconnect	
4.8.1 AHB multilayer priorities	
ower and clock management.	5
1 Power management	
5.1.1 System Disabled mode	
5.1.2 System OFF mode	
5.1.3 System ON mode	
·	
5.1.4 Registers	
5.1.5 Electrical specification	
2 Power supply	
5.2.1 General purpose I/O supply	
3 Power supply monitoring	
5.3.1 Power supply supervisor	
5.3.2 External power failure warning	
5.3.3 Battery monitoring on VDD	
5.3.4 Registers	
5.3.5 Electrical specification	
4 Clock management	
5.4.1 HFCLK clock controller	
5.4.2 LFCLK clock controller	
5.4.3 Registers	
5.4.4 Electrical specification	
5 Reset	
5.5.1 Power-on reset	
5.5.2 Pin reset	
5.5.3 Wakeup from System OFF mode reset	
5.5.4 Soft reset	
5.5.5 Watchdog reset	
5.5.6 Brownout reset	
5.5.7 Retained registers	
5.5.8 Reset behavior	
5.5.9 Registers	
5.5.10 Electrical specification	
6 Current consumption	
5.6.1 Electrical specification	
7 Register description	
5.7.1 POWER — Power control	
5.7.2 CLOCK — Clock control	
5.7.3 REGULATORS — Voltage regulators control	
eripherals	8
1 CRYPTOCELL — ARM TrustZone CryptoCell 310	
6.1.1 Usage	
6.1.2 Always-on (AO) power domain	



4418_1315 v2.1 iv

6.1.5 Direct memory access (DMA)	. 86
6.1.6 Standards	. 86
6.1.7 Registers	
6.1.8 Host interface	
6.2 DPPI - Distributed programmable peripheral interconnect	. 91
6.2.1 Subscribing to and publishing on channels	. 92
6.2.2 DPPI configuration (DPPIC)	
6.2.3 Connection examples	
6.2.4 Special considerations for a system implementing TrustZone for Cortex-M processors	
6.2.5 Registers	
6.3 EGU — Event generator unit	
6.3.1 Registers	
6.3.2 Electrical specification	
6.4 GPIO — General purpose input/output	102
6.4.1 Pin configuration	
6.4.2 Pin sense mechanism	
6.4.3 GPIO security	
6.4.4 Registers	
6.4.5 Electrical specification	
6.5 GPIOTE — GPIO tasks and events	
6.5.1 Pin events and tasks	
6.5.2 Port event	
6.5.3 Tasks and events pin configuration	
6.5.4 Registers	
6.5.5 Electrical specification	
6.6 IPC — Interprocessor communication	
6.6.1 IPC and PPI connections	
6.6.2 Registers	
6.6.3 Electrical specification	
6.7 I ² S — Inter-IC sound interface	
6.7.1 Mode	125
6.7.2 Transmitting and receiving	
6.7.3 Left right clock (LRCK)	
6.7.4 Serial clock (SCK)	. 126
6.7.5 Master clock (MCK)	. 127
6.7.6 Width, alignment and format	. 127
6.7.7 EasyDMA	129
6.7.8 Module operation	131
6.7.9 Pin configuration	. 133
6.7.10 Registers	. 133
6.7.11 Electrical specification	144
6.8 KMU — Key management unit	. 144
6.8.1 Functional view	145
6.8.2 Access control	145
6.8.3 Protecting the UICR content	146
6.8.4 Usage	146
6.8.5 Registers	150
6.9 PDM — Pulse density modulation interface	. 154
6.9.1 Master clock generator	154
6.9.2 Module operation	155
6.9.3 Decimation filter	
6.9.4 EasyDMA	
6.9.5 Hardware example	156
6.9.6 Pin configuration	
	· 10/



6.9.7 Registers	157
6.9.8 Electrical specification	165
6.10 PWM — Pulse width modulation	166
6.10.1 Wave counter	166
6.10.2 Decoder with EasyDMA	170
6.10.3 Limitations	177
	177
	177
	188
	189
	189
	190
	190
	190 191
	191 191
	191 191
·	191 193
, , ,	
9	195
'	203
	203
	203
	204
	205
· ·	205
,	207
6.12.6 Resistor ladder	208
6.12.7 Reference	209
6.12.8 Acquisition time	209
6.12.9 Limits event monitoring	210
6.12.10 Registers	211
	228
	229
	229
,	230
	231
	232
	232 232
,	232 232
·	232 233
	233 244
·	244 245
	243 246
,	246
!	246
	248
	249
	249
'	262
	264
!	264
	265
	268
6.15.4 Peripheral access control	271
6.15.5 Pin access control	273



4418_1315 v2.1 Vi

6.15.6 DPPI access control	273 275
6.15.8 TrustZone for Cortex-M ID allocation	275
6.15.9 Registers	277 286
6.16 TIMER — Timer/counter	286
6.16.2 Compare	287
6.16.3 Task delays	
6.16.4 Task priority	287
6.16.5 Registers	288 295
6.16.6 Electrical specification	
6.17 TWIM — I ² C compatible two-wire interface master with EasyDMA	293
6.17.2 EasyDMA	
•	
6.17.3 Master write sequence	297
6.17.4 Master read sequence	298 299
6.17.5 Master repeated start sequence	300
6.17.6 Low power	300
6.17.7 Master mode pin configuration	300
6.17.8 Registers	315
6.17.9 Electrical specification	315
6.17.10 Pullup resistor	316
6.18.1 Shared resources	318
6.18.2 EasyDMA	
6.18.3 TWI slave responding to a read command	
6.18.4 TWI slave responding to a write command	
6.18.5 Master repeated start sequence	321
6.18.6 Terminating an ongoing TWI transaction	
6.18.7 Low power	322
6.18.8 Slave mode pin configuration	322
6.18.9 Registers	
6.18.10 Electrical specification	
6.19 UARTE — Universal asynchronous receiver/transmitter with EasyDMA	336
6.19.1 EasyDMA	
6.19.2 Transmission	337
6.19.3 Reception	338
6.19.4 Error conditions	340
6.19.5 Using the UARTE without flow control	340
6.19.6 Parity and stop bit configuration	340
6.19.7 Low power	340
6.19.8 Pin configuration	341
6.19.9 Registers	341
6.19.10 Electrical specification	359
6.20 WDT — Watchdog timer	359
6.20.1 Reload criteria	359
6.20.2 Temporarily pausing the watchdog	360
6.20.3 Watchdog reset	360
6.20.4 Registers	360
6.20.5 Electrical specification	364
	30 T
LTE modem	365
7.1 SIM card interface	366
7.2 LTE modem coexistence interface	367

4418_1315 v2.1 vii

7



	7.3 LTE modem RF control external interface	. 368
	7.4 RF front-end interface	369
	7.5 Registers	
	7.6 Electrical specification	
	7.6.1 Key RF parameters for Cat-M1	
	7.6.2 Key RF parameters for Cat-NB1 and Cat-NB2	
	7.6.3 Receiver parameters for Cat-M1	370
	7.6.4 Receiver parameters for Cat-NB1 and Cat-NB2	
	7.6.5 Transmitter parameters for Cat-M1	
	7.6.6 Transmitter parameters for Cat-NB1 and Cat-NB2	3/1
8	GPS receiver.	372
	8.1 Electrical specification	372
	·	
9	Debug and trace	374
	9.1 Special consideration regarding debugger access	374
	9.2 DAP - Debug access port	375
	9.3 Debug interface mode	
	9.4 Real-time debug	
	9.5 Trace	
	9.6 Registers	
	9.6.1 TARGETID	
	9.7 Electrical specification	
	9.7.1 Trace port	
	9.8.1 Reset request	
	9.8.2 Erase all	
	9.8.3 Mailbox interface	
	9.8.4 Disabling erase protection	
	9.8.5 Debugger registers	
	9.8.6 Registers	
	9.9 TAD - Trace and debug control	. 385
	9.9.1 Registers	386
10	Hardware and layout.	. 390
10		
	10.1 Pin assignments	
	10.1.1 LGA pin assignments	
	10.2.1 16.00 x 10.50 mm package	
	10.3 Reference circuitry	
	10.3.1 Schematic SIxA LGA127	
	10.4 Reflow conditions	
	10.5 Shelf and floor life	
11	Operating conditions	396
11		
	11.1 VDD_GPIO considerations	396
12	Absolute maximum ratings.	397
13	Ordering information.	398
	13.1 IC marking	
	13.1 IC IIIdi Kilig	. 390

4418_1315 v2.1 viii



	13.3 Order code	400
14	Regulatory information	403
15	Legal notices.	404



4418_1315 v2.1 ix

1 Revision history

Date	Version	Description
October 2021	2.1	Updated the following:
		Added Shelf and floor life on page 395
		 UICR — User information configuration registers on page 43 - Added APPNVMCPOFGUARD information
September 2020	2.0	Updated the following:
		 Updated format of all figures Removed deprecated columns in all register tables CPU on page 22 - Updated CoreMark[®] values
		 Power supply monitoring on page 54 - Added LTE modem startup and shutdown information to Device startup times Current consumption on page 63:
		current consumption on page 05.



Date	Version	Description
Date	Version	Description Updated application domain, LTE modem, and GPS receiver information Added LTE modem PSM TAU event energy and duration information Updated parameters PWM — Pulse width modulation on page 166 - Added code example for typical configuration SPU — System protection unit on page 264 - Editorial updates UARTE — Universal asynchronous receiver/transmitter with EasyDMA on page 336 - Added parameters Pin assignments on page 390 - Updated description for SIM_DET pin Absolute maximum ratings on page 397 - Updated ATEX compliance parameters Ordering information on page 398 - Updated Order code Legal notices on page 404 - Updated text for Life support applications
April 2020	1.2	 Updated the following: Operating conditions on page 396 – Updated with MAGPIO, COEX, MIPI RFFE, SIMIF pins voltage supply references Absolute maximum ratings on page 397: Updated with GPS antenna input level and ATEX compliance information Decreased maximum storage temperature to 95 °C Power and clock management: Updated ENABLE pin information Added SYSTEM DISABLED mode information Updated Pin reset voltage level and pull-up information Current consumption on page 63: Updated peripherals consumption information Added SYSTEM DISABLED mode information Updated LTE modem Cat-M1 information Updated GPS receiver information Updated GPS receiver information LTE modem: Added MAGPIO, COEX, and MIPI RFFE timing information Added information on SIM card power down support during eDRX idle mode GPS receiver on page 372 - updated with performance information Pin reset on page 60 - updated description and added schematic Current consumption on page 63 - 1 GPS_SINGLE value increased due to design changes to improve performance in poor conditions Added: Reflow conditions on page 395
October 2019	1.1	 Renow conditions on page 395 Updated: Debug and trace Debug and trace on page 374: Added debug access port. Updated SDK version Memory on page 23: Added a reference LGA pin assignments on page 390: Several updates



Date	Version	Description
		Operating conditions on page 396: Changed chapter name. Updated
		MAGPIO values. Updated VDD_GPIO restrictions.
		Ordering information on page 398: Updated Product options
		Added:
		Reference circuitry on page 393
May 2019	1.0	First release



2 About this document

This document is organized into chapters that are based on the modules and peripherals available in the IC. The relevant Product Specification version for each nRF9160 revision is described by the nRF9160 Compatibility Matrix.

2.1 Document status

The document status reflects the level of maturity of the document.

Document name	Description
Objective Product Specification (OPS)	Applies to document versions up to 1.0. This document contains target specifications for product development.
Product Specification (PS)	Applies to document versions 1.0 and higher. This document contains final product specifications. Nordic Semiconductor ASA reserves the right to make changes at any time without notice in order to improve design and supply the best possible product.

Table 1: Defined document names

2.2 Peripheral chapters

Every peripheral has a unique capitalized name or an abbreviation of its name, e.g. TIMER, used for identification and reference. This name is used in chapter headings and references, and it will appear in the ARM Cortex Microcontroller Software Interface Standard (CMSIS) hardware abstraction layer to identify the peripheral.

The peripheral instance name, which is different from the peripheral name, is constructed using the peripheral name followed by a numbered postfix, starting with 0, for example, TIMERO. A postfix is normally only used if a peripheral can be instantiated more than once. The peripheral instance name is also used in the CMSIS to identify the peripheral instance.

The chapters describing peripherals may include the following information:

- A detailed functional description of the peripheral
- Register configuration for the peripheral
- Electrical specification tables, containing performance data which apply for the operating conditions described in Operating conditions on page 396.



2.3 Register tables

Individual registers are described using register tables. These tables are built up of two sections. The first three colored rows describe the position and size of the different fields in the register. The following rows describe the fields in more detail.

2.3.1 Fields and values

The **Id** (**Field Id**) row specifies the bits that belong to the different fields in the register. If a field has enumerated values, then every value will be identified with a unique value id in the **Value Id** column.

A blank space means that the field is reserved and read as undefined, and it also must be written as 0 to secure forward compatibility. If a register is divided into more than one field, a unique field name is specified for each field in the **Field** column. The **Value Id** may be omitted in the single-bit bit fields when values can be substituted with a Boolean type enumerator range, e.g. true/false, disable(d)/enable(d), on/off, and so on.

Values are usually provided as decimal or hexadecimal. Hexadecimal values have a 0x prefix, decimal values have no prefix.

The Value column can be populated in the following ways:

- Individual enumerated values, for example 1, 3, 9.
- Range of values, e.g. [0..4], indicating all values from and including 0 and 4.
- Implicit values. If no values are indicated in the **Value** column, all bit combinations are supported, or alternatively the field's translation and limitations are described in the text instead.

If two or more fields are closely related, the **Value Id**, **Value**, and **Description** may be omitted for all but the first field. Subsequent fields will indicate inheritance with '..'.

A feature marked **Deprecated** should not be used for new designs.

2.3.2 Permissions

Different fields in a register might have different access permissions enforced by hardware.

The access permission for each register field is documented in the Access column in the following ways:

Access	Description	Hardware behavior
RO	Read-only	Field can only be read. A write will be ignored.
wo	Write-only	Field can only be written. A read will return an undefined value.
RW	Read-write	Field can be read and written multiple times.
W1	Write-once	Field can only be written once per reset. Any subsequent write will be ignored. A read will return an undefined value.
RW1	Read-write-once	Field can be read multiple times, but only written once per reset. Any subsequent write will be ignored.

Table 2: Register field permission schemes

2.4 Registers

Register	Offset	Description
DUMMY	0x514	Example of a register controlling a dummy feature

Table 3: Register overview



2.4.1 DUMMY

Address offset: 0x514

Example of a register controlling a dummy feature

Bit r	number			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				DDDD	O CCC B A A
Rese	et 0x000	50002		0 0 0 0 0 0 0	0 0 0 0 0 1 0 1 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	FIELD_A			Example of a read-write field with several enumerated values
			Disabled	0	The example feature is disabled
			NormalMode	1	The example feature is enabled in normal mode
			ExtendedMode	2	The example feature is enabled along with extra functionality
В	RW	FIELD_B			Example of a deprecated read-write field
					This field is deprecated.
			Disabled	0	The override feature is disabled
			Enabled	1	The override feature is enabled
С	RW	FIELD_C			Example of a read-write field with a valid range of values
			ValidRange	[27]	Example of allowed values for this field
D	RW	FIELD_D			Example of a read-write field with no restriction on the values



3 Product overview

The nRF9160 is a low-power cellular IoT (Internet of Things) solution, integrating an ARM[®] Cortex[®]-M33 processor with advanced security features, a range of peripherals, as well as a complete LTE modem compliant with 3GPP LTE release 13 Cat-M1 and Cat-NB1, and 3GPP LTE release 14 Cat-NB1 and Cat-NB2 standards.

The ARM Cortex-M33 processor is exclusively for user application software, and it offers 1 MB of flash and 256 kB of RAM dedicated to this use. The M33 application processor shares the power, clock and peripheral architecture with Nordic Semiconductor nRF51 and nRF52 Series of PAN/LAN SoCs, ensuring minimal porting efforts.

The peripheral set offers a variety of analog and digital functionality enabling single-chip implementation of a wide range of cellular IoT (Internet of Things) applications. ARM TrustZone technology, Cryptocell 310 and supporting blocks for system protection and key management, are embedded to enable advanced security needed for IoT applications.

The LTE modem integrates a very flexible transceiver that in hardware supports frequency range from 700 to 2200 MHz (through a single 50 Ω antenna pin), and a baseband processor handling LTE Cat-M1/NB1/NB2 protocol layers L1-L3 as well as IP upper layers offering secure socket API for the application. The modem is supported by pre-qualified software builds available for free from Nordic Semiconductor.

On specific nRF9160 device variants, the LTE modem supports A-GPS operation during sleep intervals in the LTE operation (RRC idle and PSM modes).

Note: The LTE modem hardware supports Cat-NB2, but needs modem firmware support to get enabled. For information on Cat-NB2 feature support, see the *nRF9160 Modem Firmware Release Notes* included in the latest nRF9160 modem firmware.

3.1 Block diagram

This block diagram illustrates the overall system. Arrows with white heads indicate signals that share physical pins with other signals.



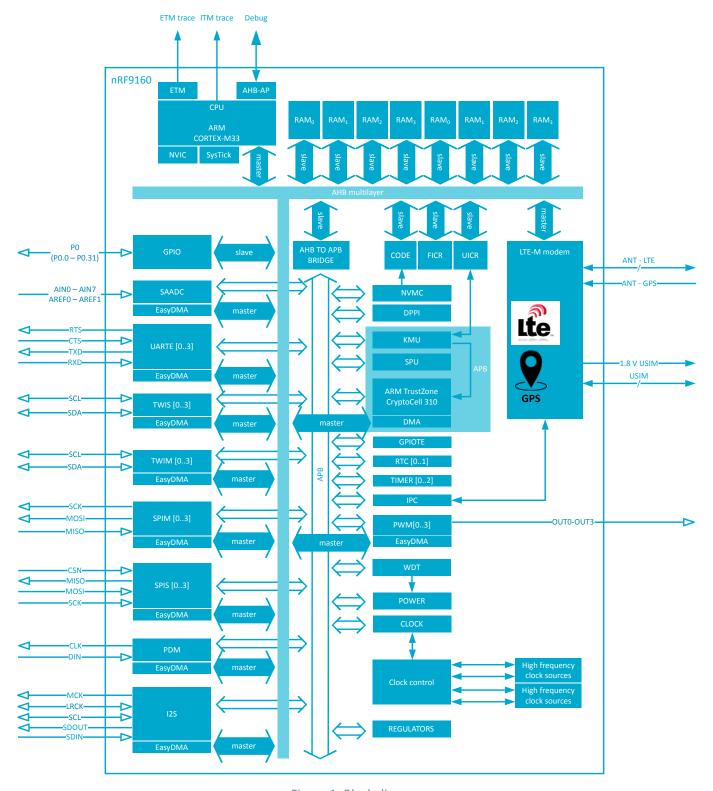


Figure 1: Block diagram

3.2 Peripheral interface

Peripherals are controlled by the CPU through configuration registers, as well as task and event registers. Task registers are inputs, enabling the CPU and other peripherals to initiate a functionality. Event registers are outputs, enabling a peripheral to trigger tasks in other peripherals and/or the CPU by tying events to CPU interrupts.



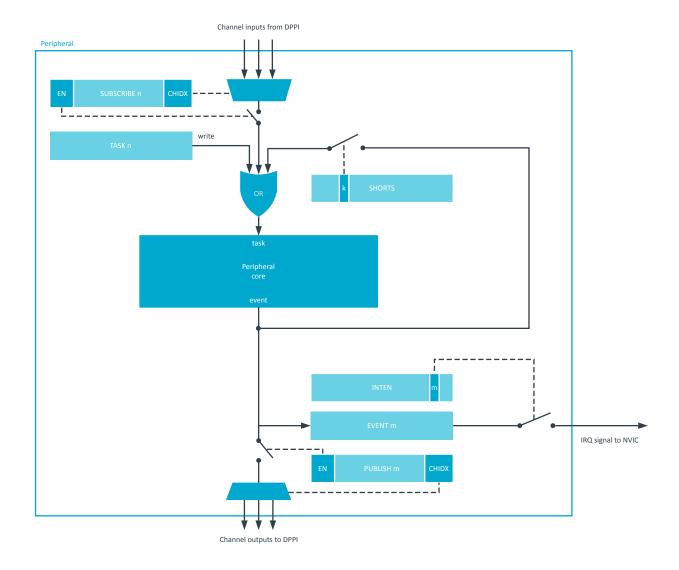


Figure 2: Peripheral interface

The distributed programmable peripheral interconnect (DPPI) feature enables peripherals to connect events to tasks without CPU intervention. For more information on DPPI and the DPPI channels, see DPPI - Distributed programmable peripheral interconnect on page 91.

3.2.1 Peripheral ID

Every peripheral is assigned a fixed block of 0x1000 bytes of address space, which is equal to 1024 x 32 bit registers.

See Instantiation on page 26 for more information about which peripherals are available and where they are located in the address map.

There is a direct relationship between peripheral ID and base address. For example, a peripheral with base address 0x40000000 is assigned ID=0, a peripheral with base address 0x40001000 is assigned ID=1, and a peripheral with base address 0x4001F000 is assigned ID=31.

Peripherals may share the same ID, which may impose one or more of the following limitations:

- Shared registers or common resources
- Limited availability due to mutually exclusive operation; only one peripheral in use at a time
- Enforced peripheral behavior when switching between peripherals (disable the first peripheral before enabling the second)

NORDIC*

3.2.2 Peripherals with shared ID

In general (with the exception of ID 0), peripherals sharing an ID and base address may not be used simultaneously. Only one peripheral can be enabled at a given ID.

When switching between two peripherals sharing an ID, the following should be performed to prevent unwanted behavior:

- **1.** Disable the previously used peripheral.
- 2. Disable any publish/subscribe connection to the DPPI system for the peripheral that is being disabled.
- **3.** Clear all bits in the INTEN register, i.e. INTENCLR = 0xFFFFFFFF.
- **4.** Explicitly configure the peripheral being enabled. Do not rely on inherited configuration from the disabled peripheral.
- **5.** Enable the now configured peripheral.

For a list of which peripherals that share an ID see Instantiation on page 26.

3.2.3 Peripheral registers

Most peripherals feature an ENABLE register. Unless otherwise specified, the peripheral registers must be configured before enabling the peripheral.

PSEL registers need to be set before a peripheral is enabled or started. Updating PSEL registers while the peripheral is running has no effect. To connect a peripheral to a different GPIO, the following must be performed:

- 1. Disable the peripheral.
- 2. Update the PSEL register.
- **3.** Re-enable the peripheral.

It takes four CPU cycles between the PSEL register update and the connection between a peripheral and a GPIO becoming effective.

Note: The peripheral must be enabled before tasks and events can be used.

Most of the register values are lost during System OFF or when a reset is triggered. Some registers will retain their values in System OFF or for some specific reset sources. These registers are marked as retained in the register description for a given peripheral. For more information on their behavior, see chapter Reset on page 60.

3.2.4 Bit set and clear

Registers with multiple single-bit bit fields may implement the set-and-clear pattern. This pattern enables firmware to set and clear individual bits in a register without having to perform a read-modify-write operation on the main register.

This pattern is implemented using three consecutive addresses in the register map, where the main register is followed by dedicated SET and CLR registers (in that exact order).

In the main register, the SET register sets individual bits and the CLR register clears them. Writing 1 to a bit in the SET or CLR register will set or clear the same bit in the main register respectively. Writing 0 to a bit in the SET or CLR register has no effect. Reading the SET or CLR register returns the value of the main register.

Note: The main register may not be visible and therefore not directly accessible in all cases.



3.2.5 Tasks

Tasks are used to trigger actions in a peripheral, such as to start a particular behavior. A peripheral can implement multiple tasks with each task having a separate register in that peripheral's task register group.

A task is triggered when firmware writes 1 to the task register, or when the peripheral itself or another peripheral toggles the corresponding task signal. See the figure Peripheral interface on page 18.

3.2.6 Events

Events are used to notify peripherals and the CPU about events that have happened, for example a state change in a peripheral. A peripheral may generate multiple events, where each event has a separate register in that peripheral's event register group.

An event is generated when the peripheral itself toggles the corresponding event signal, and the event register is updated to reflect that the event has been generated, see figure Peripheral interface on page 18. An event register is cleared when a 0 is written to it by firmware. Events can be generated by the peripheral even when the event register is set to 1.

3.2.7 Publish and subscribe

Events and tasks from different peripherals can be connected together through the DPPI system using the PUBLISH and SUBSCRIBE registers in each peripheral. See Peripheral interface on page 18. An event can be published onto a DPPI channel by configuring the event's PUBLISH register. Similarly, a task can subscribe to a DPPI channel by configuring the task's SUBSCRIBE register.

See DPPI - Distributed programmable peripheral interconnect on page 91 for details.

3.2.8 Shortcuts

A shortcut is a direct connection between an event and a task within the same peripheral. If a shortcut is enabled, the associated task is automatically triggered when its associated event is generated.

Using shortcuts is equivalent to making the connection outside the peripheral and through the DPPI. However, the propagation delay when using shortcuts is usually shorter than the propagation delay through the DPPI.

Shortcuts are predefined, which means that their connections cannot be configured by firmware. Each shortcut can be individually enabled or disabled through the shortcut register, one bit per shortcut, giving a maximum of 32 shortcuts for each peripheral.

3.2.9 Interrupts

All peripherals support interrupts which are generated by events.

A peripheral only occupies one interrupt, and the interrupt number follows the peripheral ID. For example, the peripheral with ID=4 is connected to interrupt number 4 in the nested vectored interrupt controller (NVIC).

Using registers INTEN, INTENSET, and INTENCLR, every event generated by a peripheral can be configured to generate that peripheral's interrupt. Multiple events can be enabled to generate interrupts simultaneously. To resolve the correct interrupt source, the event registers in the event group of peripheral registers will indicate the source.

Some peripherals implement only INTENSET and INTENCLR registers, and the INTEN register is not available on those peripherals. See the individual peripheral chapters for details. In all cases, reading back the INTENSET or INTENCLR register returns the same information as in INTEN.

Each event implemented in the peripheral is associated with a specific bit position in the INTEN, INTENSET, and INTENCLR registers.



The relationship between tasks, events, shortcuts, and interrupts is illustrated in figure Peripheral interface on page 18.

3.2.9.1 Interrupt clearing and disabling

Interrupts should always be cleared by writing 0 to the corresponding EVENT register.

Until cleared, interrupts will immediately be re-triggered and cause software interrupt service routines to be executed repeatedly.

Because the clearing of the EVENT register may take a number of CPU clock cycles, the program should perform a read from the EVENT register that has been cleared before exiting the interrupt service routine. This will ensure that the EVENT clearing has taken place before the interrupt service routine is exited. Care should be taken to ensure that the compiler does not remove the read operation as an optimization.

Similarly, when disabling an interrupt inside an interrupt service routine, the program should perform a read from the INTEN or INTENCLR registers to ensure that the interrupt is disabled before exiting the interrupt service routine.

3.2.10 Secure/non-secure peripherals

For some peripherals, the security configuration can change from secure to non-secure, or vice versa. Care must be taken when changing the security configuration of a peripheral, to prevent security information leakage and ensure correct operation.

The following sequence should be followed, where applicable, when configuring and changing the security settings of a peripheral in the SPU — System protection unit on page 264.

- 1. Stop peripheral operation.
- 2. Disable the peripheral.
- 3. Remove pin connections.
- 4. Disable DPPI connections.
- 5. Clear sensitive registers (e.g. writing back default values).
- **6.** Change peripheral security setting in the SPU System protection unit on page 264.
- **7.** Re-enable the peripheral.

Note: Changing security settings on a peripheral during runtime is not advisable.



4 Application core

The nRF9160 application core has a modern and powerful ARM Cortex-M33 with on-chip flash and RAM exclusively for application use.

4.1 CPU

The ARM Cortex-M33 processor has a 32-bit instruction set (Thumb-2 technology) that implements a superset of 16 and 32-bit instructions to maximize code density and performance.

This processor implements several features that enable energy-efficient arithmetic and high-performance signal processing, including:

- Digital signal processing (DSP) instructions
- Single-cycle multiply and accumulate (MAC) instructions
- Hardware divide
- 8- and 16-bit single instruction, multiple data (SIMD) instructions
- Single-precision floating-point unit (FPU)
- Memory Protection Unit (MPU)
- ARM TrustZone for ARMv8-M

The ARM Cortex Microcontroller Software Interface Standard (CMSIS) hardware abstraction layer for the ARM Cortex processor series is implemented and available for the M33 CPU.

Real-time execution is highly deterministic in thread mode, to and from sleep modes, and when handling events at configurable priority levels via the nested vectored interrupt controller (NVIC).

Executing code from internal or external flash will have a wait state penalty. The instruction cache can be enabled to minimize flash wait states when fetching instructions. For more information on cache, see Cache on page 33. The section Electrical specification on page 23 shows CPU performance parameters including the wait states in different modes, CPU current and efficiency, and processing power and efficiency based on the CoreMark benchmark.

4.1.1 Floating-point interrupt

The floating-point unit (FPU) may generate exceptions when used due to e.g. overflow or underflow, which in turn will trigger the FPU interrupt.

See Instantiation on page 26 for more information about which exception number (peripheral ID) is triggered by an FPU exception.

The FPU is not affected by any security configuration. Thus, it appears as not present in PERIPHID[n].PERM register located in the SPU — System protection unit on page 264.

To clear the IRQ (interrupt request) line when an exception has occurred, the relevant exception bit within the floating-point status and control register (FPSCR) needs to be cleared. For more information about the FPSCR or other FPU registers, see *Cortex-M33 Devices Generic User Guide*.

4.1.2 CPU and support module configuration

The ARM Cortex-M33 processor has a number of CPU options and support modules implemented on the device.



Option / Module	Description	Implemented
Core options		
NVIC	Nested vectored interrupt controller	
PRIORITIES	Priority bits	3
WIC	Wake-up interrupt controller	NO
Endianness	Memory system endianness	Little endian
DWT	Data watchpoint and trace	YES
Modules		
MPU_NS	Number of non-secure memory protection unit (MPU) regions	16
MPU_S	Number of secure MPU regions	16
SAU	Number of security attribution unit (SAU) regions	0, see SPU for more information about
		secure regions.
FPU	Floating-point unit	YES
DSP	Digital signal processing extension	YES
ARMv8-M TrustZone	ARMv8-M security extensions	YES
CPIF	Co-processor interface	NO
ETM	Embedded trace macrocell	YES
ITM	Instrumentation trace macrocell	YES
МТВ	Micro trace buffer	NO
СТІ	Cross trigger interface	YES
BPU	Breakpoint unit	YES
нтм	AMBA AHB trace macrocell	NO

4.1.3 Electrical specification

4.1.3.1 CPU performance

The CPU clock speed is 64 MHz. Current and efficiency data is taken when in System ON and the CPU is executing the CoreMark benchmark. It includes power regulator and clock base currents. All other blocks are IDLE.

Symbol	Description	Min.	Тур.	Max.	Units
W _{FLASH}	CPU wait states, running from flash, cache disabled	0		4	
W _{FLASHCACHE}	CPU wait states, running from flash, cache enabled	0		2	
W_{RAM}	CPU wait states, running from RAM			0	
CM _{FLASH}	CoreMark ¹ , running from flash, cache enabled		243		CoreMark
CM _{FLASH/MHz}	CoreMark per MHz, running from flash, cache enabled		3.79		CoreMark/
					MHz
CM _{FLASH/mA}	CoreMark per mA, running from flash, cache enabled, DC/		110.45		CoreMark/
	DC				mA

4.2 Memory

The application microcontroller has embedded 1024 kB flash and 256 kB RAM for application code and data storage.

As illustrated in Memory layout on page 24, both CPU and EasyDMA are able to access RAM via the AHB multilayer interconnect. See AHB multilayer interconnect on page 49 and EasyDMA on page 47 for more information about AHB multilayer interconnect and EasyDMA respectively. The LTE modem can access all application MCU memory, but typically a small portion of RAM is dedicated to data exchange between application MCU and the modem baseband controller.

NORDIC® SEMICONDUCTOR

¹ Using IAR compiler

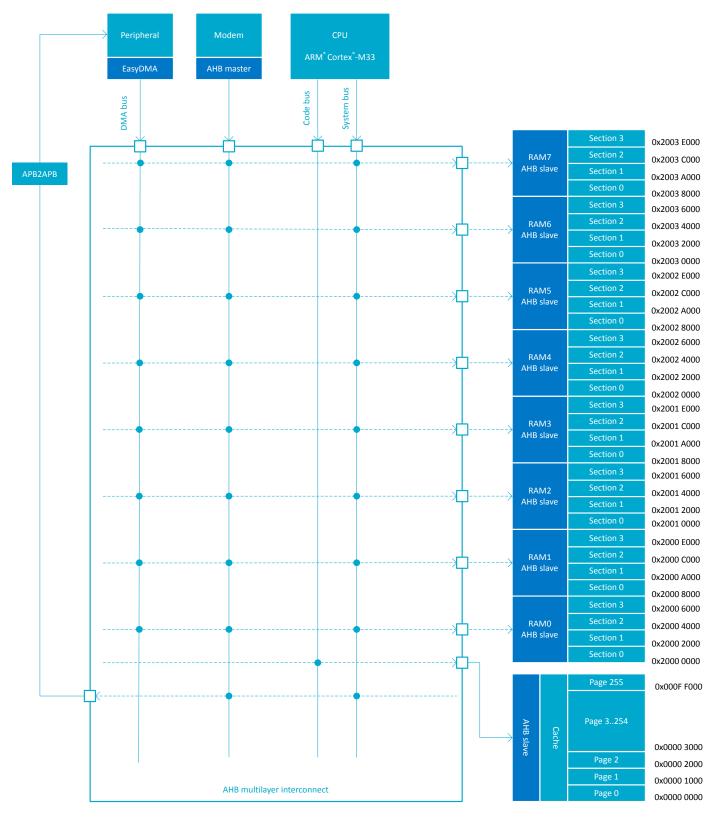


Figure 3: Memory layout

RAM - Random access memory

RAM can be read and written an unlimited number of times by the CPU and the EasyDMA.

Each RAM AHB slave is connected to one or more RAM sections. See Memory layout on page 24 for more information.



The RAM blocks power states and retention states in System ON and System OFF modes are controlled by the VMC.

Flash - Non-volatile memory

Flash can be read an unlimited number of times by the CPU and is accessible via the AHB interface connected to the CPU, see Memory layout on page 24 for more information. There are restrictions on the number of times flash can be written and erased, and also on how it can be written. For more information, see Absolute maximum ratings on page 397. Writing to flash is managed by the non-volatile memory controller (NVMC).

4.2.1 Memory map

All memory and registers are found in the same address space, as illustrated in the device memory map below.



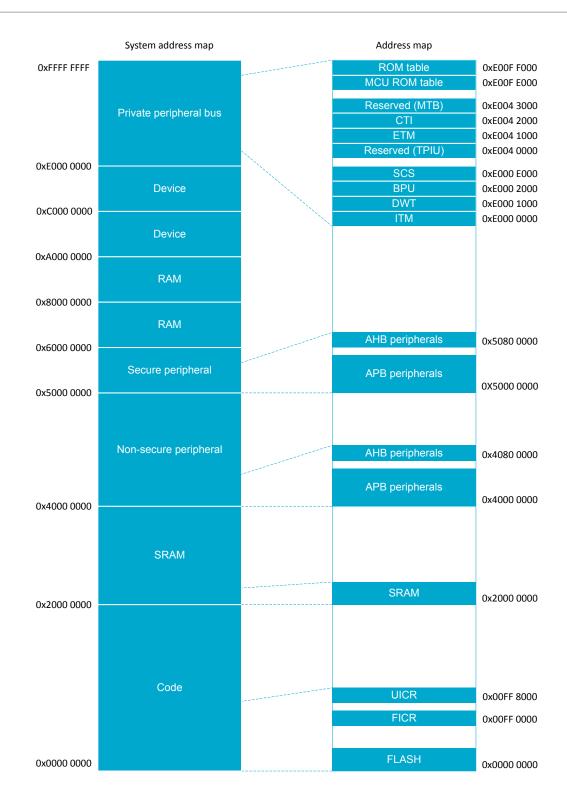


Figure 4: Memory map

Some of the registers are retained (their values kept). Read more about retained registers in Retained registers on page 61 and Reset behavior on page 61.

4.2.2 Instantiation

ID	Base address	Peripheral	Instance	Secure mapping	DMA security	Description
3	0x50003000	SPU	SPU	S	NA	System Protection Unit



Decoderation REGULATIONS REGULATIONS Name Regulators on Figuration	ID	Base address	Peripheral	Instance	Secure mapping	DMA security	Description
0.50005000 CLOCK : 5 C	4		REGULATORS			NA	Regulator configuration
5 0x50005000 0x60005000 POWER POWER INS FOWER INS US NA Power control 8 0x50008000 0x60008000 SPIM SPIMO: SS SPIMO: SS SPIMO: SS SPISO: INS US SA SPI master 0 8 0x50008000 0x60008000 SPIS SPISO: INS SPISO: INS SPISO: INS Dx60008000 US SA SPI slave 0 8 0x50008000 0x60008000 TWIM TWIMO: SS TWINO: INS TWIMO: SN Dx60008000 US SA TWO-write interface master 0 8 0x50008000 0x60008000 TWIS TWISO: SS TWING: INS UARTEO: INS Dx60008000 UARTE US SA Universal asynchronous receiver/transmitter with Easy0MAD 9 0x50008000 0x40009000 SPIM SPIRIL: S SPIRIL: S US SA SPI slave 1 0x50009000 0x40009000 SPIS SPISI: SS SPISI: INS Dx60009000 US SA TWO-wire interface master 1 0x50009000 0x40009000 TWIMI : SI Dx60009000 US SA TWO-wire interface slave 1 0x50009000 0x40009000 TWIMI : SI Dx60009000 US SA TWO-wire interface master 1 0x500000000 0x40009000 TWIS TWIS:	5	0x50005000	CLOCK	CLOCK : S		NA	Clock control
6 0.550006000 CTRLAPPEN CTRLAP_PEN S NA CTRLAP-PEN 8 0.550008000 SPIM SPIMO: S US SA SPI master 0 8 0.550008000 SPIS SPISO: S US SA SPI slave 0 8 0.55008000 TWIM TWIMO: S US SA Two-wire interface master 0 8 0.55008000 TWIM TWIMO: S US SA Two-wire interface slave 0 9 0.55008000 TWIM TWINSO: S US SA Universal asynchronous receiver/transmitter with EasyDMA: 0 9 0.55009000 TWIM SPIMI: S US SA SPI master 1 9 0.55009000 SPIM SPIMI: S US SA SPI slave 1 9 0.55009000 TWIM TWIMI: S US SA SPI slave 1 9 0.55009000 TWIMI TWIMI: S US SA Two-wire interface master 1 0.50000000 TWIMI TWIMI: S US SA </td <td>5</td> <td>0x50005000</td> <td>POWER</td> <td>POWER : S</td> <td>US</td> <td>NA</td> <td>Power control</td>	5	0x50005000	POWER	POWER : S	US	NA	Power control
8 0x40008000 SPIM SPIMO : NS US SA SPI master 0 8 0x50008000 SPIS SPISO : S SPISO : NS US SA SPI slave 0 0x50008000 TWIM TWIMO : NS US SA Two-wire interface master 0 0x50008000 TWIS TWISO : S TWISO : NS US SA Two-wire interface slave 0 0x50008000 LUARTE : TWISO : S Ox40008000 UARTE : UARTED : S UARTED : NS US SA Universal asynchronous receiver/transmitter with EasyDMA 0 9 0x50009000 SPIM : S SPIMI : NS US SA SPI master 1 9 0x50009000 SPIS : S SPISI : NS US SA SPI slave 1 9 0x50009000 TWIM : TWIMI : S TWIST : NS US SA Two-wire interface master 1 9 0x50009000 TWIS : TWIST : NS US SA Two-wire interface master 2 10 0x50004000 TWIS : TWIST : NS US SA Universal asynchronous receiver/transmitter with EasyDMA 1 10 0x50004000 TWIST : TWIST : NS	6		CTRLAPPERI		S	NA	CTRL-AP-PERI
8 Dx40008000 SPIS SPISO : NS US SA SPI slave 0 8 Dx50008000 TWIM TWIM0 : NS US SA Two-wire interface master 0 8 Dx50008000 TWIS : TWISO : NS US SA Two-wire interface slave 0 8 Dx50008000 LARTE : NS US SA Universal asynchronous receiver/transmitter with EasypMA 0 9 Dx50009000 SPIM SPIMI : NS US SA SPI master 1 9 Dx50009000 SPIS : SPIS : NS US SA SPI slave 1 9 Dx50009000 SPIS : SPIS : NS US SA SPI slave 1 9 Dx50009000 TWIM TWIMI : NS US SA Two-wire interface master 1 9 Dx50009000 TWIM TWISE : S US SA Two-wire interface master 1 9 Dx50009000 TWIM TWISE : S US SA Universal asynchronous receiver/transmitter with Easy0MA 1 10 Dx50009000 TWIM SPIMI : S	8		SPIM		US	SA	SPI master 0
8 0x40008000 TWIM TWINS : S TWINS : TWINS : S TWINS : S TWINS : TWINS :	8		SPIS		US	SA	SPI slave 0
8 0x40008000 TWIS TWISO:NS US SA Two-wire interface slave 0 8 0x50008000 UARTE UARTEC:S US SA Universal asynchronous receiver/transmitter with EasyDMA.0 9 0x50009000 SPIM SPIMI:S US SA SPI master 1 9 0x50009000 SPIS SPISI:SPIS:SPIS:NS US SA SPI slave 1 9 0x50009000 TWIM TWISI:NS US SA Two-wire interface master 1 9 0x50009000 TWIS TWISI:NS US SA Two-wire interface slave 1 9 0x50009000 TWIS TWISI:NS US SA Universal asynchronous receiver/transmitter with EasyDMA 1 10 0x40009000 UARTE UARTEL:NS US SA SPI master 2 10 0x5000A000 SPIM SPIM2:S US SA SPI master 2 10 0x5000A000 SPIS SPIS2:S US SA Two-wire interface master 2 10 0	8		TWIM		US	SA	Two-wire interface master 0
	8		TWIS		US	SA	Two-wire interface slave 0
9	8		UARTE		US	SA	
9	9		SPIM		US	SA	SPI master 1
9 0x40009000	9		SPIS		US	SA	SPI slave 1
9 0x40009000	9		TWIM		US	SA	Two-wire interface master 1
9 0x40009000 UARTE UARTE1: NS US SA with EasyDMA 1 10 0x5000A000 0x4000A000 SPIM SPIM2: S SPIM2: NS US SA SPI master 2 10 0x5000A000 0x4000A000 SPIS SPIS2: S SPIS2: NS US SA SPI slave 2 10 0x5000A000 0x4000A000 TWIM TWIM2: S TWIM2: NS US SA Two-wire interface master 2 10 0x5000A000 0x4000A000 TWIS TWIS2: S TWIS2: NS US SA Two-wire interface slave 2 10 0x5000A000 0x4000A000 UARTE UARTE2: S UARTE2: NS US SA Universal asynchronous receiver/transmitter with EasyDMA 2 11 0x5000B000 0x4000B000 SPIM SPIM3: NS SPIM3: NS US SA SPI master 3 11 0x5000B000 0x4000B000 TWIM TWIM3: NS TWIM3: NS US SA SPI slave 3 11 0x5000B000 0x4000B000 TWIS TWIS3: S TWIS3: NS US SA Two-wire interface master 3 11 0x5000B000 0x4000B000 TWIS TWIS3: S T	9		TWIS		US	SA	Two-wire interface slave 1
10	9		UARTE		US	SA	
10	10		SPIM		US	SA	SPI master 2
10	10		SPIS		US	SA	SPI slave 2
10 0x4000A000 TWIS US SA Two-wire interface slave 2 10 0x5000A000 0x4000A000 UARTE UARTE2: S UARTE2: NS US SA Universal asynchronous receiver/transmitter with EasyDMA 2 11 0x5000B000 0x4000B000 SPIM SPIM3: S SPIM3: NS US SA SPI master 3 11 0x5000B000 0x4000B000 SPIS SPIS3: S SPIS3: NS US SA SPI slave 3 11 0x5000B000 0x4000B000 TWIM TWIM3: S TWIM3: NS US SA Two-wire interface master 3 11 0x5000B000 0x4000B000 TWIS TWIS3: S TWIS3: NS US SA Two-wire interface slave 3 11 0x5000B000 0x4000B000 UARTE UARTE3: S UARTE3: NS US SA Universal asynchronous receiver/transmitter with EasyDMA 3 13 0x5000B000 0x4000B000 GPIOTE GPIOTE0 S NA Secure GPIO tasks and events 14 0x5000E000 0x4000B000 TIMER TIMERO: S US NA Timer 0	10		TWIM		US	SA	Two-wire interface master 2
10	10		TWIS		US	SA	Two-wire interface slave 2
11 0x40008000 SPIM US SA SPI master 3 11 0x50008000 SPIS SPIS3 : S US SA SPI slave 3 11 0x50008000 TWIM TWIM3 : S US SA Two-wire interface master 3 11 0x50008000 TWIS TWIS3 : S US SA Two-wire interface slave 3 11 0x50008000 UARTE UARTE3 : S US SA Universal asynchronous receiver/transmitter with EasyDMA 3 13 0x50008000 GPIOTE GPIOTE0 S NA Secure GPIO tasks and events 14 0x5000E000 SAADC : S SAADC : S SAADC : S SAADC : S 15 0x5000F000 TIMER TIMER0 : S US NA Timer 0	10		UARTE		US	SA	•
11 0x4000B000 SPIS US SA SPI slave 3 11 0x5000B000 0x4000B000 TWIM TWIM3:S TWIM3:NS US SA Two-wire interface master 3 11 0x5000B000 0x4000B000 TWIS TWIS3:S TWIS3:NS US SA Two-wire interface slave 3 11 0x5000B000 0x4000B000 UARTE UARTE3:NS US SA Universal asynchronous receiver/transmitter with EasyDMA 3 13 0x5000D000 GPIOTE GPIOTE0 S NA Secure GPIO tasks and events 14 0x5000E000 0x4000E000 SAADC:S SAADC:NS US SA Analog to digital converter 15 0x5000F000 TIMER TIMERO:S US NA Timer 0	11		SPIM		US	SA	SPI master 3
11 TWIM US SA Two-wire interface master 3 11 0x5000B000 0x4000B000 TWIS TWIS3:S TWIS3:NS US SA Two-wire interface slave 3 11 0x5000B000 0x4000B000 UARTE UARTE3:S UARTE3:NS US SA Universal asynchronous receiver/transmitter with EasyDMA 3 13 0x5000D000 GPIOTE GPIOTE0 S NA Secure GPIO tasks and events 14 0x5000E000 0x4000E000 SAADC:S SAADC:NS US SA Analog to digital converter 15 TIMER TIMERO:S US NA Timer 0	11		SPIS		US	SA	SPI slave 3
11 0x4000B000 TWIS US SA Two-wire interface slave 3 11 0x5000B000 0x4000B000 UARTE UARTE3 : S UARTE3 : NS US SA Universal asynchronous receiver/transmitter with EasyDMA 3 13 0x5000D000 GPIOTE GPIOTE0 S NA Secure GPIO tasks and events 14 0x5000E000 0x4000E000 SAADC : S SAADC : NS US SA Analog to digital converter 15 0x5000F000 TIMER US NA Timer 0	11		TWIM		US	SA	Two-wire interface master 3
11 0x4000B000 UARTE US SA 13 0x5000D000 GPIOTE GPIOTE0 S NA Secure GPIO tasks and events 14 0x5000E000 0x4000E000 SAADC : S SAADC : NS US SA Analog to digital converter 15 0x5000F000 TIMER US NA Timer 0	11		TWIS		US	SA	Two-wire interface slave 3
14	11		UARTE		US	SA	
14	13	0x5000D000	GPIOTE	GPIOTE0	S	NA	Secure GPIO tasks and events
15 TIMER US NA Timer 0	14		SAADC		US	SA	Analog to digital converter
	15		TIMER		US	NA	Timer 0



	ID	Base address	Peripheral	Instance	Secure mapping	DMA security	Description
12		0x50010000		TIMER1 : S			
17	16	0x40010000	TIMER	TIMER1 : NS	US	NA	Timer 1
Decided 1900 Process				TIMER2 : S			
Deconsider National Property National P	17	0x40011000	TIMER	TIMER2 : NS	US	NA	Timer 2
Oxfo015000		0x50014000		RTC0 : S			
21	20	0x40014000	RTC	RTC0 : NS	US	NA	Real time counter 0
Description Particle Partic		0x50015000		RTC1:S			
23	21	0x40015000	RTC	RTC1 : NS	US	NA	Real time counter 1
23							
Discollation Wolf Wolf S US	23		DPPIC		SPLIT	NA	DPPI configuration
24				WDT : S			
27	24		WDT		US	NA	Watchdog timer
27							
28	27		EGU		US	NA	Event generator unit 0
28							
29	28		EGU		US	NA	Event generator unit 1
29							
10	29		EGU		US	NA	Event generator unit 2
0x4001E000							
10	30		EGU		US	NA	Event generator unit 3
1							
0x50020000	31		EGU		US	NA	Event generator unit 4
Section Sect							
Note	32		EGU	1 2U	NA	Event generator unit 5	
33 0x40021000 PWM PWM0 : NS US SA Pulse width modulation unit 0 34 0x50022000 PWM PWM1 : S US SA Pulse width modulation unit 1 35 0x50023000 PWM PWM2 : S US SA Pulse width modulation unit 2 36 0x50024000 PWM PWM3 : NS US SA Pulse width modulation unit 3 36 0x50024000 PWM PWM3 : NS US SA Pulse density modulation unit 3 38 0x50026000 PDM PDM : S US SA Pulse density modulation (digital microphone) interface 40 0x50028000 12S 12S : S US SA Inter-IC Sound 42 0x50028000 1PC IPC : S US NA Inter-IC Sound 43 0x50022000 PPU FPU : S US NA Floating-point unit 49 0x40025000 FPU FPU : S NA NA Nosecure GPIO tasks and events 57 0x5003							
No.	33		PWM		US	SA	Pulse width modulation unit 0
National Content National Co							
Section Sect	34		PWM		US	SA	Pulse width modulation unit 1
Nation N							
No.	35		PWM		US	SA	Pulse width modulation unit 2
36 0x40024000 PWM PWM3 : NS US SA Pulse width modulation unit 3 38 0x50026000 PDM PDM : S US SA Pulse density modulation (digital microphone) interface 40 0x50028000 12S IZS : S US SA Interface 42 0x5002A000 IPC IPC : S US NA Interprocessor communication 44 0x5002C000 0x4002C000 FPU FPU : S US NA Floating-point unit 49 0x40031000 GPIOTE GPIOTE1 NS NA Non Secure GPIO tasks and events 57 0x50039000 0x40039000 KMU : S SPLIT NA Key management unit 57 0x50039000 0x40039000 NVMC : S SPLIT NA Non-volatile memory controller 58 0x5003A000 0x4003A000 VMC VMC : S VMC : S NA Volatile memory controller 64 0x50840000 CC_HOST_RGF CC_HOST_RGF S NSA Host platform interface							
National Content National Co	36		PWM		US	SA	Pulse width modulation unit 3
38 DAMOUZEGOOD PDM US SA interface 40 0x50028000 0x40028000 12S 12S : S US SA Inter-IC Sound 42 0x50028000 0x4002A000 IPC IPC : S IPC : NS US NA Interprocessor communication 44 0x5002C000 0x4002C000 FPU FPU : S FPU : NS US NA Floating-point unit 49 0x40031000 GPIOTE GPIOTE1 NS NA Non Secure GPIO tasks and events 57 0x50039000 0x40039000 KMU KMU : S KMU : NS SPLIT NA Non-volatile memory controller 58 0x50034000 VMC VMC : S VMC : NS US NA Volatile memory controller 64 0x50840000 CC_HOST_RGF CC_HOST_RGF S NSA Host platform interface 64 0x50842500 0x40842500 GPIO P0 : S P0 : NS SPLIT NA General purpose input and output N/A 0x00FF0000 FICR FICR S NA Factory information configuration							
A0	38		PDM		US	SA	, , , , , , , , , , , , , , , , , , , ,
125							іптеггасе
A2	40		I2S		US	SA	Inter-IC Sound
PC							
A4	42		IPC		US	NA	Interprocessor communication
44 0x4002C000 FPU NS VS NA Floating-point unit 49 0x40031000 GPIOTE GPIOTE1 NS NA Non Secure GPIO tasks and events 57 0x50039000 0x40039000 KMU KMU : S KMU : NS SPLIT NVMC : S NA Key management unit 57 0x50039000 0x40039000 NVMC NVMC : NS SPLIT NVMC : NS NA Non-volatile memory controller 58 0x5003A000 0x4003A000 VMC VMC : S VMC : NS US VMC : NS NA Volatile memory controller 64 0x50840000 CC_HOST_RGF CC_HOST_RGF S NSA Host platform interface 64 0x50840000 CRYPTOCELL CRYPTOCELL S NSA CryptoCell sub-system control interface 66 0x50842500 0x40842500 GPIO PO : S PO : NS SPLIT PO : NS NA General purpose input and output N/A 0x00FF0000 FICR FICR S NA Factory information configuration							
49 0x40031000 GPIOTE GPIOTE1 NS NA Non Secure GPIO tasks and events 57 0x50039000 0x40039000 KMU : NS SPLIT KMU : NS NA Key management unit 57 0x50039000 0x40039000 NVMC NVMC : S NVMC : NS SPLIT NA NA Non-volatile memory controller 58 0x5003A000 0x4003A000 VMC VMC : S VMC : NS US VMC : NS NA Volatile memory controller 64 0x50840000 CC_HOST_RGF CC_HOST_RGF S NSA Host platform interface 64 0x50840000 CRYPTOCELL CRYPTOCELL S NSA CryptoCell sub-system control interface 66 0x50842500 0x40842500 GPIO P0 : S P0 : NS SPLIT NA NA General purpose input and output N/A 0x00FF0000 FICR FICR S NA Factory information configuration	44		FPU		US	NA	Floating-point unit
57 0x50039000 Ox40039000 Ox40039000 KMU : NS SPLIT NA NA Key management unit 57 0x50039000 Ox40039000 Ox40039000 NVMC NVMC : S NVMC : NS NA Non-volatile memory controller 58 0x5003A000 Ox4003A000 Ox4003A000 VMC : S VMC : NS US NSA NA Volatile memory controller 64 0x50840000 Ox50840000 Ox7000 Ox70000 Ox70000 Ox70000 Ox70000 Ox70000 Ox70000 Ox70000 Ox70000 Ox700000 Ox70000 Ox70000 Ox70000 Ox70000 Ox70000 Ox70000 Ox70000 Ox70000 Ox70000 Ox700000 Ox7000000 Ox7000000 Ox7000000 Ox7000000 Ox700000 Ox7000000 Ox700000 Ox700000 Ox700000 Ox700000 Ox7000000 Ox700000 Ox7000000 Ox7000000 Ox700000 Ox700000 Ox7000000 Ox700000 Ox700000 Ox700000 Ox700000 Ox700000 Ox7000000 Ox70000000 Ox7000000 Ox7000000 Ox7000000 Ox70000000 Ox7000000 Ox70000000 Ox7000000 Ox7000000 Ox70000000 Ox70000000 Ox7000000 Ox70000000 Ox7000000 Ox70000000 Ox70000000 Ox700000000 Ox70000000 Ox700000000 Ox7000000 Ox70000000 Ox700000000 Ox70000000 Ox700000000 Ox							
57 0x40039000 KMU KMU : NS SPLIT NA Key management unit 57 0x50039000 0x40039000 NVMC NVMC : S VMC : NS SPLIT NVMC : NS NA Non-volatile memory controller 58 0x5003A000 0x4003A000 VMC VMC : S VMC : NS US NA Volatile memory controller 64 0x50840000 CC_HOST_RGF CC_HOST_RGF S NSA Host platform interface 64 0x50840000 CRYPTOCELL CRYPTOCELL S NSA CryptoCell sub-system control interface 66 0x50842500 0x40842500 P0 : S SPLIT NA General purpose input and output N/A 0x00FF0000 FICR FICR S NA Factory information configuration	49		GPIOTE		NS	NA	Non Secure GPIO tasks and events
57 0x50039000 0x40039000 NVMC NVMC : NS SPLIT NA Non-volatile memory controller 58 0x5003A000 0x4003A000 VMC VMC : NS US NA Volatile memory controller 64 0x50840000 CC_HOST_RGF CC_HOST_RGF S NSA Host platform interface 64 0x50840000 CRYPTOCELL CRYPTOCELL S NSA CryptoCell sub-system control interface 66 0x50842500 0x40842500 GPIO P0 : S SPLIT NA General purpose input and output N/A 0x00FF0000 FICR FICR S NA Factory information configuration	57		KMU		SPLIT	NA	Key management unit
57							
0x40039000 NVMC : NS 58 0x5003A000 0x4003A000 VMC : S VMC : NS US VMC : NS NA Volatile memory controller 64 0x50840000 CC_HOST_RGF CC_HOST_RGF S NSA Host platform interface 64 0x50840000 CRYPTOCELL CRYPTOCELL S NSA CryptoCell sub-system control interface 66 0x50842500 0x40842500 GPIO 0x40842500 P0 : NS SPLIT P0 : NS NA General purpose input and output N/A 0x00FF0000 FICR FICR S NA Factory information configuration	57		NVMC		SPLIT	NA	Non-volatile memory controller
58							
0x4003A000 VMC : NS 64 0x50840000 CC_HOST_RGF CC_HOST_RGF S NSA Host platform interface 64 0x50840000 CRYPTOCELL S NSA CryptoCell sub-system control interface 66 0x50842500 P0 : S SPLIT NA General purpose input and output N/A 0x00FF0000 FICR FICR S NA Factory information configuration	58		VMC		US	NA	Volatile memory controller
64 0x50840000 CRYPTOCELL CRYPTOCELL S NSA CryptoCell sub-system control interface 66 0x50842500 GPIO P0 : S 0x40842500 P0 : NS N/A 0x00FF0000 FICR FICR S NA Factory information configuration							·
66 0x50842500 GPIO PO : S Ox40842500 PO : NS N/A 0x00FF0000 FICR FICR S NA Factory information configuration		0x50840000	CC_HOST_RGF	CC_HOST_RGF	S	NSA	Host platform interface
66 GPIO SPLIT NA General purpose input and output N/A 0x00FF0000 FICR FICR S NA Factory information configuration	64		CRYPTOCELL		S	NSA	CryptoCell sub-system control interface
0x40842500 P0 : NS N/A 0x00FF0000 FICR FICR S NA Factory information configuration	66	0x50842500	GPIO		SPLIT	NA	General purpose input and output
	-	0x40842500					
N/A 0x00FF8000 UICR UICR S NA User information configuration	N/A	0x00FF0000	FICR	FICR	S	NA	Factory information configuration
	N/A	0x00FF8000	UICR	UICR	S	NA	User information configuration



ID	Base address	Peripheral	Instance	Secure mapping	DMA security	Description
N/A	0xE0080000	TAD	TAD	S	NA	Trace and debug control

Table 4: Instantiation table

4.2.3 Peripheral access control capabilities

Information about the peripheral access control capabilities can be found in the instantiation table.

The instantiation table has two columns containing the information about access control capabilities for a peripheral:

- Secure mapping: This column defines configuration capabilities for TrustZone-M secure attribute.
- DMA security: This column indicates if the peripheral has DMA capabilities, and if DMA transfer can be assigned to a different security attribute than the peripheral itself.

For details on options in secure mapping column and DMA security column, see the following tables respectively.

Abbreviation	Description
NS	Non-secure: This peripheral is always accessible as a non-secure peripheral.
S	Secure: This peripheral is always accessible as a secure peripheral.
US	User-selectable: Non-secure or secure attribute for this peripheral is defined by the PERIPHID[0].PERM register.
SPLIT	Both non-secure and secure: The same resource is shared by both secure and non-secure code.

Table 5: Secure mapping column options

Abbreviation	Description
NA	Not applicable: Peripheral has no DMA capability.
NSA	No separate attribute: Peripheral has DMA, and DMA transfers always have the same security attribute as assigned to the peripheral.
SA	Separate attribute: Peripheral has DMA, and DMA transfers can have a different security attribute than the one assigned to the peripheral.

Table 6: DMA security column options

4.3 VMC — Volatile memory controller

The volatile memory controller (VMC) provides power control of RAM blocks.

Each of the available RAM blocks, which can contain multiple RAM sections, can be turned on or off independently in System ON mode, using the RAM[n]registers. These registers also control if a RAM block, or some of its sections, is retained in System OFF mode. See Memory chapter for more information about RAM blocks and sections.

Note: Powering up a RAM block takes typically 10 cycles. Thus, it is recommended reading the POWER register before accessing a RAM block that has been recently powered on.



4.3.1 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x5003A000	VMC : S		uc	NA	Valatila sa	
0x4003A000	VIVIC	VMC : NS	US	NA	Volatile memory controller	

Table 7: Instances

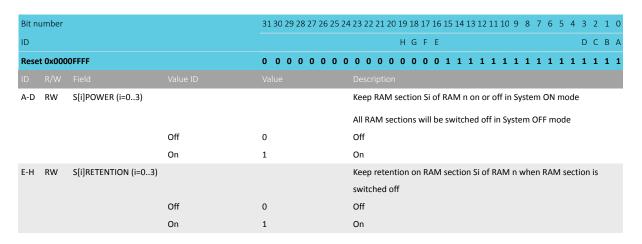
Register	Offset	Security	Description
RAM[n].POWER	0x600		RAMn power control register
RAM[n].POWERSET	0x604		RAMn power control set register
RAM[n].POWERCLR	0x608		RAMn power control clear register

Table 8: Register overview

4.3.1.1 RAM[n].POWER (n=0..7)

Address offset: $0x600 + (n \times 0x10)$

RAMn power control register



4.3.1.2 RAM[n].POWERSET (n=0..7)

Address offset: $0x604 + (n \times 0x10)$ RAMn power control set register

When read, this register will return the value of the POWER register.

Bit number				31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID	ID				H G F E D C B A
Rese	Reset 0x0000FFFF			0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 1 1 1 1 1 1 1 1 1 1 1 1
ID					
A-D	W	S[i]POWER (i=03)	POWER (i=03)		Keep RAM section Si of RAM n on or off in System ON mode
			On	1	On
E-H	W	S[i]RETENTION (i=03)			Keep retention on RAM section Si of RAM n when RAM section is
					switched off
			On	1	On



4.3.1.3 RAM[n].POWERCLR (n=0..7)

Address offset: $0x608 + (n \times 0x10)$

RAMn power control clear register

When read, this register will return the value of the POWER register.

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					H G F E D C B A
Rese	Reset 0x0000FFFF			0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 1 1 1 1 1 1 1 1 1 1 1
ID					
A-D	W	S[i]POWER (i=03)			Keep RAM section Si of RAM n on or off in System ON mode
			Off	1	Off
E-H	W	S[i]RETENTION (i=03)			Keep retention on RAM section Si of RAM n when RAM section is
					switched off

4.4 NVMC — Non-volatile memory controller

The non-volatile memory controller (NVMC) is used for writing and erasing of the internal flash memory and the user information configuration register (UICR).

The NVMC is a split security peripheral. This means that when the NVMC is configured as non-secure, only a subset of the registers is available from the non-secure code. See SPU — System protection unit on page 264 and Registers on page 34 for more details.

When the NVMC is configured to be a secure peripheral, only secure code has access.

Before a write can be performed, the NVMC must be enabled for writing in CONFIG.WEN. Similarly, before an erase can be performed, the NVMC must be enabled for erasing in CONFIG.EEN, see CONFIG on page 35. The user must make sure that writing and erasing are not enabled at the same time. Failing to do so may result in unpredictable behavior.

4.4.1 Writing to flash

When writing is enabled, in CONFIG register for secure region, or in CONFIGNS register for non-secure region, flash is written by writing a full 32-bit word to a word-aligned address in flash.

Secure code has access to both secure and non-secure regions, by using the appropriate configuration of CONFIG and CONFIGNS registers. Non-secure code, in constrast, has access to non-secure regions only. Thus, non-secure code only needs CONFIGNS.

The NVMC is only able to write '0' to erased bits in flash, that is bits set to '1'. It cannot write a bit back to '1'.

As illustrated in Memory on page 23, flash is divided into multiple pages. The same address in flash can only be written n_{WRITE} number of times before a page erase must be performed.

Only full 32-bit words can be written to flash using the NVMC interface. To write less than 32 bits to flash, write the data as a word, and set all the bits that should remain unchanged in the word to '1'. Note that the restriction about the number of writes (see above) still applies in this case.

The time it takes to write a word to flash is specified by t_{WRITE} . If CPU executes code from flash while the NVMC is writing to flash, the CPU will be stalled.

Only word-aligned writes are allowed. Byte or half-word-aligned writes will result in a bus fault.



4.4.2 Erasing a secure page in flash

When secure region erase is enabled (in CONFIG register), a flash page can be erased by writing 0xFFFFFFFF into the first 32-bit word in a flash page.

Page erase is only applicable to the code area in the flash and does not work with UICR.

After erasing a flash page, all bits in the page are set to '1'. The time it takes to erase a page is specified by $t_{\sf ERASEPAGE}$. The CPU is stalled if the CPU executes code from the flash while the NVMC performs the erase operation.

See Partial erase of a page in flash for information on splitting the erase time in smaller chunks.

4.4.3 Erasing a non-secure page in flash

When non-secure region erase is enabled, a non-secure flash page can be erased by writing 0xFFFFFFF into the first 32-bit word of the flash page.

Page erase is only applicable to the code area in the flash and does not work with UICR.

After erasing a flash page, all bits in the page are set to '1'. The time it takes to erase a page is specified by $t_{\text{ERASEPAGE}}$. The CPU is stalled if the CPU executes code from the flash while the NVMC performs the erase operation.

4.4.4 Writing to user information configuration registers (UICR)

User information configuration registers (UICR) are written in the same way as flash. After UICR has been written, the new UICR configuration will only take effect after a reset.

UICR is only accessible by secure code. Any write from non-secure code will be faulted.

In order to lock the chip after uploading non-secure code, a simple sequence must be followed:

- 1. Block access to secure code by setting UICR register SECUREAPPROTECT on page 45 to protected
- 2. Use the WRITEUICRNS on page 37 register, via non-secure debugger, in order to set APPROTECT (APPROTECT is automatically written to 0x00000000 by the NVMC)

UICR can only be written nwRITE number of times before an erase must be performed using ERASEALL.

The time it takes to write a word to the UICR is specified by t_{WRITE} . The CPU is stalled if the CPU executes code from the flash while the NVMC is writing to the UICR.

4.4.5 Frase all

When erase is enabled, the whole flash and UICR can be erased in one operation by using the ERASEALL register. ERASEALL will not erase the factory information configuration registers (FICR).

This functionality can be blocked by some configuration of the UICR protection bits, see the table NVMC protection (1 - Enabled, 0 - Disabled, X - Don't care) on page 33.

The time it takes to perform an ERASEALL on page 35 command is specified by t_{ERASEALL} . The CPU is stalled if the CPU executes code from the flash while the NVMC performs the erase operation.

4.4.6 NVMC protection mechanisms

This chapter describes the different protection mechanisms for the non-volatile memory.

4.4.6.1 NVMC blocking

UICR integrity is assured through use of multiple levels of protection. UICR protection bits can be configured to allow or block certain operations.

The table below shows the different status of UICR protection bits, and which operations are allowed or blocked.



	UICR protection bit	NVMC protection		
SECUREAPPRO	TECT APPROTECT	ERASEPROTECT	CTRL-AP	NVMC
			ERASEALL	ERASEALL
0	0	0	Available	Available
1	X	0	Available	Blocked
X	1	0	Available	Blocked
Χ	X	1	Blocked	Blocked

Table 9: NVMC protection (1 - Enabled, 0 - Disabled, X - Don't care)

Note: Erase can still be performed through CTRL-AP, regardless of the above settings. See CTRL-AP - Control access port on page 377 for more information.

Uploading code with secure debugging blocked

Non-secure code can program non-secure flash regions. In order to perform these operations, the NVMC has the following non-secure registers: CONFIGNS, READY and READYNEXT.

Register CONFIGNS on page 36 works as the CONFIG register but it is used only for non-secure transactions. Both page erase and writing inside the flash require a write transaction (see Erasing a secure page in flash on page 32 or Erasing a non-secure page in flash on page 32). Because of this, the SPU — System protection unit on page 264 will guarantee that the non-secure code cannot write inside a secure page, since the transaction will never reach the NVMC controller.

4.4.6.2 NVMC power failure protection

NVMC power failure protection is possible through use of power-fail comparator that is monitoring power supply.

If the power-fail comparator is enabled, and the power supply voltage is below V_{POF} threshold, the power-fail comparator will prevent the NVMC from performing erase or write operations in non-volatile memory (NVM).

If a power failure warning is present at the start of an NVM write or erase operation, the NVMC will block the operation and a bus error will be signalled. If a power failure warning occurs during an ongoing NVM write operation, the NVMC will try to finish the operation. And if the power failure warning persists, consecutive NVM write operations will be blocked by the NVMC, and a bus error will be signalled. If a power failure warning occurs during an NVM erase operation, the operation is aborted and a bus error is signalled.

4.4.7 Cache

An instruction cache (I-Cache) can be enabled for the ICODE bus in the NVMC.

See Memory map on page 25 for the location of flash.

A cache hit is an instruction fetch from the cache, and it has a 0 wait-state delay. The number of wait-states for a cache miss, where the instruction is not available in the cache and needs to be fetched from flash, depends on the processor frequency, see CPU parameter W_FLASHCACHE.

Enabling the cache can increase the CPU performance, and reduce power consumption by reducing the number of wait cycles and the number of flash accesses. This will depend on the cache hit rate. Cache draws current when enabled. If the reduction in average current due to reduced flash accesses is larger than the cache power requirement, the average current to execute the program code will be reduced.

When disabled, the cache does not draw current and its content is not retained.



It is possible to enable cache profiling to analyze the performance of the cache for your program using the register ICACHECNF. When profiling is enabled, registers IHIT and IMISS are incremented for every instruction cache hit or miss respectively.

4.4.8 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x50039000	NVMC	NVMC : S	SPLIT	NA	Non-volatile memory	
0x40039000		NVMC : NS	Jr Lii		controller	

Table 10: Instances

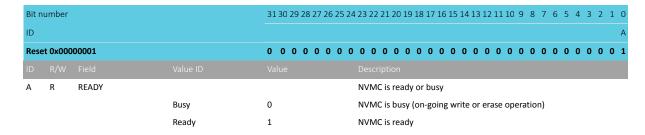
Register	Offset	Security	Description
READY	0x400	NS	Ready flag
READYNEXT	0x408	NS	Ready flag
CONFIG	0x504	S	Configuration register
ERASEALL	0x50C	S	Register for erasing all non-volatile user memory
ERASEPAGEPARTIALCFG	0x51C	S	Register for partial erase configuration
ICACHECNF	0x540	S	I-code cache configuration register
IHIT	0x548	S	I-code cache hit counter
IMISS	0x54C	S	I-code cache miss counter
CONFIGNS	0x584	NS	
WRITEUICRNS	0x588	NS	Non-secure APPROTECT enable register

Table 11: Register overview

4.4.8.1 READY

Address offset: 0x400

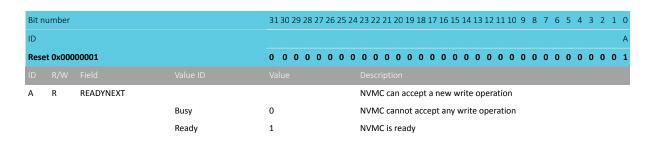
Ready flag



4.4.8.2 READYNEXT

Address offset: 0x408

Ready flag



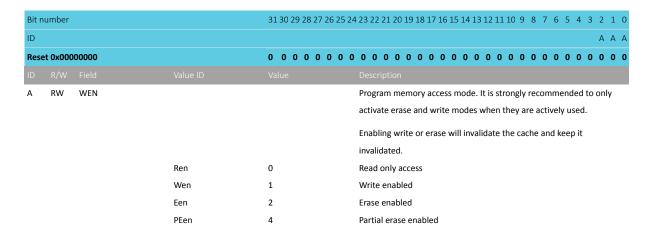




4.4.8.3 CONFIG

Address offset: 0x504 Configuration register

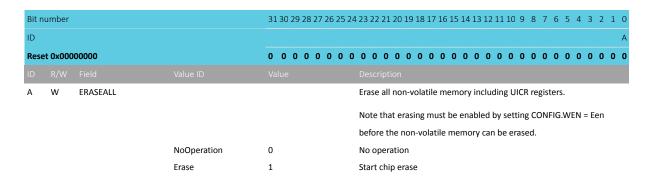
Note: This register is one hot



4.4.8.4 ERASEALL

Address offset: 0x50C

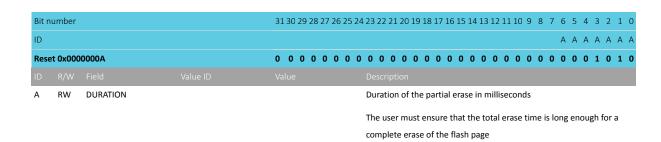
Register for erasing all non-volatile user memory



4.4.8.5 ERASEPAGEPARTIALCFG

Address offset: 0x51C

Register for partial erase configuration

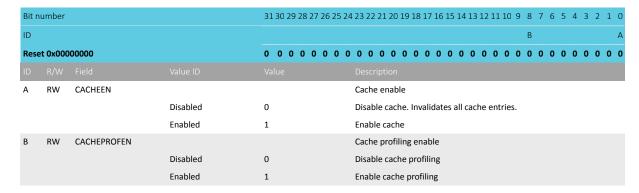


4.4.8.6 ICACHECNF

Address offset: 0x540



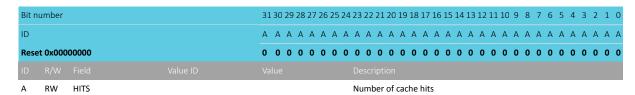
I-code cache configuration register



4.4.8.7 IHIT

Address offset: 0x548

I-code cache hit counter

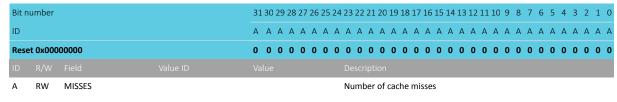


Write zero to clear

4.4.8.8 IMISS

Address offset: 0x54C

I-code cache miss counter



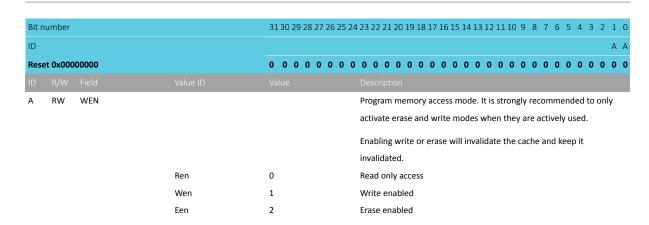
Write zero to clear

4.4.8.9 CONFIGNS

Address offset: 0x584

Note: This register is one hot

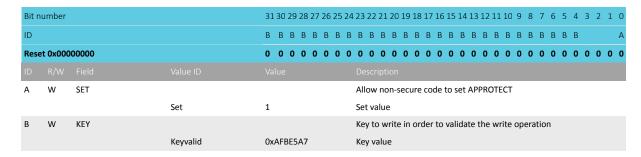




4.4.8.10 WRITEUICRNS

Address offset: 0x588

Non-secure APPROTECT enable register



4.4.9 Electrical specification

4.4.9.1 Flash programming

Symbol	Description	Min.	Тур.	Max.	Units
n _{WRITE}	Number of times a 32-bit word can be written before erase			2	
n _{ENDURANCE}	Erase cycles per page	10,000			
t _{WRITE}	Time to write one 32-bit word			43	μs
t _{ERASEPAGE}	Time to erase one page			87	ms
t _{ERASEALL}	Time to erase all flash			173	ms
t _{ERASEPAGEPARTIAL,se}	tul Setup time for one partial erase			1.08	ms

4.4.9.2 Cache size

Symbol	Description	Min.	Тур.	Max.	Units
Sizercone	I-Code cache size		2048		Bytes

4.5 FICR — Factory information configuration registers

Factory information configuration registers (FICR) are pre-programmed in factory and cannot be erased by the user. These registers contain chip-specific information and configuration.





4.5.1 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x00FF0000	FICR	FICR	S	NA	Factory information	
					configuration	

Table 12: Instances

Register	Offset	Security	Description
SIPINFO.PARTNO	0x140		SIP part number
SIPINFO.HWREVISION[n]	0x144		SIP hardware revision, encoded in ASCII, ex B0A or B1A
SIPINFO.VARIANT[n]	0x148		SIP VARIANT, encoded in ASCII, ex SIAA, SIBA or SICA
INFO.DEVICEID[n]	0x204		Device identifier
INFO.RAM	0x218		RAM variant
INFO.FLASH	0x21C		Flash variant
INFO.CODEPAGESIZE	0x220		Code memory page size
INFO.CODESIZE	0x224		Code memory size
INFO.DEVICETYPE	0x228		Device type
TRIMCNF[n].ADDR	0x300		Address
TRIMCNF[n].DATA	0x304		Data
TRNG90B.BYTES	0xC00		Amount of bytes for the required entropy bits
TRNG90B.RCCUTOFF	0xC04		Repetition counter cutoff
TRNG90B.APCUTOFF	0xC08		Adaptive proportion cutoff
TRNG90B.STARTUP	0xC0C		Amount of bytes for the startup tests
TRNG90B.ROSC1	0xC10		Sample count for ring oscillator 1
TRNG90B.ROSC2	0xC14		Sample count for ring oscillator 2
TRNG90B.ROSC3	0xC18		Sample count for ring oscillator 3
TRNG90B.ROSC4	0xC1C		Sample count for ring oscillator 4

Table 13: Register overview

4.5.1.1 SIPINFO.PARTNO

Address offset: 0x140

SIP part number



4.5.1.2 SIPINFO.HWREVISION[n] (n=0..3)

Address offset: $0x144 + (n \times 0x1)$

SIP hardware revision, encoded in ASCII, ex BOA or B1A

Note: When treated as a c-string, content is not NULL-terminated





4.5.1.3 SIPINFO.VARIANT[n] (n=0..3)

Address offset: $0x148 + (n \times 0x1)$

SIP VARIANT, encoded in ASCII, ex SIAA, SIBA or SICA

Note: When treated as a c-string, content is not NULL-terminated



4.5.1.4 INFO.DEVICEID[n] (n=0..1)

Address offset: $0x204 + (n \times 0x4)$

Device identifier



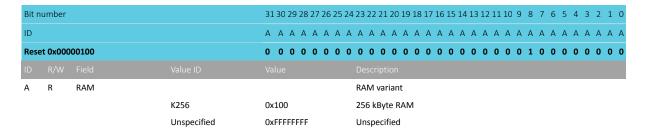
DEVICEID[0] contains the least significant bits of the device identifier.

DEVICEID[1] contains the most significant bits of the device identifier.

4.5.1.5 INFO.RAM

Address offset: 0x218

RAM variant



4.5.1.6 INFO.FLASH

Address offset: 0x21C

Flash variant





ID				A A A A A A	A A A A A A A A A A A A A A A A A A A
Rese	t 0x000	00400		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	R	FLASH			Flash variant
			K1024	0x400	1 MByte FLASH

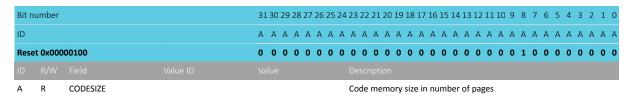
4.5.1.7 INFO.CODEPAGESIZE

Address offset: 0x220 Code memory page size

Bit n	umber		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			A A A A A A	A A A A A A A A A A A A A A A A A A A
Rese	t 0x000	01000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 1 0 0 0 0 0 0 0
ID				
Α	R	CODEPAGESIZE		Code memory page size

4.5.1.8 INFO.CODESIZE

Address offset: 0x224 Code memory size



Total code space is: CODEPAGESIZE * CODESIZE

4.5.1.9 INFO.DEVICETYPE

Address offset: 0x228

Device type

Bit n	umber			31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A A A A A A	A A A A A A A A A A A A A A A A A A A
Rese	t OxFFF	FFFFF		1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID					
Α	R	DEVICETYPE			Device type
			Die	0x0000000	Device is an physical DIE
			FPGA	0xFFFFFFF	Device is an FPGA

4.5.1.10 TRIMCNF[n].ADDR (n=0..255)

Address offset: $0x300 + (n \times 0x8)$

Address





ID R/W Field Value ID Value Description	
Reset 0xFFFFFFF 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID A A A A A A A A A A A A A A A A A A A	A A A A A A A A A A A A A A A A A A A
Bit number 31 30 29 28 27 26 25 24 23 22 21 20 19 3	8 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

4.5.1.11 TRIMCNF[n].DATA (n=0..255)

Address offset: $0x304 + (n \times 0x8)$

Data

Rese	t OxFFF				1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID	R/W	Field	Value ID	Value	Description

4.5.1.12 TRNG90B.BYTES

Address offset: 0xC00

Amount of bytes for the required entropy bits

Bit r	umber		313	0 29	28	27 2	26 2	5 2	4 2	3 22	2 2:	1 20	19	18 :	17 1	6 1	5 14	13	12 1	111	0 9	8	7	6	5 -	4 3	2	1	O
ID			A A	4 A	Α	Α.	Α ,	4 /	4 /	4 A	A	. A	Α	Α	A	Δ Δ	A	Α	Α	A A	A A	Α	Α	Α	Α.	A A	A	Α	Δ
Rese	et OxFFF	FFFFF	1 1	1 1	1	1	1 :	1 1	1 :	1 1	. 1	1	1	1	1 :	1 1	. 1	1	1	1 1	l 1	1	1	1	1	1 1	. 1	1	1
ID																													
Α	R	BYTES							Α	mo	unt	of	byt	es fo	or tl	ne r	equ	ired	l en	trop	y bi	ts							

4.5.1.13 TRNG90B.RCCUTOFF

Address offset: 0xC04
Repetition counter cutoff

Bit n	umber		31 30 29 28 27 26 2	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			A A A A A A	
Rese	t OxFFF	FFFFF	1 1 1 1 1 1 :	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID				
Α	R	RCCUTOFF		Repetition counter cutoff

4.5.1.14 TRNG90B.APCUTOFF

Address offset: 0xC08

Adaptive proportion cutoff



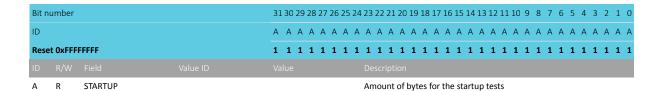
A R APCUTOFF Adaptive proportion cutoff



4.5.1.15 TRNG90B.STARTUP

Address offset: 0xC0C

Amount of bytes for the startup tests



4.5.1.16 TRNG90B.ROSC1

Address offset: 0xC10

Sample count for ring oscillator 1

Α	R	ROSC1								San	nple	e co	unt	for	ring	os	cilla	tor :	1										
ID																													
Res	et OxFFF	FFFFF	1	1 :	1 1	1	1	1	1	1	1 :	1 1	. 1	1	1	1	1 1	. 1	1	1	1 1	. 1	1	1	1	1	1 1	1	1
ID			Α .	A A	A A	AA	Α	Α	Α	Α.	Α /	4 Α	A	Α	Α	Α.	A A	A	Α	Α	A A	A	Α	Α	Α	Α.	A A	A	Α
Bit r	number		313	30 2	29 2	8 27	26	25	24 2	23 2	22 2	1 2	0 19	18	17	16 1	15 1	4 13	12	11 :	10 9	8	7	6	5	4	3 2	2 1	0

4.5.1.17 TRNG90B.ROSC2

Address offset: 0xC14

Sample count for ring oscillator 2

Α	R	ROSC2							Sa	amp	le c	oui	nt fo	r ri	ng c	scil	lato	r 2										
ID																												
Res	et OxFFF	FFFFF	1 1	l 1	1	1	1 1	l 1	. 1	1	1	1	1	1 1	l 1	1	1	1	1 1	1	1	1	1	1	1	1 1	1	1 1
ID			A A	A A	Α	Α.	A A	Α Α	A	Α	Α	Α	A	Δ /	A A	Α	Α	Α.	А А	A	Α	Α	Α	Α	A	A A	Α	A A
Bit r	number		313	0 29	28	27 2	26 2	5 24	4 23	3 22	21	20	19 1	.8 1	7 16	15	14	13 1	.2 13	1 10	9	8	7	6	5 4	4 3	2	1 0

4.5.1.18 TRNG90B.ROSC3

Address offset: 0xC18

Sample count for ring oscillator 3

Bit n	umber		31	30 29	9 28	27	26 2	25 2	24 2	3 2:	2 21	1 20	19	18 1	7 1	6 15	14	13	12 1	1 1	0 9	8	7	6	5	4	3 2	2 1	0
ID			Α	А А	A	Α	Α	Α	A .	ДД	A	A	Α	Α,	A A	A	Α	Α	Α,	Δ Δ	A A	A	Α	Α	Α	Α,	4 Δ	A A	Α
Rese	t OxFFF	FFFFF	1	1 1	. 1	1	1	1	1	1 1	. 1	1	1	1	1 1	. 1	1	1	1	1 1	1	1	1	1	1	1 :	1 1	l 1	1
ID																													
Α	R	ROSC3							9	am	ole	cou	nt f	or ri	ing	osci	llate	or 3											

4.5.1.19 TRNG90B.ROSC4

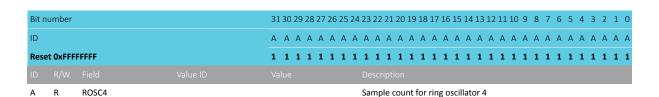
Address offset: 0xC1C

4418_1315 v2.1

Sample count for ring oscillator 4

42





4.6 UICR — User information configuration registers

The user information configuration registers (UICRs) are non-volatile memory (NVM) registers for configuring user specific settings.

For information on writing UICR registers, see the NVMC — Non-volatile memory controller on page 31 and Memory on page 23 chapters.

4.6.1 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x00FF8000	UICR	UICR	S	NA	User information	
					configuration	

Table 14: Instances

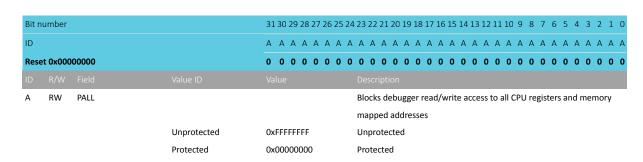
Register	Offset	Security	Description
APPROTECT	0x000		Access port protection
XOSC32M	0x014		Oscillator control
HFXOSRC	0x01C		HFXO clock source selection
HFXOCNT	0x020		HFXO startup counter
APPNVMCPOFGUARD	0x024		Enable blocking NVM WRITE and aborting NVM ERASE for Application NVM in POFWARN
			condition .
SECUREAPPROTECT	0x02C		Secure access port protection
ERASEPROTECT	0x030		Erase protection
OTP[n]	0x108		One time programmable memory
KEYSLOT.CONFIG[n].DEST	0x400		$Destination\ address\ where\ content\ of\ the\ key\ value\ registers\ (KEYSLOT.KEYn.VALUE[0-3])\ will$
			be pushed by KMU. Note that this address must match that of a peripherals APB mapped
			write-only key registers, else the KMU can push this key value into an address range which
			the CPU can potentially read.
KEYSLOT.CONFIG[n].PERM	0x404		Define permissions for the key slot. Bits 0-15 and 16-31 can only be written when equal to
			OXFFFF.
KEYSLOT.KEY[n].VALUE[o]	0x800		Define bits [31+o*32:0+o*32] of value assigned to KMU key slot.

Table 15: Register overview

4.6.1.1 APPROTECT

Address offset: 0x000
Access port protection





4.6.1.2 XOSC32M

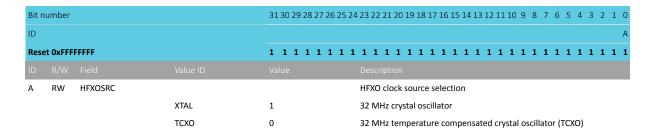
Address offset: 0x014
Oscillator control



4.6.1.3 HFXOSRC

Address offset: 0x01C

HFXO clock source selection



4.6.1.4 HFXOCNT

Address offset: 0x020 HFXO startup counter

Bit n	umber			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					A A A A A A A
Rese	t OxFFF	FFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID					Description
Α	RW	HFXOCNT			HFXO startup counter. Total debounce time = $HFXOCNT*64$ us + 0.5 us
			MinDebounceTime	0	Min debounce time = $(0*64 \text{ us} + 0.5 \text{ us})$
			MaxDebounceTime	255	Max debounce time = $(255*64 \text{ us} + 0.5 \text{ us})$

4.6.1.5 APPNVMCPOFGUARD

Address offset: 0x024

Enable blocking NVM WRITE and aborting NVM ERASE for Application NVM in POFWARN condition .



Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					A
Rese	t OxFFFI	FFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID					
Α	RW	NVMCPOFGUARDEN			Enable blocking NVM WRITE and aborting NVM ERASE in POFWARN
					condition
			Disabled	0	NVM WRITE and NVM ERASE are not blocked in POFWARN condition
			Enabled	1	NVM WRITE and NVM ERASE are blocked in POFWARN condition

4.6.1.6 SECUREAPPROTECT

Address offset: 0x02C

Secure access port protection

Bit n	umber			313	30 2	29 2	28 2	27 2	26 2	25 2	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3 2	2 1	0
ID				Α .	Α.	A A	Α.	Α	Α.	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	A .	ДД	A A	Α
Rese	t 0x000	00000		0	0	0 (0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 0	0	0
ID												De:																						
Α	RW	PALL										Blo	cks	de	bu	gge	er r	ead	d/w	/rit	e a	cce	SS 1	о а	ıll s	ecu	re (CPL	J re	egis	ters	an	d	
												sec	ure	m	em	or	/ m	ар	peo	d a	ddr	ess	es											
			Unprotected	0xF	FFF	FFF	F					Un	pro	tec	tec	b																		
			Protected	0x0	000	200	00					D		tec																				

4.6.1.7 ERASEPROTECT

Address offset: 0x030

Erase protection

Bit nu	umber			313	30 29	28 2	27 26	5 25	24	23	22 2	21 2	20 1	.9 18	8 17	16	15	L4 1	3 12	11 1	.0 9	8	7	6	5	4 3	3 2	1 0
ID				Α	A A	Α	A A	Α	Α	Α	Α	A	A A	4 Α	A	Α	Α	A A	A	Α ,	4 A	Α	Α	Α	Α	A A	AA	A A
Reset	t 0x000	00000		0	0 0	0	0 0	0	0	0	0	0	0 (0 0	0	0	0	0 0	0	0	0 0	0	0	0	0	0 (0	0 0
ID																												
Α	RW	PALL								Blo	cks	NV	'MC	ER.	ASE	ALL	and	СТ	RLAF	ERA	\SEA	LL 1	un	ctio	nali	ity		
			Unprotected	0xF	FFFF	FFF				Un	pro	tec	ted															
			Protected	0x0	0000	0000	1			Pro	tec	ted																

4.6.1.8 OTP[n] (n=0..189)

Address offset: $0x108 + (n \times 0x4)$ One time programmable memory

Bit n	umber		31	30	29	28	27 2	6 25	24	23 2	22 2	1 20	19	18	17	16	15	14	13	12 :	11 1	.0 9	8	7	6	5	4	3	2	1
ID			В	В	В	В	В	ВВ	В	В	ВЕ	3 B	В	В	В	В	Α	Α	Α	Α	A .	4 4	A A	Α	Α	Α	Α	Α	Α	A .
Rese	t OxFFF	FFFFF	1	1	1	1	1 :	1 1	1	1	1 :	l 1	1	1	1	1	1	1	1	1	1	1 1	l 1	1	1	1	1	1	1	1
Α	RW1	LOWER								Lov	ver l	half	wo	rd																
											N	ote:	: Ca	n o	nly	be	wr	itte	n t	o a	noi	า 0x	FFF	Fva	ılue	e or	nce	•		
	RW1	UPPER								Upp	oer l	half	wo	rd																
В	KVVI																													



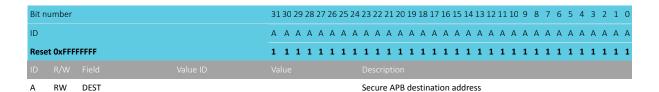


4.6.1.9 KEYSLOT.CONFIG[n].DEST (n=0..127)

Address offset: $0x400 + (n \times 0x8)$

Destination address where content of the key value registers (KEYSLOT.KEYn.VALUE[0-3]) will be pushed by KMU. Note that this address must match that of a peripherals APB mapped write-only key registers, else the KMU can push this key value into an address range which the CPU can potentially read.

Note: Writing/reading this register requires the KMU SELECTKEYSLOT register to be set to n+1.



4.6.1.10 KEYSLOT.CONFIG[n].PERM (n=0..127)

Address offset: $0x404 + (n \times 0x8)$

Define permissions for the key slot. Bits 0-15 and 16-31 can only be written when equal to 0xFFFF.

Note: Writing/reading this register requires the KMU SELECTKEYSLOT register to be set to n+1.

Bit r	number			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					D C B A
Res	et OxFFF	FFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID					Description
Α	RW	WRITE			Write permission for key slot
			Disabled	0	Disable write to the key value registers
			Enabled	1	Enable write to the key value registers
В	RW	READ			Read permission for key slot
			Disabled	0	Disable read from key value registers
			Enabled	1	Enable read from key value registers
С	RW	PUSH			Push permission for key slot
			Disabled	0	Disable pushing of key value registers over secure APB, but can be read
					if field READ is Enabled
			Enabled	1	Enable pushing of key value registers over secure APB. Register
					KEYSLOT.CONFIGn.DEST must contain a valid destination address!
D	RW	STATE			Revocation state for the key slot
					Note that it is not possible to undo a key revocation by writing the
					value '1' to this field
			Revoked	0	Key value registers can no longer be read or pushed
			Active	1	Key value registers are readable (if enabled) and can be pushed (if
					enabled)

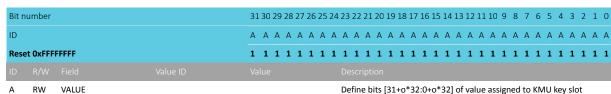
4.6.1.11 KEYSLOT.KEY[n].VALUE[o] (n=0..127) (o=0..3)

Address offset: $0x800 + (n \times 0x10) + (o \times 0x4)$

Define bits [31+o*32:0+o*32] of value assigned to KMU key slot.

Note: Writing/reading this register requires the KMU SELECTKEYSLOT register to be set to n+1.





Define bits [31+o*32:0+o*32] of value assigned to KMU key slot

4.7 EasyDMA

EasyDMA is a module implemented by some peripherals to gain direct access to Data RAM.

EasyDMA is an AHB bus master similar to CPU and is connected to the AHB multilayer interconnect for direct access to Data RAM. EasyDMA is not able to access flash.

A peripheral can implement multiple EasyDMA instances to provide dedicated channels. For example, for reading and writing of data between the peripheral and RAM. This concept is illustrated in EasyDMA example on page 47.

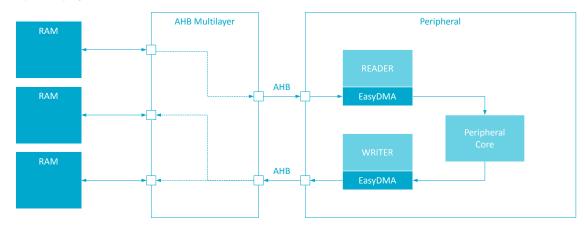


Figure 5: EasyDMA example

An EasyDMA channel is implemented in the following way, but some variations may occur:

```
READERBUFFER SIZE 5
WRITERBUFFER SIZE 6
uint8 t readerBuffer[READERBUFFER_SIZE] __at__ 0x20000000;
uint8_t writerBuffer[WRITERBUFFER_SIZE] __at__ 0x20000005;
// Configuring the READER channel
MYPERIPHERAL->READER.MAXCNT = READERBUFFER SIZE;
MYPERIPHERAL->READER.PTR = &readerBuffer;
// Configure the WRITER channel
MYPERIPHERAL->WRITER.MAXCNT = WRITEERBUFFER SIZE;
MYPERIPHERAL->WRITER.PTR = &writerBuffer;
```

This example shows a peripheral called MYPERIPHERAL that implements two EasyDMA channels - one for reading called READER, and one for writing called WRITER. When the peripheral is started, it is assumed that the peripheral will perform the following tasks:

Read 5 bytes from the readerBuffer located in RAM at address 0x20000000



4418 1315 v2.1 47

- Process the data
- Write no more than 6 bytes back to the writerBuffer located in RAM at address 0x20000005

The memory layout of these buffers is illustrated in EasyDMA memory layout on page 48.

0x20000000	readerBuffer[0]	readerBuffer[1]	readerBuffer[2]	readerBuffer[3]
0x20000004	readerBuffer[4]	writerBuffer[0]	writerBuffer[1]	writerBuffer[2]
0x20000008	writerBuffer[3]	writerBuffer[4]	writerBuffer[5]	

Figure 6: EasyDMA memory layout

The WRITER.MAXCNT register should not be specified larger than the actual size of the buffer (writerBuffer). Otherwise, the channel would overflow the writerBuffer.

Once an EasyDMA transfer is completed, the AMOUNT register can be read by the CPU to see how many bytes were transferred. For example, CPU can read MYPERIPHERAL->WRITER.AMOUNT register to see how many bytes WRITER wrote to RAM.

Note: The PTR register of a READER or WRITER must point to a valid memory region before use. The reset value of a PTR register is not guaranteed to point to valid memory. See Memory on page 23 for more information about the different memory regions and EasyDMA connectivity.

4.7.1 EasyDMA error handling

Some errors may occur during DMA handling.

If READER.PTR or WRITER.PTR is not pointing to a valid memory region, an EasyDMA transfer may result in a HardFault or RAM corruption. See Memory on page 23 for more information about the different memory regions.

If several AHB bus masters try to access the same AHB slave at the same time, AHB bus congestion might occur. An EasyDMA channel is an AHB master. Depending on the peripheral, the peripheral may either stall and wait for access to be granted, or lose data.

4.7.2 EasyDMA array list

EasyDMA is able to operate in Array List mode.

The Array List mode is implemented in channels where the LIST register is available.

The array list does not provide a mechanism to explicitly specify where the next item in the list is located. Instead, it assumes that the list is organized as a linear array where items are located one after the other in RAM.



The EasyDMA Array List can be implemented by using the data structure ArrayList_type as illustrated in the code example below using a READER EasyDMA channel as an example:

```
#define BUFFER_SIZE 4

typedef struct ArrayList
{
   uint8_t buffer[BUFFER_SIZE];
} ArrayList_type;

ArrayList_type ReaderList[3] __at__ 0x20000000;

MYPERIPHERAL->READER.MAXCNT = BUFFER_SIZE;
MYPERIPHERAL->READER.PTR = &ReaderList;
MYPERIPHERAL->READER.LIST = MYPERIPHERAL_READER_LIST_ArrayList;
```

The data structure only includes a buffer with size equal to the size of READER.MAXCNT register. EasyDMA uses the READER.MAXCNT register to determine when the buffer is full.

READER.PTR = &ReaderList
•

0x20000000 : ReaderList[0]	buffer[0]	buffer[1]	buffer[2]	buffer[3]
0x20000004 : ReaderList[1]	buffer[0]	buffer[1]	buffer[2]	buffer[3]
0x20000008 : ReaderList[2]	buffer[0]	buffer[1]	buffer[2]	buffer[3]

Figure 7: EasyDMA array list

4.8 AHB multilayer interconnect

On the AHB multilayer interconnect, the application CPU and all EasyDMA instances are AHB bus masters while RAM, cache and peripherals are AHB slaves. External MCU subsystems can be seen both as master and slave on the AHB multilayer interconnect.

Multiple AHB masters can access slave resources within the AHB multilayer interconnect as illustrated in Memory on page 23. Access rights to each of the AHB slaves are resolved using the natural priority of the different bus masters in the system.

4.8.1 AHB multilayer priorities

Each master connected to the AHB multilayer is assigned a default natural priority.



Bus master name	Natural relative priority	In/Out
System (CPU)	Highest priority	1/0
LTE Modem		1/0
125		I/O
PDM		1
SPIMO/SPISO/TWIMO/TWISO/UARTEO		1/0
SPIM1/SPIS1/TWIM1/TWIS1/UARTE1		1/0
SPIM2/SPIS2/TWIM2/TWIS2/UARTE2		1/0
SPIM3/SPIS3/TWIM3/TWIS3/UARTE3		1/0
SAADC		1
PWM0		0
PWM1		0
PWM2		0
PWM3		0
CC310	Lowest priority	1/0

Table 16: AHB bus masters (listed from highest to lowest priority)



5 Power and clock management

The power and clock management system automatically ensures maximum power efficiency.

The nRF9160 provides a total of three power modes; two internal (automatically handled by the device), and one external (driven by the ENABLE pin and overriding internal ones).

The core of the automatic power and clock management is the power management unit (PMU) illustrated in the following image.

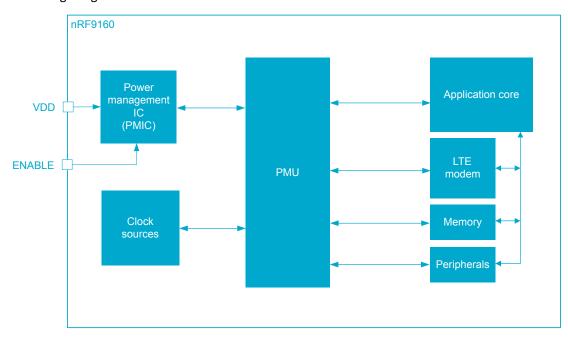


Figure 8: Power management unit

When the device is powered and enabled, the PMU automatically tracks the power and clock resources required by the different components in the system. It then starts/stops and chooses operation modes in supply regulators and clock sources, without user interaction, to achieve the lowest power consumption possible.

5.1 Power management

The two internal modes are handled by the power management unit (PMU), whereas the external is handled by the user via the ENABLE pin.

The System Disabled mode provides a way to override the PMU by manipulating voltages presented to the ENABLE pin.

The PMU steers system-wide clock and power in order to provide the power modes - System ON and System OFF. Under the various modes, internal blocks are automatically powered by the PMU as required by the application.

5.1.1 System Disabled mode

The entire device can be powered down by presenting the appropriate voltage to the externally available ENABLE pin.



The nRF9160 provides a feature to be able disable power throughout the entire device externally. This can be useful when the device is operating as slave processor where it does not need to be powered on at all times, then it is possible to avoid unnecessary current leaking by driving the ENABLE pin to low. The nRF9160 will not start if is not enabled. Moreover, a change from disable to enable, will result in a power-on-reset behavior inside the device.

Note: VDD_GPIO input must be driven low when device is disabled, failing to do so could result in increased leakage. For more information, see VDD_GPIO considerations in Operating conditions on page 396.

Note: In case the System Disabled mode is not used, ENABLE must be connected to VDD.

Pin Value	Power status	description
Low	Disabled	Device's internal power regulator disabled
High	Enabled	Device's internal power regulator enabled

Table 17: ENABLE pin configuration

5.1.2 System OFF mode

System OFF is the deepest internal power saving mode the system can enter.

In this mode, the core system functionality is powered down and ongoing tasks terminated, and only the reset and the wakeup functions are available and responsive.

The device is put into System OFF mode using the REGULATORS register interface. When in System OFF mode, one of the following signals/actions will wake up the device:

- 1. DETECT signal, generated by the GPIO peripheral
- 2. RESET
- **3.** start of debug session

When the device wakes up from System OFF mode, a system reset is performed.

One or more RAM blocks can be retained in System OFF mode depending on the settings in the RAM[n].POWER registers in VMC. RAM[n].POWER are retained registers, see Reset behavior on page 61. Note that these registers are usually overwritten by the startup code provided with the nRF application examples.

Before entering System OFF mode, the user must make sure that all on-going EasyDMA transactions have completed. This can be accomplished by making sure that EasyDMA enabled peripherals have stopped and END events from them received. The LTE modem also needs to be stopped, by issuing a command through the modem API, before entering System OFF mode. Once the command is issued, one should wait for the modem to respond that it actually has stopped, as there may be a delay until modem is disconnected from the network.

5.1.2.1 Emulated System OFF mode

If the device is in debug interface mode, System OFF will be emulated to secure that all required resources needed for debugging are available during System OFF.

See Debug and trace on page 374 chapter for more information. Required resources needed for debugging include the following key components: Debug and trace on page 374, CLOCK — Clock control on page 74, POWER — Power control on page 68, NVMC — Non-volatile memory controller on page 31, CPU on page 22, flash, and RAM. Since the CPU is kept on in emulated System OFF mode, it is required to add an infinite loop directly after entering System OFF, to prevent the CPU from executing code that normally should not be executed.



5.1.3 System ON mode

System ON is the power mode entered after a power-on reset.

While in System ON, the system can reside in one of two sub modes:

- · Low power
- Constant latency

The low power mode is default after power-on reset.

In low power mode, whenever no application or wireless activity takes place, function blocks like the application CPU, LTE modem and all peripherals are in IDLE state. That particular state is referred to as System ON IDLE. In this state, all function blocks retain their state and configuration, so they are ready to become active once configured by the CPU.

If any application or modem activity occurs, the system leaves the System ON IDLE state. Once a given activity in a function block is completed, the system automatically returns to IDLE, retaining its configuration.

As long as the system resides in low power mode, the PMU ensures that the appropriate regulators and clock sources are started or stopped based on the needs of the function blocks active at any given time.

This automatic power management can be overridden by switching to constant latency mode. In this mode, the CPU wakeup latency and the PPI task response are constant and kept at a minimum. This is secured by keeping a set of base resources that are always enabled. The advantage of having a constant and predictable latency will be at the cost of having significantly increased power consumption compared to the low power mode. The constant latency mode is enabled by triggering the CONSTLAT task (TASKS_CONSTLAT on page 68).

While the system is in constant latency mode, the low power mode can be enabled by triggering LOWPWR task (TASKS LOWPWR on page 69).

To reduce power consumption while in System ON IDLE, RAM blocks can be turned off in System ON mode while enabling the retention of these RAM blocks in RAM[n].POWER registers in VMC. RAM[n].POWER are retained registers, see Reset behavior on page 61. Note that these registers are usually overwritten by the startup code provided with the nRF application examples.

5.1.4 Registers

5.1.5 Electrical specification

5.1.5.1 ENABLE pin voltage requirements

Symbol	Description	Min.	Тур.	Max.	Units
V _{SYSTEM_DISABLED_ON}	Operational voltage to enforce System-Disabled power	0.8*VDD			V
	mode.				
V _{SYSTEM_DISABLED_OFF}	Operational voltage to cancel System-Disabled power			0.4	V
	mode.				

5.2 Power supply

The nRF9160 has a single main power supply VDD, and the internal components are powered by integrated voltage regulators. The PMU manages these regulators automatically, no voltage regulator control needs to be included in application firmware.





5.2.1 General purpose I/O supply

The input/output (I/O) drivers of P0.00 - P0.31 pins are supplied independently of VDD through VDD_GPIO. This enables easy match to signal voltage levels in the printed circuit board design.

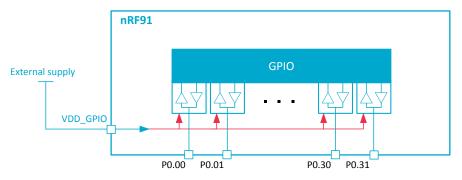


Figure 9: GPIO supply input (VDD_GPIO)

The I/Os are supplied via VDD_GPIO pin as shown in figure above. VDD_GPIO pin supports voltage levels within range given in table Operating conditions on page 396

5.3 Power supply monitoring

Power monitor solutions are available in the device, in order to survey the VDD (battery voltage).

5.3.1 Power supply supervisor

The power supply supervisor enables monitoring of the connected power supply.

Two functionalities are implemented:

- Power-on reset (POR): Generates a reset when the supply is applied to the device, and ensures that the device starts up in a known state
- Brownout reset (BOR): Generates a reset when the supply drops below the minimum voltage required for safe operations

Two BOR levels are used:

- V_{BOROFF}, used in System OFF
- V_{BORON}, used in System ON

The power supply supervisor is illustrated in the image below.



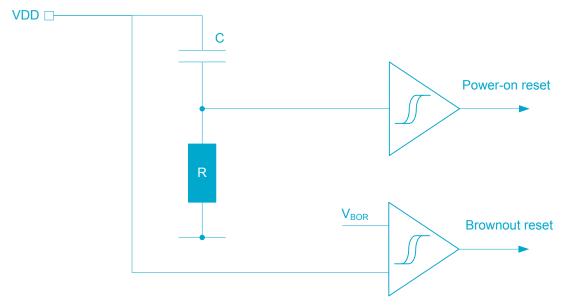


Figure 10: Power supply supervisor

5.3.2 External power failure warning

The external power failure (EXTPOF) warning can provide the CPU an early warning of an imminent power failure. It will not reset the system, but give the CPU time to prepare for an orderly power-down. EXTPOF detects power failures external to PMU from the device internal PMIC.

Note: This feature is only supported with nRF9160 modem firmware version 1.3.1 and higher.

The user can start and stop the PMIC EXTPOF feature and set the battery voltage low threshold level through the modem API.

To receive the power failure warning events on application core the user must also enable the EXTPOFCON on page 82 register in REGULATORS — Voltage regulators control on page 82. If this is disabled, the state of the PMIC warning input is ignored and the power failure warning events are not delivered to application core.

The available time for the CPU to prepare for a power-down depends on the set warning threshold level, the load of the running tasks, and the type of power source used.

Note: For details on services provided by the modem AT command interface, see nRF Connect SDK AT interface and nRF91 AT Commands.

The EXTPOF arrangement is illustrated in the following image.



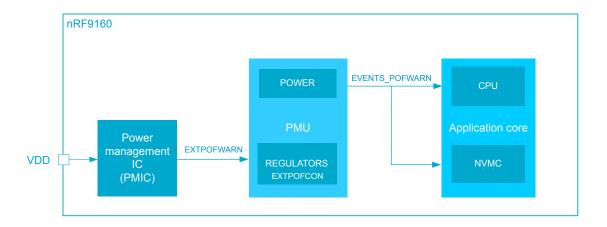


Figure 11: External power failure warning arrangement

If EXTPOF is enabled and the device internal PMIC detects battery voltage dropping below the programmed low threshold level, the POFWARN event is generated (see EVENTS_POFWARN on page 69). The POFWARN event to CPU can be cleared in this event register, however the PMIC input continues to indicate warning as long as the battery voltage stays below the low threshold level.

POFWARN event also sets the LTE modem in offline mode.

Note: If power failure warning occurs during an ongoing NVM write operation, the NVMC will try to finish the operation. Consecutive NVM write operations will be blocked by the NVMC as long as the PMIC input indicates warning. The CPU will see a blocked NVM write as a fault, which needs to be handled in the software. If power failure warning occurs during an ongoing NVM erase operation, the operation will be aborted. Blocking NVM writes and aborting NVM erase operations can be disabled in APPNVMCPOFGUARD on page 44.

The external power failure warning doesn't trigger wakeup from System OFF.

The external power failure warning is disabled in System OFF mode.

5.3.3 Battery monitoring on VDD

A battery voltage (VDD) monitoring capability is provided via a modem API.

Note: For details on services provided by the modem AT command interface, see nRF Connect SDK AT interface and nRF91 AT Commands.

5.3.4 Registers

5.3.5 Electrical specification

5.3.5.1 Device startup times

Symbol	Description	Min.	Тур.	Max.	Units	
t _{POR}	Time in power-on reset after VDD has reached 3V, ENABLE		1.2		ms	
	is tied to VDD.					



Symbol	Description	Min.	Тур.	Max.	Units
t _{PINR}	The maximum time taken to pull up the nRESET pin and				
	release reset after power-on reset. Dependent on the pin				
	capacitive load (C) ² : t=TRC; Typical: T=2 R=13 k Ω ; Max: T=5				
	R=16 k Ω .				
t _{PINR,500nF}	C=500 nF		13	40	ms
t _{PINR,10uF}	C=10 µF		260	800	ms
t _{R2ON}	Time from reset to ON (CPU execute)		127	135	μs
t _{OFF2ON}	Time from OFF to CPU execute		73	92	μs
t _{WFE2CPU}	Time from WFE to CPU execute		70	90	μs
t _{WFI2CPU}	Time from WFI to CPU execute		69	90	μs
t _{EVTSET,CL1}	Time from HW event to PPI event in constant latency		0.1	0.1	μs
	System ON mode				
t _{EVTSET,CLO}	Time from HW event to PPI event in low power System ON		0.1	0.7	μs
	mode				
t _{LTEMODEM,TYP}	LTE modem typical startup time. Time from application			200	ms
	core powering up the modem until the modem is ready to				
	receive the first AT command.				
t _{LTEMODEM} , worstcase	LTE modem worst case startup time. Time from application			250	ms
	core powering up the modem until the modem is ready to				
	receive the first AT command, with modem FW variable				
	elements included.				
t _{LTEMODEM} ,FOTA	LTE modem startup time after modem FOTA update. Time			7.5	S
	from application core powering up the modem after a				
	modem FOTA update until the modem is ready to receive				
	the first AT command.				
t _{LTEMODEM} , FOTAREJECT	LTE modem startup time after a rejected modem FOTA			90	S
	update. Time from application core powering up the				
	modem after a rejected modem FOTA update until the				
	modem is ready to receive the first AT command. Modem				
	will revert back to original FW image.				
t _{LTEMODEM} ,STOP,TYP	LTE modem typical shutdown time. Time from application			1.6	S
	core calling bsd_shutdown command until bsd_shutdown				
	returns.				
t _{LTEMODEM} ,STOP,WORST	LTE modem worst case shutdown time. Time from			79	S
	application core calling bsd_shutdown command until				
	bsd_shutdown returns, with modem FW variable elements				
	included.				

5.3.5.2 Power supply supervisor

Symbol	Description	Min.	Тур.	Max.	Units
V_{BOR}	Brownout reset voltage threshold.		2.00		V
V_{POR}	Voltage threshold at which the device enters power-on			2.15	V
	reset (POR) when VDD is ramping up.				

5.4 Clock management

The clock control system can source the system clocks from a range of high and low frequency oscillators, and distribute them to modules based upon a module's individual requirements.



² To decrease the maximum time a device could be held in reset, a strong external pull-up resistor can be used.

Clock generation and distribution is handled automatically by PMU to optimize current consumption. This optimization has consequences on predictability of the oscillator's startup times under different device operating conditions. However, it is possible to bypass some of the power saving mechanisms by explicity keeping the system on constant latency submode (more about constant latency in System ON mode on page 53) and/or manipulating START/STOP clock task registers.

Listed here are the available clock signal sources:

- 64 MHz oscillator (HFINT)
- 64 MHz high accuracy oscillator (HFXO)
- 32.768 kHz RC oscillator (LFRC)
- 32.768 kHz high accuracy oscillator (LFXO)

The clock and oscillator resources are configured and controlled via the CLOCK peripheral as illustrated below.

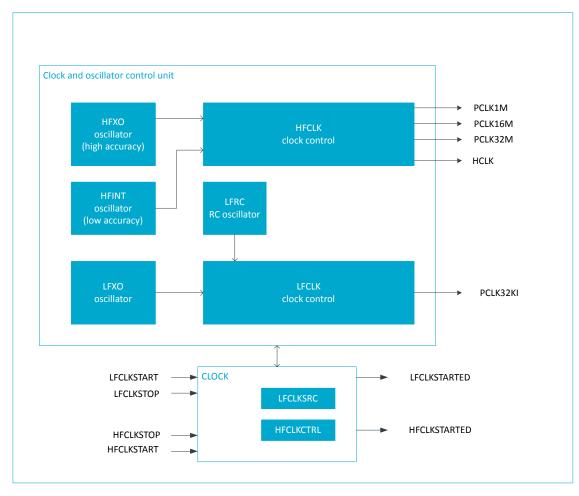


Figure 12: Clock and oscillator setup

5.4.1 HFCLK clock controller

The HFCLK clock controller provides several clocks in the system.

These are as follows:

- HCLK: 64 MHz CPU clock
- PCLK1M: 1 MHz peripheral clock
- PCLK16M: 16 MHz peripheral clock
- PCLK32M: 32 MHz peripheral clock

The HFCLK controller uses the following high frequency clock (HFCLK) sources:

NORDIC*

- 64 MHz oscillator (HFINT)
- 64 MHz high accuracy oscillator (HFXO)

For illustration, see Clock and oscillator setup on page 58.

The HFCLK controller will automatically provide the clock(s) requested by the system. If the system does not request any clocks from the HFCLK controller, the controller will switch off all its clock sources and enter a power saving mode.

The HFINT source will be used when HFCLK is requested and HFXO has not been started.

The HFXO is started by triggering the HFCLKSTART task and stopped using the HFCLKSTOP task. A HFCLKSTARTED event will be generated when the HFXO has started and its frequency is stable.

5.4.2 LFCLK clock controller

The system supports several low frequency clock sources.

As illustrated in Clock and oscillator setup on page 58, the system supports the following low frequency clock sources:

- LFRC: 32.768 kHz RC oscillator
- · LFXO: 32.768 kHz high accuracy oscillator

The LFCLK clock controller and all LFCLK clock sources are always switched off when in System OFF mode.

The LFCLK clock is started by first selecting the preferred clock source in the LFCLKSRC on page 81 register and then triggering the LFCLKSTART task. LFXO is highly recommended as the LFCLK clock source, since the LFRC has a large frequency variation.

Note: The LTE modem requires using LFXO as the LFCLK source.

Switching between LFCLK clock sources can be done without stopping the LFCLK clock. A LFCLK clock source which is running prior to triggering the LFCLKSTART task will continue to run until the selected clock source has been available. After that the clock sources will be switched. Switching between clock sources will never introduce a glitch but it will stretch a clock pulse by 0.5 to 1.0 clock cycle (i.e. will delay rising edge by 0.5 to 1.0 clock cycle).

Note: If the watchdog timer (WDT) is running, the default LFCLK clock source (LFRC - see LFCLKSRC on page 81) is started automatically (LFCLKSTART task doesn't have to be triggered).

A LFCLKSTARTED event will be generated when the selected LFCLK clock source has started.

Note: When selecting LFXO as clock source for the first time, LFRC quality is provided until LFXO is stable.

A LFCLKSTOP task will stop global requesting of the LFCLK clock. However, if any system component (e.g. WDT, modem) requires the LFCLK, the clock won't be stopped. The LFCLKSTOP task should only be triggered after the STATE field in the LFCLKSTAT register indicates a LFCLK running-state.

5.4.2.1 32.768 kHz RC oscillator (LFRC)

The default source of the low frequency clock (LFCLK) is the 32.768 kHz RC oscillator (LFRC).

The LFRC frequency will be affected by variation in temperature.



5.4.3 Registers

5.4.4 Electrical specification

5.4.4.1 64 MHz internal oscillator (HFINT)

Symbol	Description	Min.	Тур.	Max.	Units
f _{NOM_HFINT}	Nominal output frequency		64		MHz
f _{TOL_HFINT}	Frequency tolerance		+-1	+-5	%
t _{START_HFINT}	Startup time		3.2		μs

5.4.4.2 64 MHz high accuracy oscillator (HFXO)

Symbol	Description	Min.	Тур.	Max.	Units
f _{NOM_HFXO}	Nominal output frequency		64		MHz
f_{TOL_HFXO}	Frequency tolerance		+-1		ppm
t _{START_HFXO}	Startup time		TBA		ms

5.4.4.3 32.768 kHz high accuracy oscillator (LFXO)

Symbol	Description	Min.	Тур.	Max.	Units
f _{NOM_LFXO}	Frequency		32.768		kHz
f_{TOL_LFXO}	Frequency tolerance		+-20		ppm
t _{START_LFXO}	Startup time		200		ms

5.4.4.4 32.768 kHz RC oscillator (LFRC)

Symbol	Description	Min.	Тур.	Max.	Units
f _{NOM_LFRC}	Nominal frequency		32.768		kHz
f_{TOL_LFRC}	Frequency tolerance		30		%
t _{START LERC}	Startup time		600		μs

5.5 Reset

There are multiple reset sources that may trigger a reset of the system. After a reset the CPU can query the RESETREAS (reset reason register) to find out which source generated the reset.

5.5.1 Power-on reset

The power-on reset generator initializes the system at power-on. The system is held in reset state until the supply has reached the minimum operating voltage and the internal voltage regulators have started.

5.5.2 Pin reset

A pin reset is generated when the physical reset pin (nRESET) on the device is pulled low.

To ensure that reset is issued correctly, the reset pin should be held low for time given in Pin reset on page 62 .



nRESET pin has an always-on internal pull-up resistor connected to nRF9160 internal voltage typically of 2.2 V level. This is illustrated in the figure below. The value of the pull-up resistor is given in Pin reset on page 62.

Note: Driving nRESET high with a voltage lower than 2.2V will result in additional leakage.

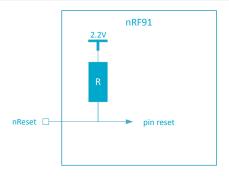


Figure 13: Pin reset internal generation

5.5.3 Wakeup from System OFF mode reset

The device is reset when it wakes up from System OFF mode.

The Debug access port is not reset following a wake up from System OFF mode if the device is in debug interface mode, see Debug and trace on page 374 chapter for more information.

5.5.4 Soft reset

A soft reset is generated when the SYSRESETREQ bit of the application interrupt and reset control register (AIRCR register) in the ARM core is set.

5.5.5 Watchdog reset

A watchdog reset is generated when the watchdog timer (WDT) times out.

See WDT — Watchdog timer on page 359 chapter for more information.

5.5.6 Brownout reset

The brownout reset generator puts the system in reset state if the supply voltage drops below the brownout reset threshold.

5.5.7 Retained registers

A retained register is a register that will retain its value in System OFF mode, and through a reset depending on reset source. See individual peripheral chapters for information of which registers are retained for the different peripherals.

5.5.8 Reset behavior

Reset behavior depends on the reset source.

The reset behavior is summarized in the table below.



Reset source	Reset target							
	CPU	Modem	Debug ³	SWJ-DP	Not retain	ed Retained	WDT	RESETREAS
					RAM ⁴	RAM ⁴		
CPU lockup ⁵	х	х						
Soft reset	х	Х						
Wakeup from System OFF	x	x	x ⁶		х		х	
mode reset								
Watchdog reset ⁷	х	х	х		x		x	
Pin reset	x	x	x	х	x		x	
Brownout reset	x	x	x	х	х	х	х	x
Power-on reset	х	x	х	x	х	x	x	

Table 18: Reset behavior for the main components

Note: The RAM is never reset but its content may be corrupted after reset in the cases given in the table above.

Reset source	Reset target					
	Regular peripheral	GPIO, SPU	NVMC NVMC		REGULATORS,	POWER.GPREGRET
	registers		WAITSTATENUM	IFCREADDELAY	OSCILLATORS	
CPU lockup ⁵	х	x	х			
Soft reset	х	х	х			
Wakeup from System OFF mode reset	х		х			
Watchdog reset ⁷	х	х	х		х	
Pin reset	х	х	х		х	
Brownout reset	х	х	х	х	х	х
Power-on reset	x	x	х	х	х	x

Table 19: Reset behavior for the retained registers

5.5.9 Registers

5.5.10 Electrical specification

5.5.10.1 Pin reset

Symbol	Description	Min.	Тур.	Max.	Units
t _{HOLDRESET}	Hold time for reset pin when doing a pin reset	5			μs
R _{PULL-UP}	Value of the internal pull-up resistor		13		kΩ

NORDIC

³ All debug components excluding SWJ-DP. See Debug and trace on page 374 chapter for more information about the different debug components in the system.

⁴ RAM can be configured to be retained using registers in VMC — Volatile memory controller on page 29

⁵ Reset from CPU lockup is disabled if the device is in debug interface mode. CPU lockup is not possible in System OFF.

The debug components will not be reset if the device is in debug interface mode.

⁷ Watchdog reset is not available in System OFF.

5.6 Current consumption

As the system is being constantly tuned by the PMU described in Power and clock management on page 51, estimating the current consumption of an application can be challenging if the designer is not able to perform measurements directly on the hardware. To facilitate the estimation process, a set of current consumption scenarios are provided to show the typical current drawn from the VDD supply.

Each scenario specifies a set of operations and conditions applying to the given scenario. Current consumption scenarios, common conditions on page 63 shows a set of common conditions used in all scenarios, unless otherwise is stated in the description of a given scenario. Similarly, Current consumption scenarios, common conditions for LTE modem on page 64 describes the conditions used for the modem current consumption specifications. All scenarios are listed in Electrical specification on page 64

Peripherals typically share one or more power sources. This results in a current consumption that does not scale linearly with the number of peripherals enabled. For example, the current consumption for an application with two peripherals enabled, is not the sum of the currents reported by their individual peripherals.

Condition	Value
Supply	3.7 V
Temperature	25 °C
CPU	WFI (wait for interrupt)/WFE (wait for event) sleep
Peripherals	All idle ⁸
Clock	Not running
RAM	No retention
Cache enabled	Yes

Table 20: Current consumption scenarios, common conditions



⁸ Except for currents reported for a given peripheral. Peripheral's currents are estimated during momentary transmission.

Condition

Cat-M1 and Cat-NB1 HD FDD mode

Good channel, RF cable, no errors in DL/UL communication

Network response times at minimum

Output power at antenna port, single-ended 50 Ω

Modem eDRX current consumption quoted with UICC that allows UICC supply shut down at eDRX intervals. $^{9\ 10\ 11}$

Modem PSM TAU event energy is measured from the modem PSM wake-up until end of RX inactivity time

All LTE modem current consumption numbers include application core idle mode consumption ¹²

Table 21: Current consumption scenarios, common conditions for LTE modem

5.6.1 Electrical specification

5.6.1.1 Current consumption during System Disabled

Symbol	Description	Min.	Тур.	Max.	Units
I _{SYSTEM_DISABLED}	ENABLE and VDD_GPIO pins grounded		150		nA

5.6.1.2 Sleep

Symbol	Description	Min.	Тур.	Max.	Units
I _{MCUOFF0}	MCU off, modem off, no RAM retention, wake on GPIO and		1.4		μΑ
	reset				
I _{MCUON0}	MCU on IDLE, modem off, RTC off		1.8		μΑ
I _{MCUON1}	MCU on IDLE, modem off, RTC on		2.2		μΑ
I _{MCUON2}	MCU on IDLE, modem off, wake on GPIOTE input (event		600.3		μΑ
	mode, LATENCY=LowLatency)				
I _{MCUON3}	MCU on IDLE, modem off, wake on GPIOTE input (event		17.8		μΑ
	mode, LATENCY=LowPower)				
I _{MCUON4}	MCU on IDLE, modem off, wake on GPIOTE input (port		1.8		μΑ
	event)				
I _{RAM}	RAM retention leakage current of a 32kB block		0.10		μΑ



⁹ Required UICC restart current consumption is included.

If the used UICC does not support supply shut down, then UICC will remain in clock stop mode. Depending on the used UICC a clock stop current of typ. 20-60uA@3.7V needs to be added to get the total average consumption.

Minimum UICC supply shut down interval and clock stop mode current consumption must be obtained from the UICC supplier.

¹² Application RAM leakage not included. Application RAM leakage quoted separately under Sleep on page 64

5.6.1.3 Application CPU active current consumption

Symbol	Description	Min.	Тур.	Max.	Units
I _{CPU0_FLASH}	CPU running CoreMark @64 MHz from flash, clock = HFINT,		2.20		mA
	cache enabled				
I _{COREMARK_PER_MA_}	COREMARK_PER_MA_FL CoreMark per mA, executing from flash, CoreMark=243		110.45		CoreMark/
					mA
I _{CPU0_RAM}	CPU running CoreMark @64 MHz from RAM, clock = HFINT		2.19		mA
I _{COREMARK_PER_MA_}	RA CoreMark per mA, executing from RAM, CoreMark=235		107.31		CoreMark/
					mA

5.6.1.4 I2S

Symbol	Description	Min.	Тур.	Max.	Units
I ₁₂₅₀	I2S transferring data left-channel (mono) @ 16 bit x 16 kHz		0.69		mA
	(CONFIG.MCKFREQ = 32MDIV8, CONFIG.RATIO = 256X),				
	Clock = HFINT				
I _{12S1}	I2S transferring data left-channel (mono) @ 16 bit x 16 kHz		1.65		mA
	(CONFIG.MCKFREQ = 32MDIV8, CONFIG.RATIO = 256X),				
	Clock = HFXO				

5.6.1.5 PDM

Symbol	Description	Min.	Тур.	Max.	Units
I _{PDM}	PDM receiving and processing data 16KHz, with FREQ =		0.71		mA
	1.28MHz, MODE.OPERATION = mono				
I _{PDM}	PDM receiving and processing data 16KHz, with FREQ =		1.67		mA
	1.28MHz, MODE.OPERATION = mono, clock HFXO				

5.6.1.6 PWM

Symbol	Description	Min.	Тур.	Max.	Units
I _{PWM0}	PWM running @ 125 kHz, fixed duty cycle		623.97		μΑ
I _{PWM1}	PWM running @ 16 MHz, fixed duty cycle		723.1		μΑ

5.6.1.7 SAADC

Symbol	Description	Min.	Тур.	Max.	Units
I _{SAADC_HFXO}	SAADC sampling @ 16 ksps, with high accuracy clock HFXO,		1288		μΑ
	acquisition time = $20 \mu s$				
I _{SAADC_HFINT}	SAADC sampling @ 16 ksps, with low accuracy clock HFINT,		297.7		μΑ
	acquisition time = 20 μs				

5.6.1.8 TIMER

Symbol	Description	Min.	Тур.	Max.	Units
I _{TIMERO}	TIMER running @ 1 MHz		503.7		μΑ
I _{TIMER1}	TIMER running @ 16 MHz		556.3		μΑ



5.6.1.9 SPIM

Symbol	Description	Min.	Тур.	Max.	Units	
I _{SPIMO}	SPIM transferring data @ 2 Mbps, Clock = HFINT		0.63		mA	
I _{SPIM1}	SPIM transferring data @ 2 Mbps, Clock = HFXO		1.58		mA	
I _{SPIM2}	SPIM transferring data @ 8 Mbps, Clock = HFINT		0.67		mA	
I _{SPIM3}	SPIM transferring data @ 8 Mbps, Clock = HFXO		1.62		mA	

5.6.1.10 SPIS

Symbol	Description	Min.	Тур.	Max. Units	
I _{SPIS_2M}	SPIS receiving data @ 2 Mbps, Clock=HFINT		0.63	mA	
I _{SPIS_2MXO}	SPIS receiving data @ 2 Mbps, Clock=HFXO		1.58	mA	
I _{SPIS_8M}	SPIS receiving data @ 8 Mbps, Clock=HFINT		0.67	mA	
I _{SPIS_8MXO}	SPIS receiving data @ 8 Mbps, Clock=HFXO		1.62	mA	

5.6.1.11 TWIM

Symbol	Description	Min.	Тур.	Max.	Units
I _{TWIM_100}	TWIM running @ 100 kbps, Clock=HFINT		0.61		mA
I _{TWIM_400}	TWIM running @ 400 kbps, Clock = HFINT		0.61		mA
I _{TWIM_100XO}	TWIM running @ 100 kbps, Clock = HFXO		1.56		mA
I _{TWIM_400XO}	TWIM running @ 400 kbps, Clock = HFXO		1.56		mA

5.6.1.12 TWIS

Symbol	Description	Min.	Тур.	Max.	Units
I _{TWIS,RUN_100}	TWIS transferring data @ 100 kbps, Clock=HFINT		0.60		mA
I _{TWIS1,RUN_400}	TWIS transferring data @ 400 kbps, Clock=HFINT		0.60		mA
I _{TWIS,RUN_100XO}	TWIS transferring data @ 100 kbps, Clock = HFXO		1.55		mA
I _{TWIS,RUN_400XO}	TWIS transferring data @ 400 kbps, Clock = HFXO		1.55		mA

5.6.1.13 UARTE

Symbol	Description	Min.	Тур.	Max.	Units
I _{UARTE,1M}	UARTE transferring data @ 1Mbps		819.2		μΑ
I _{UARTE,115K}	UARTE transferring data @ 115200 bps		620.6		μΑ

5.6.1.14 WDT

Symbol	Description	Min.	Тур.	Max.	Units
I_{WDT}	WDT started		2.50		μΑ

5.6.1.15 Modem current consumption

For estimating particular use cases, see nRF9160 Online Power Profiler for LTE



Symbol	Description	B13	B20	В3	В4	Units
		(typ.)	(typ.)	(typ.)	(typ.)	
Sleep currer	t consumption, Cat-M1 and Cat-NB1					
I _{PSM}	PSM floor current	2.7	2.7	2.7	2.7	μΑ
PSM TAU ev	ent energy and duration, Cat-M1					
E _{PSM_TAU}	Pout 23 dBm, QPSK, resource blocks 6, TBS index 9, UICC included	105	-	-	-	mJ
T _{PSM_TAU}	Pout 23 dBm, QPSK, resource blocks 6, TBS index 9, UICC included	1.5	-	-	-	S
PSM TAU ev	ent energy and duration, Cat-NB1					
E _{PSM_TAU}	Pout 23 dBm, QPSK, UICC included; UL: 12SC, MCS Index 5 Resource Units 1, Repetitions 1; DL, 12SC,	550	-	-	-	mJ
	MCS Index 6, Subframes 3, Repetitions 1					
T _{PSM_TAU}	Pout 23 dBm, QPSK, UICC included; UL: 12SC, MCS Index 5 Resource Units 1, Repetitions 1; DL, 12SC,	2.7	_	_	_	S
	MCS Index 6, Subframes 3, Repetitions 1					
Average cur	rent consumption, radio resource control (RRC) mode, Cat-M1					
I _{EDRX}	eDRX average current, 81.92 s, one PO/PTW, PTW = 2.56 s	18	18	18	18	μΑ
I _{IEDRX}	Idle eDRX average current, 655 s, one PO/PTW, PTW = 2.56 s	6	6	6	6	μА
I _{RMC_ODBM}	Uplink 180 kbit/s, Pout 0 dBm, RMC settings as per 3GPP TS 36.521-1 Annex A.2	45	45	45	45	mA
	Uplink 180 kbit/s, Pout 10 dBm, RMC settings as per 3GPP TS 36.521-1 Annex A.2	50	50	55	55	mA
I _{RMC_10DBM}	Uplink 180 kbit/s, Pout 23 dBm, RMC settings as per 3GPP TS 36.521-1 Annex A.2	100	105	115	115	mA
RMC_23DBM		100	103	113	113	IIIA
	rent consumption, radio resource control (RRC) mode, Cat-NB1	27	27	27	27	
I _{EDRX}	eDRX average current, 81.92 s, one PO/PTW, PTW = 2.56 s	37	37	37	37	μΑ
I _{IEDRX}	Idle eDRX average current, 655 s, one PO/PTW, PTW = 2.56 s	9	9	9	9	μΑ
I _{RMC_ODBM}	Pout 0 dBm, QPSK, 1SC, 15 kHz, TX 33% RX 33% ("balanced TX and RX"), RMC settings as per 3GPP TS	35	35	40	40	mA
	36.101 Annex A.2.4					
I _{RMC_10DBM}	Pout 10 dBm, QPSK, 1SC, 15 kHz, TX 33% RX 33% ("balanced TX and RX"), RMC settings as per 3GPP	40	45	45	45	mA
	TS 36.101 Annex A.2.4					
I _{RMC_23DBM}	Pout 23 dBm, QPSK, 1SC, 15 kHz, TX 33% RX 33% ("balanced TX and RX"), RMC settings as per 3GPP	95	105	110	110	mA
	TS 36.101 Annex A.2.4					
I _{RMC_ODBM}	Pout 0 dBm, BPSK, 1SC, 3.75 kHz, TX 80% RX 10% ("TX intensive"), RMC settings as per 3GPP TS	50	50	55	55	mA
	36.101 Annex A.2.4					
I _{RMC_10DBM}	Pout 10 dBm, BPSK, 1SC, 3.75 kHz, TX 80% RX 10% ("TX intensive"), RMC settings as per 3GPP TS	65	65	75	75	mA
	36.101 Annex A.2.4					
I _{RMC_23DBM}	Pout 23 dBm, BPSK, 1SC, 3.75 kHz, TX 80% RX 10% ("TX intensive"), RMC settings as per 3GPP TS	190	190	225	225	mA
	36.101 Annex A.2.4					
Peak curren	t consumption, nominal operating conditions, Cat-M1					
I _{TX_ODBM}	TX subframe, Pout 0 dBm	60	60	65	65	mA
I _{TX_10DBM}	TX subframe, Pout 10 dBm	80	85	90	90	mA
I _{TX_23DBM}	TX subframe, Pout 23 dBm	255	275	295	290	mA
I _{RX90DBM}	RX subframe, Pin -90 dBm	45	45	45	45	mA
I _{TX_TRANSIENT}	TX transient	35	35	35	35	mA/μs
Peak curren	t consumption, nominal operating conditions, Cat-NB1					
I _{TX_0DBM}	TX subframe, Pout 0 dBm	55	60	65	65	mA
I _{TX_10DBM}	TX subframe, Pout 10 dBm	75	85	90	85	mA
I _{TX_23DBM}	TX subframe, Pout 23 dBm	230	255	275	275	mA
I _{RX90DBM}	RX subframe, Pin -90 dBm	35	35	35	35	mA
I _{TX TRANSIENT}	TX transient	35	35	35	35	mA/μs
_	t consumption, extreme operating conditions, Cat-M1					, ,
I _{TX_PEAK}	TX subframe, Pout >21 dBm, Ant VSWR3	330	355	360	360	mA
	TX subframe, Pout >20 dBm, Ant VSWR3, Vbat 3.5 V, Temp 85 °C	355	390	375	375	mA
TX_PEAK	TX subframe, Pout >20 dBm, Ant VSWR3, Vbat 3.0 V, Temp 85 °C	415	415	435	435	mA
I _{TX_PEAK}		713	413	733	733	111/4
	t consumption, extreme operating conditions, Cat-NB1	200	210	225	225	A
TX_PEAK	TX subframe, Pout >21 dBm, Ant VSWR3	280	310	325	325	mA m A
TX_PEAK	TX subframe, Pout >20 dBm, Ant VSWR3, Vbat 3.5 V, Temp 85 °C	315	350	365	365	mA
I _{TX_PEAK}	TX subframe, Pout >20 dBm, Ant VSWR3, Vbat 3.0 V, Temp 85 °C	370	405	425	425	mA





5.6.1.16 GPS current consumption

Symbol	Description	Min.	Тур.	Max.	Units	
I _{GPS_CONTINUOUS}		44.3		mA		
	saving mode					
I _{GPS_CONTINUOUS_PS}	_{SM} Continuous tracking, power saving mode		9.6		mA	
I _{GPS SINGLE}	Single shot, one fix every 2 minutes		2.5		mA	

5.7 Register description

5.7.1 POWER — Power control

The POWER module provides an interface to tasks, events, interrupt and reset related configuration settings of the power management unit.

Note: Registers INTEN on page 71, INTENSET on page 71, and INTENCLR on page 72 are the same registers (at the same address) as corresponding registers in CLOCK — Clock control on page 74.

5.7.1.1 Registers

Base add	ress Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x500050	000 POWER	POWER: S	US	NA	Power control	
0x400050		POWER : NS	03	NA	rower control	

Table 22: Instances

Register	Offset	Security	Description
TASKS_CONSTLAT	0x78		Enable constant latency mode.
TASKS_LOWPWR	0x7C		Enable low power mode (variable latency)
SUBSCRIBE_CONSTLAT	0xF8		Subscribe configuration for task CONSTLAT
SUBSCRIBE_LOWPWR	0xFC		Subscribe configuration for task LOWPWR
EVENTS_POFWARN	0x108		Power failure warning
EVENTS_SLEEPENTER	0x114		CPU entered WFI/WFE sleep
EVENTS_SLEEPEXIT	0x118		CPU exited WFI/WFE sleep
PUBLISH_POFWARN	0x188		Publish configuration for event POFWARN
PUBLISH_SLEEPENTER	0x194		Publish configuration for event SLEEPENTER
PUBLISH_SLEEPEXIT	0x198		Publish configuration for event SLEEPEXIT
INTEN	0x300		Enable or disable interrupt
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
RESETREAS	0x400		Reset reason
POWERSTATUS	0x440		Modem domain power status
GPREGRET[n]	0x51C		General purpose retention register
LTEMODEM.STARTN	0x610		Start LTE modem
LTEMODEM.FORCEOFF	0x614		Force off LTE modem

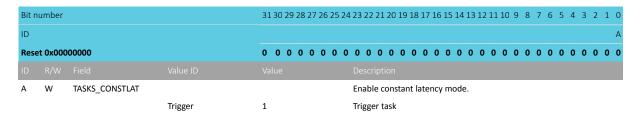
Table 23: Register overview

5.7.1.1.1 TASKS_CONSTLAT

Address offset: 0x78



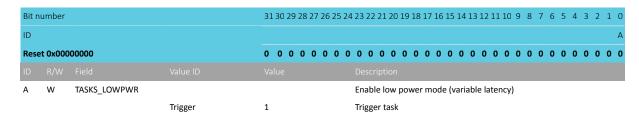
Enable constant latency mode.



5.7.1.1.2 TASKS_LOWPWR

Address offset: 0x7C

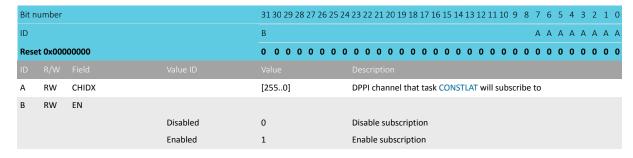
Enable low power mode (variable latency)



5.7.1.1.3 SUBSCRIBE_CONSTLAT

Address offset: 0xF8

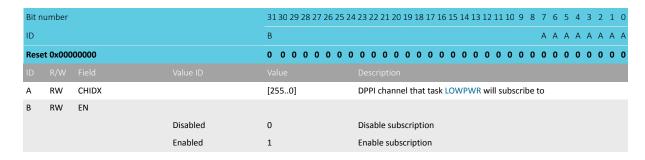
Subscribe configuration for task CONSTLAT



5.7.1.1.4 SUBSCRIBE_LOWPWR

Address offset: 0xFC

Subscribe configuration for task LOWPWR

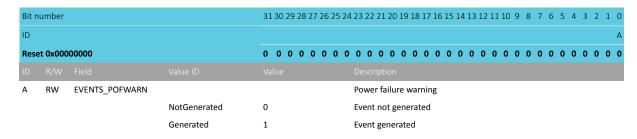


5.7.1.1.5 EVENTS_POFWARN

Address offset: 0x108



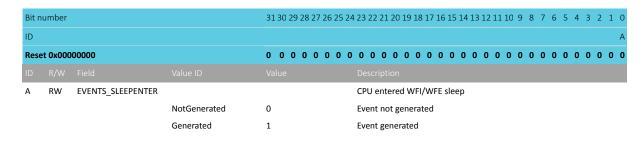
Power failure warning



5.7.1.1.6 EVENTS SLEEPENTER

Address offset: 0x114

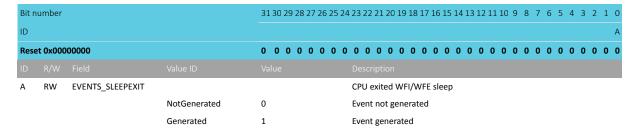
CPU entered WFI/WFE sleep



5.7.1.1.7 EVENTS_SLEEPEXIT

Address offset: 0x118

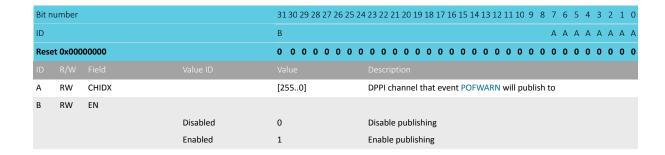
CPU exited WFI/WFE sleep



5.7.1.1.8 PUBLISH_POFWARN

Address offset: 0x188

Publish configuration for event POFWARN



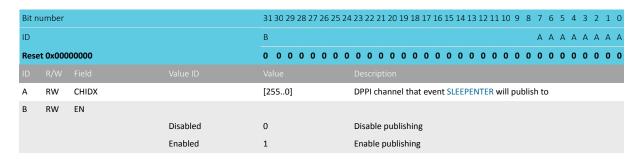




5.7.1.1.9 PUBLISH_SLEEPENTER

Address offset: 0x194

Publish configuration for event **SLEEPENTER**



5.7.1.1.10 PUBLISH_SLEEPEXIT

Address offset: 0x198

Publish configuration for event SLEEPEXIT

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[2550]	DPPI channel that event SLEEPEXIT will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing

5.7.1.1.11 INTEN

Address offset: 0x300

Enable or disable interrupt

Bit r	number			31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					E D A
Res	et 0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	POFWARN			Enable or disable interrupt for event POFWARN
			Disabled	0	Disable
			Enabled	1	Enable
D	RW	SLEEPENTER			Enable or disable interrupt for event SLEEPENTER
			Disabled	0	Disable
			Enabled	1	Enable
E	RW	SLEEPEXIT			Enable or disable interrupt for event SLEEPEXIT
			Disabled	0	Disable
			Enabled	1	Enable

5.7.1.1.12 INTENSET

Address offset: 0x304

Enable interrupt





Bit r	umber			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					E D A
Rese	et 0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
					Description
Α	RW	POFWARN			Write '1' to enable interrupt for event POFWARN
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
D	RW	SLEEPENTER			Write '1' to enable interrupt for event SLEEPENTER
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
Е	RW	SLEEPEXIT			Write '1' to enable interrupt for event SLEEPEXIT
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled

5.7.1.1.13 INTENCLR

Address offset: 0x308

Disable interrupt

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					E D A
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	POFWARN			Write '1' to disable interrupt for event POFWARN
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
D	RW	SLEEPENTER			Write '1' to disable interrupt for event SLEEPENTER
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
E	RW	SLEEPEXIT			Write '1' to disable interrupt for event SLEEPEXIT
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled

5.7.1.1.14 RESETREAS

Address offset: 0x400

Reset reason

Note: Unless cleared, the RESETREAS register will be cumulative. A field is cleared by writing '1' to it. If none of the reset sources are flagged, this indicates that the chip was reset from the on-chip reset generator, which will indicate a power-on reset or a brownout reset.

Bit r	number			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					G F E D C B A
Res	et 0x000	000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	RESETPIN			Reset from pin reset detected
			NotDetected	0	Not detected
			Detected	1	Detected
В	RW	DOG			Reset from global watchdog detected
			NotDetected	0	Not detected
			Detected	1	Detected
С	RW	OFF			Reset due to wakeup from System OFF mode, when wakeup is
					triggered by DETECT signal from GPIO
			NotDetected	0	Not detected
			Detected	1	Detected
D	RW	DIF			Reset due to wakeup from System OFF mode, when wakeup is
					triggered by entering debug interface mode
			NotDetected	0	Not detected
			Detected	1	Detected
E	RW	SREQ			Reset from AIRCR.SYSRESETREQ detected
			NotDetected	0	Not detected
			Detected	1	Detected
F	RW	LOCKUP			Reset from CPU lock-up detected
			NotDetected	0	Not detected
			Detected	1	Detected
G	RW	CTRLAP			Reset triggered through CTRL-AP
			NotDetected	0	Not detected
			Detected	1	Detected

5.7.1.1.15 POWERSTATUS

Address offset: 0x440

Modem domain power status

Bit n	umber			31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					A
Rese	t 0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	R	LTEMODEM			LTE modem domain status
			OFF	0	LTE modem domain is powered off
			ON	1	LTE modem domain is powered on

5.7.1.1.16 GPREGRET[n] (n=0..1)

Address offset: $0x51C + (n \times 0x4)$ General purpose retention register

Α	RW	GPREGRET		General purpose retention register
ID				
Res	et 0x000	00000	0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				A A A A A A A
Bit r	number		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

This register is a retained register

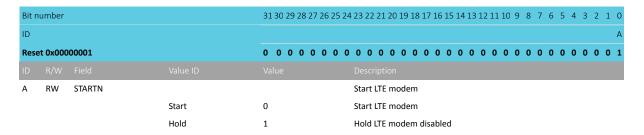


5.7.1.1.17 LTEMODEM.STARTN

Address offset: 0x610

Start LTE modem

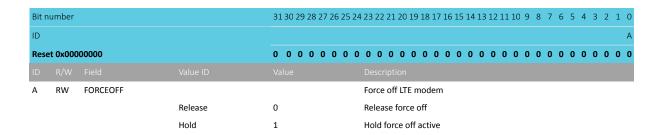
Note: Starting and stopping LTE modem must only be done through the LTE modem API to guarantee correct sequence in FW and HW and to avoid possible malfunctions.



5.7.1.1.18 LTEMODEM.FORCEOFF

Address offset: 0x614
Force off LTE modem

Note: Starting and stopping LTE modem must only be done through the LTE modem API to guarantee correct sequence in FW and HW and to avoid possible malfunctions.



5.7.2 CLOCK — Clock control

The CLOCK module provides one of the interfaces to power and clock management configuration settings.

Through CLOCK module it is able to configure the following:

- LFCLK clock source setup
- LFCLK and HFCLK status
- Tasks and events
- Interrupts
- Reset

Note: Registers INTEN on page 78, INTENSET on page 79, and INTENCLR on page 79 are the same registers (at the same address) as corresponding registers in POWER — Power control on page 68.



5.7.2.1 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x50005000	CLOCK	CLOCK : S	US		Clask control	
0x40005000	CLOCK	CLOCK : NS	U3	NA	Clock control	

Table 24: Instances

Register	Offset	Security	Description
TASKS_HFCLKSTART	0x000		Start HFCLK source
TASKS_HFCLKSTOP	0x004		Stop HFCLK source
TASKS_LFCLKSTART	0x008		Start LFCLK source
TASKS_LFCLKSTOP	0x00C		Stop LFCLK source
SUBSCRIBE_HFCLKSTART	0x080		Subscribe configuration for task HFCLKSTART
SUBSCRIBE_HFCLKSTOP	0x084		Subscribe configuration for task HFCLKSTOP
SUBSCRIBE_LFCLKSTART	0x088		Subscribe configuration for task LFCLKSTART
SUBSCRIBE_LFCLKSTOP	0x08C		Subscribe configuration for task LFCLKSTOP
EVENTS_HFCLKSTARTED	0x100		HFCLK oscillator started
EVENTS_LFCLKSTARTED	0x104		LFCLK started
PUBLISH_HFCLKSTARTED	0x180		Publish configuration for event HFCLKSTARTED
PUBLISH_LFCLKSTARTED	0x184		Publish configuration for event LFCLKSTARTED
INTEN	0x300		Enable or disable interrupt
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
INTPEND	0x30C		Pending interrupts
HFCLKRUN	0x408		Status indicating that HFCLKSTART task has been triggered
HFCLKSTAT	0x40C		The register shows if HFXO has been requested by triggering HFCLKSTART task and if it has
			been started (STATE)
LFCLKRUN	0x414		Status indicating that LFCLKSTART task has been triggered
LFCLKSTAT	0x418		The register shows which LFCLK source has been requested (SRC) when triggering LFCLKSTART
			task and if the source has been started (STATE)
LFCLKSRCCOPY	0x41C		Copy of LFCLKSRC register, set after LFCLKSTART task has been triggered
LFCLKSRC	0x518		Clock source for the LFCLK. LFCLKSTART task starts starts a clock source selected with this
			register.

Table 25: Register overview

5.7.2.1.1 TASKS_HFCLKSTART

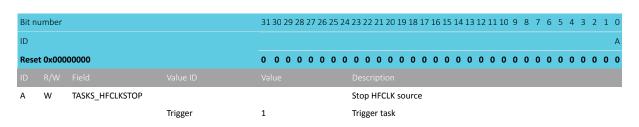
Address offset: 0x000 Start HFCLK source

			Trigger		Trigger task
Α	W	TASKS_HFCLKSTART			Start HFCLK source
					Description
Rese	t 0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					А
Bit n	umber			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

5.7.2.1.2 TASKS_HFCLKSTOP

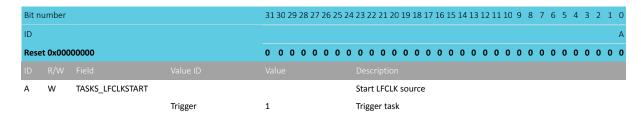
Address offset: 0x004 Stop HFCLK source





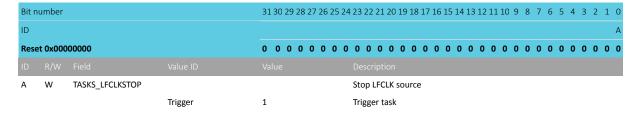
5.7.2.1.3 TASKS LFCLKSTART

Address offset: 0x008 Start LFCLK source



5.7.2.1.4 TASKS_LFCLKSTOP

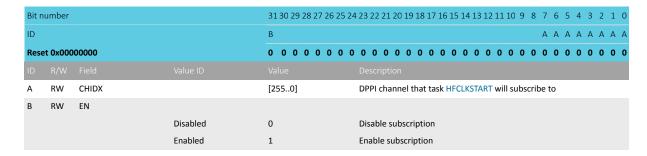
Address offset: 0x00C Stop LFCLK source



5.7.2.1.5 SUBSCRIBE_HFCLKSTART

Address offset: 0x080

Subscribe configuration for task HFCLKSTART



5.7.2.1.6 SUBSCRIBE_HFCLKSTOP

Address offset: 0x084

Subscribe configuration for task HFCLKSTOP



Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[2550]	DPPI channel that task HFCLKSTOP will subscribe to
В	RW	EN			
			Disabled	0	Disable subscription
			Enabled	1	Enable subscription

5.7.2.1.7 SUBSCRIBE_LFCLKSTART

Address offset: 0x088

Subscribe configuration for task LFCLKSTART

Bit n	umber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1
ID				В	A A A A A A
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[2550]	DPPI channel that task LFCLKSTART will subscribe to
В	RW	EN			
			Disabled	0	Disable subscription
			Enabled	1	Enable subscription

5.7.2.1.8 SUBSCRIBE_LFCLKSTOP

Address offset: 0x08C

Subscribe configuration for task LFCLKSTOP

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1	. 0
ID				В	A A A A A A	A
Reset 0x00000000				0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0) 0
ID						
Α	RW	CHIDX		[2550]	DPPI channel that task LFCLKSTOP will subscribe to	
В	RW	EN				
			Disabled	0	Disable subscription	
			Enabled	1	Enable subscription	

5.7.2.1.9 EVENTS_HFCLKSTARTED

Address offset: 0x100

HFCLK oscillator started

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					A
Rese	Reset 0x00000000			0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	EVENTS_HFCLKSTARTED)		HFCLK oscillator started
			NotGenerated	0	Event not generated
			Generated	1	Event generated

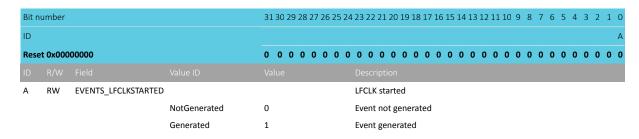




5.7.2.1.10 EVENTS_LFCLKSTARTED

Address offset: 0x104

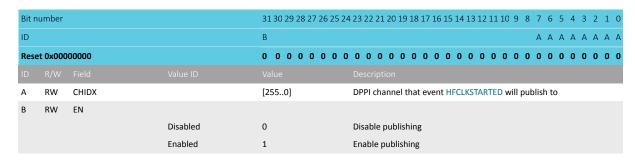
LFCLK started



5.7.2.1.11 PUBLISH_HFCLKSTARTED

Address offset: 0x180

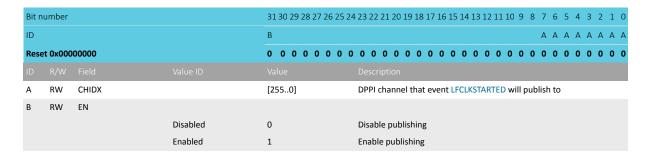
Publish configuration for event HFCLKSTARTED



5.7.2.1.12 PUBLISH_LFCLKSTARTED

Address offset: 0x184

Publish configuration for event LFCLKSTARTED



5.7.2.1.13 INTEN

Address offset: 0x300

Enable or disable interrupt



Rit n	umber			31 30 29 28 27	27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
	idilibei			3130232027	
ID					В А
Rese	et 0x000	00000		0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	HFCLKSTARTED			Enable or disable interrupt for event HFCLKSTARTED
			Disabled	0	Disable
			Enabled	1	Enable
В	RW	LFCLKSTARTED			Enable or disable interrupt for event LFCLKSTARTED
			Disabled	0	Disable
			Enabled	1	Enable

5.7.2.1.14 INTENSET

Address offset: 0x304

Enable interrupt

Rit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
	idilibei			313023202720232	
ID					В А
Rese	et 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	HFCLKSTARTED			Write '1' to enable interrupt for event HFCLKSTARTED
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
В	RW	LFCLKSTARTED			Write '1' to enable interrupt for event LFCLKSTARTED
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled

5.7.2.1.15 INTENCLR

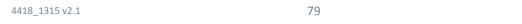
Address offset: 0x308

Disable interrupt

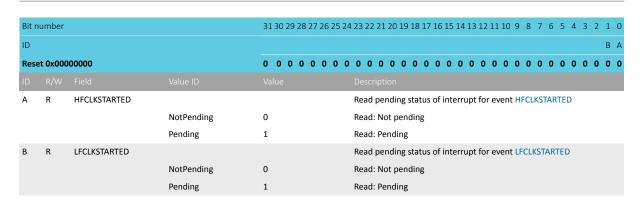
Bit n	umber			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID	ID				В А
Rese	Reset 0x00000000			0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	HFCLKSTARTED			Write '1' to disable interrupt for event HFCLKSTARTED
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
В	RW	LFCLKSTARTED			Write '1' to disable interrupt for event LFCLKSTARTED
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled

5.7.2.1.16 INTPEND

Address offset: 0x30C Pending interrupts







5.7.2.1.17 HFCLKRUN

Address offset: 0x408

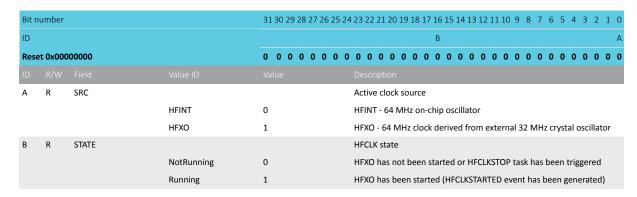
Status indicating that HFCLKSTART task has been triggered



5.7.2.1.18 HFCLKSTAT

Address offset: 0x40C

The register shows if HFXO has been requested by triggering HFCLKSTART task and if it has been started (STATE)

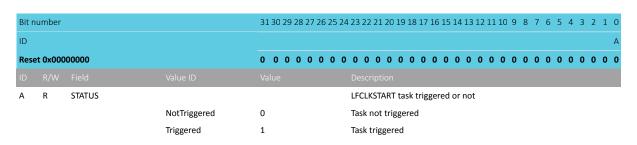


5.7.2.1.19 LFCLKRUN

Address offset: 0x414

Status indicating that LFCLKSTART task has been triggered

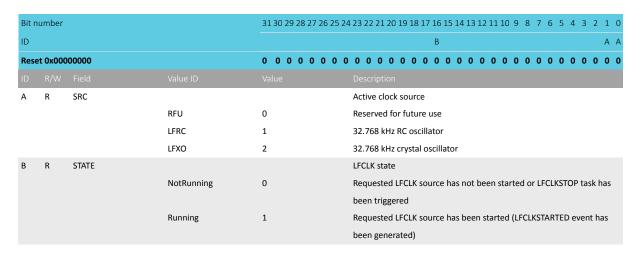




5.7.2.1.20 LFCLKSTAT

Address offset: 0x418

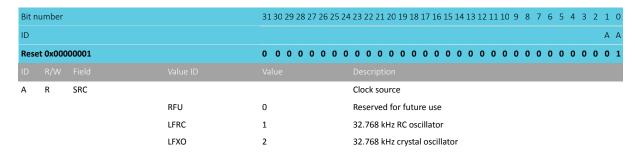
The register shows which LFCLK source has been requested (SRC) when triggering LFCLKSTART task and if the source has been started (STATE)



5.7.2.1.21 LFCLKSRCCOPY

Address offset: 0x41C

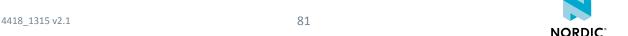
Copy of LFCLKSRC register, set after LFCLKSTART task has been triggered

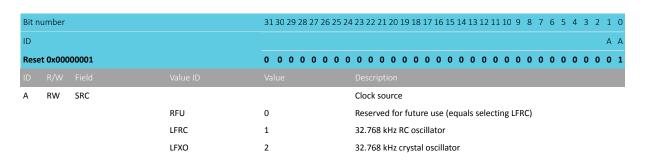


5.7.2.1.22 LFCLKSRC

Address offset: 0x518

Clock source for the LFCLK. LFCLKSTART task starts a clock source selected with this register.





5.7.3 REGULATORS — Voltage regulators control

The REGULATORS module provides an interface to certain configuration settings of on-chip voltage regulators.

5.7.3.1 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
		REGULATORS :				
0x50004000	REGULATORS	S	US	NA	Regulator configuration	
0x40004000		REGULATORS :				
		NS				

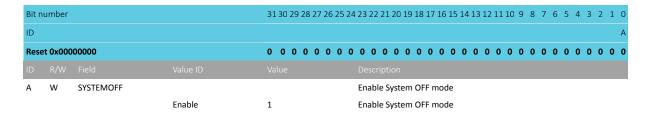
Table 26: Instances

Register	Offset	Security	Description
SYSTEMOFF	0x500		System OFF register
EXTPOFCON	0x514		External power failure warning configuration
DCDCEN	0x578		Enable DC/DC mode of the main voltage regulator.

Table 27: Register overview

5.7.3.1.1 SYSTEMOFF

Address offset: 0x500 System OFF register

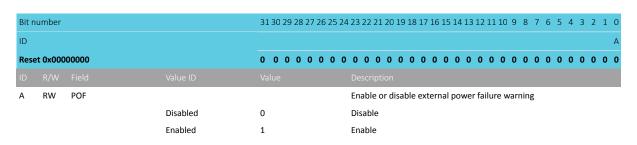


5.7.3.1.2 EXTPOFCON

Address offset: 0x514

External power failure warning configuration



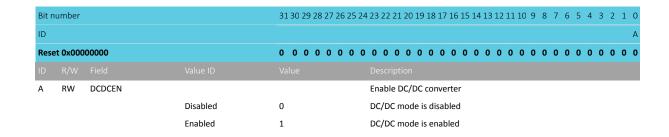


5.7.3.1.3 DCDCEN

Address offset: 0x578

Enable DC/DC mode of the main voltage regulator.

Note: DCDCEN must be set to 1 (enabled) before the LTE modem is started.





6 Peripherals

The nRF9160 application core peripherals are found in Instantiation on page 26.

6.1 CRYPTOCELL — ARM TrustZone CryptoCell 310

ARM TrustZone CryptoCell 310 (CRYPTOCELL) is a security subsystem which provides root of trust (RoT) and cryptographic services for a device.

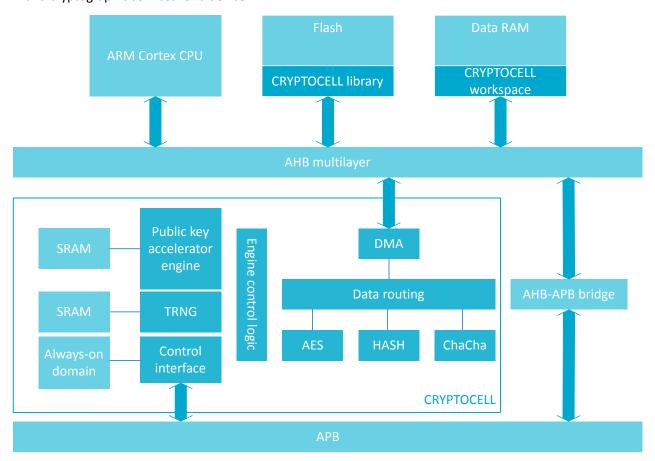


Figure 14: Block diagram for CRYPTOCELL

The following cryptographic features are provided:

- True random number generator (TRNG) compliant with NIST 800-90B, AIS-31, and FIPS 140-2
- Pseudorandom number generator (PRNG) using underlying AES engine compliant with NIST 800-90A
- RSA public key cryptography
 - Up to 2048-bit key size
 - PKCS#1 v2.1/v1.5
 - Optional CRT support
- Elliptic curve cryptography (ECC)
 - NIST FIPS 186-4 recommended curves using pseudorandom parameters, up to 521 bits:
 - Prime field: P-192, P-224, P-256, P-384, P-521
 - SEC 2 recommended curves using pseudorandom parameters, up to 521 bits:

NORDIC*

- Prime field: secp160r1, secp192r1, secp224r1, secp256r1, secp384r1, secp521r1
- Koblitz curves using fixed parameters, up to 256 bits:
 - Prime field: secp160k1, secp192k1, secp224k1, secp256k1
- Edwards/Montgomery curves:
 - Ed25519, Curve25519
- ECDH/ECDSA support
- Secure remote password protocol (SRP)
 - Up to 3072-bit operations
- · Hashing functions
 - SHA-1, SHA-2 up to 256 bits
 - Keyed-hash message authentication code (HMAC)
- · AES symmetric encryption
 - General purpose AES engine (encrypt/decrypt, sign/verify)
 - 128-bit key size
 - Supported encryption modes: ECB, CBC, CMAC/CBC-MAC, CTR, CCM/CCM* (CCM* is a minor variation of CCM)
- ChaCha20/Poly1305 symmetric encryption
 - Supported key size: 128 and 256 bits
 - Authenticated encryption with associated data (AEAD) mode

6.1.1 Usage

The CRYPTOCELL state is controlled via a register interface. The cryptographic functions of CRYPTOCELL are accessible by using a software library provided in the device SDK, not directly via a register interface.

To enable CRYPTOCELL, use register **ENABLE** on page 87.

Note: Keeping the CRYPTOCELL subsystem enabled will prevent the device from reaching the System ON, All Idle state.

6.1.2 Always-on (AO) power domain

The CRYPTOCELL subsystem has an internal always-on (AO) power domain for retaining device secrets when CRYPTOCELL is disabled.

The following information is retained by the AO power domain:

- 4 bits indicating the configured CRYPTOCELL lifecycle state (LCS)
- 1 bit indicating if the hard-coded RTL key, K_{PRTL} (see RTL key on page 86), is available for use
- 128-bit device root key, K_{DR} (see Device root key on page 86)

A reset from any reset source will erase the content in the AO power domain.

6.1.3 Lifecycle state (LCS)

Lifecycle refers to multiple states a device goes through during its lifetime. Two valid lifecycle states are offered for the device - debug and secure.

The CRYPTOCELL subsystem lifecycle state (LCS) is controlled through register HOST_IOT_LCS on page 90. A valid LCS is configured by writing either value <code>Debug</code> or <code>Secure</code> into the LCS field of this register. A correctly configured LCS can be validated by reading back the read-only field LCS_IS_VALID from the abovementioned register. The LCS_IS_VALID field value will change from <code>Invalid</code> to <code>Valid</code> once a valid LCS value has been written.



LCS field value	LCS_IS_VALID field value	Description
Secure	Invalid	Default reset value indicating that LCS has not been configured.
Secure	Valid	$LCS \ set \ to \ secure \ mode, and \ LCS \ is \ valid. \ Registers \ HOST_IOT_KDR[03] \ can \ only \ be \ written \ once \ per \ reset \ cycle.$
		Any additional writes will be ignored.
Debug	Valid	LCS set to debug mode, and LCS is valid. Registers HOST_IOT_KDR[03] can be written multiple times.

Table 28: Lifecycle states

6.1.4 Cryptographic key selection

The CRYPTOCELL subsystem can be instructed to operate on different cryptographic keys.

Through register HOST_CRYPTOKEY_SEL on page 88, the following key types can be selected for cryptographic operations:

- RTL key K_{PRTL}
- Device root key K_{DR}
- Session key

K_{PRTL} and K_{DR} are configured as part of the CRYPTOCELL initialization process, while session keys are provided by the application through the software library API.

6.1.4.1 RTL key

The ARM TrustZone CryptoCell 310 contains one hard-coded RTL key referred to as K_{PRTL} . This key is set to the same value for all devices with the same part code in the hardware design and cannot be changed.

The K_{PRTL} key can be requested for use in cryptographic operations by the CRYPTOCELL, without revealing the key value itself. Access to use of K_{PRTL} in cryptographic operations can be disabled until next reset by writing to register HOST_IOT_KPRTL_LOCK on page 89. If a locked K_{PRTL} key is requested for use, a zero vector key will be routed to the AES engine instead.

6.1.4.2 Device root key

The device root key K_{DR} is a 128-bit AES key programmed into the CRYPTOCELL subsystem using firmware. It is retained in the AO power domain until the next reset.

Once configured, it is possible to perform cryptographic operations using the the CRYPTOCELL subsystem where K_{DR} is selected as key input without having access to the key value itself. The K_{DR} key value must be written to registers HOST_IOT_KDR[0..3]. These 4 registers are write-only if LCS is set to debug mode, and write-once if LCS is set to secure mode. The K_{DR} key value is successfully retained when the read-back value of register HOST_IOT_KDR0 on page 89 changes to 1.

6.1.5 Direct memory access (DMA)

The CRYPTOCELL subsystem implements direct memory access (DMA) for accessing memory without CPU intervention.

Any data stored in memory type(s) not accessible by the DMA engine must be copied to SRAM before it can be processed by the CRYPTOCELL subsystem. Maximum DMA transaction size is limited to 2¹⁶-1 bytes.

6.1.6 Standards

ARM TrustZone CryptoCell 310 (CRYPTOCELL) supports a number of cryptography standards.



Algorithm family	Identification code	Document title
TRNG	NIST SP 800-90B	Recommendation for the Entropy Sources Used for Random Bit Generation
	AIS-31	A proposal for: Functionality classes and evaluation methodology for physical random number generators
	FIPS 140-2	Security Requirements for Cryptographic Modules
PRNG	NIST SP 800-90A	Recommendation for Random Number Generation Using Deterministic Random Bit Generators
Stream cipher	Chacha	ChaCha, a variant of Salsa20, Daniel J. Bernstein, January 28th 2008
MAC	Poly1305	The Poly1305-AES message-authentication code, Daniel J. Bernstein
		Cryptography in NaCl, Daniel J. Bernstein
Key agreement	SRP	The Secure Remote Password Protocol, Thomas Wu, November 11th 1997
AES	FIPS-197	Advanced Encryption Standard (AES)
	NIST SP 800-38A	Recommendation for Block Cipher Modes of Operation - Methods and Techniques
	NIST SP 800-38B	Recommendation for Block Cipher Modes of Operation: The CMAC Mode for Authentication
	NIST SP 800-38C	Recommendation for Block Cipher Modes of Operation: The CCM Mode for Authentication and Confidentiality
	ISO/IEC 9797-1	AES CBC-MAC per ISO/IEC 9797-1 MAC algorithm 1
	IEEE 802.15.4-2011	IEEE Standard for Local and metropolitan area networks - Part 15.4: Low-Rate Wireless Personal Area
		Networks (LR-WPANs), Annex B.4: Specification of generic CCM* mode of operation
Hash	FIPS 180-3	Secure Hash Standard (SHA1, SHA-224, SHA-256)
	RFC2104	HMAC: Keyed-Hashing for Message Authentication
RSA	PKCS#1	Public-Key Cryptography Standards (PKCS) #1: RSA Cryptography Specifications v1.5/2.1
Diffie-Hellman	ANSI X9.42	Public Key Cryptography for the Financial Services Industry: Agreement of Symmetric Keys Using Discrete
		Logarithm Cryptography
	PKCS#3	Diffie-Hellman Key-Agreement Standard
ECC	ANSI X9.63	Public Key Cryptography for the Financial Services Industry - Key Agreement and Key Transport Using Elliptic Curve Cryptography
	IEEE 1363	Standard Specifications for Public-Key Cryptography
	ANSI X9.62	Public Key Cryptography For The Financial Services Industry: The Elliptic Curve Digital Signature Algorithm (ECDSA)
	Ed25519	Edwards-curve, Ed25519: high-speed high-security signatures, Daniel J. Bernstein, Niels Duif, Tanja Lange,
		Peter Schwabe, and Bo-Yin Yang
	Curve25519	Montgomery curve, Curve25519: new Diffie-Hellman speed records, Daniel J. Bernstein
	FIPS 186-4	Digital Signature Standard (DSS)
	SEC 2	Recommended Elliptic Curve Domain Parameters, Certicom Research
	NIST SP 800-56A rev. 2	Recommendation for Pair-Wise Key Establishment Schemes Using Discrete Logarithm Cryptography

Table 29: CRYPTOCELL cryptography standards

6.1.7 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x50840000	CRYPTOCELL	CRYPTOCELL	S	NSA	CryptoCell sub-system contro	I
					interface	

Table 30: Instances

Register	Offset	Security	Description
ENABLE	0x500		Enable CRYPTOCELL subsystem

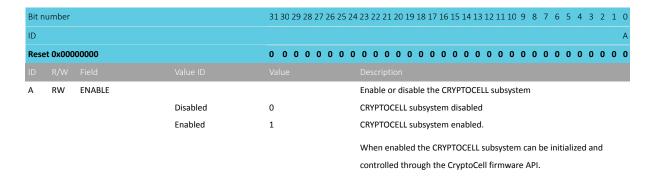
Table 31: Register overview

6.1.7.1 ENABLE

Address offset: 0x500



Enable CRYPTOCELL subsystem



6.1.8 Host interface

This chapter describes host registers used to control the CRYPTOCELL subsystem behavior.

6.1.8.1 HOST RGF block

The HOST_RGF block contains registers for configuring LCS and device root key K_{DR}, in addition to selecting which cryptographic key is connected to the AES engine.

6.1.8.1.1 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x50840000	CC_HOST_RGF	CC_HOST_RGF	: S	NSA	Host platform interface	

Table 32: Instances

Register	Offset	Security	Description
HOST_CRYPTOKEY_SEL	0x1A38		AES hardware key select
HOST_IOT_KPRTL_LOCK	0x1A4C		This write-once register is the K_PRTL lock register. When this register is set, K_PRTL cannot
			be used and a zeroed key will be used instead. The value of this register is saved in the
			CRYPTOCELL AO power domain.
HOST_IOT_KDR0	0x1A50		This register holds bits 31:0 of K_DR. The value of this register is saved in the CRYPTOCELL AO $$
			power domain. Reading from this address returns the K_DR valid status indicating if K_DR is
			successfully retained.
HOST_IOT_KDR1	0x1A54		This register holds bits 63:32 of K_DR. The value of this register is saved in the CRYPTOCELL
			AO power domain.
HOST_IOT_KDR2	0x1A58		This register holds bits 95:64 of K_DR. The value of this register is saved in the CRYPTOCELL
			AO power domain.
HOST_IOT_KDR3	0x1A5C		This register holds bits 127:96 of K_DR. The value of this register is saved in the CRYPTOCELL
			AO power domain.
HOST_IOT_LCS	0x1A60		Controls lifecycle state (LCS) for CRYPTOCELL subsystem

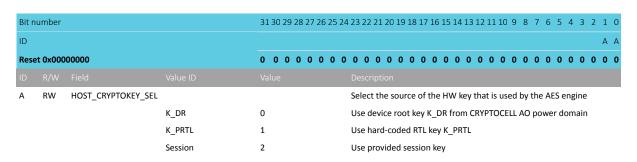
Table 33: Register overview

6.1.8.1.1.1 HOST_CRYPTOKEY_SEL

Address offset: 0x1A38
AES hardware key select

Note: If the HOST_IOT_KPRTL_LOCK register is set, and the HOST_CRYPTOKEY_SEL register set to 1, then the HW key that is connected to the AES engine is zero

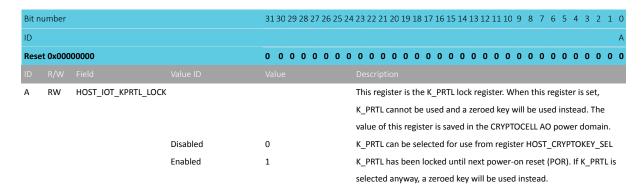




6.1.8.1.1.2 HOST_IOT_KPRTL_LOCK

Address offset: 0x1A4C

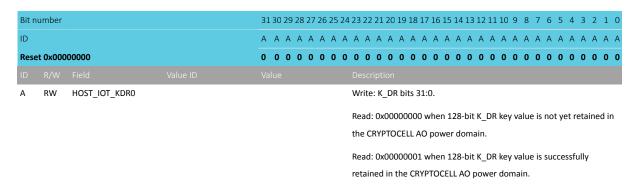
This write-once register is the K_PRTL lock register. When this register is set, K_PRTL cannot be used and a zeroed key will be used instead. The value of this register is saved in the CRYPTOCELL AO power domain.



6.1.8.1.1.3 HOST_IOT_KDR0

Address offset: 0x1A50

This register holds bits 31:0 of K_DR. The value of this register is saved in the CRYPTOCELL AO power domain. Reading from this address returns the K_DR valid status indicating if K_DR is successfully retained.

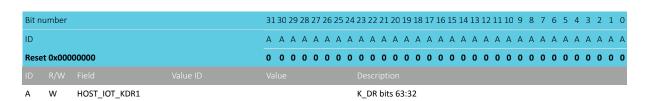


6.1.8.1.1.4 HOST_IOT_KDR1

Address offset: 0x1A54

This register holds bits 63:32 of K_DR. The value of this register is saved in the CRYPTOCELL AO power domain.

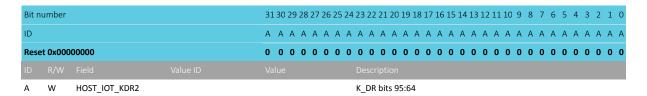




6.1.8.1.1.5 HOST_IOT_KDR2

Address offset: 0x1A58

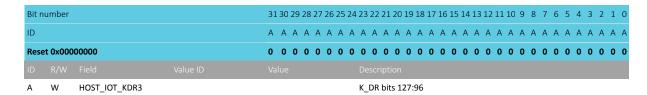
This register holds bits 95:64 of K_DR. The value of this register is saved in the CRYPTOCELL AO power domain.



6.1.8.1.1.6 HOST_IOT_KDR3

Address offset: 0x1A5C

This register holds bits 127:96 of K_DR. The value of this register is saved in the CRYPTOCELL AO power domain.



6.1.8.1.1.7 HOST_IOT_LCS

Address offset: 0x1A60

Controls lifecycle state (LCS) for CRYPTOCELL subsystem

Bit n	umber			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					B AAA
Rese	t 0x000	00002		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	LCS			Lifecycle state value. This field is write-once per reset.
			Debug	0	CC310 operates in debug mode
			Secure	2	CC310 operates in secure mode
В	RW	LCS_IS_VALID			Read-only field. Indicates if CRYPTOCELL LCS has been successfully
					configured since last reset.
			Invalid	0	Valid LCS not yet retained in the CRYPTOCELL AO power domain
			Valid	1	Valid LCS successfully retained in the CRYPTOCELL AO power domain



6.2 DPPI - Distributed programmable peripheral interconnect

The distributed programmable peripheral interconnect (DPPI) enables peripherals to interact autonomously with each other by using tasks and events, without any intervention from the CPU. DPPI allows precise synchronization between peripherals when real-time application constraints exist, and eliminates the need for CPU involvement to implement behavior which can be predefined using the DPPI.

Note: For more information on tasks, events, publish/subscribe, interrupts, and other concepts, see Peripheral interface on page 17.

The DPPI has the following features:

- · Peripheral tasks can subscribe to channels
- Peripheral events can be published on channels
- Publish/subscribe pattern enabling multiple connection options that include the following:
 - One-to-one
 - · One-to-many
 - Many-to-one
 - Many-to-many

The DPPI consists of several PPIBus modules, which are connected to a fixed number of DPPI channels and a DPPI configuration (DPPIC).



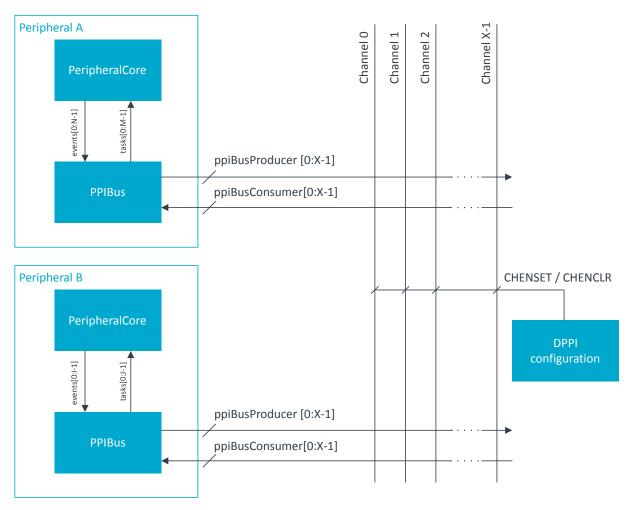


Figure 15: DPPI overview

6.2.1 Subscribing to and publishing on channels

The PPIBus can route peripheral events onto the channels (publishing), or route events from the channels into peripheral tasks (subscribing).

All peripherals include the following:

- One subscribe register per task
- One publish register per event

Publish and subscribe registers use a channel index field to determine the channel to which the event is published or tasks subscribed. In addition, there is an enable bit for the subscribe and publish registers that needs to be enabled before the subscription or publishing takes effect.

Writing non-existing channel index (CHIDX) numbers into a peripheral's publish or subscribe registers will yield unexpected results.

One event can trigger multiple tasks by subscribing different tasks to the same channel. Similarly, one task can be triggered by multiple events by publishing different events to the same channel. For advanced use cases, multiple events and multiple tasks can connect to the same channel forming a many-to-many connection. If multiple events are published on the same channel at the same time, the events are merged and only one event is routed through the DPPI.

How peripheral events are routed onto different channels based on publish registers is illustrated in the following figure.



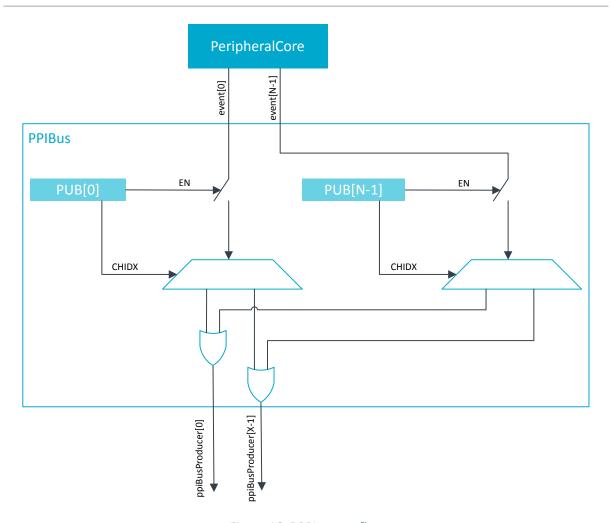


Figure 16: DPPI events flow

The following figure illustrates how peripheral tasks are triggered from different channels based on subscribe registers.



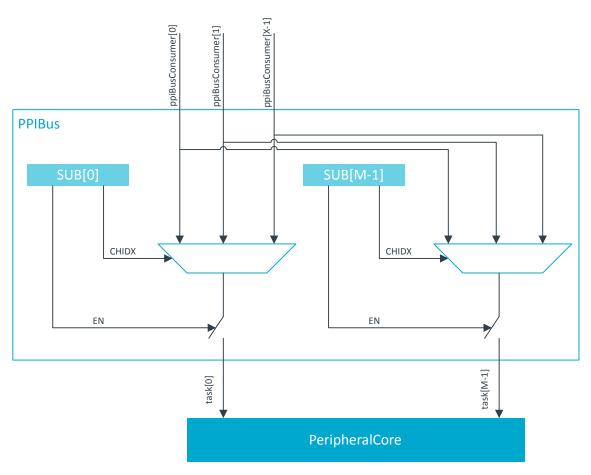


Figure 17: DPPI tasks flow

6.2.2 DPPI configuration (DPPIC)

Enabling and disabling of channels globally is handled through the DPPI configuration (DPPIC). Connection (connect/disconnect) between a channel and a peripheral is handled locally by the PPIBus.

There are two ways of enabling and disabling global channels using the DPPI configuration:

- Enable or disable channels individually using registers CHEN, CHENSET, and CHENCLR.
- Enable or disable channels in channel groups using the groups' tasks ENABLE and DISABLE. It needs to be defined which channels belong to which channel groups before these tasks are triggered.

Note: ENABLE tasks are prioritized over DISABLE tasks. When a channel belongs to two or more groups, for example group m and n, and the tasks CHG[m].EN and CHG[n].DIS occur simultaneously (m and n can be equal or different), the CHG[m].EN task on that channel is prioritized.

The DPPI configuration tasks (for example CHG[0].EN) can be triggered through DPPI like any other task, which means they can be linked to a DPPI channel through the subscribe registers.

In order to write to CHG[x], the corresponding CHG[x].EN and CHG[x].DIS subscribe registers must be disabled. Writes to CHG[x] are ignored if any of the two subscribe registers are enabled.

6.2.3 Connection examples

DPPI offers several connection options. Examples are given for how to create one-to-one and many-to-many connections.



One-to-one connection

This example shows how to create a one-to-one connection between TIMER compare register and SAADC start task.

The channel configuration is set up first. TIMERO will publish its COMPAREO event on channel 0, and SAADC will subscribe its START task to events on the same channel. After that, the channel is enabled through the DPPIC.

Many-to-many connection

The example shows how to create a many-to-many connection, showcasing the DPPIC's channel group functionality.

A channel group that includes only channel 0 is set up first. Then the GPIOTE and TIMERO configure their INO and COMPAREO events respectively to be published on channel 0, while the SAADC configures its START task to subscribe to events on channel 0. Through DPPIC, the CHGO DISABLE task is configured to subscribe to events on channel 0. After an event is received on channel 0 it will be disabled. Finally, channel 0 is enabled using the DPPIC task to enable a channel group.

6.2.4 Special considerations for a system implementing TrustZone for Cortex-M processors

DPPI is implemented with split security, meaning it handles both secure and non-secure accesses. In a system implementing the TrustZone for Cortex-M technology, DPPI channels can be defined as secure or non-secure using the SPU.

A peripheral configured as non-secure will only be able to subscribe to or publish on non-secure DPPI channels. A peripheral configured as secure will be able to access all DPPI channels. DPPI handles both secure and non-secure accesses, but behaves differently depending on the access type:

• A non-secure peripheral access can only configure and control the DPPI channels defined as non-secure in the SPU.DPPI.PERM[] register(s)



A secure peripheral access can control all the DPPI channels, independently of the SPU.DPPI.PERM[]
register(s)

A group of channels can be created, making it possible to simultaneously enable or disable all channels within the group. The security attribute of a group of channels (secure or non-secure) is defined as follows:

- If all channels (enabled or not) within a group are non-secure, then the group is considered non-secure
- If at least one of the channels (enabled or not) within the group is secure, then the group is considered secure

A non-secure access to a DPPI register, or a bit field, controlling a channel marked as secure in SPU.DPPI[].PERM register(s) will be ignored. Write accesses will have no effect, and read accesses will always return a zero value.

No exceptions are triggered when non-secure accesses target a register or a bit field controlling a secure channel. For example, if the bit \pm is set in the SPU.DPPI[0].PERM register (declaring DPPI channel i as secure), then:

- Non-secure write accesses to registers CHEN, CHENSET, and CHENCLR cannot write bit i of these registers
- Non-secure write accesses to TASK_CHG[j].EN and TASK_CHG[j].DIS registers are ignored if the channel group j contains at least one channel defined as secure (it can be the channel i itself or any channel declared as secure)
- Non-secure read accesses to registers CHEN, CHENSET, and CHENCLR always read 0 for the bit at
 position i

For the channel configuration registers (CHG[]), access from non-secure code is only possible if the included channels are all non-secure, whether the channels are enabled or not. If a CHG[g] register included one or more secure channel(s), then the group g is considered as secure, and only secure transfers can read to or write from CHG[g]. A non-secure write access is ignored, and a non-secure read access returns 0.

The DPPI can subscribe to secure and non-secure channels through the SUBSCRIBE_CHG[] registers, in order to trigger the task for enabling or disabling groups of channels. An event from a secure channel will be ignored if the group subscribing to this channel is non-secure. A secure group can subscribe to a non-secure channel or a secure channel.

6.2.5 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x50017000	DDDIC	DPPIC : S	SPLIT	NA	DPPI configuration	
0x40017000	DPPIC	DPPIC : NS				

Table 34: Instances



Register	Offset	Security	Description
TASKS_CHG[n].EN	0x000		Enable channel group n
TASKS_CHG[n].DIS	0x004		Disable channel group n
SUBSCRIBE_CHG[n].EN	0x080		Subscribe configuration for task CHG[n].EN
SUBSCRIBE_CHG[n].DIS	0x084		Subscribe configuration for task CHG[n].DIS
CHEN	0x500		Channel enable register
CHENSET	0x504		Channel enable set register
CHENCLR	0x508		Channel enable clear register
CHG[n]	0x800		Channel group n
			Note: Writes to this register are ignored if either SUBSCRIBE_CHG[n].EN or
			SUBSCRIBE_CHG[n].DIS is enabled

Table 35: Register overview

6.2.5.1 TASKS_CHG[n].EN (n=0..5)

Address offset: $0x000 + (n \times 0x8)$

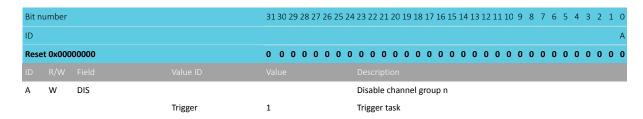
Enable channel group n

Bit r	umber			31 30 29 28 27 2	6 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					A
Rese	et 0x000	000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	W	EN			Enable channel group n
			Trigger	1	Trigger task

6.2.5.2 TASKS_CHG[n].DIS (n=0..5)

Address offset: $0x004 + (n \times 0x8)$

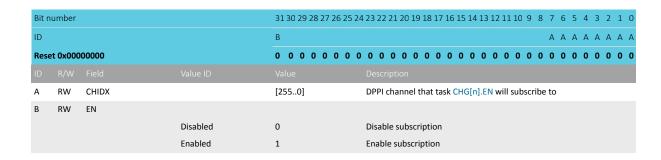
Disable channel group n



6.2.5.3 SUBSCRIBE_CHG[n].EN (n=0..5)

Address offset: $0x080 + (n \times 0x8)$

Subscribe configuration for task CHG[n].EN

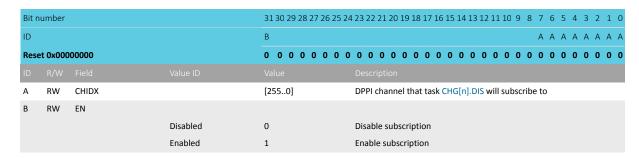




6.2.5.4 SUBSCRIBE_CHG[n].DIS (n=0..5)

Address offset: $0x084 + (n \times 0x8)$

Subscribe configuration for task CHG[n].DIS



6.2.5.5 CHEN

Address offset: 0x500 Channel enable register

Bit n	umber			31 30 29 28 2	7 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					PONMLKJIHGFEDCBA
Rese	t 0x000	00000		0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
A-P	RW	CH[i] (i=015)			Enable or disable channel i
			Disabled	0	Disable channel
			Enabled	1	Enable channel

6.2.5.6 CHENSET

Address offset: 0x504

Channel enable set register

Note: Read: Reads value of CH{i} field in CHEN register

Bit nu	ımber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					PONMLKJIHGFEDCBA
Reset	0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
A-P	RW	CH[i] (i=015)			Channel i enable set register. Writing 0 has no effect.
			Disabled	0	Read: Channel disabled
			Enabled	1	Read: Channel enabled
			Set	1	Write: Enable channel

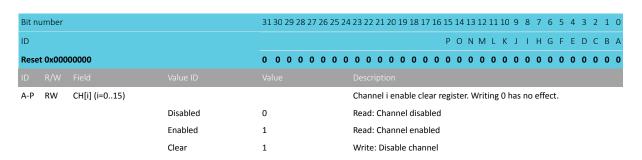
6.2.5.7 CHENCLR

Address offset: 0x508

Channel enable clear register

Note: Read: Reads value of CH{i} field in CHEN register



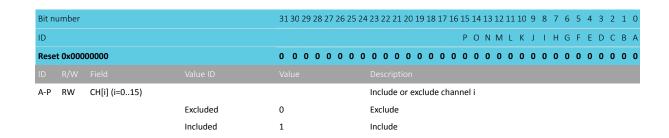


6.2.5.8 CHG[n] (n=0..5)

Address offset: $0x800 + (n \times 0x4)$

Channel group n

Note: Writes to this register are ignored if either SUBSCRIBE_CHG[n].EN or SUBSCRIBE_CHG[n].DIS is enabled



6.3 EGU — Event generator unit

Event generator unit (EGU) provides support for interlayer signaling. This means providing support for atomic triggering of both CPU execution and hardware tasks, from both firmware (by CPU) and hardware (by PPI). This feature can, for instance, be used for triggering CPU execution at a lower priority execution from a higher priority execution, or to handle a peripheral's interrupt service routine (ISR) execution at a lower priority for some of its events. However, triggering any priority from any priority is possible.

Listed here are the main EGU features:

- · Software-enabled interrupt triggering
- Separate interrupt vectors for every EGU instance
- Up to 16 separate event flags per interrupt for multiplexing

Each instance of EGU implements a set of tasks which can individually be triggered to generate the corresponding event, for example, the corresponding event for TASKS_TRIGGER[n] is EVENTS_TRIGGERED[n]. See Instances on page 100 for a list of EGU instances.



6.3.1 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x5001B000	EGU	EGU0 : S	US	NA	Event generator unit 0	
0x4001B000	200	EGU0 : NS	03	NA .	Event generator unit o	
0x5001C000	EGU	EGU1:S	US	NA	Event generator unit 1	
0x4001C000	LOO	EGU1: NS	03	NA .	Event generator unit 1	
0x5001D000	EGU	EGU2 : S	US	NA	Event generator unit 2	
0x4001D000	LGO	EGU2 : NS	03	NA	Event generator unit 2	
0x5001E000	EGU	EGU3:S	US	NA	Event generator unit 3	
0x4001E000	100	EGU3 : NS	03	NA.	Event generator unit 3	
0x5001F000	EGU	EGU4 : S	US	NA	Event generator unit 4	
0x4001F000	Luo	EGU4 : NS	03	NA	Event generator unit 4	
0x50020000	EGU	EGU5 : S	US	NA	Event generator unit 5	
0x40020000	LGO	EGU5 : NS	03	INA	Event Remerator unit 3	

Table 36: Instances

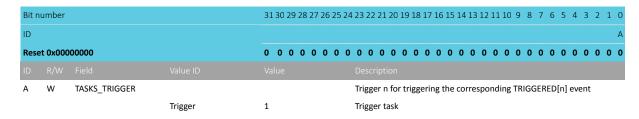
Register	Offset	Security	Description
TASKS_TRIGGER[n]	0x000		Trigger n for triggering the corresponding TRIGGERED[n] event
SUBSCRIBE_TRIGGER[n]	0x080		Subscribe configuration for task TRIGGER[n]
EVENTS_TRIGGERED[n]	0x100		Event number n generated by triggering the corresponding TRIGGER[n] task
PUBLISH_TRIGGERED[n]	0x180		Publish configuration for event TRIGGERED[n]
INTEN	0x300		Enable or disable interrupt
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt

Table 37: Register overview

6.3.1.1 TASKS_TRIGGER[n] (n=0..15)

Address offset: $0x000 + (n \times 0x4)$

Trigger n for triggering the corresponding TRIGGERED[n] event

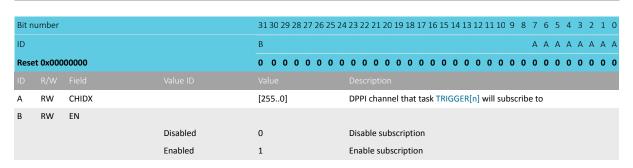


6.3.1.2 SUBSCRIBE_TRIGGER[n] (n=0..15)

Address offset: $0x080 + (n \times 0x4)$

Subscribe configuration for task TRIGGER[n]

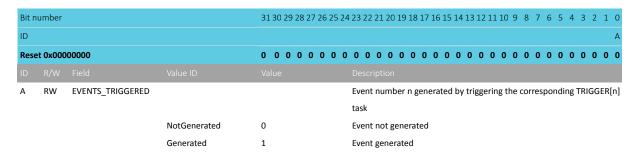




6.3.1.3 EVENTS_TRIGGERED[n] (n=0..15)

Address offset: $0x100 + (n \times 0x4)$

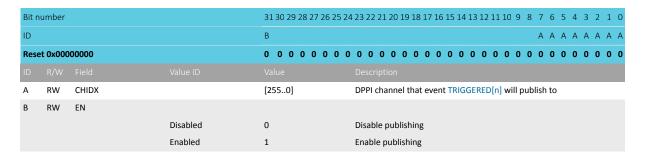
Event number n generated by triggering the corresponding TRIGGER[n] task



6.3.1.4 PUBLISH TRIGGERED[n] (n=0..15)

Address offset: $0x180 + (n \times 0x4)$

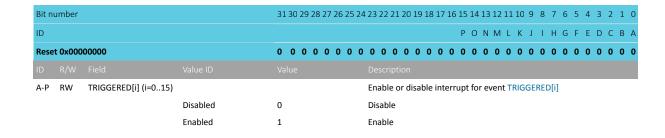
Publish configuration for event TRIGGERED[n]



6.3.1.5 INTEN

Address offset: 0x300

Enable or disable interrupt

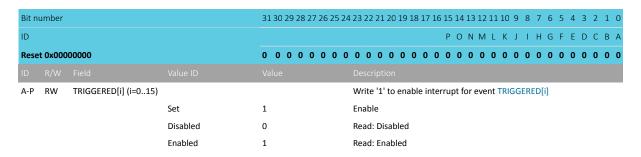




6.3.1.6 INTENSET

Address offset: 0x304

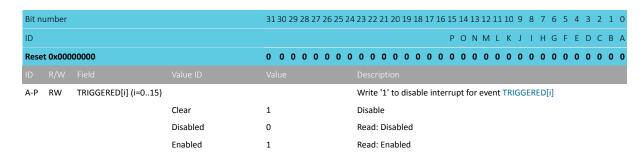
Enable interrupt



6.3.1.7 INTENCLR

Address offset: 0x308

Disable interrupt



6.3.2 Electrical specification

6.3.2.1 EGU Electrical Specification

Symbol	Description	Min.	Тур.	Max.	Units
t _{EGU,EVT}	Latency between setting an EGU event flag and the system		1		cycles
	setting an interrupt				

6.4 GPIO — General purpose input/output

The general purpose input/output pins (GPIOs) are grouped as one or more ports with each port having up to 32 GPIOs.

The number of ports and GPIOs per port may vary with product variant and package. Refer to Registers on page 106 and Pin assignments on page 390 for more information about the number of GPIOs that are supported.

GPIO has the following user-configurable features:

- Up to 32 GPIO pins per GPIO port
- Configurable output drive strength
- Internal pull-up and pull-down resistors
- Wake-up from high or low level triggers on all pins

NORDIC*

- Trigger interrupt on state changes on any pin
- All pins can be used by the PPI task/event system
- One or more GPIO outputs can be controlled through PPI and GPIOTE channels
- All pins can be individually mapped to interface blocks for layout flexibility
- GPIO state changes captured on SENSE signal can be stored by LATCH register
- Support for secure and non-secure attributes for pins in conjunction with the system protection unit (SPU — System protection unit on page 264)

GPIO port and the GPIO pin details on page 103 illustrates the GPIO port containing 32 individual pins, where PINO is illustrated in more detail as a reference. All signals on the left side in the illustration are used by other peripherals in the system and therefore not directly available to the CPU.

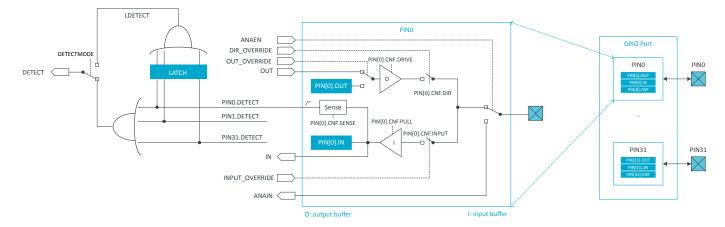


Figure 18: GPIO port and the GPIO pin details

6.4.1 Pin configuration

The GPIO port peripheral implements up to 32 pins, PIN0 through PIN31. Each of these pins can be individually configured in the PIN_CNF[n] registers (n=0..31).

The following parameters can be configured through these registers:

- Direction
- Drive strength
- Enabling of pull-up and pull-down resistors
- Pin sensing
- Input buffer disconnect
- Analog input (for selected pins)

Note: All write-capable registers are retained registers, see POWER — Power control on page 68 for more information.

The input buffer of a GPIO pin can be disconnected from the pin to enable power savings when the pin is not used as an input, see GPIO port and the GPIO pin details on page 103. Inputs must be connected to get a valid input value in the IN register, and for the sense mechanism to get access to the pin.

Other peripherals in the system can connect to GPIO pins and override their output value and configuration, or read their analog or digital input value. See GPIO port and the GPIO pin details on page 103.

Selected pins also support analog input signals, see ANAIN in GPIO port and the GPIO pin details on page 103. The assignment of the analog pins can be found in Pin assignments on page 390.

The following delays should be taken into considerations:

• There is a delay of 2 CPU clock cycles from the GPIO pad to the IN register.



 The GPIO pad must be low (or high depending on the SENSE polarity) for 3 CPU clock cycles after DETECT has gone high to generate a new DETECT signal.

Note: When a pin is configured as digital input, care has been taken to minimize increased current consumption when the input voltage is between V_{IL} and V_{IH} . However, it is a good practice to ensure that the external circuitry does not drive that pin to levels between V_{IL} and V_{IH} for a long period of time.

6.4.2 Pin sense mechanism

Pins sensitivity can be individually configured, through the SENSE field in the PIN_CNF[n] register, to detect either a high level or a low level on their input.

When the correct level is detected on any such configured pin, the sense mechanism will set the DETECT signal high. Each pin has a separate DETECT signal. Default behavior, defined by the DETECTMODE register, is that the DETECT signals from all pins in the GPIO port are combined into one common DETECT signal that is routed throughout the system, which then can be utilized by other peripherals. This mechanism is functional in both System ON and System OFF modes.

DETECTMODE and DETECTMODE_SEC are provided to handle secure and non-secure pins.

DETECTMODE_SEC register is available to control the behavior associated to pin marked as secure, while the DETECTMODE register is restricted to pin marked as non-secure. Please refer to GPIO security on page 105 for more details.

Make sure that a pin is in a level that cannot trigger the sense mechanism before enabling it. The DETECT signal will go high immediately if the SENSE condition configured in the PIN_CNF registers is met when the sense mechanism is enabled. This will trigger a PORT event if the DETECT signal was low before enabling the sense mechanism.

The DETECT signal is also used by power and clock management system to exit from System OFF mode, and by GPIOTE to generate the PORT event. In addition GPIOTE_SEC is used for PORT event related to secure pins). See POWER — Power control on page 68 and GPIOTE — GPIO tasks and events on page 111 for more information about how the DETECT signal is used.

When a pin's PINx.DETECT signal goes high, a flag will be set in the LATCH register. For example, when the PINO.DETECT signal goes high, bit 0 in the LATCH register will be set to '1'. If the CPU performs a clear operation on a bit in the LATCH register when the associated PINx.DETECT signal is high, the bit in the LATCH register will not be cleared. The LATCH register will only be cleared if the CPU explicitly clears it by writing a '1' to the bit that shall be cleared, i.e. the LATCH register will not be affected by a PINx.DETECT signal being set low.

The LDETECT signal will be set high when one or more bits in the LATCH register are '1'. The LDETECT signal will be set low when all bits in the LATCH register are successfully cleared to '0'.

If one or more bits in the LATCH register are '1' after the CPU has performed a clear operation on the LATCH registers, a rising edge will be generated on the LDETECT signal. This is illustrated in DETECT signal behavior on page 105.

Note: The CPU can read the LATCH register at any time to check if a SENSE condition has been met on one or more of the the GPIO pins, even if that condition is no longer met at the time the CPU queries the LATCH register. This mechanism will work even if the LDETECT signal is not used as the DETECT signal.

The LDETECT signal is by default not connected to the GPIO port's DETECT signal, but via the DETECTMODE register it is possible to change from default behavior to DETECT signal being derived directly from the LDETECT signal instead. See GPIO port and the GPIO pin details on page 103. DETECT signal behavior on page 105 illustrates the DETECT signal behavior for these two alternatives.



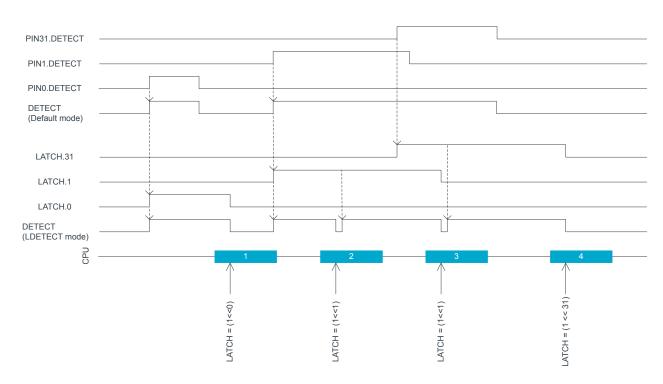


Figure 19: DETECT signal behavior

6.4.3 GPIO security

The general purpose input/output (GPIO) peripheral is implemented as a *split-security* peripheral. If marked as non-secure, it can be accessed by both secure and non-secure accesses but will behave differently depending on the access type.

A non-secure peripheral access will only be able to configure and control pins defined as non-secure in the system protection unit (SPU) GPIOPORT.PERM[] register(s).

A non-secure access to a register or a bitfield controlling a pin marked as secure in GPIO.PERM[] register(s) will be ignored. Write access will have no effect and read access will return a zero value.

No exception is triggered when a non-secure access targets a register or bitfield controlling a secure pin. For example, if the bit \pm is set in the SPU.GPIO.PERM[0] register (declaring Pin P0. \pm as secure), then

- non-secure write accesses to OUT, OUTSET, OUTCLR, DIR, DIRSET, DIRCLR and LATCH registers will not be able to write to bit i of those registers
- non-secure write accesses to registers PIN[i].OUT and PIN_CNF[i] will be ignored
- non-secure read accesses to registers OUT, OUTSET, OUTCLR, IN, DIR, DIRSET, DIRCLR and LATCH will always read a '0' for the bit at position $\dot{\text{1}}$
- non-secure read accesses to registers PIN[i].OUT, PIN[i].OUT and PIN_CNF[i] will always return 0

The GPIO.DETECTMODE and GPIO.DETECTMODE_SEC registers are handled differently than the other registers mentioned before. When accessed by a secure access, the DETECTMODE_SEC register control the source for the DETECT_SEC signal for the pins marked as secure. When accessed by a non-secure access, the DETECTMODE_SEC is read as zero and write accesses are ignored. The GPIO.DETECTMODE register controls the source for the DETECT_NSEC signal for the pins defined as non-secure.

The DETECT_NSEC signal is routed to the GPIOTE peripheral, allowing generation of events and interrupts from pins marked as non-secure. The DETECT_SEC signal is routed to the GPIOTESEC peripheral, allowing generation of events and interrupts from pins marked as secure. Principle of direct pin access on page 106 illustrates how the DETECT_NSEC and DETECT_SEC signals are generated from the GPIO PIN[].DETECT signals.



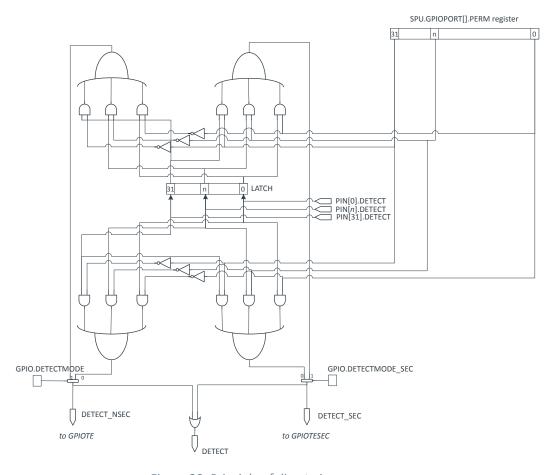


Figure 20: Principle of direct pin access

6.4.4 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x50842500	GPIO	P0 : S	SPLIT	NA	General purpose input and	
0x40842500	Grio	P0 : NS	JFLI1	INA	output	

Table 38: Instances

Register	Offset	Security	Description
OUT	0x004		Write GPIO port
			This register is retained.
OUTSET	0x008		Set individual bits in GPIO port
OUTCLR	0x00C		Clear individual bits in GPIO port
IN	0x010		Read GPIO port
DIR	0x014		Direction of GPIO pins
			This register is retained.
DIRSET	0x018		DIR set register
DIRCLR	0x01C		DIR clear register
LATCH	0x020		Latch register indicating what GPIO pins that have met the criteria set in the
			PIN_CNF[n].SENSE registers
			This register is retained.
DETECTMODE	0x024		Select between default DETECT signal behavior and LDETECT mode (For non-secure pin only)
			This register is retained.



Register	Offset	Security	Description
DETECTMODE_SEC	0x028		Select between default DETECT signal behavior and LDETECT mode (For secure pin only)
			This register is retained.
PIN_CNF[n]	0x200		Configuration of GPIO pins
			This register is retained.

Table 39: Register overview

6.4.4.1 OUT (Retained)

Address offset: 0x004

Write GPIO port

This register is retained.

Bit number			31	.30	29	28	27 :	26 2	25 2	24 2	23 2	22 2	1 2	0 19	9 18	17	16	15 1	4 1	3 12	2 11	. 10	9	8	7	6 !	5 4	1 3	2	1 0
ID			f	е	d	С	b	а	Ζ	Υ :	X١	w '	Vι	JΤ	S	R	Q	Р	1 C	N N	1 L	K	J	I	Н	G I	F E	E D	С	ВА
Reset 0x00	000000		0	0	0	0	0	0	0	0	0	0	0 0	0	0	0	0	0	0 (0	0	0	0	0	0	0 (0 (0	0	0 0
ID R/W																														
A-f RW	PIN[i] (i=031)									F	Pin	i																		
		Low	0							F	Pin	dri	ver	is lo	w															
		High	1				Pin driver is high																							

6.4.4.2 OUTSET

Address offset: 0x008

Set individual bits in GPIO port

Note: Read: reads value of OUT register.

Bit number				31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				fedcbaZY	X W V U T S R Q P O N M L K J I H G F E D C B A
Rese	et 0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
A-f	RW	PIN[i] (i=031)			Pin i
			Low	0	Read: pin driver is low
			High	1	Read: pin driver is high

6.4.4.3 OUTCLR

Address offset: 0x00C

Clear individual bits in GPIO port

Note: Read: reads value of OUT register.



Bit number		21	20	20	20	27 2	- JI	- 24	22		1 11	20	10.1	0 1	7 1 (1 1 5	11	10	121	1 10		0	7	C	_	1	2 -	1	0
																													U
ID				d	С	b a	Z	Y	Х	W	' V	U	Т	S R	Q	. Р	0	N	M I	_ K	J	1	Н	G	F	Ε	D (В	Α
Reset 0x00000000 0			0	0	0	0 0	0	0	0	0	0	0	0	0 0	0	0	0	0	0 (0	0	0	0	0	0	0	0 (0	0
ID R/W Field																													
A-f RW PIN[i] (i=031)									Pi	n i																			
	Low	0							Re	ead	: piı	n dr	iver	is lo	w														
	High	1							Re	ead	: piı	n dr	iver	is h	igh														
	Clear	1					Write: writing a '1' sets the pin low; writing a '0' has no effect																						

6.4.4.4 IN

Address offset: 0x010

Read GPIO port

Bit nu	ımber			31	L 30	29	9 28	27	26	25 2	24 2	23 2	22 2	1 20	0 19	18	17	16 1	.5 1	4 13	12	11	10	9 8	7	6	5	4	3	2 1	. 0
ID				f	е	d	С	b	а	Z	Υ :	ΧV	N V	/ U	ΙT	S	R	Q	P C	N	М	L	K	J I	Н	G	F	Ε	D	C E	3 A
Reset	0x000	00000		0	0	0	0	0	0	0	0	0 (0 0	0	0	0	0	0	0 0	0	0	0	0	0 0	0	0	0	0	0	0 (0
ID																															
A-f	R	PIN[i] (i=031)									Pin i																				
			Low	0				Pin input is low																							
			High	1					Pin input is high																						

6.4.4.5 DIR (Retained)

Address offset: 0x014
Direction of GPIO pins
This register is retained.

Bit n	Bit number 31					29	28	27	26	25	24 2	23 2	22 2	21 2	0 1	9 1	8 1	7 16	15	14	13	12 1	.11	0 9	8	7	6	5	4	3 2	2 1	. 0
ID	ID f				е	d	С	b	а	Z	Υ	Χ '	W '	νι	- ر	Γ 9	S R	Q	Р	0	N	М	L I	(J	-1	Н	G	F	Ε	D (C E	Α
Rese	t 0x000	00000		0	0	0	0	0	0	0	0	0	0	0 () () (0 0	0	0	0	0	0	0 (0	0	0	0	0	0	0 () (0
ID																																
A-f	RW	PIN[i] (i=031)									Pin i																					
			Input	0	0				Pin set as input																							
			Output	1	1						Pin set as output																					

6.4.4.6 DIRSET

Address offset: 0x018

DIR set register

Note: Read: reads value of DIR register.

Bit no	Bit number 3				31 30 29 28 27 26 25 24 2						4 23 22 21 20 19 18 17 16							5 15	15 14 13 12 11				0 9	8	7	6	5 4	4 3	2	1 0
ID				f	е	d	С	b	a :	Z١	γX	(W	/ V	U	Т	S F	≀ Q	. Р	0	N	М	LI	(J	-1	Н	G	F	E C) С	ВА
Rese	et 0x00000000					0	0	0	0	0 (0	0	0	0	0	0 (0	0	0	0	0	0 (0	0	0	0	0	0 0	0	0 0
ID									Description																					
A-f	RW	PIN[i] (i=031)		9				Set as output pin i																						
			Input	0				Read: pin set as input																						
			Output	1					Read: pin set as output																					
			Set	1							Write: writing a '1' sets pin to output; writing a '0' has no effect																			

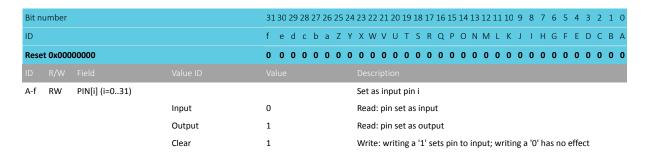


6.4.4.7 DIRCLR

Address offset: 0x01C

DIR clear register

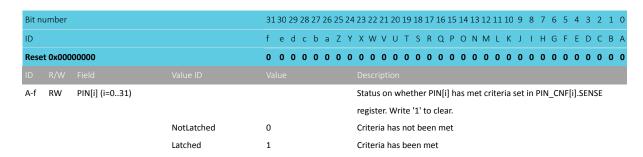
Note: Read: reads value of DIR register.



6.4.4.8 LATCH (Retained)

Address offset: 0x020

Latch register indicating what GPIO pins that have met the criteria set in the PIN_CNF[n].SENSE registers This register is retained.

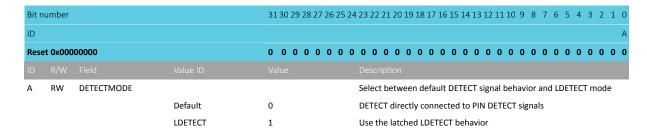


6.4.4.9 DETECTMODE (Retained)

Address offset: 0x024

Select between default DETECT signal behavior and LDETECT mode (For non-secure pin only)

This register is retained.



6.4.4.10 DETECTMODE_SEC (Retained)

Address offset: 0x028

Select between default DETECT signal behavior and LDETECT mode (For secure pin only)

This register is retained.



Bit number			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			А	
Reset 0x00	000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID R/W				
A RW	DETECTMODE			Select between default DETECT signal behavior and LDETECT mode
		Default	0	DETECT directly connected to PIN DETECT signals
		LDETECT	1	Use the latched LDETECT behavior

6.4.4.11 PIN_CNF[n] (n=0..31) (Retained)

Address offset: $0x200 + (n \times 0x4)$

Configuration of GPIO pins

This register is retained.

Bit n	umber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					E E DDD CCBA
Rese	et 0x000	00002		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
Α	RW	DIR			Pin direction. Same physical register as DIR register
			Input	0	Configure pin as an input pin
			Output	1	Configure pin as an output pin
В	RW	INPUT			Connect or disconnect input buffer
			Connect	0	Connect input buffer
			Disconnect	1	Disconnect input buffer
С	RW	PULL			Pull configuration
			Disabled	0	No pull
			Pulldown	1	Pull down on pin
			Pullup	3	Pull up on pin
D	RW	DRIVE			Drive configuration
			S0S1	0	Standard '0', standard '1'
			H0S1	1	High drive '0', standard '1'
			SOH1	2	Standard '0', high drive '1'
			H0H1	3	High drive '0', high 'drive '1"
			D0S1	4	Disconnect '0', standard '1' (normally used for wired-or connections)
			D0H1	5	Disconnect '0', high drive '1' (normally used for wired-or connections)
			SOD1	6	Standard '0', disconnect '1' (normally used for wired-and connections)
			H0D1	7	High drive '0', disconnect '1' (normally used for wired-and connections)
E	RW	SENSE			Pin sensing mechanism
			Disabled	0	Disabled
			High	2	Sense for high level
			Low	3	Sense for low level

6.4.5 Electrical specification

6.4.5.1 GPIO Electrical Specification

Note: VDD in the following table refers to VDD_GPIO.

Symbol	Description	Min.	Тур.	Max.	Units
V _{IH}	Input high voltage	0.7 x		VDD	V
		VDD			



Symbol	Description	Min.	Тур.	Max.	Units
V _{IL}	Input low voltage	VSS		0.3 x	V
				VDD	
V _{OH,SD}	Output high voltage, standard drive, 0.5 mA, VDD \geq 1.7 V	VDD-0.4	ı	VDD	V
V _{OH,HDH}	Output high voltage, high drive, 5 mA, VDD ≥ 2.7 V	VDD-0.4	l	VDD	V
V _{OH,HDL}	Output high voltage, high drive, 3 mA, VDD \geq 1.7 V	VDD-0.4	l	VDD	V
$V_{OL,SD}$	Output low voltage, standard drive, 0.5 mA, VDD ≥ 1.7 V	VSS		VSS+0.4	V
V _{OL,HDH}	Output low voltage, high drive, 5 mA, VDD ≥ 2.7 V	VSS		VSS+0.4	V
$V_{OL,HDL}$	Output low voltage, high drive, 3 mA, VDD ≥ 1.7 V	VSS		VSS+0.4	V
I _{OL,SD}	Current at VSS + 0.4 V, output set low, standard drive, VDD	1	2	4	mA
	≥ 1.7 V				
I _{OL,HDH}	Current at VSS + 0.4 V, output set low, high drive, VDD ≥ 2.7	6	10	15	mA
	V				
I _{OL,HDL}	Current at VSS + 0.4 V, output set low, high drive, VDD ≥ 1.7	3			mA
	V				
I _{OH,SD}	Current at VDD - 0.4 V, output set high, standard drive, VDD	1	2	4	mA
	≥1.7				
I _{OH,HDH}	Current at VDD - 0.4 V, output set high, high drive, VDD ≥	6	9	14	mA
	2.7 V				
I _{OH,HDL}	Current at VDD - 0.4 V, output set high, high drive, VDD ≥	3			mA
	1.7 V	_	_		
t _{RF,15pF}	Rise/fall time, standard drive mode, 10 to 90%, 15 pF load ¹	6	9	19	ns
t _{RF,25pF}	Rise/fall time, standard drive mode, 10 to 90%, 25 pF load ¹	10	13	30	ns
t _{RF,50pF}	Rise/fall time, standard drive mode, 10 to 90%, 50 pF load ¹	18	25	61	ns
t _{HRF,15pF}	Rise/Fall time, high drive mode, 10 to 90%, 15 pF load ¹	2	4	8	ns
t _{HRF,25pF}	Rise/Fall time, high drive mode, 10 to 90%, 25 pF load ¹	3	5	11	ns
t _{HRF,50pF}	Rise/Fall time, high drive mode, 10 to 90%, 50 pF load ¹	5	8	19	ns
R _{PU}	Pull-up resistance	11	13	16	kΩ
R _{PD}	Pull-down resistance	11	13	16	kΩ
C _{PAD}	Pad capacitance		3		pF

6.5 GPIOTE — GPIO tasks and events

The GPIO tasks and events (GPIOTE) module provides functionality for accessing GPIO pins using tasks and events. Each GPIOTE channel can be assigned to one pin.

A GPIOTE block enables GPIOs to generate events on pin state change which can be used to carry out tasks through the PPI system. A GPIO can also be driven to change state on system events using the PPI system. Tasks and events are briefly introduced in Peripheral interface on page 17, and GPIO is described in more detail in GPIO — General purpose input/output on page 102.

Low power detection of pin state changes is possible when in System ON or System OFF.

Instance	Number of GPIOTE channels
GPIOTE	8

Table 40: GPIOTE properties

Up to three tasks can be used in each GPIOTE channel for performing write operations to a pin. Two tasks are fixed (SET and CLR), and one (OUT) is configurable to perform following operations:

• Set



¹ Rise and fall times based on simulations

- Clear
- Toggle

An event can be generated in each GPIOTE channel from one of the following input conditions:

- · Rising edge
- Falling edge
- Any change

6.5.1 Pin events and tasks

The GPIOTE module has a number of tasks and events that can be configured to operate on individual GPIO pins.

The tasks SET[n], CLR[n], and OUT[n] can write to individual pins, and events IN[n] can be generated from input changes of individual pins.

The SET task will set the pin selected in GPIOTE.CONFIG[n].PSEL to high. The CLR task will set the pin low.

The effect of the OUT task on the pin is configurable in CONFIG[n].POLARITY. It can set the pin high, set it low, or toggle it.

Tasks and events are configured using the CONFIG[n] registers. One CONFIG[n] register is associated with a set of SET[n], CLR[n], and OUT[n] tasks and IN[n] events.

As long as a SET[n], CLR[n], and OUT[n] task or an IN[n] event is configured to control pin **n**, the pin's output value will only be updated by the GPIOTE module. The pin's output value, as specified in the GPIO, will be ignored as long as the pin is controlled by GPIOTE. Attempting to write to the pin as a normal GPIO pin will have no effect. When the GPIOTE is disconnected from a pin, the associated pin gets the output and configuration values specified in the GPIO module, see MODE field in CONFIG[n] register.

When conflicting tasks are triggered simultaneously (i.e. during the same clock cycle) in one channel, the priority of the tasks is as described in the following table.

Priority	Task
1	OUT
2	CLR
3	SET

Table 41: Task priorities

When setting the CONFIG[n] registers, MODE=Disabled does not have the same effect as MODE=Task and POLARITY=None. In the latter case, a CLR or SET task occurring at the exact same time as OUT will end up with no change on the pin, based on the priorities described in the table above.

When a GPIOTE channel is configured to operate on a pin as a task, the initial value of that pin is configured in the OUTINIT field of CONFIG[n].

6.5.2 Port event

PORT is an event that can be generated from multiple input pins using the GPIO DETECT signal.

The event will be generated on the rising edge of the DETECT signal. See GPIO — General purpose input/output on page 102 for more information about the DETECT signal.

The GPIO DETECT signal will not wake the system up again if the system is put into System ON IDLE while the DETECT signal is high. Clear all DETECT sources before entering sleep. If the LATCH register is used as a source, a new rising edge will be generated on DETECT if any bit in LATCH is still high after clearing all or part of the register. This could occur if one of the PINx.DETECT signals is still high, for example. See Pin sense mechanism on page 104 for more information.



Setting the system to System OFF while DETECT is high will cause a wakeup from System OFF reset.

This feature can be used to wake up the CPU from a WFI or WFE type sleep in System ON when all peripherals and the CPU are idle, meaning the lowest power consumption in System ON mode.

To prevent spurious interrupts from the PORT event while configuring the sources, the following steps must be performed:

- 1. Disable interrupts on the PORT event (through INTENCLR.PORT).
- **2.** Configure the sources (PIN_CNF[n].SENSE).
- 3. Clear any potential event that could have occurred during configuration (write 0 to EVENTS_PORT).
- 4. Enable interrupts (through INTENSET.PORT).

6.5.3 Tasks and events pin configuration

Each GPIOTE channel is associated with one physical GPIO pin through the CONFIG.PSEL field.

When Event mode is selected in CONFIG.MODE, the pin specified by CONFIG.PSEL will be configured as an input, overriding the DIR setting in GPIO. Similarly, when Task mode is selected in CONFIG.MODE, the pin specified by CONFIG.PSEL will be configured as an output overriding the DIR setting and OUT value in GPIO. When Disabled is selected in CONFIG.MODE, the pin specified by CONFIG.PSEL will use its configuration from the PIN[n].CNF registers in GPIO. CONFIG.MODE must be disabled in order to be able to change the value of the PSEL field.

Note: A pin can only be assigned to one GPIOTE channel at a time. Failing to do so may result in unpredictable behavior.

6.5.4 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x5000D000	GPIOTE	GPIOTE0	S	NA	Secure GPIO tasks and events	
0x40031000	GPIOTE	GPIOTE1	NS	NA	Non Secure GPIO tasks and	
					events	

Table 42: Instances

Register	Offset	Security	Description
TASKS_OUT[n]	0x000		Task for writing to pin specified in CONFIG[n].PSEL. Action on pin is configured in
			CONFIG[n].POLARITY.
TASKS_SET[n]	0x030		Task for writing to pin specified in $CONFIG[n].PSEL.$ Action on pin is to set it high.
TASKS_CLR[n]	0x060		Task for writing to pin specified in CONFIG[n].PSEL. Action on pin is to set it low.
SUBSCRIBE_OUT[n]	0x080		Subscribe configuration for task OUT[n]
SUBSCRIBE_SET[n]	0x0B0		Subscribe configuration for task SET[n]
SUBSCRIBE_CLR[n]	0x0E0		Subscribe configuration for task CLR[n]
EVENTS_IN[n]	0x100		Event generated from pin specified in CONFIG[n].PSEL
EVENTS_PORT	0x17C		Event generated from multiple input GPIO pins with SENSE mechanism enabled
PUBLISH_IN[n]	0x180		Publish configuration for event IN[n]
PUBLISH_PORT	0x1FC		Publish configuration for event PORT
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
CONFIG[n]	0x510		Configuration for OUT[n], SET[n], and CLR[n] tasks and IN[n] event

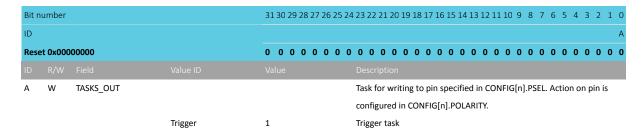
Table 43: Register overview



6.5.4.1 TASKS_OUT[n] (n=0..7)

Address offset: $0x000 + (n \times 0x4)$

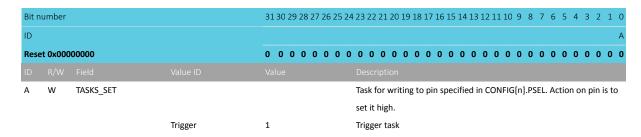
Task for writing to pin specified in CONFIG[n].PSEL. Action on pin is configured in CONFIG[n].POLARITY.



6.5.4.2 TASKS SET[n] (n=0..7)

Address offset: $0x030 + (n \times 0x4)$

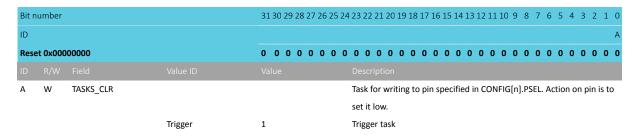
Task for writing to pin specified in CONFIG[n].PSEL. Action on pin is to set it high.



6.5.4.3 TASKS_CLR[n] (n=0..7)

Address offset: $0x060 + (n \times 0x4)$

Task for writing to pin specified in CONFIG[n].PSEL. Action on pin is to set it low.

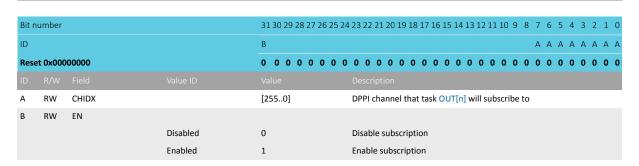


6.5.4.4 SUBSCRIBE_OUT[n] (n=0..7)

Address offset: $0x080 + (n \times 0x4)$

Subscribe configuration for task OUT[n]

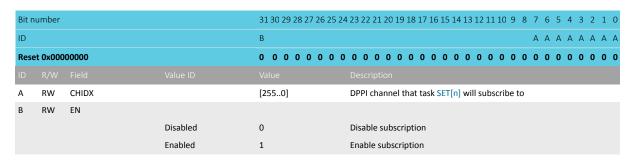




6.5.4.5 SUBSCRIBE_SET[n] (n=0..7)

Address offset: $0x0B0 + (n \times 0x4)$

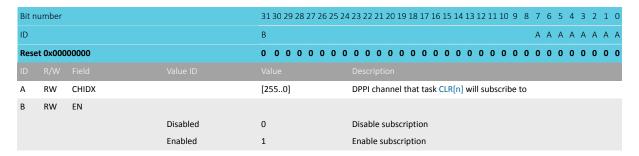
Subscribe configuration for task SET[n]



6.5.4.6 SUBSCRIBE_CLR[n] (n=0..7)

Address offset: $0x0E0 + (n \times 0x4)$

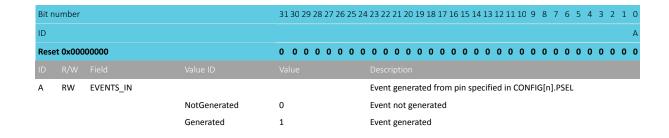
Subscribe configuration for task CLR[n]



6.5.4.7 EVENTS_IN[n] (n=0..7)

Address offset: $0x100 + (n \times 0x4)$

Event generated from pin specified in CONFIG[n].PSEL



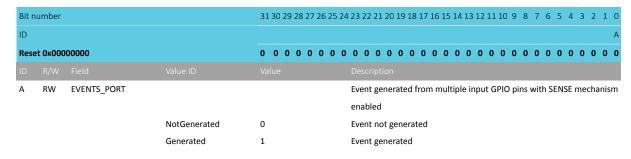




6.5.4.8 EVENTS_PORT

Address offset: 0x17C

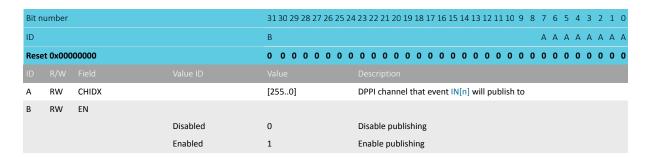
Event generated from multiple input GPIO pins with SENSE mechanism enabled



6.5.4.9 PUBLISH_IN[n] (n=0..7)

Address offset: $0x180 + (n \times 0x4)$

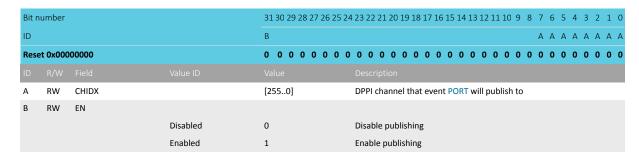
Publish configuration for event IN[n]



6.5.4.10 PUBLISH PORT

Address offset: 0x1FC

Publish configuration for event PORT



6.5.4.11 INTENSET

Address offset: 0x304

Enable interrupt



D.11	-			24 20 20 20 27 26 25 2	122222420404047464544424242444000076542224
Bit n	umber			31 30 29 28 27 26 25 24	1 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				T	HGFEDCBA
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
A-H	RW	IN[i] (i=07)			Write '1' to enable interrupt for event IN[i]
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
1	RW	PORT			Write '1' to enable interrupt for event PORT
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled

6.5.4.12 INTENCLR

Address offset: 0x308

Disable interrupt

Bit number			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			1	HGFEDCBA
Reset 0x00000	0000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID R/W F				
A-H RW I	IN[i] (i=07)			Write '1' to disable interrupt for event IN[i]
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
I RW F	PORT			Write '1' to disable interrupt for event PORT
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled

6.5.4.13 CONFIG[n] (n=0..7)

Address offset: $0x510 + (n \times 0x4)$

Configuration for OUT[n], SET[n], and CLR[n] tasks and IN[n] event

Bit number		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			E DD BBBBB AA
Reset 0x00000000		0 0 0 0 0 0 0	$0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \$
ID R/W Field			
A RW MODE			Mode
	Disabled	0	Disabled. Pin specified by PSEL will not be acquired by the GPIOTE
			module.
	Event	1	Event mode
			The pin specified by PSEL will be configured as an input and the IN[n]
			event will be generated if operation specified in POLARITY occurs on
			the pin.





D:+	umber			21 20 20 20 27 26 25 2	A 22 22 24 20 40 40 47 46 45 4A 42 42 44 40 0 0 7 6 5 A 2 2 2 4 0
	umber			31 30 29 28 27 26 25 24	423 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID -					E D D B B B B B A A
	et 0x000			0 0 0 0 0 0 0 0	
ID	R/W	Field	Value ID	Value	Description
			Task	3	Task mode
					The GPIO specified by PSEL will be configured as an output and
					triggering the $\mbox{SET}[n], \mbox{CLR}[n]$ or $\mbox{OUT}[n]$ task will perform the operation
					specified by POLARITY on the pin. When enabled as a task the \ensuremath{GPIOTE}
					module will acquire the pin and the pin can no longer be written as a
					regular output pin from the GPIO module.
В	RW	PSEL		[031]	GPIO number associated with SET[n], CLR[n], and OUT[n] tasks and
					IN[n] event
D	RW	POLARITY			When In task mode: Operation to be performed on output when
					OUT[n] task is triggered. When In event mode: Operation on input that
					shall trigger IN[n] event.
			None	0	Task mode: No effect on pin from OUT[n] task. Event mode: no IN[n]
					event generated on pin activity.
			LoToHi	1	Task mode: Set pin from OUT[n] task. Event mode: Generate IN[n]
					event when rising edge on pin.
			HiToLo	2	Task mode: Clear pin from OUT[n] task. Event mode: Generate IN[n]
					event when falling edge on pin.
			Toggle	3	Task mode: Toggle pin from OUT[n]. Event mode: Generate IN[n] when
					any change on pin.
E	RW	OUTINIT			When in task mode: Initial value of the output when the GPIOTE
					channel is configured. When in event mode: No effect.
			Low	0	Task mode: Initial value of pin before task triggering is low
			High	1	Task mode: Initial value of pin before task triggering is high

6.5.5 Electrical specification

6.6 IPC — Interprocessor communication

The interprocessor communication (IPC) peripheral is used to send and receive events between MCUs in the system.



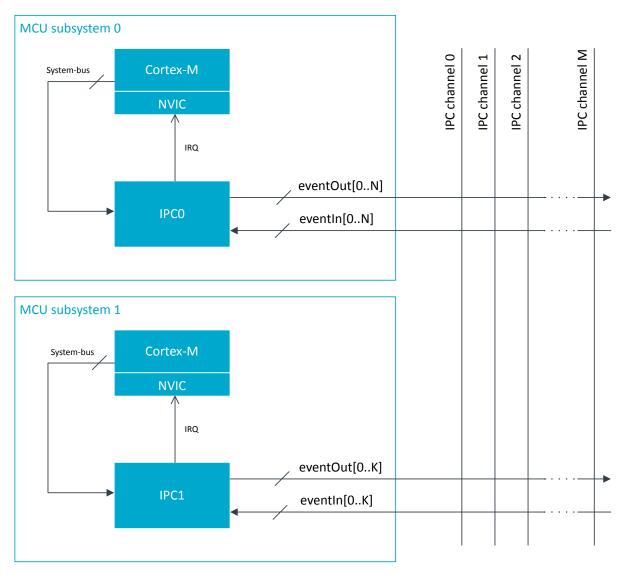


Figure 21: IPC block diagram

Functional description

IPC block diagram on page 119 illustrates the interprocessor communication (IPC) peripheral. In a multi-MCU system, each MCU has one dedicated IPC peripheral. The IPC peripheral can be used to send and receive events to and from other IPC peripherals. An instance of the IPC peripheral can have multiple SEND tasks and RECEIVE events. A single SEND task can be configured to signal an event on one or more IPC channels, and a RECEIVE event can be configured to listen on one or more IPC channels. The IPC channels that are triggered in a SEND task can be configured through the SEND_CNF registers, and the IPC channels that trigger a RECEIVE event are configured through the RECEIVE_CNF registers. The figure below illustrates how the SEND_CNF and RECEIVE_CNF registers work. Both the SEND task and the RECEIVE event can be connected to all IPC channels.



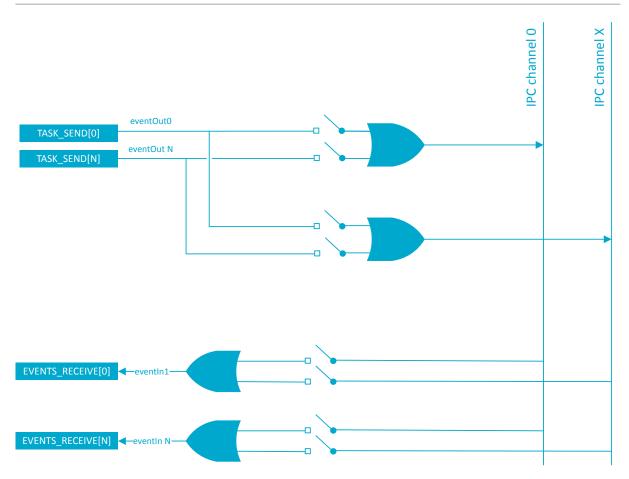


Figure 22: IPC registers SEND_CNF and RECEIVE_CNF

A SEND task can be viewed as broadcasting events onto one or more IPC channels, and a RECEIVE event can be seen as subscribing to a subset of IPC channels. It is possible for multiple IPCs to trigger events onto the same channel at the same time. When two or more events on the same channel occur within t_{IPC} , the events may be merged into a single event seen from the IPC receiver. One of the events can therefore be lost. To prevent this, the user must ensure that events on the same IPC channel do not occur within t_{IPC} of each other. When implementing firmware data structures, such as queues or mailboxes, this can be done by using one channel for acknowledgements.

An IPC event often does not contain any data itself, it is used to signal other MCUs that something has occurred. Data can be shared through shared memory, for example in the form of a software implemented mailbox, or command/event queues. It is up to software to assign a logical functionality to an IPC channel. For instance, one IPC channel can be used to signal that a command is ready to be executed, and any processor in the system can subscribe to that particular channel and decode/execute the command.

General purpose memory

The GPMEM registers can be used freely to store information. These registers are accessed like any other of the IPC peripheral's registers.

6.6.1 IPC and PPI connections

The IPC SEND tasks and RECEIVE events can be connected through PPI channels. This makes it possible to relay events from peripherals in one MCU to another, without CPU involvement.

Figure below illustrates a timer COMPARE event that is relayed from one MCU to IPC using PPI, then back into a timer CAPTURE event in another MCU.



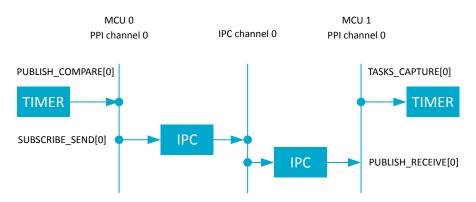


Figure 23: Example of PPI and IPC connections

6.6.2 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x5002A000	IPC	IPC:S	US	NA	Interprocessor	
0x4002A000	IPC	IPC : NS	03		communication	

Table 44: Instances

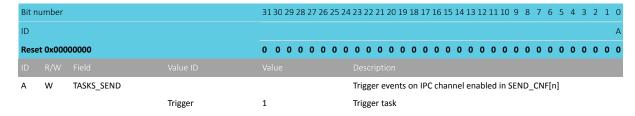
Register	Offset	Security	Description
TASKS_SEND[n]	0x000		Trigger events on IPC channel enabled in SEND_CNF[n]
SUBSCRIBE_SEND[n]	0x080		Subscribe configuration for task SEND[n]
EVENTS_RECEIVE[n]	0x100		Event received on one or more of the enabled IPC channels in RECEIVE_CNF[n]
PUBLISH_RECEIVE[n]	0x180		Publish configuration for event RECEIVE[n]
INTEN	0x300		Enable or disable interrupt
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
INTPEND	0x30C		Pending interrupts
SEND_CNF[n]	0x510		Send event configuration for TASKS_SEND[n]
RECEIVE_CNF[n]	0x590		Receive event configuration for EVENTS_RECEIVE[n]
GPMEM[n]	0x610		General purpose memory

Table 45: Register overview

6.6.2.1 TASKS_SEND[n] (n=0..7)

Address offset: $0x000 + (n \times 0x4)$

Trigger events on IPC channel enabled in SEND_CNF[n]

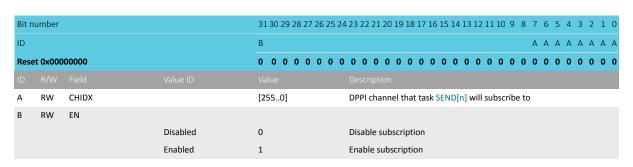


6.6.2.2 SUBSCRIBE_SEND[n] (n=0..7)

Address offset: $0x080 + (n \times 0x4)$

Subscribe configuration for task SEND[n]

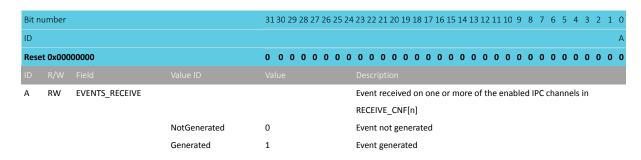




6.6.2.3 EVENTS_RECEIVE[n] (n=0..7)

Address offset: $0x100 + (n \times 0x4)$

Event received on one or more of the enabled IPC channels in RECEIVE_CNF[n]



6.6.2.4 PUBLISH_RECEIVE[n] (n=0..7)

Address offset: $0x180 + (n \times 0x4)$

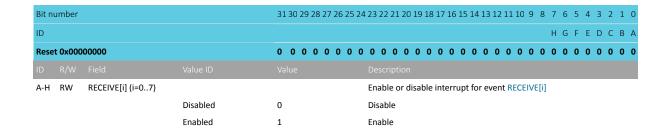
Publish configuration for event RECEIVE[n]

Bit n	umber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[2550]	DPPI channel that event RECEIVE[n] will publish to
В	RW	EN			
					St. 11 1911
			Disabled	0	Disable publishing

6.6.2.5 INTEN

Address offset: 0x300

Enable or disable interrupt





6.6.2.6 INTENSET

Address offset: 0x304

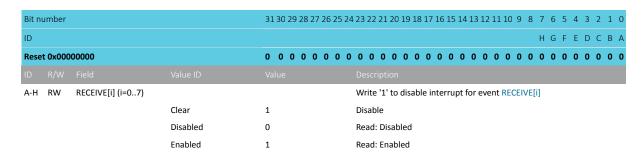
Enable interrupt

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					HGFEDCBA
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
A-H	RW	RECEIVE[i] (i=07)			Write '1' to enable interrupt for event RECEIVE[i]
			Set	1	Enable
			Disabled	0	Read: Disabled

6.6.2.7 INTENCLR

Address offset: 0x308

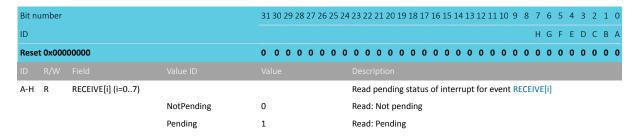
Disable interrupt



6.6.2.8 INTPEND

Address offset: 0x30C

Pending interrupts

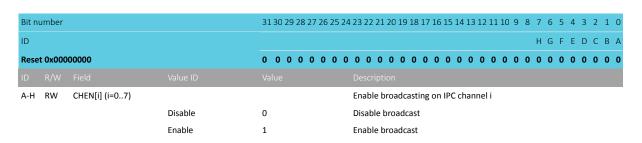


6.6.2.9 SEND_CNF[n] (n=0..7)

Address offset: $0x510 + (n \times 0x4)$

Send event configuration for TASKS_SEND[n]

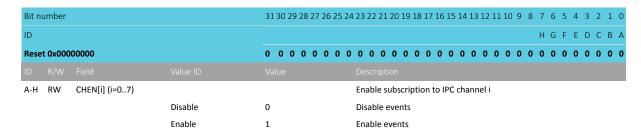




6.6.2.10 RECEIVE_CNF[n] (n=0..7)

Address offset: $0x590 + (n \times 0x4)$

Receive event configuration for EVENTS_RECEIVE[n]

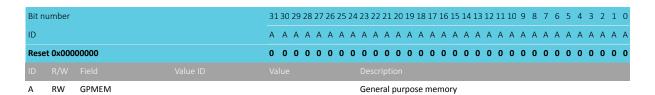


6.6.2.11 GPMEM[n] (n=0..3)

Address offset: $0x610 + (n \times 0x4)$

General purpose memory

Retained only in System ON mode



6.6.3 Electrical specification

6.6.3.1 IPC Electrical Specification

Symbol	Description	Min.	Тур.	Max.	Units
t _{IPC}	Time window during which IPC events can be merged			165	μs

6.7 I²S — Inter-IC sound interface

The I²S (Inter-IC Sound) module, supports the original two-channel I²S format, and left or right-aligned formats. It implements EasyDMA for sample transfer directly to and from RAM without CPU intervention.

The I²S peripheral has the following main features:

- Master and Slave mode
- · Simultaneous bi-directional (TX and RX) audio streaming
- Original I²S and left- or right-aligned format



- 8, 16 and 24-bit sample width
- · Low-jitter Master Clock generator
- Various sample rates

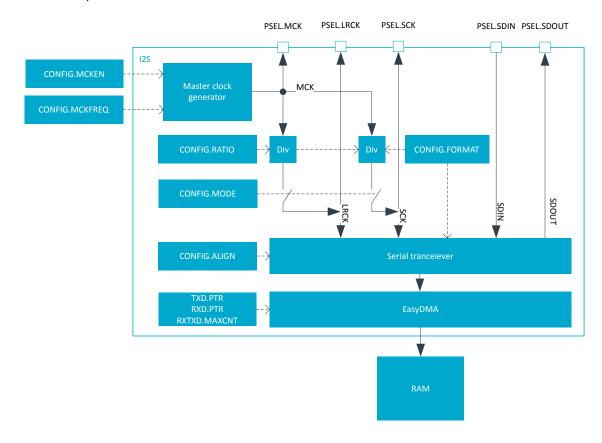


Figure 24: I²S master

6.7.1 Mode

The I²S protocol specification defines two modes of operation, Master and Slave.

The I²S mode decides which of the two sides (Master or Slave) shall provide the clock signals LRCK and SCK, and these signals are always supplied by the Master to the Slave.

6.7.2 Transmitting and receiving

The I²S module supports both transmission (TX) and reception (RX) of serial data. In both cases the serial data is shifted synchronously to the clock signals SCK and LRCK.

TX data is written to the SDOUT pin on the falling edge of SCK, and RX data is read from the SDIN pin on the rising edge of SCK. The most significant bit (MSB) is always transmitted first.

Note: When starting a transmission in master mode, two frames (two left-and-right sample pairs) of value zero will be transmitted after triggering the START task, prior to the RXTXD.MAXCNT samples specified by the TXD.PTR pointer.

TX and RX are available in both Master and Slave modes and can be enabled/disabled independently in the CONFIG.TXEN on page 139 and CONFIG.RXEN on page 139.

Transmission and/or reception is started by triggering the START task. When started and transmission is enabled (in CONFIG.TXEN on page 139), the TXPTRUPD event will be generated for every RXTXD.MAXCNT on page 142 number of transmitted data words (containing one or more samples).

NORDIC

Similarly, when started and reception is enabled (in CONFIG.RXEN on page 139), the RXPTRUPD event will be generated for every RXTXD.MAXCNT on page 142 received data words.

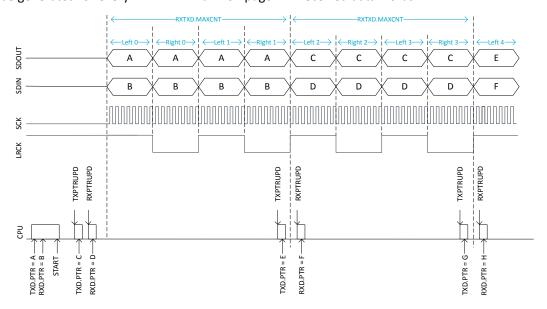


Figure 25: Transmitting and receiving. CONFIG.FORMAT = Aligned, CONFIG.SWIDTH = 8Bit, CONFIG.CHANNELS = Stereo, RXTXD.MAXCNT = 1.

6.7.3 Left right clock (LRCK)

The Left Right Clock (LRCK), often referred to as "word clock", "sample clock" or "word select" in I²S context, is the clock defining the frames in the serial bit streams sent and received on SDOUT and SDIN, respectively.

In I2S mode, each frame contains one left and right sample pair, with the left sample being transferred during the low half period of LRCK followed by the right sample being transferred during the high period of LRCK.

In Aligned mode, each frame contains one left and right sample pair, with the left sample being transferred during the high half period of LRCK followed by the right sample being transferred during the low period of LRCK.

Consequently, the LRCK frequency is equivalent to the audio sample rate.

When operating in Master mode, the LRCK is generated from the MCK, and the frequency of LRCK is then given as:

```
LRCK = MCK / CONFIG.RATIO
```

LRCK always toggles around the falling edge of the serial clock SCK.

6.7.4 Serial clock (SCK)

The serial clock (SCK), often referred to as the serial bit clock, pulses once for each data bit being transferred on the serial data lines SDIN and SDOUT.

When operating in Master mode the SCK is generated from the MCK, and the frequency of SCK is then given as:

```
SCK = 2 * LRCK * CONFIG.SWIDTH
```

The falling edge of the SCK falls on the toggling edge of LRCK.

When operating in Slave mode SCK is provided by the external I²S master.



6.7.5 Master clock (MCK)

The master clock (MCK) is the clock from which LRCK and SCK are derived when operating in Master mode.

The MCK is generated by an internal MCK generator. This generator always needs to be enabled when in Master mode, but the generator can also be enabled when in Slave mode. Enabling the generator when in slave mode can be useful in the case where the external Master is not able to generate its own master clock.

The MCK generator is enabled/disabled in the register CONFIG.MCKEN on page 139, and the generator is started or stopped by the START or STOP tasks.

In Master mode the LRCK and the SCK frequencies are closely related, as both are derived from MCK and set indirectly through CONFIG.RATIO on page 140 and CONFIG.SWIDTH on page 141.

When configuring these registers, the user is responsible for fulfilling the following requirements:

1. SCK frequency can never exceed the MCK frequency, which can be formulated as:

```
CONFIG.RATIO >= 2 * CONFIG.SWIDTH
```

2. The MCK/LRCK ratio shall be a multiple of 2 * CONFIG.SWIDTH, which can be formulated as:

```
Integer = (CONFIG.RATIO / (2 * CONFIG.SWIDTH))
```

The MCK signal can be routed to an output pin (specified in PSEL.MCK) to supply external I²S devices that require the MCK to be supplied from the outside.

When operating in Slave mode, the I²S module does not use the MCK and the MCK generator does not need to be enabled.

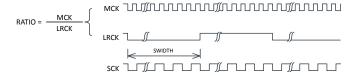


Figure 26: Relation between RATIO, MCK and LRCK.

Desired LRCK [Hz]	CONFIG.SWID	CONFIG.RATIO	CONFIG.MCKF	MCK [Hz]	LRCK [Hz]	LRCK error [%]
16000	16Bit	32X	32MDIV63	507936.5	15873.0	-0.8
16000	16Bit	64X	32MDIV31	1032258.1	16129.0	0.8
16000	16Bit	256X	32MDIV8	4000000.0	15625.0	-2.3
32000	16Bit	32X	32MDIV31	1032258.1	32258.1	0.8
32000	16Bit	64X	32MDIV16	2000000.0	31250.0	-2.3
44100	16Bit	32X	32MDIV23	1391304.3	43478.3	-1.4
44100	16Bit	64X	32MDIV11	2909090.9	45454.5	3.1

Table 46: Configuration examples

6.7.6 Width, alignment and format

The CONFIG.SWIDTH register primarily defines the sample width of the data written to memory. In master mode, it then also sets the amount of bits per frame. In Slave mode it controls padding/trimming if required. Left, right, transmitted, and received samples always have the same width. The CONFIG.FORMAT



register specifies the position of the data frames with respect to the LRCK edges in both Master and Slave modes.

When using I²S format, the first bit in a half-frame (containing one left or right sample) gets sampled on the second rising edge of the SCK after a LRCK edge. When using Aligned mode, the first bit in a half-frame gets sampled on the first rising edge of SCK following a LRCK edge.

For data being received on SDIN the sample value can be either right or left-aligned inside a half-frame, as specified in CONFIG.ALIGN on page 141. CONFIG.ALIGN on page 141 affects only the decoding of the incoming samples (SDIN), while the outgoing samples (SDOUT) are always left-aligned (or justified).

When using left-alignment, each half-frame starts with the MSB of the sample value (both for data being sent on SDOUT and received on SDIN).

When using right-alignment, each half-frame of data being received on SDIN ends with the LSB of the sample value, while each half-frame of data being sent on SDOUT starts with the MSB of the sample value (same as for left-alignment).

In Master mode, the size of a half-frame (in number of SCK periods) equals the sample width (in number of bits), and in this case the alignment setting does not care as each half-frame in any case will start with the MSB and end with the LSB of the sample value.

In slave mode, however, the sample width does not need to equal the frame size. This means you might have extra or fewer SCK pulses per half-frame than what the sample width specified in CONFIG.SWIDTH requires.

In the case where we use **left-alignment** and the number of SCK pulses per half-frame is **higher** than the sample width, the following will apply:

- For data received on SDIN, all bits after the LSB of the sample value will be discarded.
- For data sent on SDOUT, all bits after the LSB of the sample value will be 0.

In the case where we use **left-alignment** and the number of SCK pulses per frame is **lower** than the sample width, the following will apply:

Data sent and received on SDOUT and SDIN will be truncated with the LSBs being removed first.

In the case where we use **right-alignment** and the number of SCK pulses per frame is **higher** than the sample width, the following will apply:

- For data received on SDIN, all bits before the MSB of the sample value will be discarded.
- For data sent on SDOUT, all bits after the LSB of the sample value will be 0 (same behavior as for left-alignment).

In the case where we use **right-alignment** and the number of SCK pulses per frame is **lower** than the sample width, the following will apply:

- Data received on SDIN will be sign-extended to "sample width" number of bits before being written to memory.
- Data sent on SDOUT will be truncated with the LSBs being removed first (same behavior as for leftalignment).

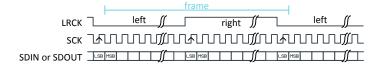


Figure 27: 1²S format. CONFIG.SWIDTH equalling half-frame size.



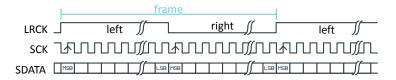


Figure 28: Aligned format. CONFIG.SWIDTH equalling half-frame size.

6.7.7 EasyDMA

The I²S module implements EasyDMA for accessing internal Data RAM without CPU intervention.

The source and destination pointers for the TX and RX data are configured in TXD.PTR on page 142 and RXD.PTR on page 142. The memory pointed to by these pointers will only be read or written when TX or RX are enabled in CONFIG.TXEN on page 139 and CONFIG.RXEN on page 139.

The addresses written to the pointer registers TXD.PTR on page 142 and RXD.PTR on page 142 are double-buffered in hardware, and these double buffers are updated for every RXTXD.MAXCNT on page 142 words (containing one or more samples) read/written from/to memory. The events TXPTRUPD and RXPTRUPD are generated whenever the TXD.PTR and RXD.PTR are transferred to these double buffers.

If TXD.PTR on page 142 is not pointing to the Data RAM region when transmission is enabled, or RXD.PTR on page 142 is not pointing to the Data RAM region when reception is enabled, an EasyDMA transfer may result in a HardFault and/or memory corruption. See Memory on page 23 for more information about the different memory regions.

Due to the nature of I²S, where the number of transmitted samples always equals the number of received samples (at least when both TX and RX are enabled), one common register RXTXD.MAXCNT on page 142 is used for specifying the sizes of these two memory buffers. The size of the buffers is specified in a number of 32-bit words. Such a 32-bit memory word can either contain four 8-bit samples, two 16-bit samples or one right-aligned 24-bit sample sign extended to 32 bit.

In stereo mode (CONFIG.CHANNELS=Stereo), the samples are stored as "left and right sample pairs" in memory. Figure Memory mapping for 8 bit stereo. CONFIG.SWIDTH = 8Bit, CONFIG.CHANNELS = Stereo. on page 129, Memory mapping for 16 bit stereo. CONFIG.SWIDTH = 16Bit, CONFIG.CHANNELS = Stereo. on page 130 and Memory mapping for 24 bit stereo. CONFIG.SWIDTH = 24Bit, CONFIG.CHANNELS = Stereo. on page 130 show how the samples are mapped to memory in this mode. The mapping is valid for both RX and TX.

In mono mode (CONFIG.CHANNELS=Left or Right), RX sample from only one channel in the frame is stored in memory, the other channel sample is ignored. Illustrations Memory mapping for 8 bit mono. CONFIG.SWIDTH = 8Bit, CONFIG.CHANNELS = Left. on page 130, Memory mapping for 16 bit mono, left channel only. CONFIG.SWIDTH = 16Bit, CONFIG.CHANNELS = Left. on page 130 and Memory mapping for 24 bit mono, left channel only. CONFIG.SWIDTH = 24Bit, CONFIG.CHANNELS = Left. on page 131 show how RX samples are mapped to memory in this mode.

For TX, the same outgoing sample read from memory is transmitted on both left and right in a frame, resulting in a mono output stream.

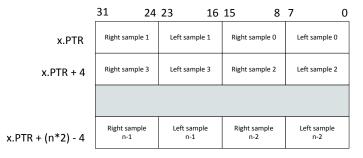


Figure 29: Memory mapping for 8 bit stereo. CONFIG.SWIDTH = 8Bit, CONFIG.CHANNELS = Stereo.



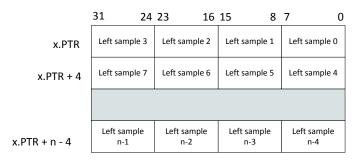


Figure 30: Memory mapping for 8 bit mono. CONFIG.SWIDTH = 8Bit, CONFIG.CHANNELS = Left.

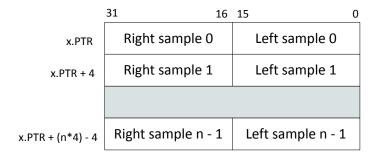


Figure 31: Memory mapping for 16 bit stereo. CONFIG.SWIDTH = 16Bit, CONFIG.CHANNELS = Stereo.

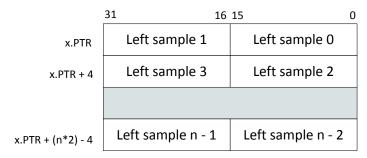


Figure 32: Memory mapping for 16 bit mono, left channel only. CONFIG.SWIDTH = 16Bit, CONFIG.CHANNELS = Left.

	31	23 0
x.PTR	Sign ext.	Left sample 0
x.PTR + 4	Sign ext.	Right sample 0
x.PTR + (n*8) - 8	Sign ext.	Left sample n - 1
x.PTR + (n*8) - 4	Sign ext.	Right sample n - 1

Figure 33: Memory mapping for 24 bit stereo. CONFIG.SWIDTH = 24Bit, CONFIG.CHANNELS = Stereo.



	31	23 0
x.PTR	Sign ext.	Left sample 0
x.PTR + 4	Sign ext.	Left sample 1
x.PTR + (n*4) - 4	Sign ext.	Left sample n - 1

Figure 34: Memory mapping for 24 bit mono, left channel only. CONFIG.SWIDTH = 24Bit, CONFIG.CHANNELS = Left.

6.7.8 Module operation

Described here is a typical operating procedure for the I²S module.

1. Configure the I²S module using the CONFIG registers

```
// Enable reception
NRF_I2S->CONFIG.RXEN = (I2S_CONFIG_RXEN_RXEN_Enabled <<
                                      12S CONFIG RXEN RXEN Pos);
// Enable transmission
NRF I2S->CONFIG.TXEN = (I2S_CONFIG_TXEN_TXEN_Enabled <<
                                      12S_CONFIG_TXEN_TXEN_Pos);
// Enable MCK generator
NRF_I2S->CONFIG.MCKEN = (I2S_CONFIG_MCKEN_MCKEN_Enabled <<
                                      12S CONFIG MCKEN MCKEN Pos);
// MCKFREQ = 4 MHz
NRF I2S->CONFIG.MCKFREQ = I2S CONFIG MCKFREQ MCKFREQ 32MDIV8 <<
                                      12S CONFIG MCKFREQ MCKFREQ Pos;
// Ratio = 256
NRF I2S->CONFIG.RATIO = I2S CONFIG RATIO RATIO 256X <<
                                      I2S CONFIG RATIO RATIO Pos;
// MCKFREQ = 4 MHz and Ratio = 256 gives sample rate = 15.625 \text{ ks/s}
// Sample width = 16 bit
NRF I2S->CONFIG.SWIDTH = I2S CONFIG SWIDTH SWIDTH 16Bit <<
                                      12S CONFIG SWIDTH SWIDTH Pos;
// Alignment = Left
NRF I2S->CONFIG.ALIGN = I2S CONFIG ALIGN ALIGN Left <<
                                       12S_CONFIG_ALIGN_ALIGN_Pos;
// Format = I2S
NRF_I2S->CONFIG.FORMAT = I2S_CONFIG_FORMAT_FORMAT_I2S <<
                                       I2S CONFIG FORMAT FORMAT Pos;
NRF I2S->CONFIG.CHANNELS = I2S CONFIG CHANNELS CHANNELS Stereo <<
                                       12S CONFIG CHANNELS CHANNELS Pos;
```



2. Map IO pins using the PINSEL registers

```
// MCK routed to pin 0
NRF_I2S->PSEL.MCK = (0 << I2S_PSEL_MCK_PIN_Pos) |
                   (I2S_PSEL_MCK_CONNECT_Connected <<
                                                 I2S PSEL MCK CONNECT Pos);
// SCK routed to pin 1
NRF I2S->PSEL.SCK = (1 << I2S PSEL SCK PIN Pos) |
                    (I2S PSEL SCK CONNECT Connected <<
                                                12S_PSEL_SCK_CONNECT_Pos);
// LRCK routed to pin 2
NRF I2S->PSEL.LRCK = (2 << I2S PSEL LRCK PIN Pos) |
                     (I2S PSEL LRCK CONNECT Connected <<
                                                12S_PSEL_LRCK_CONNECT_Pos);
// SDOUT routed to pin 3
NRF I2S->PSEL.SDOUT = (3 << I2S PSEL SDOUT PIN Pos) |
                     (I2S_PSEL_SDOUT_CONNECT_Connected <<
                                                12S_PSEL_SDOUT_CONNECT_Pos);
// SDIN routed on pin 4
NRF_I2S->PSEL.SDIN = (4 << I2S_PSEL_SDIN_PIN_POs) |
                     (I2S PSEL SDIN CONNECT Connected <<
                                                 12S PSEL SDIN CONNECT Pos);
```

3. Configure TX and RX data pointers using the TXD, RXD and RXTXD registers

```
NRF_I2S->TXD.PTR = my_tx_buf;
NRF_I2S->RXD.PTR = my_rx_buf;
NRF_I2S->TXD.MAXCNT = MY_BUF_SIZE;
```

4. Enable the I²S module using the ENABLE register

```
NRF_I2S->ENABLE = 1;
```

5. Start audio streaming using the START task

```
NRF_I2S->TASKS_START = 1;
```

6. Handle received and transmitted data when receiving the TXPTRUPD and RXPTRUPD events

```
if(NRF_I2S->EVENTS_TXPTRUPD != 0)
{
    NRF_I2S->TXD.PTR = my_next_tx_buf;
    NRF_I2S->EVENTS_TXPTRUPD = 0;
}
if(NRF_I2S->EVENTS_RXPTRUPD != 0)
{
    NRF_I2S->RXD.PTR = my_next_rx_buf;
    NRF_I2S->EVENTS_RXPTRUPD = 0;
}
```



6.7.9 Pin configuration

The MCK, SCK, LRCK, SDIN and SDOUT signals associated with the I²S module are mapped to physical pins according to the pin numbers specified in the PSEL.x registers.

These pins are acquired whenever the I²S module is enabled through the register ENABLE on page 138.

When a pin is acquired by the I²S module, the direction of the pin (input or output) will be configured automatically, and any pin direction setting done in the GPIO module will be overridden. The directions for the various I²S pins are shown below in GPIO configuration before enabling peripheral (master mode) on page 133 and GPIO configuration before enabling peripheral (slave mode) on page 133.

To secure correct signal levels on the pins when the system is in OFF mode, and when the I²S module is disabled, these pins must be configured in the GPIO peripheral directly.

I ² S signal	I ² S pin	Direction	Output value	Comment
MCK	As specified in PSEL.MCK	Output	0	
LRCK	As specified in PSEL.LRCK	Output	0	
SCK	As specified in PSEL.SCK	Output	0	
SDIN	As specified in PSEL.SDIN	Input	Not applicable	
SDOUT	As specified in PSEL.SDOUT	Output	0	

Table 47: GPIO configuration before enabling peripheral (master mode)

I ² S signal	I ² S pin	Direction	Output value	Comment
МСК	As specified in PSEL.MCK	Output	0	
LRCK	As specified in PSEL.LRCK	Input	Not applicable	
SCK	As specified in PSEL.SCK	Input	Not applicable	
SDIN	As specified in PSEL.SDIN	Input	Not applicable	
SDOUT	As specified in PSEL.SDOUT	Output	0	

Table 48: GPIO configuration before enabling peripheral (slave mode)

6.7.10 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x50028000	I2S	12S : S	US	SA	Inter-IC Sound	
0x40028000	123	12S : NS	03	эн	inter-ic sound	

Table 49: Instances

Register	Offset	Security	Description
TASKS_START	0x000		Starts continuous I2S transfer. Also starts MCK generator when this is enabled.
TASKS_STOP	0x004		Stops I2S transfer. Also stops MCK generator. Triggering this task will cause the STOPPED
			event to be generated.
SUBSCRIBE_START	0x080		Subscribe configuration for task START
SUBSCRIBE_STOP	0x084		Subscribe configuration for task STOP
EVENTS_RXPTRUPD	0x104		The RXD.PTR register has been copied to internal double-buffers. When the I2S module is
			started and RX is enabled, this event will be generated for every RXTXD.MAXCNT words that
			are received on the SDIN pin.
EVENTS_STOPPED	0x108		I2S transfer stopped.
EVENTS_TXPTRUPD	0x114		The TDX.PTR register has been copied to internal double-buffers. When the I2S module is
			started and TX is enabled, this event will be generated for every RXTXD.MAXCNT words that
			are sent on the SDOUT pin.

133



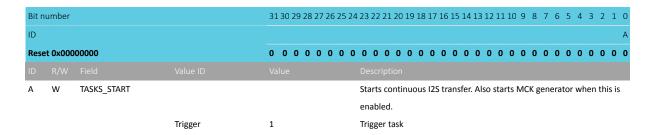
Register	Offset	Security	Description
PUBLISH_RXPTRUPD	0x184	•	Publish configuration for event RXPTRUPD
PUBLISH_STOPPED	0x188		Publish configuration for event STOPPED
PUBLISH_TXPTRUPD	0x194		Publish configuration for event TXPTRUPD
INTEN	0x300		Enable or disable interrupt
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
ENABLE	0x500		Enable I2S module.
CONFIG.MODE	0x504		I2S mode.
CONFIG.RXEN	0x508		Reception (RX) enable.
CONFIG.TXEN	0x50C		Transmission (TX) enable.
CONFIG.MCKEN	0x510		Master clock generator enable.
CONFIG.MCKFREQ	0x514		Master clock generator frequency.
CONFIG.RATIO	0x518		MCK / LRCK ratio.
CONFIG.SWIDTH	0x51C		Sample width.
CONFIG.ALIGN	0x520		Alignment of sample within a frame.
CONFIG.FORMAT	0x524		Frame format.
CONFIG.CHANNELS	0x528		Enable channels.
RXD.PTR	0x538		Receive buffer RAM start address.
TXD.PTR	0x540		Transmit buffer RAM start address.
RXTXD.MAXCNT	0x550		Size of RXD and TXD buffers.
PSEL.MCK	0x560		Pin select for MCK signal.
PSEL.SCK	0x564		Pin select for SCK signal.
PSEL.LRCK	0x568		Pin select for LRCK signal.
PSEL.SDIN	0x56C		Pin select for SDIN signal.
PSEL.SDOUT	0x570		Pin select for SDOUT signal.

Table 50: Register overview

6.7.10.1 TASKS_START

Address offset: 0x000

Starts continuous I2S transfer. Also starts MCK generator when this is enabled.

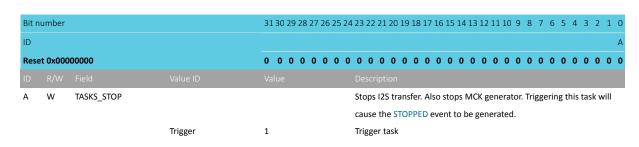


6.7.10.2 TASKS_STOP

Address offset: 0x004

Stops I2S transfer. Also stops MCK generator. Triggering this task will cause the STOPPED event to be generated.





6.7.10.3 SUBSCRIBE_START

Address offset: 0x080

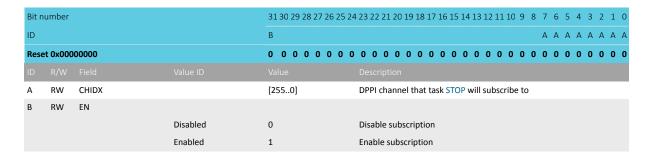
Subscribe configuration for task START

Bit n	umber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2	1 0
ID				В	A A A A A	АА
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0
ID						
Α	RW	CHIDX		[2550]	DPPI channel that task START will subscribe to	
В	RW	EN				
			Disabled	0	Disable subscription	
			Enabled	1	Enable subscription	

6.7.10.4 SUBSCRIBE_STOP

Address offset: 0x084

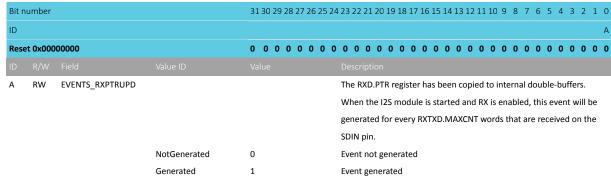
Subscribe configuration for task STOP



6.7.10.5 EVENTS_RXPTRUPD

Address offset: 0x104

The RXD.PTR register has been copied to internal double-buffers. When the I2S module is started and RX is enabled, this event will be generated for every RXTXD.MAXCNT words that are received on the SDIN pin.

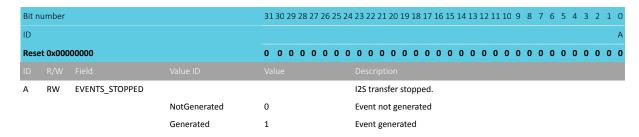




6.7.10.6 EVENTS_STOPPED

Address offset: 0x108

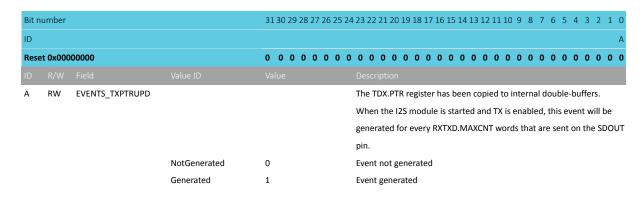
12S transfer stopped.



6.7.10.7 EVENTS TXPTRUPD

Address offset: 0x114

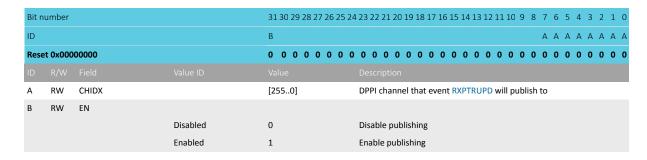
The TDX.PTR register has been copied to internal double-buffers. When the I2S module is started and TX is enabled, this event will be generated for every RXTXD.MAXCNT words that are sent on the SDOUT pin.



6.7.10.8 PUBLISH RXPTRUPD

Address offset: 0x184

Publish configuration for event RXPTRUPD

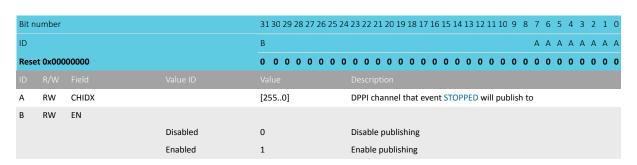


6.7.10.9 PUBLISH STOPPED

Address offset: 0x188

Publish configuration for event STOPPED





6.7.10.10 PUBLISH_TXPTRUPD

Address offset: 0x194

Publish configuration for event TXPTRUPD

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[2550]	DPPI channel that event TXPTRUPD will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing

6.7.10.11 INTEN

Address offset: 0x300

Enable or disable interrupt

Bit r	number			31 30 29 28 27 26	5 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					F C B
Res	et 0x000	00000		0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
В	RW	RXPTRUPD			Enable or disable interrupt for event RXPTRUPD
			Disabled	0	Disable
			Enabled	1	Enable
С	RW	STOPPED			Enable or disable interrupt for event STOPPED
			Disabled	0	Disable
			Enabled	1	Enable
F	RW	TXPTRUPD			Enable or disable interrupt for event TXPTRUPD
			Disabled	0	Disable
			Enabled	1	Enable

6.7.10.12 INTENSET

Address offset: 0x304

Enable interrupt

В	RW	RXPTRUPD			Write ':	1' to e	nable	inter	rupt	for ev	ent F	RXPT	RUP	D					
ID																			
Res	et 0x000	00000	0 0 0 0 0	0 0 0	0 0 0	0 0	0 0	0 0	0 0	0	0 0	0 0	0	0	0	0 (0	0	0 0
ID																F		С	В
Bit r	number		31 30 29 28 27	26 25 24	1 23 22 2	1 20 1	.9 18 1	7 16	15 14	1 13 1	.2 11	10 9	8	7	6	5 4	1 3	2	1 0



Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					F CB
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
С	RW	STOPPED			Write '1' to enable interrupt for event STOPPED
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
F	RW	TXPTRUPD			Write '1' to enable interrupt for event TXPTRUPD
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled

6.7.10.13 INTENCLR

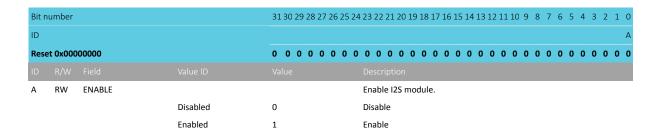
Address offset: 0x308

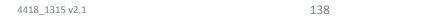
Disable interrupt

D:+	umber			24 20 20 20 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
BILL	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					F C B
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
В	RW	RXPTRUPD			Write '1' to disable interrupt for event RXPTRUPD
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
С	RW	STOPPED			Write '1' to disable interrupt for event STOPPED
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
F	RW	TXPTRUPD			Write '1' to disable interrupt for event TXPTRUPD
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled

6.7.10.14 ENABLE

Address offset: 0x500 Enable I2S module.



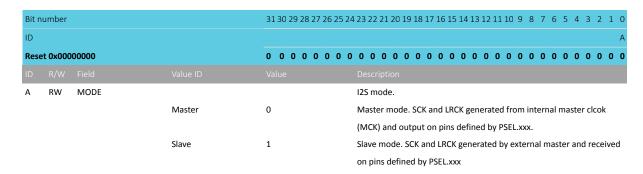




6.7.10.15 CONFIG.MODE

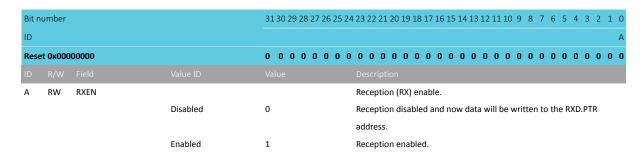
Address offset: 0x504

I2S mode.



6.7.10.16 CONFIG.RXEN

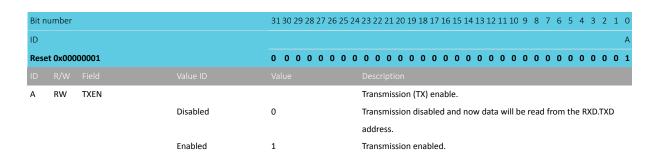
Address offset: 0x508 Reception (RX) enable.



6.7.10.17 CONFIG.TXEN

Address offset: 0x50C

Transmission (TX) enable.

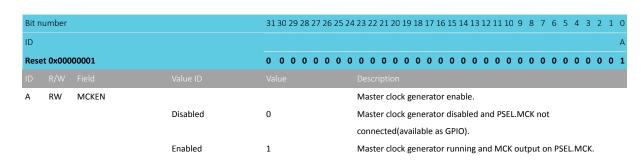


6.7.10.18 CONFIG.MCKEN

Address offset: 0x510

Master clock generator enable.





6.7.10.19 CONFIG.MCKFREQ

Address offset: 0x514

Master clock generator frequency.

Bit r	umber			31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A A A A A A A	A A A A A A A A A A A A A A A A A A A
Rese	et 0x200	00000		0 0 1 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	MCKFREQ			Master clock generator frequency.
			32MDIV8	0x20000000	32 MHz / 8 = 4.0 MHz
			32MDIV10	0x18000000	32 MHz / 10 = 3.2 MHz
			32MDIV11	0x16000000	32 MHz / 11 = 2.9090909 MHz
			32MDIV15	0x11000000	32 MHz / 15 = 2.1333333 MHz
			32MDIV16	0x10000000	32 MHz / 16 = 2.0 MHz
			32MDIV21	0x0C000000	32 MHz / 21 = 1.5238095
			32MDIV23	0x0B000000	32 MHz / 23 = 1.3913043 MHz
			32MDIV30	0x0880000	32 MHz / 30 = 1.0666667 MHz
			32MDIV31	0x08400000	32 MHz / 31 = 1.0322581 MHz
			32MDIV32	0x08000000	32 MHz / 32 = 1.0 MHz
			32MDIV42	0x06000000	32 MHz / 42 = 0.7619048 MHz
			32MDIV63	0x04100000	32 MHz / 63 = 0.5079365 MHz
			32MDIV125	0x020C0000	32 MHz / 125 = 0.256 MHz

6.7.10.20 CONFIG.RATIO

Address offset: 0x518

MCK / LRCK ratio.

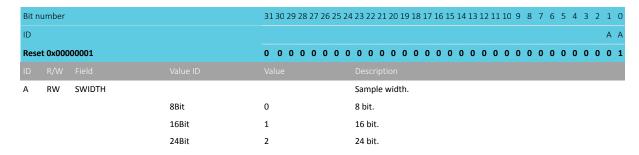
Bit r	umber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					ААА
Rese	t 0x000	00006		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	RATIO			MCK / LRCK ratio.
			32X	0	LRCK = MCK / 32
			48X	1	LRCK = MCK / 48
			64X	2	LRCK = MCK / 64
			96X	3	LRCK = MCK / 96
			128X	4	LRCK = MCK / 128
			192X	5	LRCK = MCK / 192
			256X	6	LRCK = MCK / 256
			384X	7	LRCK = MCK / 384
			512X	8	LRCK = MCK / 512



6.7.10.21 CONFIG.SWIDTH

Address offset: 0x51C

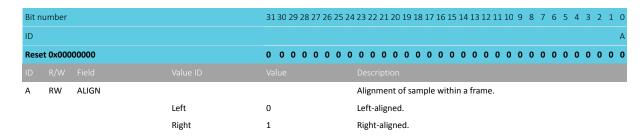
Sample width.



6.7.10.22 CONFIG.ALIGN

Address offset: 0x520

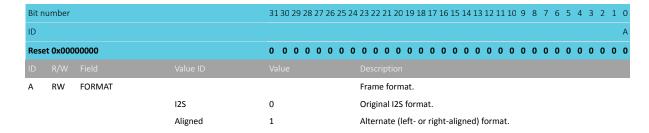
Alignment of sample within a frame.



6.7.10.23 CONFIG.FORMAT

Address offset: 0x524

Frame format.

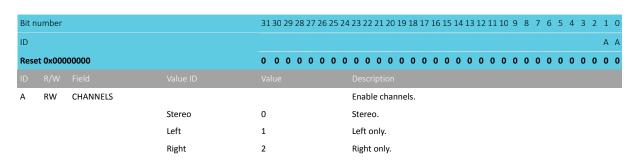


6.7.10.24 CONFIG.CHANNELS

Address offset: 0x528

Enable channels.





6.7.10.25 RXD.PTR

Address offset: 0x538

Receive buffer RAM start address.

Bit n	umber		313	80 29	28 2	7 2	6 25	24	23	22 :	21 2	20 1	9 18	17	16 1	5 14	113	12	11 1	.0 9	8 8	7	6	5	4 3	2	1 0
ID			A A	А А	A A	Δ Δ	A A	Α	Α	Α	Α.	A A	A	Α	A A	A A	A	Α	A	Δ Δ	A	Α	Α	Α	A A	A	A A
Rese	et 0x000	000000	0 (0 0	0 (0 0	0	0	0	0	0	0 (0	0	0 (0	0	0	0 (0	0	0	0	0	0 0	0	0 0
ID																											
Α	RW	PTR							Re	ceiv	e b	uffe	r Da	ita F	RAM	sta	rt ac	ldre	ess. '	Whe	en r	ece	ivin	g, v	vord	S	
									100	ntai	nin	g sa	mpl	es w	/ill b	e w	ritte	n to	thi	s ac	ddre	ss.	This	s ad	dres	s is	a
									wo	rd a	aligi	ned	Dat	a RA	M a	ddr	ess.										

6.7.10.26 TXD.PTR

Address offset: 0x540

Transmit buffer RAM start address.

Bit no	umber		31	30 2	9 28	27 2	6 25	5 24	123	22	21 2	20 1	.9 18	3 17	16 1	L5 14	13	12 1	1 10	9	8	7 6	5	4	3	2 1	. 0
ID			Α	A A	4 A	Α ,	4 Α	A	Α	Α	Α .	A A	4 Α	Α.	Α	А А	Α	A A	A A	Α	Α,	A A	A	A	Α .	А А	A
Rese	t 0x000	00000	0	0 (0 0	0 (0 0	0	0	0	0	0 (0 0	0	0	0 0	0	0 0	0	0	0 (0 (0	0	0	0 0	0 (
ID																											
Α	RW	PTR							Tra	ansr	mit l	buff	fer [ata	RAI	√l sta	ırt a	ddre	ss. V	Vhe	n tr	ans	mit	ting	, wo	rds	
									со	ntai	inin	g sa	mp	les v	vill k	e fe	tche	d fro	m t	his a	addı	ess	. Th	is a	ddre	ss is	s a
									wo	ord	aligi	ned	Dat	a R	AM :	addr	ess.										

6.7.10.27 RXTXD.MAXCNT

Address offset: 0x550

Size of RXD and TXD buffers.

Α	RW					S	ize o	f RX	D ar	nd TX	D bı	ıffer	s in r	num	ber	of 3	2 bi	t w	ords	i.						
ID																										
Res	et 0x000	00000		0 0	0 (0 0	0 0	0 (0 0	0	0 0	0	0 0	0	0 (0	0	0	0 0	0	0	0	0 (0	0	0
ID															A	A	Α	Α	А А	Α	Α	Α	Α,	Α Α	Α	Α
Bit r	number			313	0 29 2	28 27	26 25	24 2	3 22	21 2	20 19	9 18 1	7 16	5 15	14 1	3 12	2 11	10	9 8	7	6	5	4	3 2	1	0

6.7.10.28 PSEL.MCK

Address offset: 0x560
Pin select for MCK signal.



Bit number				31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				С	АААА
Reset 0xFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1		
ID					
Α	RW	PIN		[031]	Pin number
С	RW	CONNECT			Connection
			Disconnected	1	Disconnect
			Connected	0	Connect

6.7.10.29 PSEL.SCK

Address offset: 0x564

Pin select for SCK signal.

Bit number				31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				С	АААА
Reset 0xFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1		
ID					Description
Α	RW	PIN		[031]	Pin number
С	RW	CONNECT			Connection
			Disconnected	1	Disconnect
			Connected	0	Connect

6.7.10.30 PSEL.LRCK

Address offset: 0x568

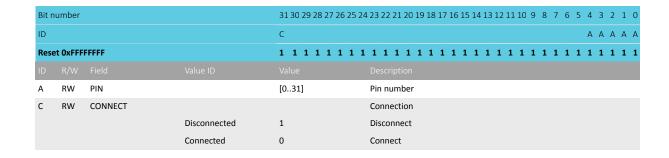
Pin select for LRCK signal.

Bit n	umber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				С	АААА
Reset 0xFFFFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1		
ID					Description
Α	RW	PIN		[031]	Pin number
С	RW	CONNECT			Connection
			Disconnected	1	Disconnect
			Connected	0	Connect

6.7.10.31 PSEL.SDIN

Address offset: 0x56C

Pin select for SDIN signal.



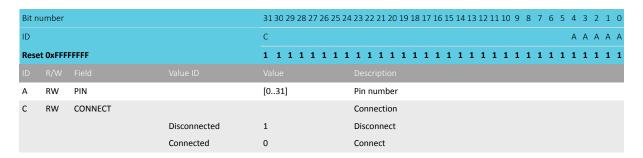




6.7.10.32 PSEL.SDOUT

Address offset: 0x570

Pin select for SDOUT signal.



6.7.11 Electrical specification

6.7.11.1 I2S timing specification

Symbol	Description	Mir	ı. T	Гур.	Max.	Units
t _{S_SDIN}	SDIN setup time before SCK rising	20				ns
t _{H_SDIN}	SDIN hold time after SCK rising	15				ns
t _{S_SDOUT}	SDOUT setup time after SCK falling	40				ns
t _{H_SDOUT}	SDOUT hold time before SCK falling	6				ns
t _{SCK_LRCK}	SCLK falling to LRCK edge	-5	(0	5	ns
f_{MCK}	MCK frequency				4000	kHz
f _{LRCK}	LRCK frequency				48	kHz
f_{SCK}	SCK frequency				2000	kHz
DC _{CK}	Clock duty cycle (MCK, LRCK, SCK)	45			55	%

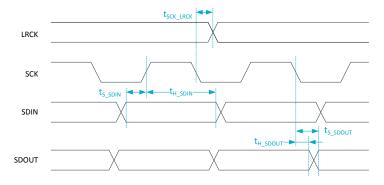


Figure 35: I2S timing diagram

6.8 KMU — Key management unit

The key management unit (KMU) enforces access policies to a subset region of user information configuration register (UICR). This subset region is used for storing cryptographic key values inside the key slots, which the CPU has no access to.

In total there are 128 key slots available, where each key slot can store one 128-bit key value together with an access policy and a destination address for the key value. Multiple key slots can be combined in order to support key sizes larger than 128 bits. The access policy of a key slot governs if and how a key value can



be used, while the destination address determines where in the memory map the KMU pushes the key value upon a request from the CPU.

Key slots can be configured to be pushed directly into write-only key registers in cryptographic accelerators, like e.g. CryptoCell, without exposing the key value itself to the CPU. This enables the CPU to use the key values stored inside the key slots for cryptographic operations without being exposed to the key value.

Access to the KMU, and the key slots in the UICR, is only allowed from secure mode.

6.8.1 Functional view

From a functional view the UICR is divided into two different regions, one-time programmable (OTP) memory and key storage.

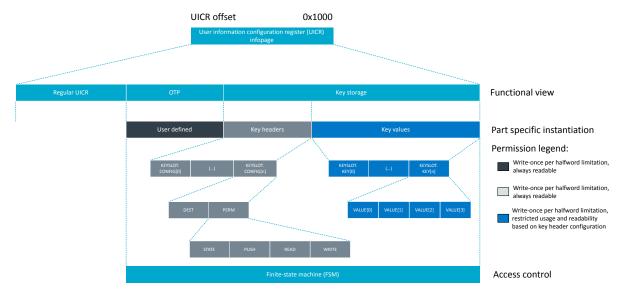


Figure 36: Memory map overview

OTP

One-time programmable (OTP) memory is typically used for holding values that are written once, and then never to be changed again throughout the product lifetime. The OTP region of UICR is emulated by placing a write-once per halfword limitation on registers defined here.

Key storage

The key storage region contains multiple key slots, where each slot consists of a key header and an associated key value. The key value is limited to 128 bits. Any key size greater than 128 bits must be divided and distributed over multiple key slot instances.

Key headers are allocated an address range of 0x400 in the UICR memory map, allowing a total of 128 keys to be addressable inside the key storage region.

Note: The use of the key storage region in UICR should be limited to keys with a certain life span, and not per-session derived keys where the CPU is involved in the key exchange.

6.8.2 Access control

Access control to the underlying UICR infopage in flash is enforced by a hardware finite-state machine (FSM). The FSM can allow or block transactions, depending both on the security of the transaction (secure or non-secure) and on the type of register being written and/or read.



Access type	Key headers	Key values
Read	Allowed	Restricted
Write	Restricted	Restricted

Table 51: Access control

Any restricted access requires an explicit key slot selection through the KMU register interface. Any illegal access to restricted key slot registers will be blocked and word <code>OxDEADDEAD</code> will be returned on the AHB.

The OTP region has individual access control behavior, while access control to the key storage region is configured on a per key slot basis. The KMU FSM operates on only one key slot instance at a time, and the permissions and the usage restriction for a key value associated with a key slot can be configured individually.

Note: Even if the KMU can be configured as non-secure, all non-secure transactions will be blocked.

6.8.3 Protecting the UICR content

The UICR content can be protected against device-internal NVMC.ERASEALL requests, in addition to device-external ERASEALL requests, through the CTRL-AP interface. This feature is useful if the firmware designers want to prevent the OTP region from being erased.

Since enabling this step will permanently disable erase for the UICR, the procedure requires an implementation defined 32-bit word to be written into the UICR's ERASEPROTECT register.

In case of a field return handling, it is still possible to erase the UICR even if the ERASEPROTECT is set. If this functionality is desired, the secure boot code must implement a secure communication channel over the CTRL-AP mailbox interface. Upon successful authentication of the external party, the secure boot code can temporarily re-enable the CTRL-AP ERASEALL functionality.

6.8.4 Usage

This section describes the specific KMU and UICR behavior in more detail, to help the reader get a better overview of KMU's features and the intended usage.

6.8.4.1 OTP

The OTP region of the UICR contains a user-defined static configuration of the device. The KMU emulates the OTP functionality by placing a write-once per halfword limitation of registers defined in this region, i.e. only halfwords containing all '1's can be written.

An OTP write transaction must consist of a full 32-bit word. Both halfwords can either be written simultaneously or one at a time. The KMU FSM will block any write to a halfword in the OTP region, if the initial value of this halfword is not 0xFFFF. When writing halfwords one at a time, the non-active halfword must be masked as 0xFFFF, otherwise the request will be blocked. For example, writing 0x1234XXXX to an OTP destination address which already contains the value 0xFFFFAABB, must be configured as 0x1234FFFF. The OTP destination address will contain the value 0x1234AABB after both write transactions have been processed.

The KMU will also only allow secure AHB write transactions into the OTP region of the UICR. Any AHB write transaction to this region that does not satisfy the above requirements will be ignored, and the STATUS.BLOCKED register will be set to '1'.

6.8.4.2 Key storage

The key storage region of the UICR can contain multiple keys of different type, including symmetrical keys, hashes, public/private key pairs and other device secrets. One of the key features of the KMU, is that these



device secrets can be installed and made available for use in cryptographic operations without revealing the actual secret values.

Keys in this region will typically have a certain life span. The region is not designed to be used for persession derived keys where the non-secure side (i.e. application) is participating in the key exchange.

All key storage is done through the concept of multiple key slots, where each key slot instance consists of one key header and an associated key value. Each key header supports the configuration of usage permissions and an optional secure destination address.

The key header secure destination address option enables the KMU to push the associated key value over a dedicated secure APB to a pre-configured secure location within the memory map. Such locations typically include a write-only key register of the hardware cryptograhic accelerator, allowing the KMU to distribute keys within the system without compromising the key values.

One key slot instance can store a key value of maximum 128 bits. If a key size exceeds this limit, the key value itself must be split over multiple key slot instances.

The following usage and read permissions scheme is applicable for each key slot:

State	Push	Read	Write	Description
Active (1)	Enabled	Enabled	Enabled	Default flash erase value. Key slot cannot be pushed, write is enabled.
	(1)	(1)	(1)	
Active (1)	Enabled	Enabled	Disabled	Key slot is active, push is enabled. Key slot VALUE registers can be read, but write is disabled.
	(1)	(1)	(0)	
Active (1)	Enabled	Disabled	Disabled	Key slot is active, push is enabled. Read and write to key slot VALUE registers are disabled.
	(1)	(0)	(0)	
Active (1)	Disabled	Enabled	Disabled	Key slot is active, push is disabled. Key slot VALUE registers can be read, but write is disabled.
	(0)	(1)	(0)	
Revoked	-	-	-	Key slot is revoked. Cannot be read or pushed over secure APB regardless of the permission settings.
(0)				

Table 52: Valid key slot permission schemes

6.8.4.2.1 Selecting a key slot

The KMU FSM is designed to process only one key slot at a time, effectively operating as a memory protection unit for the key storage region. Whenever a key slot is selected, the KMU will allow access to writing, reading, and/or pushing the associated key value according to the selected slot configuration.

A key slot must be selected prior to use, by writing the key slot ID into the KMU SELECTKEYSLOT register. Because the reset value of this register is 0x00000000, there is no key slot associated with ID=0 and no slot is selected by default. All key slots are addressed using IDs from 1 to 128.

SELECTED status is set when a key slot is selected, and a read or write acccess to that keyslot occurs.

BLOCKED status is set when any illegal access to key slot registers is detected.

When the use of the particular key slot is stopped, the key slot selection in SELECTKEYSLOT must be set back to '0'.

By default, all KMU key slots will consist of a 128-bit key value of '1's, where the key headers have no secure destination address, or any usage and read restrictions.

6.8.4.2.2 Writing to a key slot

Writing a key slot into UICR is a five-step process.

- 1. Select which key slot the KMU shall operate on by writing the desired key slot ID into KMU->SELECTKEYSLOT. The selected key slot must be empty in order to add a new entry to UICR.
- **2.** If the key value shall be pushable over secure APB, the destination address of the recipient must be configured in register KEYSLOT.CONFIG[ID-1].DEST.

NORDIC*

- 3. Write the 128-bit key value into KEYSLOT.KEY[ID-1].VALUE[0-3].
- **4.** Write the desired key slot permissions into KEYSLOT.CONFIG[ID-1].PERM, including any applicable usage restrictions.
- **5.** Select key slot 0.

In case the total key size is greater than 128 bits, the key value itself must be split into 128-bit segments and written to multiple key slot instances. Steps 1 through 5 above must be repeated for the entire key size.

Note: If a key slot is configured as readable, and KEYSLOT.CONFIG[ID-1].DEST is not to be used, it is recommended to disable the push bit in KEYSLOT.CONFIG[ID-1].PERM when configuring key slot permissions.

Note: A key value distributed over multiple key slots should use the same key slot configuration in its key headers, but the secure destination address for each key slot instance must be incremented by 4 words (128 bits) for each key slot instance spanned.

Note: Write to flash must be enabled in NVMC->CONFIG prior to writing keys to flash, and subsequently disabled once writing is complete.

Steps 1 through 5 above will be blocked if any of the following violations are detected:

- No key slot selected
- Non-empty key slot selected
- NVM destination address not empty
- AHB write to KEYSLOT.KEY[ID-1].VALUE[0-3] registers not belonging to selected key slot

6.8.4.2.3 Reading a key value

Key slots that are configured as readable can have their key value read directly from the UICR memory map by the CPU.

Readable keys are typically used during the secure boot sequence, where the CPU is involved in falsifying or verifying the integrity of the system. Since the CPU is involved in this decision process, it makes little sense not to trust the CPU having access to the actual key value but ultimately trust the decision of the integrity check. Another use-case for readable keys is if the key type in question does not have a HW peripheral in the platform that is able to accept such keys over secure APB.

Reading a key value from the UICR is a three-step process:

- 1. Select the key slot which the KMU shall operate on by writing the desired key slot ID into KMU->SELECTKEYSLOT.
- 2. If STATE and READ permission requirements are fulfilled as defined in KEYSLOT.CONFIG[ID-1].PERM, the key value can be read from region KEYSLOT.KEY[ID-1].VALUE[0-3] for selected key slot.
- **3.** Select key slot 0.

Step 2 will be blocked and word 0xDEADDEAD will be returned on AHB if any of the following violations are detected:

- No key slot selected
- Key slot not configured as readable
- · Key slot is revoked
- AHB read to KEYSLOT.KEY[ID-1].VALUE[0-3] registers not belonging to selected key slot



6.8.4.2.4 Push over secure APB

Key slots that are configured as non-readable cannot be read by the CPU regardless of the mode the system is in, and must be pushed over secure APB in order to use the key value for cryptographic operations.

The secure APB destination address is set in the key slot configuration DEST register. Such destination addresses are typically write-only key registers in a hardware cryptographic accelerators memory map. The secure APB allows key slots to be utilized by the software side, without exposing the key value itself.

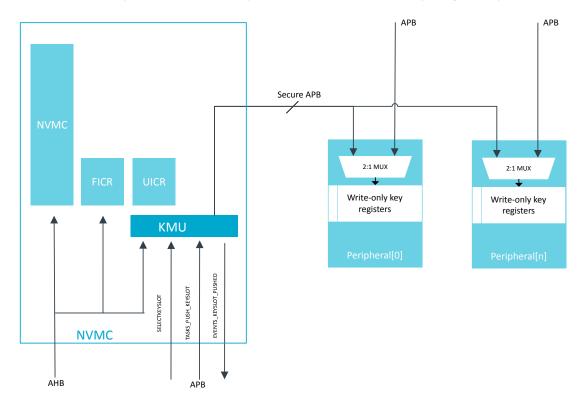


Figure 37: Tasks and events pattern for key slots

Pushing a key slot over secure APB is a four-step process:

- 1. Select the key slot on which the KMU shall operate by writing the desired key slot ID into KMU->SELECTKEYSLOT.
- **2.** Start TASKS_PUSH_KEYSLOT to initiate a secure APB transaction, writing the 128-bit key value associated with the selected key slot into address defined in KEYSLOT.CONFIG[ID-1].DEST.
- **3.** After completing the secure APB transaction, the 128-bit key value is ready for use by the peripheral and EVENTS_KEYSLOT_PUSHED is triggered.
- **4.** Select key slot 0.

Note: If a key value is distributed over multiple key slots due to its key size, exceeding the maximum 128-bit key value limitation, then each distributed key slot must be pushed individually in order to transfer the entire key value over secure APB.

Step 3 will trigger other events than EVENTS_KEYSLOT_PUSHED if the following violations are detected:

- EVENTS_KEYSLOT_ERROR:
 - If no key slot is selected
 - If a key slot has no destination address configured
 - If when pushing a key slot, flash or peripheral returns an error
 - · If pushing a key slot when push permissions are disabled

NORDIC SEMICONDUCTOR

- If attempting to push a key slot with default permissions
- EVENTS_KEYSLOT_REVOKED if a key slot is marked as revoked in its key header configuration

6.8.4.2.5 Revoking the key slots

All key slots within the key storage area can be marked as revoked.

To revoke any key slots, write to the STATE field in the KEYSLOT.CONFIG[ID-1].PERM register. The following rules apply to keys that have been revoked:

- Key slots that have the PUSH field enabled in PERM register can no longer be pushed. If a revoked key slot is selected and task TASKS_PUSH_KEYSLOT is started, the event EVENTS_KEYSLOT_REVOKED is triggered.
- **2.** Key slots that have the READ field enabled in PERM register can no longer be read. Any read operation to a revoked key value will return word 0xDEADDEAD.
- **3.** Previously pushed key values stored in a peripheral write-only key register are not affected by key revocation. If secure code wants to enforce that a revoked key is no longer usable by a peripheral for cryptographic operations, the secure code should disable or reset the peripheral in question.

6.8.4.3 STATUS register

The KMU uses a STATUS register to indicate its status of operation. The SELECTED bit will be asserted whenever the currently selected key slot is successfully read from or written to.

All read or write operations to other key slots than what is currently selected in KMU->SELECTKEYSLOT will assert the BLOCKED bit. The BLOCKED bit will also be asserted if the KMU fails to select a key slot, or if a request has been blocked due to an access violation. Normal operation using the KMU should never trigger the BLOCKED bit. If this bit is triggered during the development phase, it indicates that the code is using the KMU incorrectly.

The STATUS register is reset every time register SELECTKEYSLOT is written.

6.8.5 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x50039000	KNALL	KMU : S	CDLIT	NA	Kay managamant unit	
0x40039000	KMU	KMU : NS	SPLIT	NA	Key management unit	

Table 53: Instances

Register	Offset	Security	Description
TASKS_PUSH_KEYSLOT	0x0000		Push a key slot over secure APB
EVENTS_KEYSLOT_PUSHED	0x100		Key slot successfully pushed over secure APB
EVENTS_KEYSLOT_REVOKED	0x104		Key slot has been revoked and cannot be tasked for selection
EVENTS_KEYSLOT_ERROR	0x108		No key slot selected, no destination address defined, or error during push operation
INTEN	0x300		Enable or disable interrupt
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
INTPEND	0x30C		Pending interrupts
STATUS	0x40C		Status bits for KMU operation
SELECTKEYSLOT	0x500		Select key slot to be read over AHB or pushed over secure APB when TASKS_PUSH_KEYSLOT
			is started

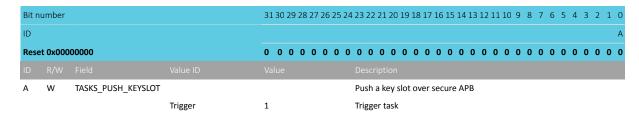
Table 54: Register overview



6.8.5.1 TASKS_PUSH_KEYSLOT

Address offset: 0x0000

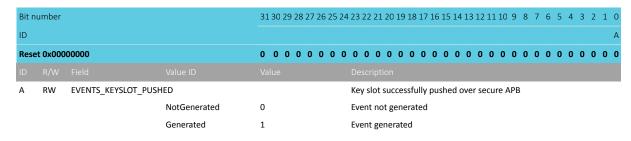
Push a key slot over secure APB



6.8.5.2 EVENTS KEYSLOT PUSHED

Address offset: 0x100

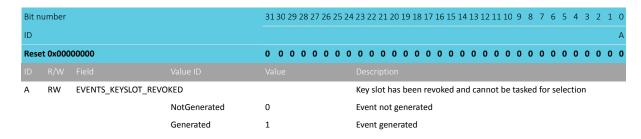
Key slot successfully pushed over secure APB



6.8.5.3 EVENTS_KEYSLOT_REVOKED

Address offset: 0x104

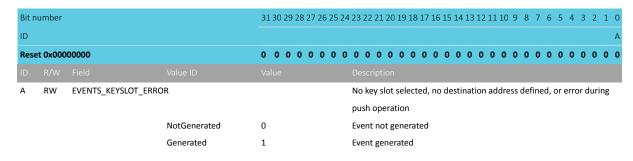
Key slot has been revoked and cannot be tasked for selection



6.8.5.4 EVENTS_KEYSLOT_ERROR

Address offset: 0x108

No key slot selected, no destination address defined, or error during push operation







6.8.5.5 INTEN

Address offset: 0x300

Enable or disable interrupt

Bit r	number			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					СВА
Res	et 0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	KEYSLOT_PUSHED			Enable or disable interrupt for event KEYSLOT_PUSHED
			Disabled	0	Disable
			Enabled	1	Enable
В	RW	KEYSLOT_REVOKED			Enable or disable interrupt for event KEYSLOT_REVOKED
			Disabled	0	Disable
			Enabled	1	Enable
С	RW	KEYSLOT_ERROR			Enable or disable interrupt for event KEYSLOT_ERROR
			Disabled	0	Disable
			Enabled	1	Enable

6.8.5.6 INTENSET

Address offset: 0x304

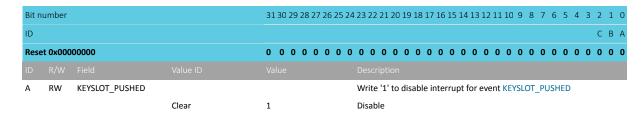
Enable interrupt

Bit n	umber			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					СВА
Rese	Reset 0x00000000 0 0 0 0 0 0			0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	KEYSLOT_PUSHED			Write '1' to enable interrupt for event KEYSLOT_PUSHED
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
В	RW	KEYSLOT_REVOKED			Write '1' to enable interrupt for event KEYSLOT_REVOKED
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
С	RW	KEYSLOT_ERROR			Write '1' to enable interrupt for event KEYSLOT_ERROR
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled

6.8.5.7 INTENCLR

Address offset: 0x308

Disable interrupt





Bit nun	mber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					СВА
Reset (0x0000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
В Г	RW	KEYSLOT_REVOKED			Write '1' to disable interrupt for event KEYSLOT_REVOKED
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
C I	RW	KEYSLOT_ERROR			Write '1' to disable interrupt for event KEYSLOT_ERROR
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled

6.8.5.8 INTPEND

Address offset: 0x30C Pending interrupts

Bit n	umber			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					СВА
Rese	t 0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	R	KEYSLOT_PUSHED			Read pending status of interrupt for event KEYSLOT_PUSHED
			NotPending	0	Read: Not pending
			Pending	1	Read: Pending
В	R	KEYSLOT_REVOKED			Read pending status of interrupt for event KEYSLOT_REVOKED
			NotPending	0	Read: Not pending
			Pending	1	Read: Pending
С	R	KEYSLOT_ERROR			Read pending status of interrupt for event KEYSLOT_ERROR
			NotPending	0	Read: Not pending
			Pending	1	Read: Pending

6.8.5.9 STATUS

Address offset: 0x40C

Status bits for KMU operation

This register is reset and re-written by the KMU whenever SELECTKEYSLOT is written

Bit r	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					B A
Rese	et 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	R	SELECTED			Key slot ID successfully selected by the KMU
			Disabled	0	No key slot ID selected by KMU
			Enabled	1	Key slot ID successfully selected by KMU
В	R	BLOCKED			Violation status
			Disabled	0	No access violation detected
			Enabled	1	Access violation detected and blocked

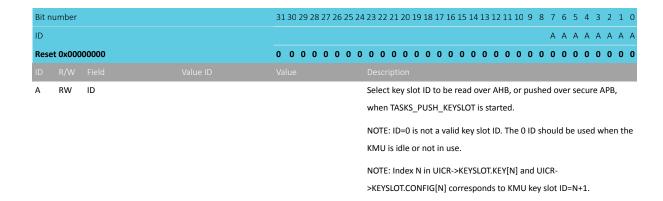




6.8.5.10 SELECTKEYSLOT

Address offset: 0x500

Select key slot to be read over AHB or pushed over secure APB when TASKS_PUSH_KEYSLOT is started



6.9 PDM — Pulse density modulation interface

The pulse density modulation (PDM) module enables input of pulse density modulated signals from external audio frontends, for example, digital microphones. The PDM module generates the PDM clock and supports single-channel or dual-channel (left and right) data input. Data is transferred directly to RAM buffers using EasyDMA.

Listed here are the main features for PDM:

- Up to two PDM microphones configured as a left/right pair using the same data input
- 16 kHz output sample rate, 16-bit samples
- EasyDMA support for sample buffering
- HW decimation filters
- Selectable ratio of 64 or 80 between PDM_CLK and output sample rate

The PDM module illustrated below is interfacing up to two digital microphones with the PDM interface. EasyDMA is implemented to relieve the real-time requirements associated with controlling of the PDM slave from a low priority CPU execution context. It also includes all the necessary digital filter elements to produce pulse code modulation (PCM) samples. The PDM module allows continuous audio streaming.

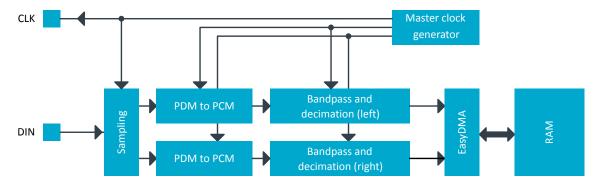


Figure 38: PDM module

6.9.1 Master clock generator

The master clock generator's PDMCLKCTRL register allows adjusting the PDM clock's frequency.

The master clock generator does not add any jitter to the HFCLK source chosen. It is recommended (but not mandatory) to use the Xtal as HFCLK source.



6.9.2 Module operation

By default, bits from the left PDM microphone are sampled on PDM_CLK falling edge, and bits for the right are sampled on the rising edge of PDM_CLK, resulting in two bitstreams. Each bitstream is fed into a digital filter which converts the PDM stream into 16-bit PCM samples, then filters and down-samples them to reach the appropriate sample rate.

The EDGE field in the MODE register allows swapping left and right, so that left will be sampled on rising edge, and right on falling.

The PDM module uses EasyDMA to store the samples coming out from the filters into one buffer in RAM. Depending on the mode chosen in the OPERATION field in the MODE register, memory either contains alternating left and right 16-bit samples (Stereo), or only left 16-bit samples (Mono). To ensure continuous PDM sampling, it is up to the application to update the EasyDMA destination address pointer as the previous buffer is filled.

The continuous transfer can be started or stopped by sending the START and STOP tasks. STOP becomes effective after the current frame has finished transferring, which will generate the STOPPED event. The STOPPED event indicates that all activity in the module is finished, and that the data is available in RAM (EasyDMA has finished transferring as well). Attempting to restart before receiving the STOPPED event may result in unpredictable behavior.

6.9.3 Decimation filter

In order to convert the incoming data stream into PCM audio samples, a decimation filter is included in the PDM interface module.

The input of the filter is the two-channel PDM serial stream (with left channel on clock high, right channel on clock low). Depending on the RATIO selected, its output is 2×16 -bit PCM samples at a sample rate either 64 times or 80 times (depending on the RATIO register) lower than the PDM clock rate.

The filter stage of each channel is followed by a digital volume control, to attenuate or amplify the output samples in a range of -20 dB to +20 dB around the default (reset) setting, defined by $G_{PDM,default}$. The gain is controlled by the GAINL and GAINR registers.

As an example, if the goal is to achieve 2500 RMS output samples (16-bit) with a 1 kHz 90 dBA signal into a -26 dBFS sensitivity PDM microphone, do the following:

- Sum the PDM module's default gain (G_{PDM,default}) and the gain introduced by the microphone and acoustic path of his implementation (an attenuation would translate into a negative gain)
- Adjust GAINL and GAINR by the above summed amount. Assuming that only the PDM module
 influences the gain, GAINL and GAINR must be set to -GPDM, default dB to achieve the requirement.

With G_{PDM,default}=3.2 dB, and as GAINL and GAINR are expressed in 0.5 dB steps, the closest value to program would be 3.0 dB, which can be calculated as:

```
GAINL = GAINR = (DefaultGain - (2 * 3))
```

Remember to check that the resulting values programmed into GAINL and GAINR fall within MinGain and MaxGain.

6.9.4 EasyDMA

Samples will be written directly to RAM, and EasyDMA must be configured accordingly.

The address pointer for the EasyDMA channel is set in SAMPLE.PTR register. If the destination address set in SAMPLE.PTR is not pointing to the Data RAM region, an EasyDMA transfer may result in a HardFault or RAM corruption. See Memory on page 23 for more information about the different memory regions.

DMA supports Stereo (Left+Right 16-bit samples) and Mono (Left only) data transfer, depending on the setting in the OPERATION field in the MODE register. The samples are stored little endian.



MODE.OPERATION	Bits per sample	Result stored per RAM	Physical RAM allocated	Result boundary indexes Note	
		word	(32-bit words)	in RAM	
Stereo	32 (2x16)	L+R	ceil(SAMPLE.MAXCNT/2)	R0=[31:16]; L0=[15:0]	Default
Mono	16	2xL	ceil(SAMPLE.MAXCNT/2)	L1=[31:16]; L0=[15:0]	

Table 55: DMA sample storage

The destination buffer in RAM consists of one block, the size of which is set in SAMPLE.MAXCNT register. Format is number of 16-bit samples. The physical RAM allocated is always:

```
(RAM allocation, in bytes) = SAMPLE.MAXCNT * 2;
```

(but the mapping of the samples depends on MODE.OPERATION.

If OPERATION=Stereo, RAM will contain a succession of left and right samples.

If OPERATION=Mono, RAM will contain a succession of left only samples.

For a given value of SAMPLE.MAXCNT, the buffer in RAM can contain half the stereo sampling time as compared to the mono sampling time.

The PDM acquisition can be started by the START task, after the SAMPLE.PTR and SAMPLE.MAXCNT registers have been written. When starting the module, it will take some time for the filters to start outputting valid data. Transients from the PDM microphone itself may also occur. The first few samples (typically around 50) might hence contain invalid values or transients. It is therefore advised to discard the first few samples after a PDM start.

As soon as the STARTED event is received, the firmware can write the next SAMPLE.PTR value (this register is double-buffered), to ensure continuous operation.

When the buffer in RAM is filled with samples, an END event is triggered. The firmware can start processing the data in the buffer. Meanwhile, the PDM module starts acquiring data into the new buffer pointed to by SAMPLE.PTR, and sends a new STARTED event, so that the firmware can update SAMPLE.PTR to the next buffer address.

6.9.5 Hardware example

PDM can be configured with a single microphone (mono), or with two microphones.

When a single microphone is used, connect the microphone clock to CLK, and data to DIN.

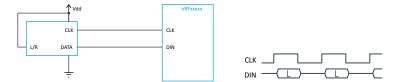


Figure 39: Example of a single PDM microphone, wired as left



Figure 40: Example of a single PDM microphone, wired as right

Note that in a single-microphone (mono) configuration, depending on the microphone's implementation, either the left or the right channel (sampled at falling or rising CLK edge respectively) will contain reliable data.



If two microphones are used, one of them has to be set as left, the other as right (L/R pin tied high or to GND on the respective microphone). It is strongly recommended to use two microphones of exactly the same brand and type so that their timings in left and right operation match.

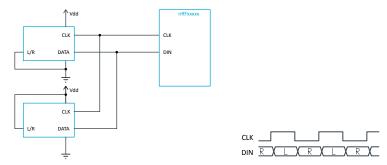


Figure 41: Example of two PDM microphones

6.9.6 Pin configuration

The CLK and DIN signals associated to the PDM module are mapped to physical pins according to the configuration specified in the PSEL.CLK and PSEL.DIN registers respectively. If the CONNECT field in any PSEL register is set to Disconnected, the associated PDM module signal will not be connected to the required physical pins, and will not operate properly.

The PSEL.CLK and PSEL.DIN registers and their configurations are only used as long as the PDM module is enabled, and retained only as long as the device is in System ON mode. See POWER — Power control on page 68 for more information about power modes. When the peripheral is disabled, the pins will behave as regular GPIOs, and use the configuration in their respective OUT bit field and PIN_CNF[n] register.

To ensure correct behavior in the PDM module, the pins used by the PDM module must be configured in the GPIO peripheral as described in GPIO configuration before enabling peripheral on page 157 before enabling the PDM module. This is to ensure that the pins used by the PDM module are driven correctly if the PDM module itself is temporarily disabled or the device temporarily enters System OFF. This configuration must be retained in the GPIO for the selected I/Os as long as the PDM module is supposed to be connected to an external PDM circuit.

Only one peripheral can be assigned to drive a particular GPIO pin at a time. Failing to do so may result in unpredictable behavior.

PDM signal	PDM pin	Direction	Output value	Comment
CLK	As specified in PSEL.CLK	Output	0	
DIN	As specified in PSEL.DIN	Input	Not applicable	

Table 56: GPIO configuration before enabling peripheral

6.9.7 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x50026000	PDM	PDM:S	uc	SA	Pulse density modulation	
0x40026000		PDM: NS	US	3A	(digital microphone) interface	e

Table 57: Instances

Register	Offset	Security	Description
TASKS_START	0x000		Starts continuous PDM transfer
TASKS_STOP	0x004		Stops PDM transfer
SUBSCRIBE START	0x080		Subscribe configuration for task START



Register	Offset	Security	Description
SUBSCRIBE_STOP	0x084		Subscribe configuration for task STOP
EVENTS_STARTED	0x100		PDM transfer has started
EVENTS_STOPPED	0x104		PDM transfer has finished
EVENTS_END	0x108		The PDM has written the last sample specified by SAMPLE.MAXCNT (or the last sample after $$
			a STOP task has been received) to Data RAM
PUBLISH_STARTED	0x180		Publish configuration for event STARTED
PUBLISH_STOPPED	0x184		Publish configuration for event STOPPED
PUBLISH_END	0x188		Publish configuration for event END
INTEN	0x300		Enable or disable interrupt
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
ENABLE	0x500		PDM module enable register
PDMCLKCTRL	0x504		PDM clock generator control
MODE	0x508		Defines the routing of the connected PDM microphones' signals
GAINL	0x518		Left output gain adjustment
GAINR	0x51C		Right output gain adjustment
RATIO	0x520		Selects the ratio between PDM_CLK and output sample rate. Change PDMCLKCTRL
			accordingly.
PSEL.CLK	0x540		Pin number configuration for PDM CLK signal
PSEL.DIN PSEL.DIN	0x544		Pin number configuration for PDM DIN signal
SAMPLE.PTR	0x560		RAM address pointer to write samples to with EasyDMA
SAMPLE.MAXCNT	0x564		Number of samples to allocate memory for in EasyDMA mode

Table 58: Register overview

6.9.7.1 TASKS_START

Address offset: 0x000

Starts continuous PDM transfer

Bit r	number			31 30 29 28 27 2	6 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					A
Res	et 0x000	00000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	W	TASKS_START			Starts continuous PDM transfer
			Trigger	1	Trigger task

6.9.7.2 TASKS_STOP

Address offset: 0x004 Stops PDM transfer

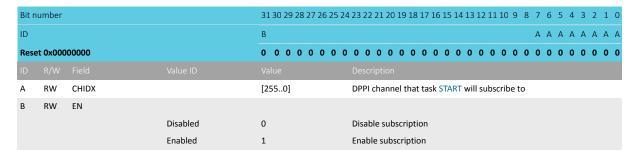
Bit n	umber			31 30 29 28 27 2	26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					A
Rese	t 0x000	00000		0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	W	TASKS_STOP			Stops PDM transfer
			Trigger	1	Trigger task

6.9.7.3 SUBSCRIBE_START

Address offset: 0x080



Subscribe configuration for task START



6.9.7.4 SUBSCRIBE_STOP

Address offset: 0x084

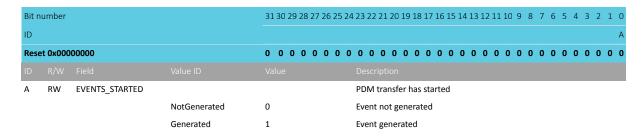
Subscribe configuration for task STOP

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A
Rese	et 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[2550]	DPPI channel that task STOP will subscribe to
В	RW	EN			
			Disabled	0	Disable subscription
			Enabled	1	Enable subscription

6.9.7.5 EVENTS_STARTED

Address offset: 0x100

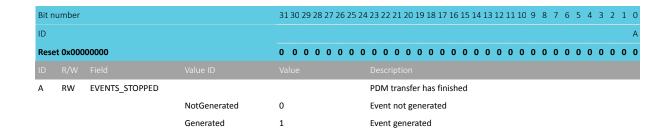
PDM transfer has started



6.9.7.6 EVENTS_STOPPED

Address offset: 0x104

PDM transfer has finished



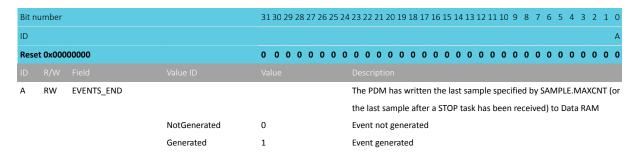




6.9.7.7 EVENTS_END

Address offset: 0x108

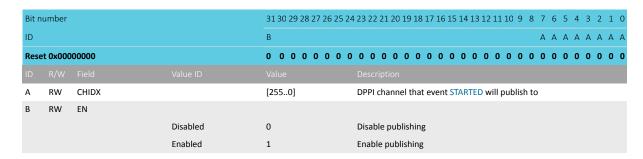
The PDM has written the last sample specified by SAMPLE.MAXCNT (or the last sample after a STOP task has been received) to Data RAM



6.9.7.8 PUBLISH STARTED

Address offset: 0x180

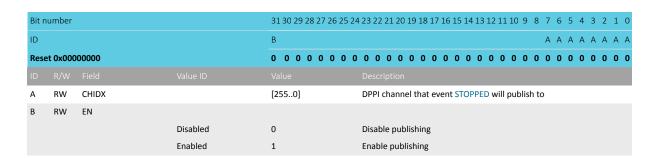
Publish configuration for event STARTED



6.9.7.9 PUBLISH STOPPED

Address offset: 0x184

Publish configuration for event STOPPED



6.9.7.10 PUBLISH_END

Address offset: 0x188

Publish configuration for event END



Bit n	umber			31 30 29 28 27 26 25 24	1 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	CHIDX		[2550]	DPPI channel that event END will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing

6.9.7.11 INTEN

Address offset: 0x300

Enable or disable interrupt

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					СВА
Rese	et 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	STARTED			Enable or disable interrupt for event STARTED
			Disabled	0	Disable
			Enabled	1	Enable
В	RW	STOPPED			Enable or disable interrupt for event STOPPED
			Disabled	0	Disable
			Enabled	1	Enable
С	RW	END			Enable or disable interrupt for event END
			Disabled	0	Disable
			Enabled	1	Enable

6.9.7.12 INTENSET

Address offset: 0x304

Enable interrupt

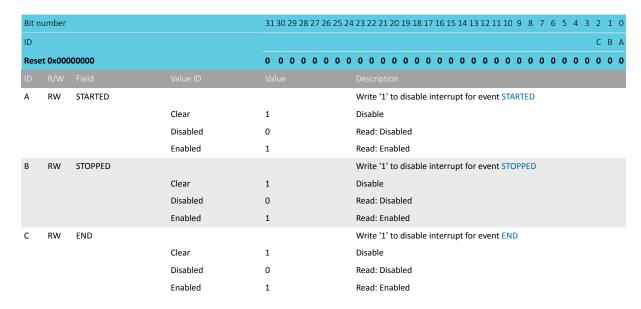
Bit nui	mber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					СВА
Reset 0x00000000 0 0 0 0 0 0				0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
Α	RW	STARTED			Write '1' to enable interrupt for event STARTED
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
В	RW	STOPPED			Write '1' to enable interrupt for event STOPPED
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
С	RW	END			Write '1' to enable interrupt for event END
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled

6.9.7.13 INTENCLR

Address offset: 0x308



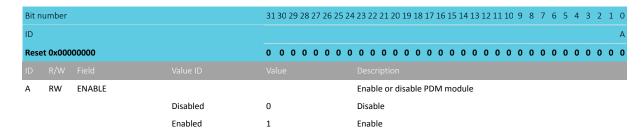
Disable interrupt



6.9.7.14 ENABLE

Address offset: 0x500

PDM module enable register



6.9.7.15 PDMCLKCTRL

Address offset: 0x504

4418_1315 v2.1

PDM clock generator control

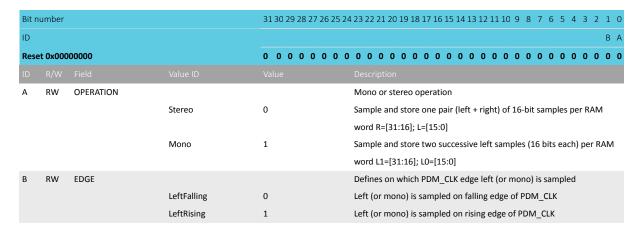
Bit no	umber			31	130	29 2	8 27	7 26	25	24 2	23 2:	2 21	1 20	19	18 17	7 16	15	14	13 1	.2 1	1 10	9	8	7	6	5	4	3	2	1 0
ID				Α	Α	A	А А	A	Α	Α	ΑД	A	A	Α	А А	A	Α	Α	Α ,	Δ ,	A A	Α	Α	Α	Α	Α	Α.	Α.	A ,	4 A
Rese	t 0x084	00000		0	0	0 () 1	. 0	0	0	0 1	. 0	0	0	0 0	0	0	0	0 (0 (0	0	0	0	0	0	0	0	0	0 0
ID																														
Α	RW	FREQ								ı	PDM	_CI	LK fı	equ	uenc	/ co	nfig	gura	tior	١.										
			1000K	0x	080	0000	00			1	PDM	L_CI	LK =	32	MHz	/ 3	2 =	1.0	00 N	ЛHz	!									
			Default	0x	084	000	00			-	PDM	L_CI	LK =	32	MHz	/ 3	1 =	1.0	32 N	ЛHz	. No	omi	nal	clo	ck f	or				
										-	RATI	O=F	Ratio	o64																
			1067K	0x	088	8000	00			1	PDM	L_CI	LK =	32	MHz	/ 3	0 =	1.0	67 N	ЛHz	:									
			1231K	0x	098	8000	00			1	PDM	L_CI	LK =	32	MHz	/ 2	6 =	1.2	31 N	ЛHz	:									
			1280K	0x	OAC	0000	00			1	PDM	L_CI	LK =	32	MHz	/ 2	5 =	1.2	80 N	ЛHz	. No	omi	nal	clo	ck f	or				
										1	RATI	O=F	Ratio	08c																
			1333K	0x	(0A8	3000	00			١	PDM	I_CI	LK =	32	MHz	/ 2	4 =	1.3	33 N	ЛHz	!									



6.9.7.16 MODE

Address offset: 0x508

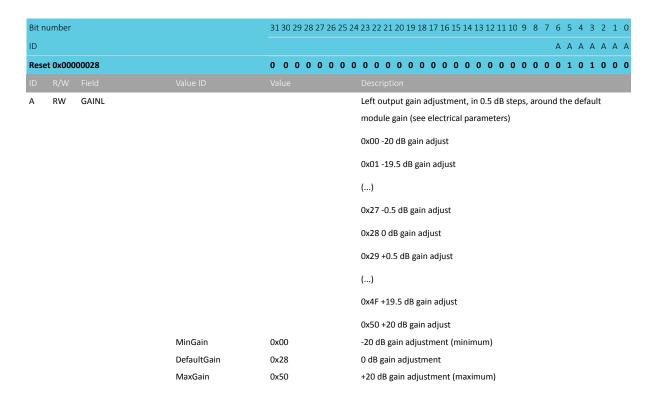
Defines the routing of the connected PDM microphones' signals



6.9.7.17 GAINL

Address offset: 0x518

Left output gain adjustment

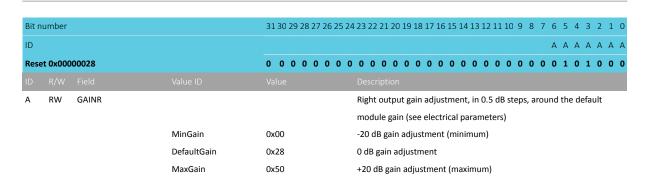


6.9.7.18 GAINR

Address offset: 0x51C

Right output gain adjustment

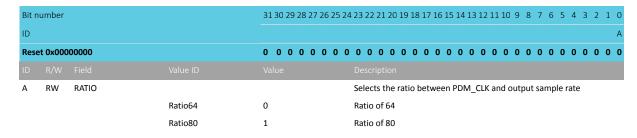




6.9.7.19 RATIO

Address offset: 0x520

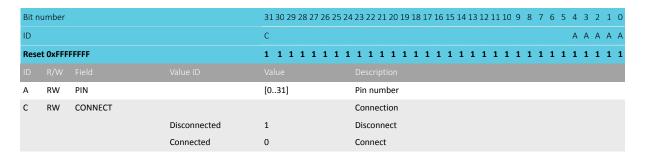
Selects the ratio between PDM CLK and output sample rate. Change PDMCLKCTRL accordingly.



6.9.7.20 PSEL.CLK

Address offset: 0x540

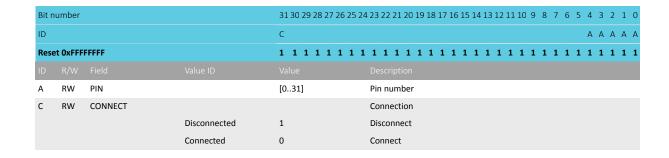
Pin number configuration for PDM CLK signal



6.9.7.21 PSEL.DIN

Address offset: 0x544

Pin number configuration for PDM DIN signal



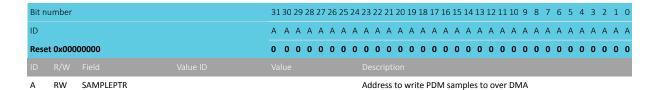




6.9.7.22 SAMPLE.PTR

Address offset: 0x560

RAM address pointer to write samples to with EasyDMA

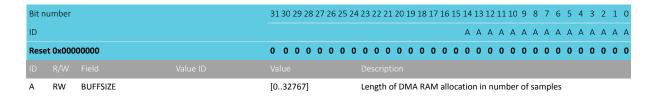


Note: See the memory chapter for details about which memories are available for EasyDMA.

6.9.7.23 SAMPLE.MAXCNT

Address offset: 0x564

Number of samples to allocate memory for in EasyDMA mode



6.9.8 Electrical specification

6.9.8.1 PDM Electrical Specification

Symbol	Description	Min.	Тур.	Max.	Units
f _{PDM,CLK,64}	PDM clock speed. PDMCLKCTRL = Default (Setting needed		1.032		MHz
	for 16 MHz sample frequency @ RATIO = Ratio64)				
f _{PDM,CLK,80}	PDM clock speed. PDMCLKCTRL = 1280K (Setting needed		1.28		MHz
	for 16 MHz sample frequency @ RATIO = Ratio80)				
$t_{\text{PDM,JITTER}}$	Jitter in PDM clock output			20	ns
$T_{dPDM,CLK}$	PDM clock duty cycle	40	50	60	%
t _{PDM,DATA}	Decimation filter delay			5	ms
$t_{PDM,cv}$	Allowed clock edge to data valid			125	ns
t _{PDM,ci}	Allowed (other) clock edge to data invalid	0			ns
t _{PDM,s}	Data setup time at f _{PDM,CLK} =1.024 MHz or 1.280 MHz	65			ns
$t_{\text{PDM,h}}$	Data hold time at $f_{\text{PDM,CLK}}$ =1.024 MHz or 1.280 MHz	0			ns
$G_{PDM,default}$	Default (reset) absolute gain of the PDM module		3.2		dB



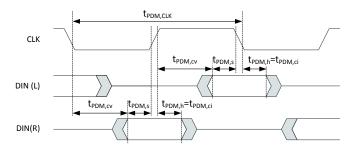


Figure 42: PDM timing diagram

6.10 PWM — Pulse width modulation

The pulse width modulation (PWM) module enables the generation of pulse width modulated signals on GPIO. The module implements an up or up-and-down counter with four PWM channels that drive assigned GPIOs.

The following are the main features of a PWM module:

- · Programmable PWM frequency
- Up to four PWM channels with individual polarity and duty cycle values
- Edge or center-aligned pulses across PWM channels
- Multiple duty cycle arrays (sequences) defined in RAM
- Autonomous and glitch-free update of duty cycle values directly from memory through EasyDMA (no CPU involvement)
- Change of polarity, duty cycle, and base frequency possibly on every PWM period
- RAM sequences can be repeated or connected into loops

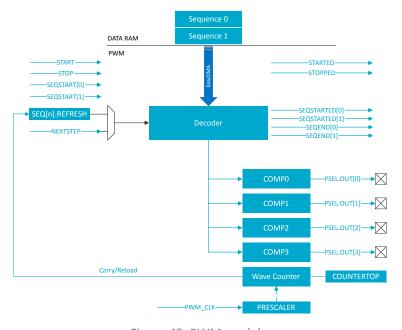


Figure 43: PWM module

6.10.1 Wave counter

The wave counter is responsible for generating the pulses at a duty cycle that depends on the compare values, and at a frequency that depends on COUNTERTOP.

There is one common 15-bit counter with four compare channels. Thus, all four channels will share the same period (PWM frequency), but can have individual duty cycle and polarity. The polarity is set by a



value read from RAM (see figure Decoder memory access modes on page 170). Whether the counter counts up, or up and down, is controlled by the MODE register.

The timer top value is controlled by the COUNTERTOP register. This register value, in conjunction with the selected PRESCALER of the PWM_CLK, will result in a given PWM period. A COUNTERTOP value smaller than the compare setting will result in a state where no PWM edges are generated. OUT[n] is held high, given that the polarity is set to FallingEdge. All compare registers are internal and can only be configured through decoder presented later. COUNTERTOP can be safely written at any time.

Sampling follows the START task. If DECODER.LOAD=WaveForm, the register value is ignored and taken from RAM instead (see section Decoder with EasyDMA on page 170 for more details). If DECODER.LOAD is anything else than the WaveForm, it is sampled following a STARTSEQ[n] task and when loading a new value from RAM during a sequence playback.

The following figure shows the counter operating in up mode (MODE=PWM_MODE_Up), with three PWM channels with the same frequency but different duty cycle:

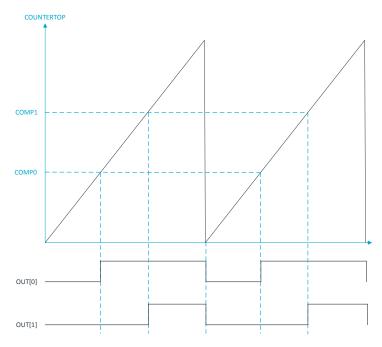


Figure 44: PWM counter in up mode example - FallingEdge polarity

The counter is automatically reset to zero when COUNTERTOP is reached and OUT[n] will invert. OUT[n] is held low if the compare value is 0 and held high if set to COUNTERTOP, given that the polarity is set to



FallingEdge. Counter running in up mode results in pulse widths that are edge-aligned. The following is the code for the counter in up mode example:

```
uint16 t pwm seq[4] = {PWM CH0 DUTY, PWM CH1 DUTY, PWM CH2 DUTY, PWM CH3 DUTY};
NRF PWM0->PSEL.OUT[0] = (first pin << PWM PSEL OUT PIN Pos) |
                         (PWM PSEL OUT CONNECT Connected <<
                                                   PWM PSEL OUT CONNECT Pos);
NRF_PWM0->PSEL.OUT[1] = (second_pin << PWM_PSEL_OUT_PIN_Pos) |
                        (PWM PSEL OUT CONNECT Connected <<
                                                   PWM PSEL OUT CONNECT Pos);
NRF_PWM0->ENABLE = (PWM_ENABLE_ENABLE_Enabled << PWM_ENABLE_ENABLE_Pos);
NRF_PWM0->MODE = (PWM_MODE_UPDOWN_Up << PWM_MODE_UPDOWN_Pos);</pre>
NRF_PWM0->PRESCALER = (PWM_PRESCALER_PRESCALER_DIV_1 <<
                                                   PWM_PRESCALER_PRESCALER_Pos);
NRF PWM0->COUNTERTOP = (16000 << PWM COUNTERTOP COUNTERTOP Pos); //1 msec
NRF_PWM0->LOOP = (PWM_LOOP_CNT_Disabled << PWM_LOOP_CNT_Pos);
NRF PWM0->DECODER = (PWM DECODER LOAD Individual << PWM DECODER LOAD Pos) |
                       (PWM DECODER MODE RefreshCount << PWM DECODER MODE Pos);
NRF_PWM0->SEQ[0].PTR = ((uint32_t)(pwm_seq) << PWM_SEQ_PTR_PTR_Pos);
NRF_PWM0->SEQ[0].CNT = ((sizeof(pwm_seq) / sizeof(uint16_t)) <<
                                                   PWM SEQ CNT CNT Pos);
NRF PWM0->SEQ[0].REFRESH = 0;
NRF PWM0->SEQ[0].ENDDELAY = 0;
NRF PWM0->TASKS SEQSTART[0] = 1;
```

When the counter is running in up mode, the following formula can be used to compute the PWM period and the step size:

```
PWM period: T_{PWM (Up)} = T_{PWM \_CLK} * COUNTERTOP
Step width/Resolution: T_{steps} = T_{PWM \ CLK}
```

The following figure shows the counter operating in up-and-down mode (MODE=PWM_MODE_UpAndDown), with two PWM channels with the same frequency but different duty cycle and output polarity:



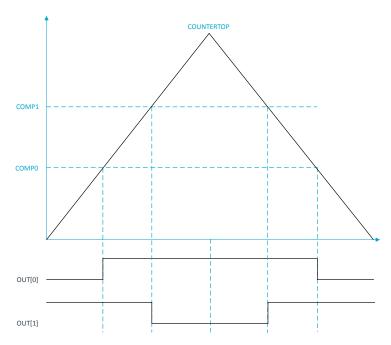


Figure 45: PWM counter in up-and-down mode example

The counter starts decrementing to zero when COUNTERTOP is reached and will invert the OUT[n] when compare value is hit for the second time. This results in a set of pulses that are center-aligned. The following is the code for the counter in up-and-down mode example:

```
uint16 t pwm seq[4] = {PWM CH0 DUTY, PWM CH1 DUTY, PWM CH2 DUTY, PWM CH3 DUTY};
NRF PWM0->PSEL.OUT[0] = (first pin << PWM PSEL OUT PIN Pos) |
                        (PWM_PSEL_OUT_CONNECT_Connected <<
                                                PWM PSEL OUT CONNECT Pos);
NRF PWM0->PSEL.OUT[1] = (second pin << PWM PSEL OUT PIN Pos) |
                        (PWM PSEL OUT CONNECT Connected <<
                                                PWM PSEL OUT CONNECT Pos);
                     = (PWM ENABLE ENABLE Enabled << PWM ENABLE ENABLE Pos);
NRF PWM0->ENABLE
NRF_PWM0->MODE
                     = (PWM MODE UPDOWN UpAndDown << PWM MODE UPDOWN Pos);
NRF PWM0->PRESCALER = (PWM PRESCALER PRESCALER DIV 1 <<
                                                PWM PRESCALER PRESCALER Pos);
NRF PWM0->COUNTERTOP = (16000 << PWM COUNTERTOP COUNTERTOP Pos); //1 msec
NRF PWM0->LOOP
               = (PWM LOOP CNT Disabled << PWM LOOP CNT Pos);
NRF PWM0->DECODER = (PWM DECODER LOAD Individual << PWM DECODER LOAD Pos) |
                     (PWM DECODER MODE RefreshCount << PWM DECODER MODE Pos);
NRF PWM0->SEQ[0].PTR = ((uint32 t) (pwm seq) << PWM SEQ PTR PTR Pos);
NRF_PWM0->SEQ[0].CNT = ((sizeof(pwm_seq) / sizeof(uint16_t)) <<
                                                PWM SEQ CNT CNT Pos);
NRF PWM0->SEQ[0].REFRESH = 0;
NRF PWM0->SEQ[0].ENDDELAY = 0;
NRF_PWM0->TASKS_SEQSTART[0] = 1;
```

When the counter is running in up-and-down mode, the following formula can be used to compute the PWM period and the step size:

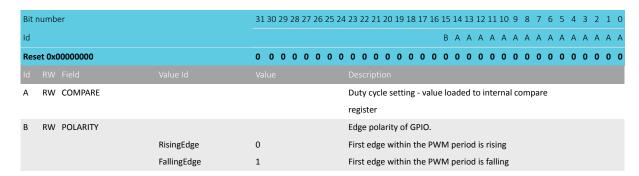
```
T_{PWM\,(Up\ And\ Down)} = T_{PWM\_CLK} * 2 * COUNTERTOP
Step width/Resolution: T_{steps} = T_{PWM\ CLK} * 2
```



6.10.2 Decoder with EasyDMA

The decoder uses EasyDMA to take PWM parameters stored in RAM and update the internal compare registers of the wave counter, based on the mode of operation.

PWM parameters are organized into a sequence containing at least one half word (16 bit). Its most significant bit[15] denotes the polarity of the OUT[n] while bit[14:0] is the 15-bit compare value.



The DECODER register controls how the RAM content is interpreted and loaded into the internal compare registers. The LOAD field controls if the RAM values are loaded to all compare channels, or to update a group or all channels with individual values. The following figure illustrates how parameters stored in RAM are organized and routed to various compare channels in different modes:

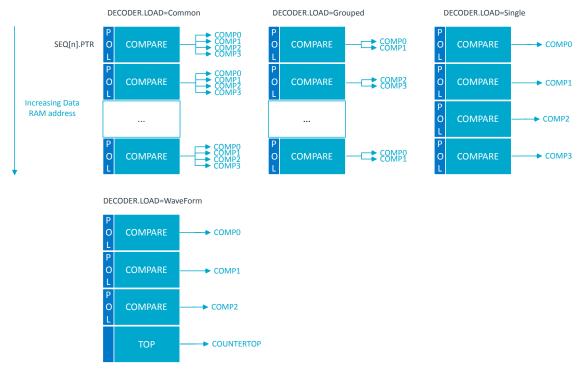


Figure 46: Decoder memory access modes

A special mode of operation is available when DECODER.LOAD is set to WaveForm. In this mode, up to three PWM channels can be enabled - OUT[0] to OUT[2]. In RAM, four values are loaded at a time: the first, second and third location are used to load the values, and the fourth RAM location is used to load the COUNTERTOP register. This way one can have up to three PWM channels with a frequency base that changes on a per PWM period basis. This mode of operation is useful for arbitrary wave form generation in applications, such as LED lighting.

The register SEQ[n].REFRESH=N (one per sequence n=0 or 1) will instruct a new RAM stored pulse width value on every (N+1)th PWM period. Setting the register to zero will result in a new duty cycle update every PWM period, as long as the minimum PWM period is observed.

NORDIC

Note that registers SEQ[n].REFRESH and SEQ[n].ENDDELAY are ignored when DECODER.MODE=NextStep. The next value is loaded upon every received NEXTSTEP task.

SEQ[n].PTR is the pointer used to fetch COMPARE values from RAM. If the SEQ[n].PTR is not pointing to a RAM region, an EasyDMA transfer may result in a HardFault or RAM corruption. See Memory on page 23 for more information about the different memory regions. After the SEQ[n].PTR is set to the desired RAM location, the SEQ[n].CNT register must be set to the number of 16-bit half words in the sequence. It is important to observe that the Grouped mode requires one half word per group, while the Single mode requires one half word per channel, thus increasing the RAM size occupation. If PWM generation is not running when the SEQSTART[n] task is triggered, the task will load the first value from RAM and then start the PWM generation. A SEQSTARTED[n] event is generated as soon as the EasyDMA has read the first PWM parameter from RAM and the wave counter has started executing it. When LOOP.CNT=0, sequence n=0 or 1 is played back once. After the last value in the sequence has been loaded and started executing, a SEQEND[n] event is generated. The PWM generation will then continue with the last loaded value. The following figure illustrates an example of a simple playback.

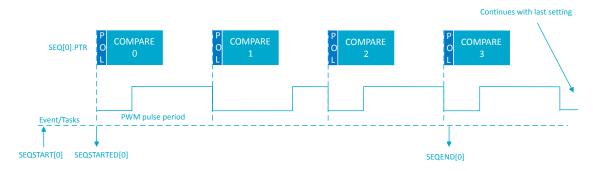


Figure 47: Simple sequence example

The following source code is used for configuration and timing details in a sequence where only sequence 0 is used and only run once with a new PWM duty cycle for each period.

```
NRF PWM0->PSEL.OUT[0] = (first_pin << PWM_PSEL_OUT_PIN_Pos) |
                        (PWM PSEL OUT CONNECT Connected <<
                                                PWM PSEL OUT CONNECT Pos);
NRF PWM0->ENABLE
                     = (PWM ENABLE ENABLE Enabled << PWM ENABLE ENABLE Pos);
NRF PWM0->MODE
                     = (PWM MODE UPDOWN Up << PWM MODE UPDOWN Pos);
NRF PWM0->PRESCALER = (PWM PRESCALER PRESCALER DIV 1 <<
                                                PWM PRESCALER PRESCALER Pos);
NRF PWM0->COUNTERTOP = (16000 << PWM COUNTERTOP COUNTERTOP Pos); //1 msec
NRF PWM0->LOOP
                     = (PWM LOOP CNT Disabled << PWM LOOP CNT Pos);
NRF PWM0->DECODER = (PWM DECODER LOAD Common << PWM DECODER LOAD Pos) |
                     (PWM_DECODER_MODE_RefreshCount << PWM_DECODER_MODE_Pos);
NRF PWM0->SEQ[0].PTR = ((uint32 t)(seq0 ram) << PWM SEQ PTR PTR Pos);
NRF PWM0->SEQ[0].CNT = ((sizeof(seq0 ram) / sizeof(uint16 t)) <<
                                                PWM SEQ CNT CNT Pos);
NRF PWM0->SEQ[0].REFRESH = 0;
NRF PWM0->SEQ[0].ENDDELAY = 0;
NRF_PWM0->TASKS_SEQSTART[0] = 1;
```

To completely stop the PWM generation and force the associated pins to a defined state, a STOP task can be triggered at any time. A STOPPED event is generated when the PWM generation has stopped at the end of the currently running PWM period, and the pins go into their idle state as defined in GPIO OUT register.



PWM generation can then only be restarted through a SEQSTART[n] task. SEQSTART[n] will resume PWM generation after having loaded the first value from the RAM buffer defined in the SEQ[n].PTR register.

The following table indicates when specific registers get sampled by the hardware. Care should be taken when updating these registers to avoid that values are applied earlier than expected.

Register	Taken into account by hardware	Recommended (safe) update
SEQ[n].PTR	When sending the SEQSTART[n] task	After having received the SEQSTARTED[n] event
SEQ[n].CNT	When sending the SEQSTART[n] task	After having received the SEQSTARTED[n] event
SEQ[0].ENDDELAY	When sending the SEQSTART[0] task	Before starting sequence [0] through a SEQSTART[0] task
	Every time a new value from sequence [0] has been loaded from	When no more value from sequence [0] gets loaded from RAM
	RAM and gets applied to the Wave Counter (indicated by the	(indicated by the SEQEND[0] event)
	PWMPERIODEND event)	At any time during sequence [1] (which starts when the
		SEQSTARTED[1] event is generated)
SEQ[1].ENDDELAY	When sending the SEQSTART[1] task	Before starting sequence [1] through a SEQSTART[1] task
	Every time a new value from sequence [1] has been loaded from	When no more value from sequence [1] gets loaded from RAM
	RAM and gets applied to the Wave Counter (indicated by the	(indicated by the SEQEND[1] event)
	PWMPERIODEND event)	At any time during sequence [0] (which starts when the
		SEQSTARTED[0] event is generated)
SEQ[0].REFRESH	When sending the SEQSTART[0] task	Before starting sequence [0] through a SEQSTART[0] task
	-	
	Every time a new value from sequence [0] has been loaded from RAM and gets applied to the Wave Counter (indicated by the	At any time during sequence [1] (which starts when the SEQSTARTED[1] event is generated)
	PWMPERIODEND event)	SEQUIANTED[1] event is generated)
SEQ[1].REFRESH	When sending the SEQSTART[1] task	Before starting sequence [1] through a SEQSTART[1] task
	Every time a new value from sequence [1] has been loaded from	At any time during sequence [0] (which starts when the
	RAM and gets applied to the Wave Counter (indicated by the	SEQSTARTED[0] event is generated)
	PWMPERIODEND event)	orac management and action actio
COUNTERTOP	In DECODER.LOAD=WaveForm: this register is ignored.	Before starting PWM generation through a SEQSTART[n] task
	In all other LOAD modes: at the end of current PWM period	After a STOP task has been triggered, and the STOPPED event has
	(indicated by the PWMPERIODEND event)	been received.
MODE	Immediately	Before starting PWM generation through a SEQSTART[n] task
		After a STOP task has been triggered, and the STOPPED event has
		been received.
DECODER	Immediately	Before starting PWM generation through a SEQSTART[n] task
		After a STOP task has been triggered, and the STOPPED event has
		been received.
PRESCALER	Immediately	Before starting PWM generation through a SEQSTART[n] task
		After a STOP task has been triggered, and the STOPPED event has
		been received.
LOOP	Immediately	Before starting PWM generation through a SEQSTART[n] task
		After a STOP task has been triggered, and the STOPPED event has
		been received.
PSEL.OUT[n]	Immediately	Before enabling the PWM instance through the ENABLE register

Table 59: When to safely update PWM registers

Note: SEQ[n].REFRESH and SEQ[n].ENDDELAY are ignored at the end of a complex sequence, indicated by a LOOPSDONE event. The reason for this is that the last value loaded from RAM is maintained until further action from software (restarting a new sequence, or stopping PWM generation).



The following figure shows a more complex example using the register LOOP on page 187.

Figure 48: Example using two sequences

In this case, an automated playback takes place, consisting of SEQ[0], delay 0, SEQ[1], delay 1, then again SEQ[0], etc. The user can choose to start a complex playback with SEQ[0] or SEQ[1] through sending the SEQSTART[0] or SEQSTART[1] task. The complex playback always ends with delay 1.

The two sequences 0 and 1 are defined by the addresses of value tables in RAM (pointed to by SEQ[n].PTR) and the buffer size (SEQ[n].CNT). The rate at which a new value is loaded is defined individually for each sequence by SEQ[n].REFRESH. The chaining of sequence 1 following the sequence 0 is implicit, the LOOP.CNT register allows the chaining of sequence 1 to sequence 0 for a determined number of times. In other words, it allows to repeat a complex sequence a number of times in a fully automated way.

In the following code example, sequence 0 is defined with SEQ[0].REFRESH set to 1, meaning that a new PWM duty cycle is pushed every second PWM period. This complex sequence is started with the SEQSTART[0] task, so SEQ[0] is played first. Since SEQ[0].ENDDELAY=1 there will be one PWM period delay between last period on sequence 0 and the first period on sequence 1. Since SEQ[1].ENDDELAY=0 there is no delay 1, so SEQ[0] would be started immediately after the end of SEQ[1]. However, as LOOP.CNT is



1, the playback stops after having played SEQ[1] only once, and both SEQEND[1] and LOOPSDONE are generated (their order is not guaranteed in this case).

```
NRF PWM0->PSEL.OUT[0] = (first pin << PWM PSEL OUT PIN Pos) |
                         (PWM PSEL OUT CONNECT Connected <<
                                                   PWM PSEL OUT CONNECT Pos);
NRF_PWM0->ENABLE = (PWM_ENABLE_ENABLE_Enabled << PWM_ENABLE_ENABLE_Pos);
NRF_PWM0->MODE = (PWM_MODE_UPDOWN_Up << PWM_MODE_UPDOWN_Pos);</pre>
NRF PWM0->PRESCALER = (PWM PRESCALER PRESCALER DIV 1 <<
                                                    PWM PRESCALER PRESCALER Pos);
NRF_PWM0->COUNTERTOP = (16000 << PWM_COUNTERTOP_COUNTERTOP_Pos); //1 msec
NRF_PWM0->LOOP = (1 << PWM_LOOP_CNT_Pos);</pre>
NRF_PWM0->DECODER = (PWM_DECODER_LOAD_Common << PWM_DECODER_LOAD_Pos) |
                       (PWM DECODER MODE RefreshCount << PWM DECODER MODE Pos);
NRF_PWM0->SEQ[0].PTR = ((uint32_t)(seq0_ram) << PWM_SEQ_PTR_PTR_Pos);</pre>
NRF PWM0->SEQ[0].CNT = ((sizeof(seq0 ram) / sizeof(uint16 t)) <<
                                                    PWM SEQ CNT CNT Pos);
NRF PWM0->SEQ[0].REFRESH = 1;
NRF PWM0->SEQ[0].ENDDELAY = 1;
NRF PWM0->SEQ[1].PTR = ((uint32 t)(seq1 ram) << PWM SEQ PTR PTR Pos);
NRF_PWM0->SEQ[1].CNT = ((sizeof(seq1_ram) / sizeof(uint16_t)) <<
                                                   PWM SEQ CNT CNT Pos);
NRF PWM0->SEQ[1].REFRESH = 0;
NRF PWM0->SEQ[1].ENDDELAY = 0;
NRF PWM0->TASKS SEQSTART[0] = 1;
```

The decoder can also be configured to asynchronously load new PWM duty cycle. If the DECODER.MODE register is set to NextStep, then the NEXTSTEP task will cause an update of internal compare registers on the next PWM period.

The following figures provide an overview of each part of an arbitrary sequence, in various modes (LOOP.CNT=0 and LOOP.CNT>0). In particular, the following are represented:

- Initial and final duty cycle on the PWM output(s)
- Chaining of SEQ[0] and SEQ[1] if LOOP.CNT>0
- Influence of registers on the sequence
- Events generated during a sequence
- DMA activity (loading of next value and applying it to the output(s))



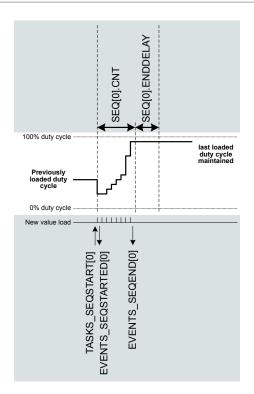


Figure 49: Single shot (LOOP.CNT=0)

Note: The single-shot example also applies to SEQ[1]. Only SEQ[0] is represented for simplicity.

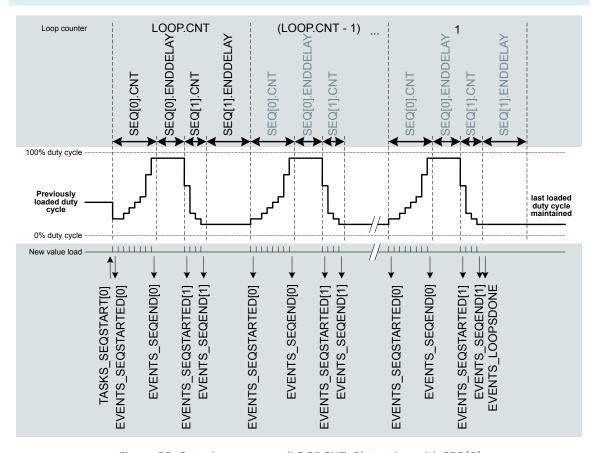


Figure 50: Complex sequence (LOOP.CNT>0) starting with SEQ[0]



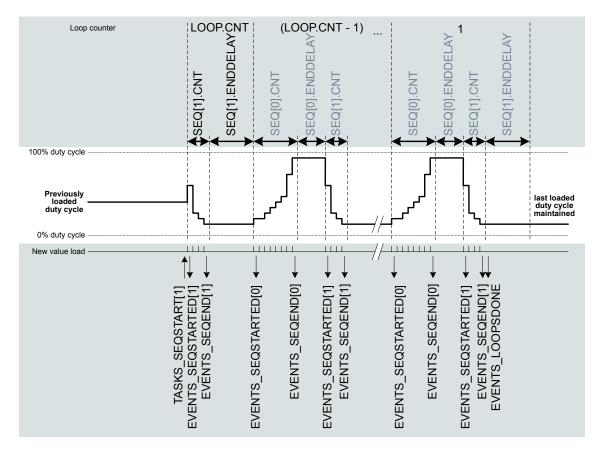


Figure 51: Complex sequence (LOOP.CNT>0) starting with SEQ[1]

Note: If a sequence is in use in a simple or complex sequence, it must have a length of SEQ[n].CNT > 0.

This example shows how the PWM module can be configured to repeat a single sequence until stopped.

```
NRF PWM0->PSEL.OUT[0] = (first pin << PWM PSEL OUT PIN Pos) |
                        (PWM PSEL OUT CONNECT Connected <<
                                                 PWM PSEL OUT CONNECT Pos);
NRF PWM0->ENABLE
                      = (PWM ENABLE ENABLE Enabled << PWM ENABLE ENABLE Pos);
                      = (PWM MODE UPDOWN Up << PWM MODE UPDOWN Pos);
NRF PWM0->MODE
NRF PWM0->PRESCALER = (PWM PRESCALER PRESCALER DIV 1 <<
                                                 PWM_PRESCALER_PRESCALER_Pos);
NRF PWM0->COUNTERTOP = (16000 << PWM COUNTERTOP COUNTERTOP Pos); //1 msec
// Enable the shortcut from LOOPSDONE event to SEQSTART1 task for infinite loop
                     = (PWM_SHORTS_LOOPSDONE_SEQSTART1_Enabled <<
NRF PWM0->SHORTS
                                          PWM SHORTS LOOPSDONE SEQSTART1 Pos);
// LOOP CNT must be greater than 0 for the LOOPSDONE event to trigger and enable looping
NRF PWM0->LOOP
                      = (1 << PWM_LOOP_CNT_Pos);
NRF PWM0->DECODER
                      = (PWM DECODER LOAD Common << PWM DECODER LOAD Pos) |
                      (PWM DECODER MODE RefreshCount << PWM DECODER MODE Pos);
// To repeat a single sequence until stopped, it must be configured in SEQ[1]
NRF PWM0->SEQ[1].PTR = ((uint32 t)(seq0 ram) << PWM SEQ PTR PTR Pos);
NRF_PWM0->SEQ[1].CNT = ((sizeof(seq0_ram) / sizeof(uint16_t)) <<
                                                 PWM SEQ CNT CNT Pos);
NRF PWM0->SEQ[1].REFRESH = 0;
NRF PWM0->SEQ[1].ENDDELAY = 0;
NRF PWM0->TASKS SEQSTART[1] = 1;
```



6.10.3 Limitations

The previous compare value is repeated if the PWM period is shorter than the time it takes for the EasyDMA to retrieve from RAM and update the internal compare registers. This is to ensure a glitch-free operation even for very short PWM periods.

Only SEQ[1] can trigger the LOOPSDONE event upon completion, not SEQ[0]. This requires looping to be enabled (LOOP > 0) and SEQ[1].CNT > 0 when sequence playback starts.

6.10.4 Pin configuration

The OUT[n] (n=0..3) signals associated with each PWM channel are mapped to physical pins according to the configuration of PSEL.OUT[n] registers. If PSEL.OUT[n].CONNECT is set to Disconnected, the associated PWM module signal will not be connected to any physical pins.

The PSEL.OUT[n] registers and their configurations are used as long as the PWM module is enabled and the PWM generation active (wave counter started). They are retained only as long as the device is in System ON mode (see the POWER section for more information about power modes).

To ensure correct behavior in the PWM module, the pins that are used must be configured in the GPIO peripheral in the following way before the PWM module is enabled:

PWM signal	PWM pin	Direction	Output value	Comment
OUT[n]	As specified in PSEL.OUT[n]	Output	0	Idle state defined in GPIO OUT
	(n=03)			register

Table 60: Recommended GPIO configuration before starting PWM generation

The idle state of a pin is defined by the OUT register in the GPIO module, to ensure that the pins used by the PWM module are driven correctly. If PWM generation is stopped by triggering a STOP task, the PWM module itself is temporarily disabled or the device temporarily enters System OFF. This configuration must be retained in the GPIO for the selected pins (I/Os) for as long as the PWM module is supposed to be connected to an external PWM circuit.

Only one peripheral can be assigned to drive a particular GPIO pin at a time. Failing to do so may result in unpredictable behavior.

6.10.5 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x50021000	PWM	PWM0:S	US	SA	Pulse width modulation unit 0	
0x40021000	PWW	PWM0: NS				
0x50022000	PWM	PWM1:S	US	SA	Pulse width modulation unit 1	
0x40022000	PVVIVI	PWM1:NS	US	SA	Puise width modulation unit 1	L
0x50023000	PWM	PWM2:S	US	SA	Pulse width modulation unit 2	
0x40023000	PVVIVI	PWM2:NS				•
0x50024000	PWM	PWM3:S	US	SA	Pulse width modulation unit 3	
0x40024000		PWM3:NS				

Table 61: Instances

Register	Offset	Security	Description	
TASKS_STOP	0x004		Stops PWM pulse generation on all channels at the end of current PWM period, and stops	
			sequence playback	



Register	Offset	Security	Description
TASKS_SEQSTART[n]	0x008		Loads the first PWM value on all enabled channels from sequence n, and starts playing
			that sequence at the rate defined in SEQ[n]REFRESH and/or DECODER.MODE. Causes PWM $$
			generation to start if not running.
TASKS_NEXTSTEP	0x010		Steps by one value in the current sequence on all enabled channels if
			DECODER.MODE=NextStep. Does not cause PWM generation to start if not running.
SUBSCRIBE_STOP	0x084		Subscribe configuration for task STOP
SUBSCRIBE_SEQSTART[n]	0x088		Subscribe configuration for task SEQSTART[n]
SUBSCRIBE_NEXTSTEP	0x090		Subscribe configuration for task NEXTSTEP
EVENTS_STOPPED	0x104		Response to STOP task, emitted when PWM pulses are no longer generated
EVENTS_SEQSTARTED[n]	0x108		First PWM period started on sequence n
EVENTS_SEQEND[n]	0x110		Emitted at end of every sequence n, when last value from RAM has been applied to wave
			counter
EVENTS_PWMPERIODEND	0x118		Emitted at the end of each PWM period
EVENTS_LOOPSDONE	0x11C		Concatenated sequences have been played the amount of times defined in LOOP.CNT
PUBLISH_STOPPED	0x184		Publish configuration for event STOPPED
PUBLISH_SEQSTARTED[n]	0x188		Publish configuration for event SEQSTARTED[n]
PUBLISH_SEQEND[n]	0x190		Publish configuration for event SEQEND[n]
PUBLISH_PWMPERIODEND	0x198		Publish configuration for event PWMPERIODEND
PUBLISH_LOOPSDONE	0x19C		Publish configuration for event LOOPSDONE
SHORTS	0x200		Shortcuts between local events and tasks
INTEN	0x300		Enable or disable interrupt
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
ENABLE	0x500		PWM module enable register
MODE	0x504		Selects operating mode of the wave counter
COUNTERTOP	0x508		Value up to which the pulse generator counter counts
PRESCALER	0x50C		Configuration for PWM_CLK
DECODER	0x510		Configuration of the decoder
LOOP	0x514		Number of playbacks of a loop
SEQ[n].PTR	0x520		Beginning address in RAM of this sequence
SEQ[n].CNT	0x524		Number of values (duty cycles) in this sequence
SEQ[n].REFRESH	0x528		Number of additional PWM periods between samples loaded into compare register
SEQ[n].ENDDELAY	0x52C		Time added after the sequence
PSEL.OUT[n]	0x560		Output pin select for PWM channel n

Table 62: Register overview

6.10.5.1 TASKS_STOP

Address offset: 0x004

Stops PWM pulse generation on all channels at the end of current PWM period, and stops sequence playback

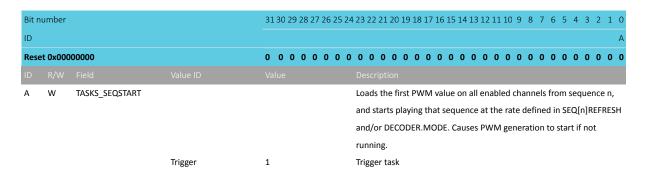
Bit n	umber			31 30 29 28 27 2	26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					A
Rese	t 0x000	00000		0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	W	TASKS_STOP			Stops PWM pulse generation on all channels at the end of current
					PWM period, and stops sequence playback
			Trigger	1	Trigger task



6.10.5.2 TASKS_SEQSTART[n] (n=0..1)

Address offset: $0x008 + (n \times 0x4)$

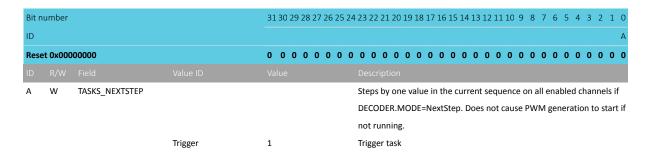
Loads the first PWM value on all enabled channels from sequence n, and starts playing that sequence at the rate defined in SEQ[n]REFRESH and/or DECODER.MODE. Causes PWM generation to start if not running.



6.10.5.3 TASKS_NEXTSTEP

Address offset: 0x010

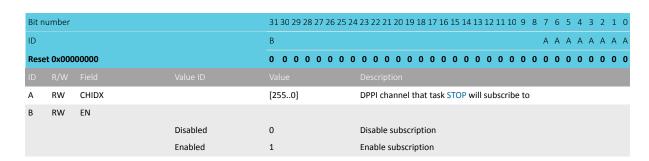
Steps by one value in the current sequence on all enabled channels if DECODER.MODE=NextStep. Does not cause PWM generation to start if not running.



6.10.5.4 SUBSCRIBE_STOP

Address offset: 0x084

Subscribe configuration for task STOP

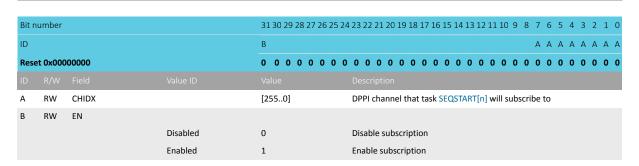


6.10.5.5 SUBSCRIBE_SEQSTART[n] (n=0..1)

Address offset: $0x088 + (n \times 0x4)$

Subscribe configuration for task SEQSTART[n]

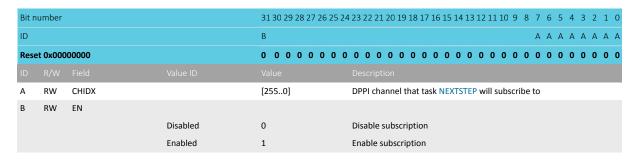




6.10.5.6 SUBSCRIBE NEXTSTEP

Address offset: 0x090

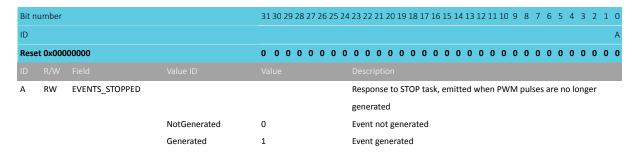
Subscribe configuration for task NEXTSTEP



6.10.5.7 EVENTS STOPPED

Address offset: 0x104

Response to STOP task, emitted when PWM pulses are no longer generated



6.10.5.8 EVENTS_SEQSTARTED[n] (n=0..1)

Address offset: $0x108 + (n \times 0x4)$

First PWM period started on sequence n



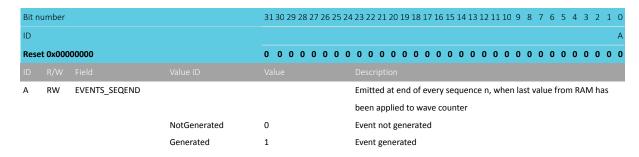




6.10.5.9 EVENTS_SEQEND[n] (n=0..1)

Address offset: $0x110 + (n \times 0x4)$

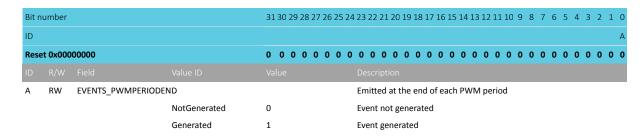
Emitted at end of every sequence n, when last value from RAM has been applied to wave counter



6.10.5.10 EVENTS_PWMPERIODEND

Address offset: 0x118

Emitted at the end of each PWM period

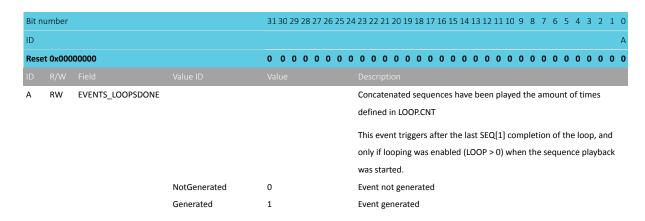


6.10.5.11 EVENTS_LOOPSDONE

Address offset: 0x11C

Concatenated sequences have been played the amount of times defined in LOOP.CNT

This event triggers after the last SEQ[1] completion of the loop, and only if looping was enabled (LOOP > 0) when the sequence playback was started.

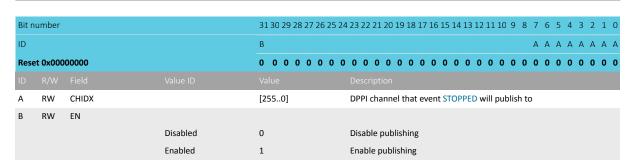


6.10.5.12 PUBLISH STOPPED

Address offset: 0x184

Publish configuration for event STOPPED

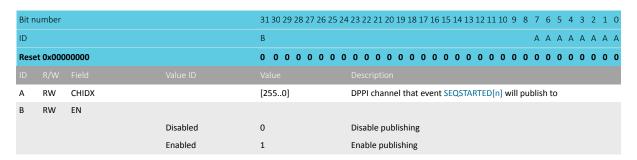




6.10.5.13 PUBLISH_SEQSTARTED[n] (n=0..1)

Address offset: $0x188 + (n \times 0x4)$

Publish configuration for event SEQSTARTED[n]



6.10.5.14 PUBLISH_SEQEND[n] (n=0..1)

Address offset: $0x190 + (n \times 0x4)$

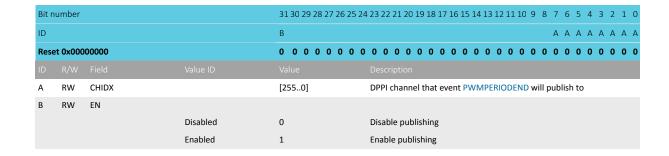
Publish configuration for event SEQEND[n]

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[2550]	DPPI channel that event SEQEND[n] will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	4	Enable publishing

6.10.5.15 PUBLISH_PWMPERIODEND

Address offset: 0x198

Publish configuration for event PWMPERIODEND





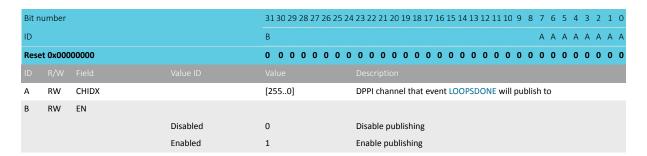


6.10.5.16 PUBLISH_LOOPSDONE

Address offset: 0x19C

Publish configuration for event LOOPSDONE

This event triggers after the last SEQ[1] completion of the loop, and only if looping was enabled (LOOP > 0) when the sequence playback was started.



6.10.5.17 SHORTS

Address offset: 0x200

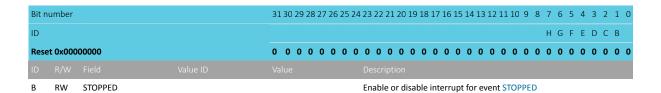
Shortcuts between local events and tasks

Bit n	umber			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					E D C B A
Rese	et 0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	SEQENDO_STOP			Shortcut between event SEQEND[0] and task STOP
			Disabled	0	Disable shortcut
			Enabled	1	Enable shortcut
В	RW	SEQEND1_STOP			Shortcut between event SEQEND[1] and task STOP
			Disabled	0	Disable shortcut
			Enabled	1	Enable shortcut
С	RW	LOOPSDONE_SEQSTAR	то		Shortcut between event LOOPSDONE and task SEQSTART[0]
			Disabled	0	Disable shortcut
			Enabled	1	Enable shortcut
D	RW	LOOPSDONE_SEQSTAR	т:		Shortcut between event LOOPSDONE and task SEQSTART[1]
			Disabled	0	Disable shortcut
			Enabled	1	Enable shortcut
Е	RW	LOOPSDONE_STOP			Shortcut between event LOOPSDONE and task STOP
			Disabled	0	Disable shortcut
			Enabled	1	Enable shortcut

6.10.5.18 INTEN

Address offset: 0x300

Enable or disable interrupt





Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					HGFEDCB
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
			Disabled	0	Disable
			Enabled	1	Enable
C-D	RW	SEQSTARTED[i] (i=01)			Enable or disable interrupt for event SEQSTARTED[i]
			Disabled	0	Disable
			Enabled	1	Enable
E-F	RW	SEQEND[i] (i=01)			Enable or disable interrupt for event SEQEND[i]
			Disabled	0	Disable
			Enabled	1	Enable
G	RW	PWMPERIODEND			Enable or disable interrupt for event PWMPERIODEND
			Disabled	0	Disable
			Enabled	1	Enable
Н	RW	LOOPSDONE			Enable or disable interrupt for event LOOPSDONE
					This event triggers after the last SEQ[1] completion of the loop, and
					only if looping was enabled (LOOP > 0) when the sequence playback
					was started.
			Disabled	0	Disable
			Enabled	1	Enable
			Litabica	±	Lindoic

6.10.5.19 INTENSET

Address offset: 0x304

Enable interrupt

Bit n	umber			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					HGFEDCB
Rese	t 0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
В	RW	STOPPED			Write '1' to enable interrupt for event STOPPED
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
C-D	RW	SEQSTARTED[i] (i=01)			Write '1' to enable interrupt for event SEQSTARTED[i]
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
E-F	RW	SEQEND[i] (i=01)			Write '1' to enable interrupt for event SEQEND[i]
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
G	RW	PWMPERIODEND			Write '1' to enable interrupt for event PWMPERIODEND
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
Н	RW	LOOPSDONE			Write '1' to enable interrupt for event LOOPSDONE
					This event triggers after the last SEQ[1] completion of the loop, and
					only if looping was enabled (LOOP > 0) when the sequence playback
					was started.
			Set	1	Enable
			Disabled	0	Read: Disabled



	Enabled	1	Read: Enabled
ID R/W Field			Description
Reset 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID			HGFEDCB
Bit number		31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

6.10.5.20 INTENCLR

Address offset: 0x308

Disable interrupt

Bit n	umber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					HGFEDCB
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
В	RW	STOPPED			Write '1' to disable interrupt for event STOPPED
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
C-D	RW	SEQSTARTED[i] (i=01)			Write '1' to disable interrupt for event SEQSTARTED[i]
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
E-F	RW	SEQEND[i] (i=01)			Write '1' to disable interrupt for event SEQEND[i]
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
G	RW	PWMPERIODEND			Write '1' to disable interrupt for event PWMPERIODEND
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
Н	RW	LOOPSDONE			Write '1' to disable interrupt for event LOOPSDONE
					This event triggers after the last SEQ[1] completion of the loop, and
					only if looping was enabled (LOOP > 0) when the sequence playback
					was started.
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled

6.10.5.21 ENABLE

Address offset: 0x500

PWM module enable register

Bit n	umber			31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					А
Rese	t 0x000	00000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	ENABLE			Enable or disable PWM module
			Disabled	0	Disabled
			Enabled	1	Enable

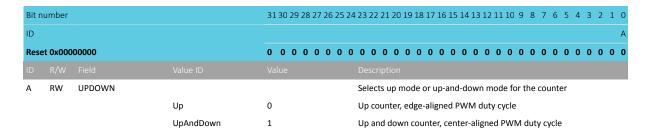




6.10.5.22 MODE

Address offset: 0x504

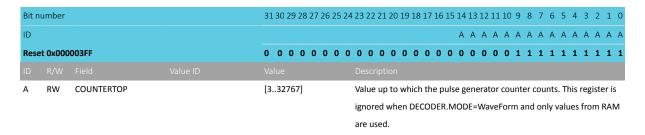
Selects operating mode of the wave counter



6.10.5.23 COUNTERTOP

Address offset: 0x508

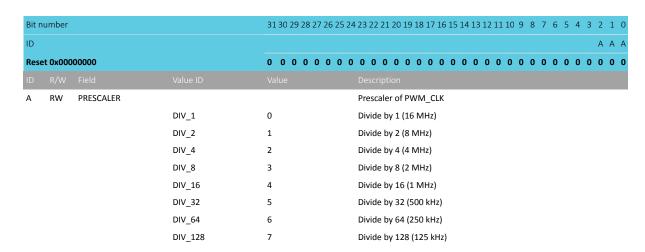
Value up to which the pulse generator counter counts



6.10.5.24 PRESCALER

Address offset: 0x50C

Configuration for PWM_CLK

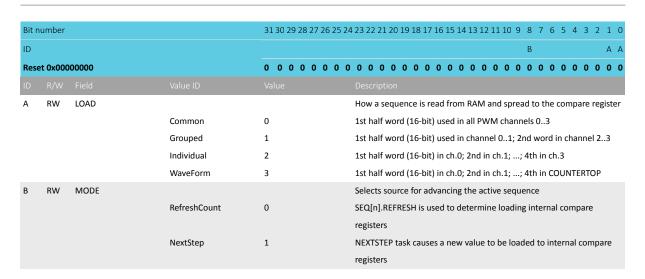


6.10.5.25 DECODER

Address offset: 0x510

Configuration of the decoder

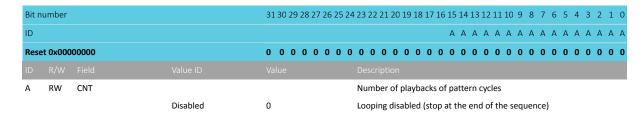




6.10.5.26 LOOP

Address offset: 0x514

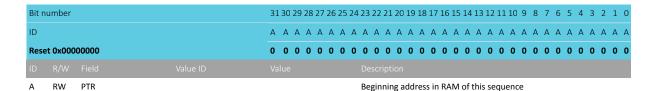
Number of playbacks of a loop



6.10.5.27 SEQ[n].PTR (n=0..1)

Address offset: $0x520 + (n \times 0x20)$

Beginning address in RAM of this sequence



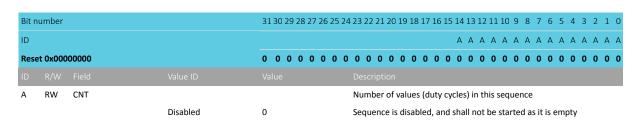
Note: See the memory chapter for details about which memories are available for EasyDMA.

6.10.5.28 SEQ[n].CNT (n=0..1)

Address offset: $0x524 + (n \times 0x20)$

Number of values (duty cycles) in this sequence

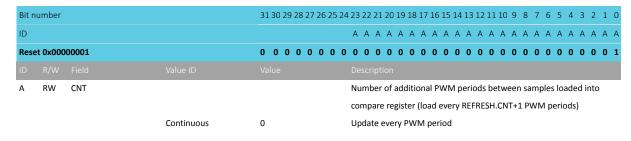




6.10.5.29 SEQ[n].REFRESH (n=0..1)

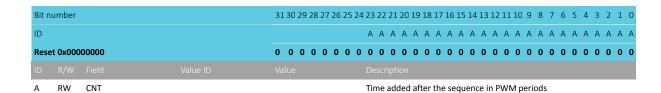
Address offset: $0x528 + (n \times 0x20)$

Number of additional PWM periods between samples loaded into compare register



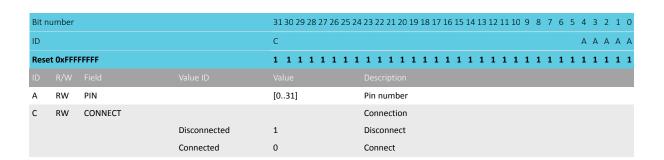
6.10.5.30 SEQ[n].ENDDELAY (n=0..1)

Address offset: $0x52C + (n \times 0x20)$ Time added after the sequence



6.10.5.31 PSEL.OUT[n] (n=0..3)

Address offset: $0x560 + (n \times 0x4)$ Output pin select for PWM channel n



6.11 RTC — Real-time counter

The real-time counter (RTC) module provides a generic, low-power timer on the low frequency clock source (LFCLK).



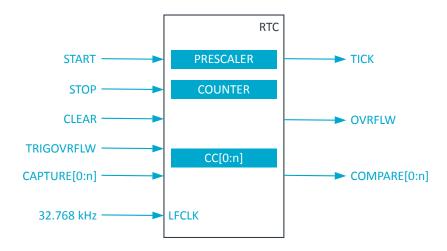


Figure 52: RTC block diagram

The RTC module features a 24-bit COUNTER, a 12-bit (1/X) prescaler, compare registers, and a tick event generator.

6.11.1 Clock source

The RTC will run off the LFCLK.

When started, the RTC will automatically request the LFCLK source with RC oscillator if the LFCLK is not already running.

See CLOCK — Clock control on page 74 for more information about clock sources.

6.11.2 Resolution versus overflow and the prescaler

The relationship between the prescaler, counter resolution, and overflow is summarized in the following table.

Prescaler	Counter resolution	Overflow
0	30.517 μs	512 seconds
2 ⁸ -1	7812.5 μs	131072 seconds
2 ¹² -1	125 ms	582.542 hours

Table 63: RTC resolution versus overflow

The counter increment frequency is given by the following equation:

```
f_{RTC} [kHz] = 32.768 / (PRESCALER + 1 )
```

The PRESCALER register can only be written when the RTC is stopped.

The prescaler is restarted on tasks START, CLEAR and TRIGOVRFLW. That is, the prescaler value is latched to an internal register (<<PRESC>>) on these tasks.

Examples:

1. Desired COUNTER frequency 100 Hz (10 ms counter period)

```
PRESCALER = round(32.768 kHz / 100 Hz) - 1 = 327 f_{RTC} = 99.9 Hz
```

10009.576 µs counter period



2. Desired COUNTER frequency 8 Hz (125 ms counter period)

PRESCALER = round(32.768 kHz / 8 Hz) - 1 = 4095

 $f_{RTC} = 8 Hz$

125 ms counter period

6.11.3 Counter register

The internal <<COUNTER>> register increments on LFCLK when the internal PRESCALER register (<<PRESC>>) is 0x00. <<PRESC>> is reloaded from the PRESCALER register. If enabled, the TICK event occurs on each increment of the COUNTER.

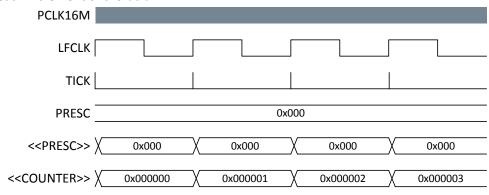


Figure 53: Timing diagram - COUNTER PRESCALER 0

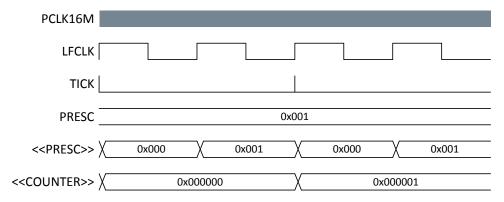


Figure 54: Timing diagram - COUNTER_PRESCALER_1

6.11.3.1 Reading the counter register

To read the COUNTER register, the internal <<COUNTER>> value is sampled.

To ensure that the <<COUNTER>> is safely sampled (considering that an LFCLK transition may occur during a read), the CPU and core memory bus are halted for PCLK16M cycles. In addition, the read takes the CPU two PCLK16M cycles, resulting in the COUNTER register read taking maximum six PCLK16M clock cycles.

6.11.4 Overflow

An OVRFLW event is generated on COUNTER register overflow (overflowing from 0xFFFFFF to 0).

The TRIGOVRFLW task will set the COUNTER value to 0xFFFFF0, to allow software test of the overflow condition.

Note: The OVRFLW event is disabled by default.



6.11.5 Tick event

The TICK event enables low-power tickless RTOS implementation, as it optionally provides a regular interrupt source for an RTOS with no need for use of the ARM SysTick feature.

Using the TICK event, rather than the SysTick, allows the CPU to be powered down while keeping RTOS scheduling active.

Note: The TICK event is disabled by default.

6.11.6 Event control

To optimize the RTC power consumption, events in the RTC can be individually disabled to prevent PCLK16M and HFCLK from being requested when those events are triggered. This is managed using the EVTEN register.

This means that the RTC implements a slightly different task and event system compared to the standard system described in Peripheral interface on page 17. The RTC task and event system is illustrated in the following figure.

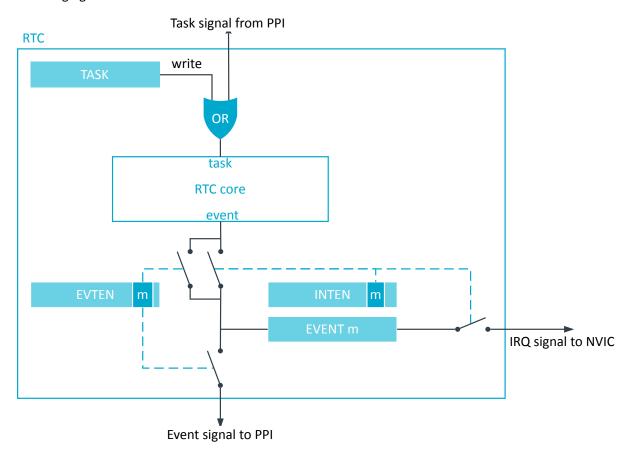


Figure 55: Tasks, events, and interrupts in the RTC

6.11.7 Compare

The RTC implements one COMPARE event for every available compare register.

When the COUNTER is incremented and then becomes equal to the value specified in the register CC[n], the corresponding compare event COMPARE[n] is generated.

When writing a CC[n] register, the RTC COMPARE event exhibits several behaviors. See the following figures for more information.

If a CC value is 0 when a CLEAR task is set, this will not trigger a COMPARE event.



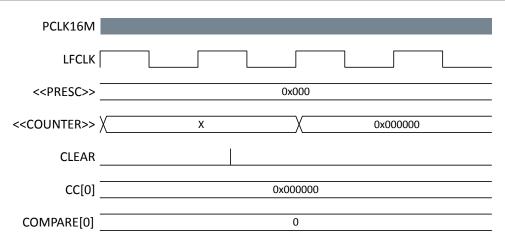


Figure 56: Timing diagram - COMPARE_CLEAR

If a CC value is N and the COUNTER value is N when the START task is set, this will not trigger a COMPARE event.

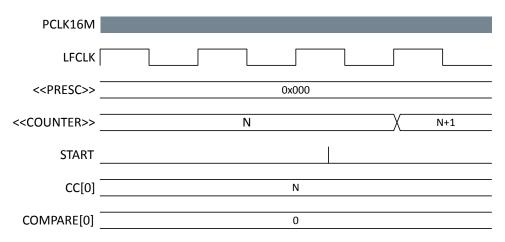


Figure 57: Timing diagram - COMPARE_START

A COMPARE event occurs when a CC value is N, and the COUNTER value transitions from N-1 to N.

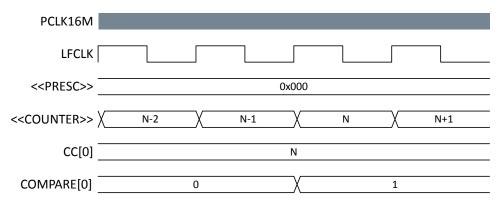


Figure 58: Timing diagram - COMPARE

If the COUNTER value is N, writing N+2 to a CC register is guaranteed to trigger a COMPARE event at N+2.

NORDIC

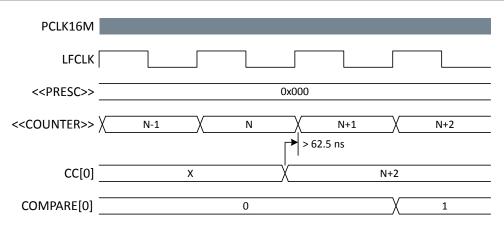


Figure 59: Timing diagram - COMPARE_N+2

If the COUNTER value is N, writing N or N+1 to a CC register may not trigger a COMPARE event.

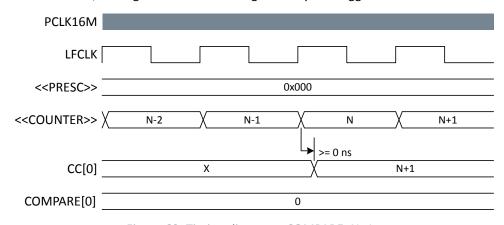


Figure 60: Timing diagram - COMPARE_N+1

If the COUNTER value is N, and the current CC value is N+1 or N+2 when a new CC value is written, a match may trigger on the previous CC value before the new value takes effect. If the current CC value is greater than N+2 when the new value is written, there will be no event due to the old value.

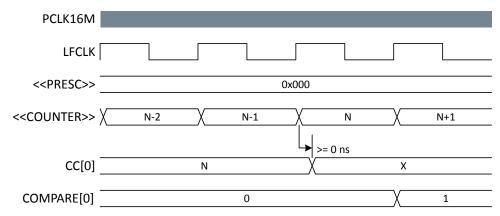


Figure 61: Timing diagram - COMPARE_N-1

6.11.8 Task and event jitter/delay

Jitter or delay in the RTC, is due to the peripheral clock being a low frequency clock (LFCLK), which is not synchronous to the faster PCLK16M.

Registers in the peripheral interface that are part of the PCLK16M domain, have a set of mirrored registers in the LFCLK domain. For example, the COUNTER value accessible from the CPU is in the PCLK16M domain, and is latched on a read from an internal COUNTER register in the LFCLK domain. The COUNTER register

is modified each time the RTC ticks. The registers are synchronised between the two clock domains (PCLK16M and LFCLK).

CLEAR and STOP (and TRIGOVRFLW, which is not shown) will be delayed as long as it takes for the peripheral to clock a falling edge and a rising edge of the LFCLK. This is between 15.2585 μ s and 45.7755 μ s – rounded to 15 μ s and 46 μ s for the remainder of the section.

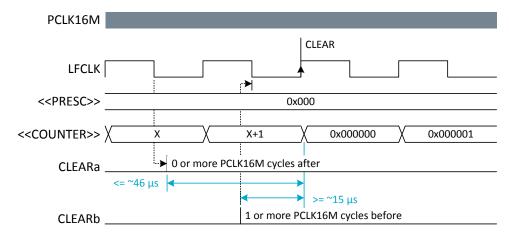


Figure 62: Timing diagram - DELAY CLEAR

When a STOP task is triggered, the PCLK16M domain will immediately prevent the generation of any EVENTS from the RTC. However, as seen in the following figure, the COUNTER value can still increment one final time.

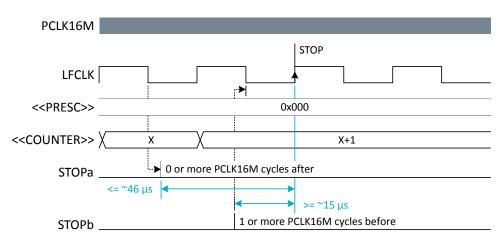


Figure 63: Timing diagram - DELAY_STOP

The START task will start the RTC. Assuming that the LFCLK was previously running and stable, the first increment of COUNTER (and instance of TICK event) will be typically after 30.5 μ s +/-15 μ s. Additional delay will occur if the RTC is started before the LFCLK is running, see CLOCK — Clock control on page 74 for LFLK startup times. The software should therefore wait for the first TICK if it has to make sure that the RTC is running. Sending a TRIGOVRFLW task sets the COUNTER to a value close to overflow. However, since the update of COUNTER relies on a stable LFCLK, sending this task while LFCLK is not running will also add additional delay as previously described. The figures show the smallest and largest delays on the START task, appearing as a +/-15 μ s jitter on the first COUNTER increment.



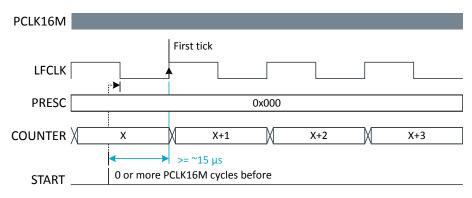


Figure 64: Timing diagram - JITTER_START-

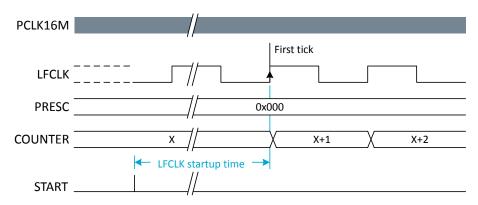


Figure 65: Timing diagram - JITTER_START+

The following tables summarize jitter introduced for tasks and events. Any 32.768 kHz clock jitter will come in addition to these numbers.

Task	Delay
CLEAR, START, STOP, TRIGOVRFLOW	+15 to 46 μs

Table 64: RTC jitter magnitudes on tasks

Operation/Function	Jitter
START to COUNTER increment	± 15 μs
COMPARE to COMPARE ¹³	± 62.5 ns

Table 65: RTC jitter magnitudes on events

6.11.9 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x50014000	RTC	RTC0 : S	US	NA	Real time counter 0	
0x40014000	RIC	RTC0 : NS	03	NA	Real time counter o	
0x50015000	RTC	RTC1:S	US	NA	Real time counter 1	
0x40015000	RIC	RTC1 : NS	03	NA	near time couliter 1	

Table 66: Instances



¹³ Assumes RTC runs continuously between these events.

Register	Offset	Security	Description
TASKS_START	0x000		Start RTC counter
TASKS_STOP	0x004		Stop RTC counter
TASKS_CLEAR	0x008		Clear RTC counter
TASKS_TRIGOVRFLW	0x00C		Set counter to 0xFFFFF0
SUBSCRIBE_START	0x080		Subscribe configuration for task START
SUBSCRIBE_STOP	0x084		Subscribe configuration for task STOP
SUBSCRIBE_CLEAR	0x088		Subscribe configuration for task CLEAR
SUBSCRIBE_TRIGOVRFLW	0x08C		Subscribe configuration for task TRIGOVRFLW
EVENTS_TICK	0x100		Event on counter increment
EVENTS_OVRFLW	0x104		Event on counter overflow
EVENTS_COMPARE[n]	0x140		Compare event on CC[n] match
PUBLISH_TICK	0x180		Publish configuration for event TICK
PUBLISH_OVRFLW	0x184		Publish configuration for event OVRFLW
PUBLISH_COMPARE[n]	0x1C0		Publish configuration for event COMPARE[n]
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
EVTEN	0x340		Enable or disable event routing
EVTENSET	0x344		Enable event routing
EVTENCLR	0x348		Disable event routing
COUNTER	0x504		Current counter value
PRESCALER	0x508		12-bit prescaler for counter frequency (32768/(PRESCALER+1)). Must be written when RTC is
			stopped.
CC[n]	0x540		Compare register n

Table 67: Register overview

6.11.9.1 TASKS_START

Address offset: 0x000

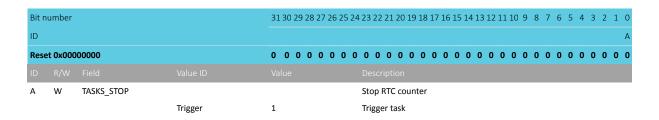
Start RTC counter

			Trigger	1	Trigger task
Α	W	TASKS_START			Start RTC counter
ID					
Res	et 0x000	00000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					A
Bit r	number			31 30 29 28 27 2	6 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

6.11.9.2 TASKS_STOP

Address offset: 0x004

Stop RTC counter



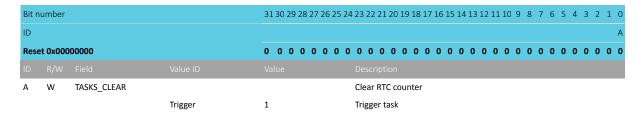




6.11.9.3 TASKS_CLEAR

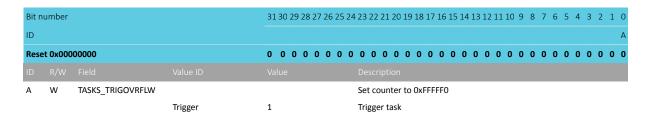
Address offset: 0x008

Clear RTC counter



6.11.9.4 TASKS TRIGOVRFLW

Address offset: 0x00C Set counter to 0xFFFFF0



6.11.9.5 SUBSCRIBE_START

Address offset: 0x080

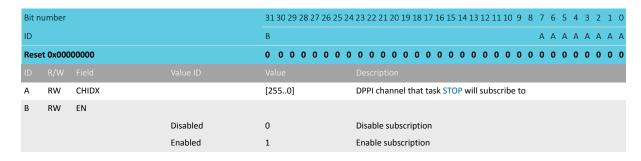
Subscribe configuration for task START

Bit n	umber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		
ID					Description
Α	RW	CHIDX		[2550]	DPPI channel that task START will subscribe to
В	RW	EN			
			Disabled	0	Disable subscription

6.11.9.6 SUBSCRIBE_STOP

Address offset: 0x084

Subscribe configuration for task STOP

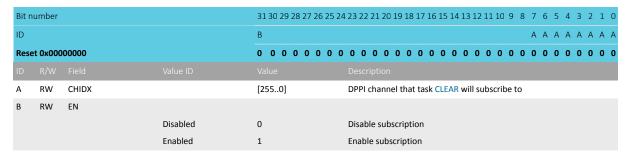




6.11.9.7 SUBSCRIBE_CLEAR

Address offset: 0x088

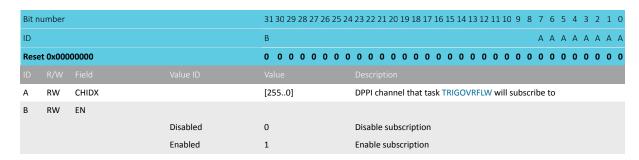
Subscribe configuration for task CLEAR



6.11.9.8 SUBSCRIBE_TRIGOVRFLW

Address offset: 0x08C

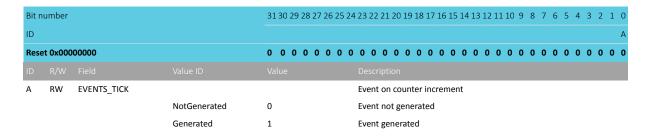
Subscribe configuration for task TRIGOVRFLW



6.11.9.9 EVENTS TICK

Address offset: 0x100

Event on counter increment



6.11.9.10 EVENTS OVRFLW

Address offset: 0x104

Event on counter overflow



Dit would be		24 20 20 20 27 20 25 2	122 22 21 20 10 10 17 16 17 14 12 12 11 10 0 0 7 6 7 4 2 2 1 0
Bit number		31 30 29 28 27 26 25 24	⁴ 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			A
Reset 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID R/W Field			
A RW EVENTS_OVRFLW			Event on counter overflow
	NotGenerated	0	Event not generated
	Generated	1	Event generated

6.11.9.11 EVENTS_COMPARE[n] (n=0..3)

Address offset: $0x140 + (n \times 0x4)$ Compare event on CC[n] match

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0	
ID					A	
Rese	Reset 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		
ID						
Α	RW	EVENTS_COMPARE			Compare event on CC[n] match	
			NotGenerated	0	Event not generated	
			Generated	1	Event generated	

6.11.9.12 PUBLISH_TICK

Address offset: 0x180

Publish configuration for event TICK

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A A
Rese	et 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[2550]	DPPI channel that event TICK will publish to
В	RW	EN			
			Disabled	0	Disable publishing

6.11.9.13 PUBLISH_OVRFLW

Address offset: 0x184

Publish configuration for event OVRFLW

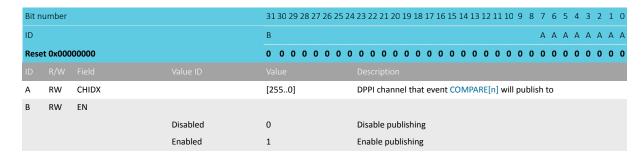
Bit n	umber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2	1 0
ID				В	A A A A A	АА
Rese	Reset 0x00000000			0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0
ID						
Α	RW	CHIDX		[2550]	DPPI channel that event OVRFLW will publish to	
В	RW	EN				
			Disabled	0	Disable publishing	
			Enabled	1	Enable publishing	

6.11.9.14 PUBLISH_COMPARE[n] (n=0..3)

Address offset: $0x1C0 + (n \times 0x4)$



Publish configuration for event COMPARE[n]



6.11.9.15 INTENSET

Address offset: 0x304

Enable interrupt

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					F E D C B A
Rese	et 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	TICK			Write '1' to enable interrupt for event TICK
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
В	RW	OVRFLW			Write '1' to enable interrupt for event OVRFLW
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
C-F	RW	COMPARE[i] (i=03)			Write '1' to enable interrupt for event COMPARE[i]
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled

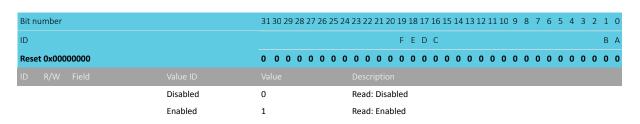
6.11.9.16 INTENCLR

Address offset: 0x308

Disable interrupt

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					F E D C B A
Rese	Reset 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	
ID					
Α	RW	TICK			Write '1' to disable interrupt for event TICK
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
В	RW	OVRFLW			Write '1' to disable interrupt for event OVRFLW
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
C-F	RW	COMPARE[i] (i=03)			Write '1' to disable interrupt for event COMPARE[i]
			Clear	1	Disable





6.11.9.17 EVTEN

Address offset: 0x340

Enable or disable event routing

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					F E D C B A
Reset 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		
ID					Description
Α	RW	TICK			Enable or disable event routing for event TICK
			Disabled	0	Disable
			Enabled	1	Enable
В	RW	OVRFLW			Enable or disable event routing for event OVRFLW
			Disabled	0	Disable
			Enabled	1	Enable
C-F	RW	COMPARE[i] (i=03)			Enable or disable event routing for event COMPARE[i]
			Disabled	0	Disable
			Enabled	1	Enable

6.11.9.18 EVTENSET

Address offset: 0x344 Enable event routing

Bit n	umber			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					F E D C B A
Rese	t 0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	TICK			Write '1' to enable event routing for event TICK
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
			Set	1	Enable
В	RW	OVRFLW			Write '1' to enable event routing for event OVRFLW
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
			Set	1	Enable
C-F	RW	COMPARE[i] (i=03)			Write '1' to enable event routing for event COMPARE[i]
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
			Set	1	Enable

6.11.9.19 EVTENCLR

Address offset: 0x348

Disable event routing

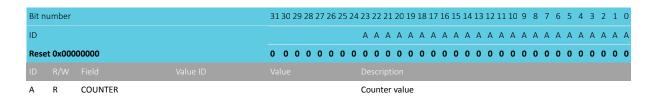




Bit n	umber			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					F E D C B A
Rese	et 0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	TICK			Write '1' to disable event routing for event TICK
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
			Clear	1	Disable
В	RW	OVRFLW			Write '1' to disable event routing for event OVRFLW
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
			Clear	1	Disable
C-F	RW	COMPARE[i] (i=03)			Write '1' to disable event routing for event COMPARE[i]
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
			Clear	1	Disable

6.11.9.20 COUNTER

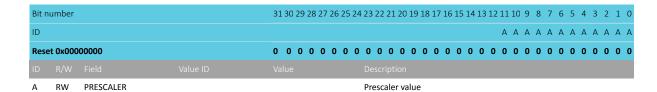
Address offset: 0x504 Current counter value



6.11.9.21 PRESCALER

Address offset: 0x508

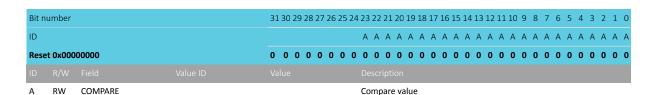
12-bit prescaler for counter frequency (32768/(PRESCALER+1)). Must be written when RTC is stopped.



6.11.9.22 CC[n] (n=0..3)

Address offset: $0x540 + (n \times 0x4)$

Compare register n





6.11.10 Electrical specification

6.12 SAADC — Successive approximation analog-to-digital converter

The SAADC is a differential successive approximation register (SAR) analog-to-digital converter.

Listed here are the main features of SAADC:

- 8/10/12-bit resolution, 14-bit resolution with oversampling
- Multiple analog inputs:
 - AINO to AIN7 pins
 - VDD GPIO pin
- Up to eight input channels:
 - One channel per single-ended input and two channels per differential input
 - · Scan mode can be configured with both single-ended channels and differential channels
 - Each channel can be configured to select any of the above analog inputs
- Full scale input range (0 to VDD_GPIO)
- Sampling triggered via a task from software or a PPI channel for full flexibility on sample frequency source from low-power 32.768 kHz RTC or more accurate 1/16 MHz timers
- One-shot conversion mode to sample a single channel
- Scan mode to sample a series of channels in sequence with configurable sample delay
- Support for direct sample transfer to RAM using EasyDMA
- Interrupts on single sample and full buffer events
- Samples stored as 16-bit two's complement values for differential and single-ended sampling
- · Continuous sampling without the need of an external timer
- · Internal resistor string
- · On-the-fly limit checking

6.12.1 Overview

The ADC supports up to eight external analog input channels. It can be operated in One-shot mode with sampling under software control, or Continuous mode with a programmable sampling rate.

The analog inputs can be configured as eight single-ended inputs, four differential inputs or a combination of these. Each channel can be configured to select:

- AINO to AIN7 pins
- VDD_GPIO pin

Channels can be sampled individually in one-shot or continuous sampling modes, or, using scan mode, multiple channels can be sampled in sequence. Channels can also be oversampled to improve noise performance.



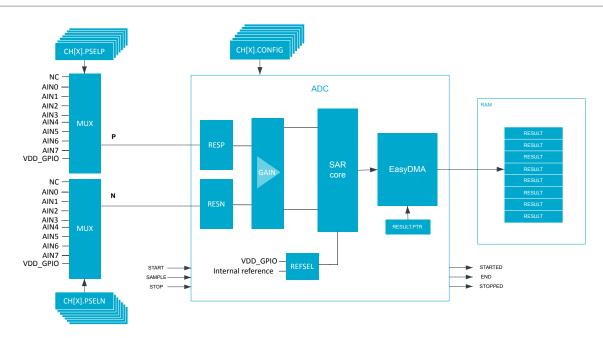


Figure 66: Simplified ADC block diagram

Internally, the ADC is always a differential analog-to-digital converter, but by default it is configured with single-ended input in the MODE field of the CH[n].CONFIG register. In single-ended mode, the negative input will be shorted to ground internally.

The assumption in single-ended mode is that the internal ground of the ADC is the same as the external ground that the measured voltage is referred to. The ADC is thus sensitive to ground bounce on the PCB in single-ended mode. If this is a concern we recommend using differential measurement.

6.12.2 Digital output

The output result of the ADC depends on the settings in the CH[n].CONFIG and RESOLUTION registers as follows:

```
RESULT = [V(P) - V(N)] * GAIN/REFERENCE * 2 (RESOLUTION - m)
```

where

V(P)

is the voltage at input P

V(N)

is the voltage at input N

GAIN

is the selected gain setting

m

is the mode setting. Use m=0 if CONFIG.MODE=SE, or m=1 if CONFIG.MODE=Diff

REFERENCE

is the selected reference voltage

The result generated by the ADC will deviate from the expected due DC errors like offset, gain, differential non-linearity (DNL), and integral non-linearity (INL). See Electrical specification for details on these parameters. The result can also vary due to AC errors like non-linearities in the GAIN block, settling errors



due to high source impedance and sampling jitter. For battery measurement, the DC errors are most noticeable.

The ADC has a wide selection of gains controlled in the GAIN field of the CH[n].CONFIG register. If CH[n].CONFIG.REFSEL=0, the input range of the ADC core is nominally ± 0.6 V differential and the input must be scaled accordingly.

The ADC has a temperature dependent offset. If the ADC is to operate over a large temperature range, we recommend running CALIBRATEOFFSET at regular intervals. The CALIBRATEDONE event will be fired when the calibration has been completed. Note that the DONE and RESULTDONE events will also be generated.

6.12.3 Analog inputs and channels

Up to eight analog input channels, CH[n](n=0..7), can be configured.

Any one of the available channels can be enabled for the ADC to operate in one-shot mode. If more than one CH[n] is configured, the ADC enters scan mode.

An analog input is selected as a positive converter input if CH[n].PSELP is set, setting CH[n].PSELP also enables the particular channel.

An analog input is selected as a negative converter input if CH[n].PSELN is set. The CH[n].PSELN register will have no effect unless differential mode is enabled, see MODE field in CH[n].CONFIG register.

If more than one of the CH[n].PSELP registers is set, the device enters scan mode. Input selections in scan mode are controlled by the CH[n].PSELP and CH[n].PSELN registers, where CH[n].PSELN is only used if the particular scan channel is specified as differential, see MODE field in CH[n].CONFIG register.

6.12.4 Operation modes

The ADC input configuration supports one-shot mode, continuous mode and scan mode.

Note: Scan mode and oversampling cannot be combined.

The ADC indicates a single ongoing conversion via the register STATUS on page 224. During scan mode, oversampling, or continuous modes, more than a single conversion take place in the ADC. As consequence, the value reflected in STATUS register will toggle at the end of each single conversion.

6.12.4.1 One-shot mode

One-shot operation is configured by enabling only one of the available channels defined by CH[n].PSELP, CH[n].PSELN, and CH[n].CONFIG registers.

Upon a SAMPLE task, the ADC starts to sample the input voltage. The CH[n].CONFIG.TACQ controls the acquisition time.

A DONE event signals that one sample has been taken.

In this mode, the RESULTDONE event has the same meaning as DONE when no oversampling takes place. Note that both events may occur before the actual value has been transferred into RAM by EasyDMA. For more information, see EasyDMA on page 207.

6.12.4.2 Continuous mode

Continuous sampling can be achieved by using the internal timer in the ADC, or triggering the SAMPLE task from one of the general purpose timers through the PPI system.

Care shall be taken to ensure that the sample rate fulfils the following criteria, depending on how many channels are active:

 $f_{SAMPLE} < 1/(t_{ACQ} + t_{conv})$



The SAMPLERATE register can be used as a local timer instead of triggering individual SAMPLE tasks. When SAMPLERATE.MODE is set to Timers, it is sufficient to trigger SAMPLE task only once in order to start the SAADC and triggering the STOP task will stop sampling. The SAMPLERATE.CC field controls the sample rate.

The SAMPLERATE timer mode cannot be combined with SCAN mode, and only one channel can be enabled in this mode.

A DONE event signals that one sample has been taken.

In this mode, the RESULTDONE event has the same meaning as DONE when no oversampling takes place. Note that both events may occur before the actual value has been transferred into RAM by EasyDMA.

6.12.4.3 Oversampling

An accumulator in the ADC can be used to average noise on the analog input. In general, oversampling improves the signal-to-noise ratio (SNR). Oversampling, however, does not improve the integral non-linearity (INL), or differential non-linearity (DNL).

Oversampling and scan should not be combined, since oversampling and scan will average over input channels.

The accumulator is controlled in the OVERSAMPLE register. The SAMPLE task must be set 2^{OVERSAMPLE} number of times before the result is written to RAM. This can be achieved by:

- Configuring a fixed sampling rate using the local timer or a general purpose timer and the PPI system to trigger a SAMPLE task
- Triggering SAMPLE 2^{OVERSAMPLE} times from software
- Enabling BURST mode

CH[n].CONFIG.BURST can be enabled to avoid setting SAMPLE task $2^{\text{OVERSAMPLE}}$ times. With BURST = 1 the ADC will sample the input $2^{\text{OVERSAMPLE}}$ times as fast as it can (actual timing: $<(t_{ACQ}+t_{CONV})\times 2^{\text{OVERSAMPLE}}$). Thus, for the user it will just appear like the conversion took a bit longer time, but other than that, it is similar to one-shot mode.

A DONE event signals that one sample has been taken.

In this mode, the RESULTDONE event signals that enough conversions have taken place for an oversampled result to get transferred into RAM. Note that both events may occur before the actual value has been transferred into RAM by EasyDMA.

6.12.4.4 Scan mode

A channel is considered enabled if CH[n].PSELP is set. If more than one channel, CH[n], is enabled, the ADC enters scan mode.

In scan mode, one SAMPLE task will trigger one conversion per enabled channel. The time it takes to sample all channels is:

```
Total time < Sum(CH[x].t_{ACQ}+t_{CONV}), x=0..enabled channels
```

A DONE event signals that one sample has been taken.

In this mode, the RESULTDONE event signals has the same meaning as DONE when no oversampling takes place. Note that both events may occur before the actual values have been transferred into RAM by EasyDMA.

The figure below provides an example of results placement in Data RAM, with an even RESULT.MAXCNT. In this example, channels 1, 2 and 5 are enabled, all others are disabled.



	31 16	15 0
RESULT.PTR	CH[2] 1 st result	CH[1] 1 st result
RESULT.PTR + 4	CH[1] 2 nd result	CH[5] 1 st result
RESULT.PTR + 8	CH[5] 2 nd result	CH[2] 2 nd result
	(.)
RESULT.PTR + 2*(RESULT.MAXCNT – 2)	CH[5] last result	CH[2] last result

Figure 67: Example of RAM placement (even RESULT.MAXCNT), channels 1, 2 and 5 enabled

The figure below provides an example of results placement in Data RAM, with an odd RESULT.MAXCNT. In this example, channels 1, 2 and 5 are enabled, all others are disabled. The last 32-bit word is populated only with one 16-bit result.

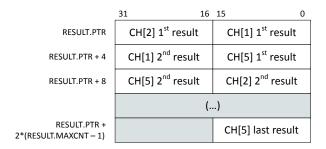


Figure 68: Example of RAM placement (odd RESULT.MAXCNT), channels 1, 2 and 5 enabled

6.12.5 EasyDMA

After configuring RESULT.PTR and RESULT.MAXCNT, the ADC resources are started by triggering the START task. The ADC is using EasyDMA to store results in a Result buffer in RAM.

The Result buffer is located at the address specified in the RESULT.PTR register. The RESULT.PTR register is double-buffered and it can be updated and prepared for the next START task immediately after the STARTED event is generated. The size of the Result buffer is specified in the RESULT.MAXCNT register and the ADC will generate an END event when it has filled up the Result buffer, see ADC on page 208. Results are stored in little-endian byte order in Data RAM. Every sample will be sign extended to 16 bit before stored in the Result buffer.

The ADC is stopped by triggering the STOP task. The STOP task will terminate an ongoing sampling. The ADC will generate a STOPPED event when it has stopped. If the ADC is already stopped when the STOP task is triggered, the STOPPED event will still be generated.



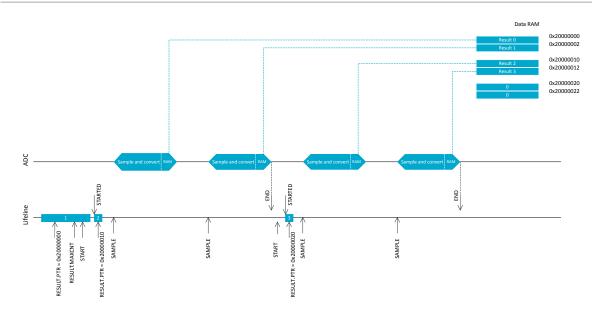


Figure 69: ADC

If the RESULT.PTR is not pointing to a RAM region accessible from the peripheral, an EasyDMA transfer may result in a HardFault and/or memory corruption. See Memory on page 23 for more information about the different memory regions.

The EasyDMA will have finished accessing the RAM when the END or STOPPED event has been generated.

The RESULT.AMOUNT register can be read following an END event or a STOPPED event to see how many results have been transferred to the Result buffer in RAM since the START task was triggered.

In scan mode, SAMPLE tasks can be triggered once the START task is triggered. The END event is generated when the number of samples transferred to memory reaches the value specified by RESULT.MAXCNT.

After an END event, the START task needs to be triggered again before new samples can be taken. Also make sure that the size of the Result buffer is large enough to have space for minimum one result from each of the enabled channels, by specifying RESULT.MAXCNT >= number of channels enabled. For more information about the scan mode, see Scan mode on page 206.

6.12.6 Resistor ladder

The ADC has an internal resistor string for positive and negative input.

See Resistor ladder for positive input (negative input is equivalent, using RESN instead of RESP) on page 209. The resistors are controlled in the CH[n].CONFIG.RESP and CH[n].CONFIG.RESN registers.



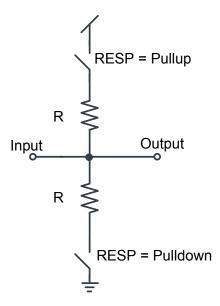


Figure 70: Resistor ladder for positive input (negative input is equivalent, using RESN instead of RESP)

6.12.7 Reference

The ADC can use two different references, controlled in the REFSEL field of the CH[n].CONFIG register.

These are:

- Internal reference
- VDD_GPIO as reference

The internal reference results in an input range of ± 0.6 V on the ADC core. VDD_GPIO as reference results in an input range of $\pm VDD_GPIO/4$ on the ADC core. The gain block can be used to change the effective input range of the ADC.

```
Input range = (+- 0.6 V or +-VDD_GPIO/4)/Gain
```

For example, choosing VDD_GPIO as reference, single ended input (grounded negative input), and a gain of 1/4 the input range will be:

```
Input range = (VDD_GPIO/4)/(1/4) = VDD_GPIO
```

With internal reference, single ended input (grounded negative input), and a gain of 1/6 the input range will be:

```
Input range = (0.6 \text{ V})/(1/6) = 3.6 \text{ V}
```

The AINO-AIN7 inputs cannot exceed VDD_GPIO, or be lower than VSS.

6.12.8 Acquisition time

To sample the input voltage, the ADC connects a capacitor to the input.

For illustration, see Simplified ADC sample network on page 210. The acquisition time indicates how long the capacitor is connected, see TACQ field in CH[n].CONFIG register. The required acquisition time depends on the source (R_{source}) resistance. For high source resistance the acquisition time should be increased, see Acquisition time on page 210.



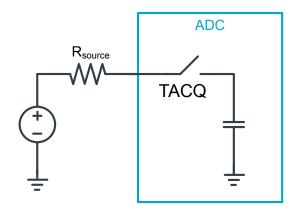


Figure 71: Simplified ADC sample network

TACQ [µs]	Maximum source resistance [kOhm]
3	10
5	40
10	100
15	200
20	400
40	800

Table 68: Acquisition time

6.12.9 Limits event monitoring

A channel can be event monitored by configuring limit register CH[n].LIMIT.

If the conversion result is higher than the defined high limit, or lower than the defined low limit, the appropriate event will get fired.

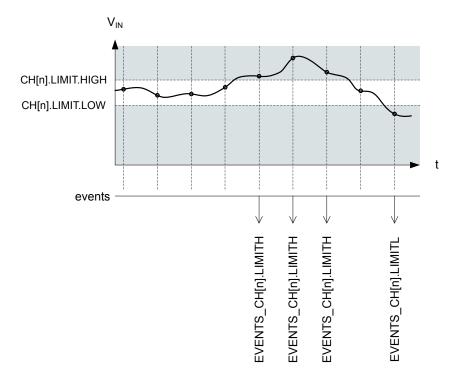


Figure 72: Example of limits monitoring on channel 'n'



Note that when setting the limits, CH[n].LIMIT.HIGH shall always be higher than or equal to CH[n].LIMIT.LOW . In other words, an event can be fired only when the input signal has been sampled outside of the defined limits. It is not possible to fire an event when the input signal is inside a defined range by swapping high and low limits.

The comparison to limits always takes place, there is no need to enable it. If comparison is not required on a channel, the software shall simply ignore the related events. In that situation, the value of the limits registers is irrelevant, so it does not matter if CH[n].LIMIT.LOW is lower than CH[n].LIMIT.HIGH or not.

6.12.10 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x5000E000	CAADC	SAADC : S	US	CA.	Analog to digital converter	
0x4000E000	SAADC	SAADC : NS	03	SA		

Table 69: Instances

Register	Offset	Security	Description
TASKS_START	0x000		Start the ADC and prepare the result buffer in RAM
TASKS_SAMPLE	0x004		Take one ADC sample, if scan is enabled all channels are sampled
TASKS_STOP	0x008		Stop the ADC and terminate any on-going conversion
TASKS_CALIBRATEOFFSET	0x00C		Starts offset auto-calibration
SUBSCRIBE_START	0x080		Subscribe configuration for task START
SUBSCRIBE_SAMPLE	0x084		Subscribe configuration for task SAMPLE
SUBSCRIBE_STOP	0x088		Subscribe configuration for task STOP
SUBSCRIBE_CALIBRATEOFFSET	0x08C		Subscribe configuration for task CALIBRATEOFFSET
EVENTS_STARTED	0x100		The ADC has started
EVENTS_END	0x104		The ADC has filled up the Result buffer
EVENTS_DONE	0x108		A conversion task has been completed. Depending on the mode, multiple conversions might
			be needed for a result to be transferred to RAM.
EVENTS_RESULTDONE	0x10C		A result is ready to get transferred to RAM.
EVENTS_CALIBRATEDONE	0x110		Calibration is complete
EVENTS_STOPPED	0x114		The ADC has stopped
EVENTS_CH[n].LIMITH	0x118		Last results is equal or above CH[n].LIMIT.HIGH
EVENTS_CH[n].LIMITL	0x11C		Last results is equal or below CH[n].LIMIT.LOW
PUBLISH_STARTED	0x180		Publish configuration for event STARTED
PUBLISH_END	0x184		Publish configuration for event END
PUBLISH_DONE	0x188		Publish configuration for event DONE
PUBLISH_RESULTDONE	0x18C		Publish configuration for event RESULTDONE
PUBLISH_CALIBRATEDONE	0x190		Publish configuration for event CALIBRATEDONE
PUBLISH_STOPPED	0x194		Publish configuration for event STOPPED
PUBLISH_CH[n].LIMITH	0x198		Publish configuration for event CH[n].LIMITH
PUBLISH_CH[n].LIMITL	0x19C		Publish configuration for event CH[n].LIMITL
INTEN	0x300		Enable or disable interrupt
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
STATUS	0x400		Status
ENABLE	0x500		Enable or disable ADC
CH[n].PSELP	0x510		Input positive pin selection for CH[n]
CH[n].PSELN	0x514		Input negative pin selection for CH[n]
CH[n].CONFIG	0x518		Input configuration for CH[n]
CH[n].LIMIT	0x51C		High/low limits for event monitoring a channel
RESOLUTION	0x5F0		Resolution configuration

Register	Offset	Security	Description
OVERSAMPLE	0x5F4		Oversampling configuration. OVERSAMPLE should not be combined with SCAN. The
			RESOLUTION is applied before averaging, thus for high OVERSAMPLE a higher RESOLUTION
			should be used.
SAMPLERATE	0x5F8		Controls normal or continuous sample rate
RESULT.PTR	0x62C		Data pointer
RESULT.MAXCNT	0x630		Maximum number of buffer words to transfer
RESULT.AMOUNT	0x634		Number of buffer words transferred since last START

Table 70: Register overview

6.12.10.1 TASKS_START

Address offset: 0x000

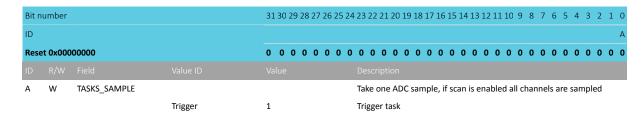
Start the ADC and prepare the result buffer in RAM

Bit n	umber			31 30 29 28 27 26 2	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					А
Rese	et 0x000	00000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	W	TASKS_START			Start the ADC and prepare the result buffer in RAM
			Trigger	1	Trigger task

6.12.10.2 TASKS_SAMPLE

Address offset: 0x004

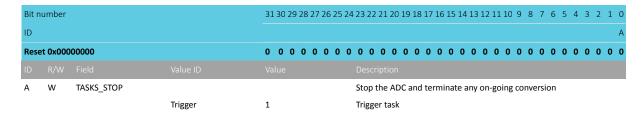
Take one ADC sample, if scan is enabled all channels are sampled



6.12.10.3 TASKS_STOP

Address offset: 0x008

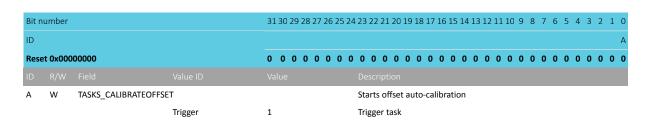
Stop the ADC and terminate any on-going conversion



6.12.10.4 TASKS CALIBRATEOFFSET

Address offset: 0x00C

Starts offset auto-calibration



6.12.10.5 SUBSCRIBE_START

Address offset: 0x080

Subscribe configuration for task START

Bit n	umber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1	0
ID				В	A A A A A A	Α
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	$\begin{array}{cccccccccccccccccccccccccccccccccccc$	0
ID						
Α	RW	CHIDX		[2550]	DPPI channel that task START will subscribe to	
В	RW	EN				
			Disabled	0	Disable subscription	
			Enabled	1	Enable subscription	

6.12.10.6 SUBSCRIBE_SAMPLE

Address offset: 0x084

Subscribe configuration for task SAMPLE

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[2550]	DPPI channel that task SAMPLE will subscribe to
В	RW	EN			
			Disabled	0	Disable subscription
			Enabled	1	Enable subscription

6.12.10.7 SUBSCRIBE_STOP

Address offset: 0x088

Subscribe configuration for task STOP

Bit n	umber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2	2 1 0
ID				В	A A A A A A	А А А
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0 0
ID						
Α	RW	CHIDX		[2550]	DPPI channel that task STOP will subscribe to	
В	RW	EN				
			Disabled	0	Disable subscription	
			Enabled	1	Enable subscription	

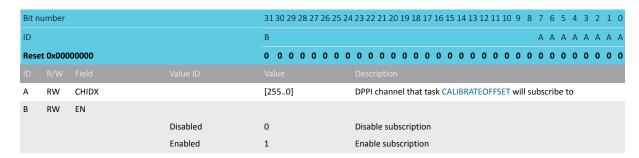
6.12.10.8 SUBSCRIBE_CALIBRATEOFFSET

Address offset: 0x08C



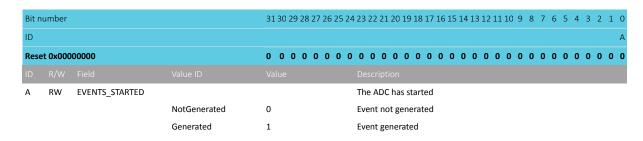


Subscribe configuration for task CALIBRATEOFFSET



6.12.10.9 EVENTS_STARTED

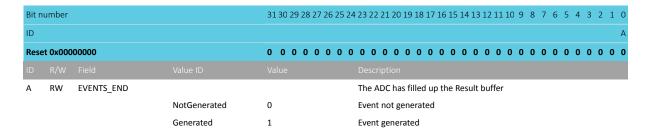
Address offset: 0x100
The ADC has started



6.12.10.10 EVENTS_END

Address offset: 0x104

The ADC has filled up the Result buffer



6.12.10.11 EVENTS DONE

Address offset: 0x108

A conversion task has been completed. Depending on the mode, multiple conversions might be needed for a result to be transferred to RAM.

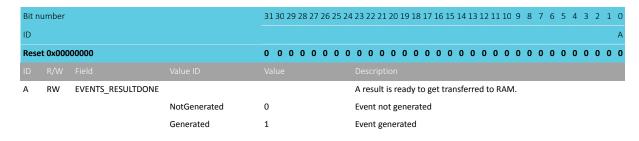


Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					А
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	EVENTS_DONE			A conversion task has been completed. Depending on the mode,
					multiple conversions might be needed for a result to be transferred to
					RAM.
			NotGenerated	0	Event not generated
			Generated	1	Event generated

6.12.10.12 EVENTS_RESULTDONE

Address offset: 0x10C

A result is ready to get transferred to RAM.



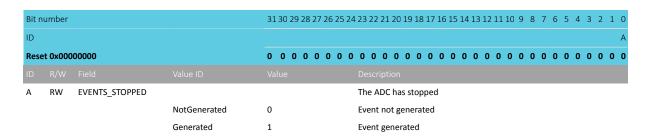
6.12.10.13 EVENTS_CALIBRATEDONE

Address offset: 0x110
Calibration is complete

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					А
Rese	et 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	EVENTS_CALIBRATEDO	NE		Calibration is complete
			NotGenerated	0	Event not generated
			Generated	1	Event generated

6.12.10.14 EVENTS_STOPPED

Address offset: 0x114
The ADC has stopped

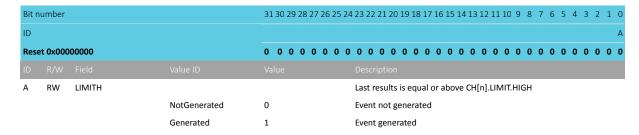


6.12.10.15 EVENTS_CH[n].LIMITH (n=0..7)

Address offset: 0x118 + (n × 0x8)



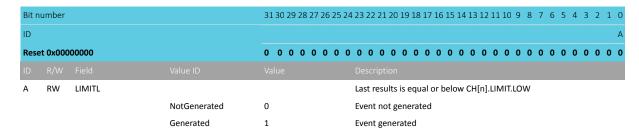
Last results is equal or above CH[n].LIMIT.HIGH



6.12.10.16 EVENTS CH[n].LIMITL (n=0..7)

Address offset: $0x11C + (n \times 0x8)$

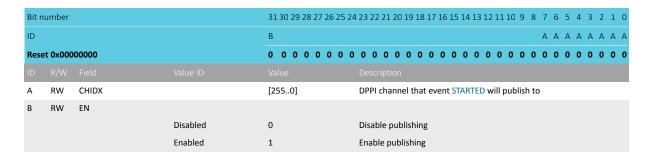
Last results is equal or below CH[n].LIMIT.LOW



6.12.10.17 PUBLISH STARTED

Address offset: 0x180

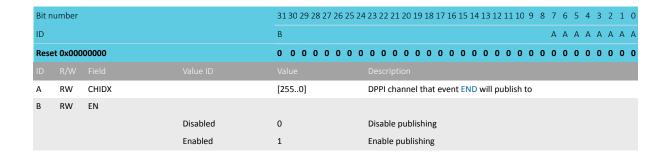
Publish configuration for event STARTED



6.12.10.18 PUBLISH END

Address offset: 0x184

Publish configuration for event END



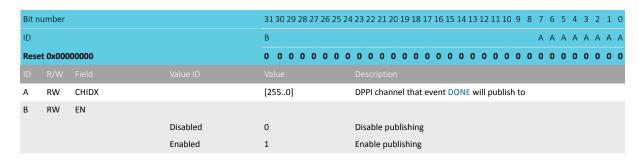




6.12.10.19 PUBLISH_DONE

Address offset: 0x188

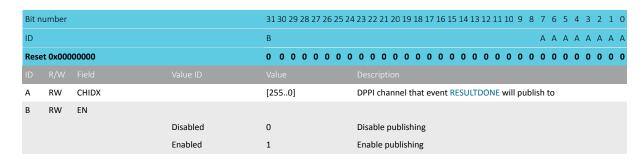
Publish configuration for event **DONE**



6.12.10.20 PUBLISH_RESULTDONE

Address offset: 0x18C

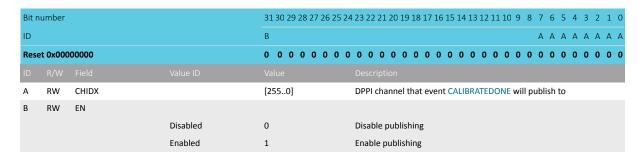
Publish configuration for event RESULTDONE



6.12.10.21 PUBLISH CALIBRATEDONE

Address offset: 0x190

Publish configuration for event CALIBRATEDONE

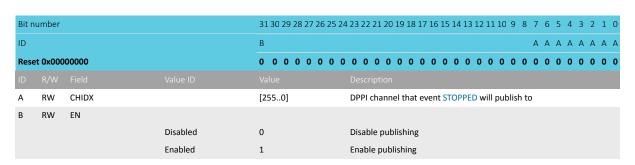


6.12.10.22 PUBLISH_STOPPED

Address offset: 0x194

Publish configuration for event STOPPED





6.12.10.23 PUBLISH_CH[n].LIMITH (n=0..7)

Address offset: $0x198 + (n \times 0x8)$

Publish configuration for event CH[n].LIMITH

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[2550]	DPPI channel that event CH[n].LIMITH will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing

6.12.10.24 PUBLISH_CH[n].LIMITL (n=0..7)

Address offset: $0x19C + (n \times 0x8)$

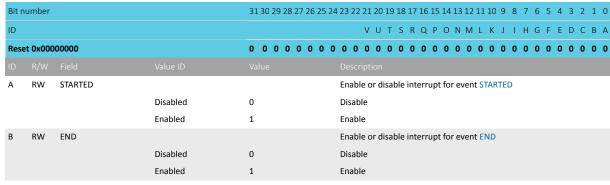
Publish configuration for event CH[n].LIMITL

Bit n	umber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[2550]	DPPI channel that event CH[n].LIMITL will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing

6.12.10.25 INTEN

Address offset: 0x300

Enable or disable interrupt







Bit r	umber			31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					V U T S R Q P O N M L K J I H G F E D C B A
Rese	et 0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
С	RW	DONE			Enable or disable interrupt for event DONE
			Disabled	0	Disable
			Enabled	1	Enable
D	RW	RESULTDONE			Enable or disable interrupt for event RESULTDONE
			Disabled	0	Disable
			Enabled	1	Enable
E	RW	CALIBRATEDONE			Enable or disable interrupt for event CALIBRATEDONE
			Disabled	0	Disable
			Enabled	1	Enable
F	RW	STOPPED			Enable or disable interrupt for event STOPPED
			Disabled	0	Disable
			Enabled	1	Enable
G	RW	CHOLIMITH			Enable or disable interrupt for event CHOLIMITH
			Disabled	0	Disable
			Enabled	1	Enable
Н	RW	CHOLIMITL	5. 11.1		Enable or disable interrupt for event CHOLIMITL
			Disabled	0	Disable
1	RW	CH1LIMITH	Enabled	1	Enable
1	KW	CHILIMITH	Disabled	0	Enable or disable interrupt for event CH1LIMITH Disable
			Enabled	1	Enable
J	RW	CH1LIMITL	Lilabled	1	Enable or disable interrupt for event CH1LIMITL
,	1000	CHILINITE	Disabled	0	Disable
			Enabled	1	Enable
K	RW	CH2LIMITH			Enable or disable interrupt for event CH2LIMITH
			Disabled	0	Disable
			Enabled	1	Enable
L	RW	CH2LIMITL			Enable or disable interrupt for event CH2LIMITL
			Disabled	0	Disable
			Enabled	1	Enable
М	RW	CH3LIMITH			Enable or disable interrupt for event CH3LIMITH
			Disabled	0	Disable
			Enabled	1	Enable
N	RW	CH3LIMITL			Enable or disable interrupt for event CH3LIMITL
			Disabled	0	Disable
			Enabled	1	Enable
0	RW	CH4LIMITH			Enable or disable interrupt for event CH4LIMITH
			Disabled	0	Disable
			Enabled	1	Enable
Р	RW	CH4LIMITL			Enable or disable interrupt for event CH4LIMITL
			Disabled	0	Disable
			Enabled	1	Enable
Q	RW	CH5LIMITH			Enable or disable interrupt for event CH5LIMITH
			Disabled	0	Disable
			Enabled	1	Enable
R	RW	CH5LIMITL	5. I.		Enable or disable interrupt for event CH5LIMITL
			Disabled	0	Disable
•	D1	CUCURATE	Enabled	1	Enable
S	RW	CH6LIMITH	Disable d	0	Enable or disable interrupt for event CH6LIMITH
			Disabled	0	Disable



Bit n	umber			31 30 29 28 27 2	26 25 2	4 2:	3 22 :	21 2	20 19	9 18	17	16	15 1	4 1.	3 12	11	10	9	8 7	6	5	4	3 2	2 1	. 0
ID								۷١	U T	S	R	Q	Ρ (N C	I M	L	K	J	I F	l G	F	Ε	D () E	3 A
Rese	t 0x000	00000		0 0 0 0 0	0 0 0	0	0	0	0 0	0	0	0	0	0	0	0	0	0	0 0	0	0	0	0 (0	0
ID																									
			Enabled	1		E	nable	e																	
Т	RW	CH6LIMITL				E	nable	e or	disa	ble	inte	erru	ıpt f	or e	ven	t Ch	16LI	Mľ	TL						
			Disabled	0		D	isabl	le																	
			Enabled	1		Disable Enable																			
U	RW	CH7LIMITH				Enable Enable or disable inte					erru	ıpt f	or e	ven	t Ch	H7LI	MI	тн							
			Disabled	0		D	isabl	le																	
			Enabled	1		E	nable	e																	
٧	RW	CH7LIMITL				E	nable	e or	disa	ble	inte	erru	ıpt f	or e	ven	t Ch	17LI	MI	TL						
			Disabled	0		D	isabl	le																	
			Enabled	1		E	nable	e																	

6.12.10.26 INTENSET

Address offset: 0x304

Enable interrupt

Bit r	number			31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					V U T S R Q P O N M L K J I H G F E D C B A
Res	et 0x000	000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
A	RW	STARTED			Write '1' to enable interrupt for event STARTED
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
В	RW	END			Write '1' to enable interrupt for event END
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
С	RW	DONE			Write '1' to enable interrupt for event DONE
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
D	RW	RESULTDONE			Write '1' to enable interrupt for event RESULTDONE
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
E	RW	CALIBRATEDONE			Write '1' to enable interrupt for event CALIBRATEDONE
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
F	RW	STOPPED			Write '1' to enable interrupt for event STOPPED
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
G	RW	CHOLIMITH			Write '1' to enable interrupt for event CH0LIMITH
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
Н	RW	CHOLIMITL			Write '1' to enable interrupt for event CHOLIMITL



Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					V U T S R Q P O N M L K J I H G F E D C B A
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	000000000000000000000000000000000000000
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
ı	RW	CH1LIMITH			Write '1' to enable interrupt for event CH1LIMITH
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
J	RW	CH1LIMITL			Write '1' to enable interrupt for event CH1LIMITL
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
K	RW	CH2LIMITH			Write '1' to enable interrupt for event CH2LIMITH
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
L	RW	CH2LIMITL			Write '1' to enable interrupt for event CH2LIMITL
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
M	RW	CH3LIMITH			Write '1' to enable interrupt for event CH3LIMITH
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
N	RW	CH3LIMITL			Write '1' to enable interrupt for event CH3LIMITL
			Set	1	Enable
			Disabled	0	Read: Disabled
_	D147	CUALINATU	Enabled	1	Read: Enabled
0	RW	CH4LIMITH	C-+	4	Write '1' to enable interrupt for event CH4LIMITH
			Set	1	Enable Parada Disabled
			Disabled	0	Read: Disabled
Р	RW	CH4LIMITL	Enabled	1	Read: Enabled Write '1' to enable interrupt for event CH4LIMITL
r	NVV	CH4LIIVII IL	Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
Q	RW	CH5LIMITH	Lilabled	1	Write '1' to enable interrupt for event CH5LIMITH
٦		5.13E.141111	Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
R	RW	CH5LIMITL			Write '1' to enable interrupt for event CH5LIMITL
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
S	RW	CH6LIMITH			Write '1' to enable interrupt for event CH6LIMITH
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
Т	RW	CH6LIMITL			Write '1' to enable interrupt for event CH6LIMITL
			Set	1	Enable
			Disabled	0	Read: Disabled



Bit n	umber			31	1 30	29 2	28 27	7 26	25 2	4 2	3 22	2 2 1	20	19	18 1	L7 1	6 1	5 14	13	12	11 10	9	8	7	6	5	4 3	3 2	1	0
ID												٧	U	Т	S	R (Q F	0	N	М	L K	J	1	Н	G	F	E [) С	В	Α
Rese	t 0x000	00000		0	0	0	0 0	0	0 () (0 0	0	0	0	0	0	0 0	0	0	0	0 0	0	0	0	0	0	0 (0	0	0
ID																														
			Enabled	1						R	Read	: Er	abl	ed																
U	RW	CH7LIMITH								٧	Vrite	e '1'	to	ena	ble	int	erru	pt	for e	ever	nt CH	7LII	MIT	Н						
			Set	1						E	nab	le																		
			Disabled	0						F	Read	: Di	sab	led																
			Enabled	1						F	Read	: Er	nabl	ed																
٧	RW	CH7LIMITL								٧	Vrite	e '1'	to	ena	ble	int	erru	pt '	for e	ever	t Ch	7LII	MIT	L						
			Set	1						Е	nab	le																		
			Disabled	0						R	Read	: Di	sab	led																
			Enabled	1						F	Read	: Er	abl	ed																

6.12.10.27 INTENCLR

Address offset: 0x308

Disable interrupt

Bit r	number			31 30 29 28 27 26 25 24 23 2	2 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					V U T S R Q P O N M L K J I H G F E D C B A
Rese	et 0x000	000000		0 0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
Α	RW	STARTED		Writ	e '1' to disable interrupt for event STARTED
			Clear	1 Disa	ble
			Disabled	0 Read	d: Disabled
			Enabled	1 Read	d: Enabled
В	RW	END		Writ	e '1' to disable interrupt for event END
			Clear	1 Disa	ble
			Disabled	0 Read	d: Disabled
			Enabled	1 Read	d: Enabled
С	RW	DONE		Writ	e '1' to disable interrupt for event DONE
			Clear	1 Disa	ble
			Disabled	0 Read	d: Disabled
			Enabled	1 Read	d: Enabled
D	RW	RESULTDONE		Writ	e '1' to disable interrupt for event RESULTDONE
			Clear	1 Disa	ble
			Disabled	0 Read	d: Disabled
			Enabled	1 Read	d: Enabled
E	RW	CALIBRATEDONE		Writ	e '1' to disable interrupt for event CALIBRATEDONE
			Clear	1 Disa	ble
			Disabled	0 Read	d: Disabled
			Enabled	1 Read	d: Enabled
F	RW	STOPPED		Writ	e '1' to disable interrupt for event STOPPED
			Clear	1 Disa	ble
			Disabled	0 Read	d: Disabled
			Enabled	1 Read	d: Enabled
G	RW	CH0LIMITH		Writ	e '1' to disable interrupt for event CHOLIMITH
			Clear	1 Disa	ble
			Disabled	0 Read	d: Disabled
			Enabled	1 Read	d: Enabled
Н	RW	CHOLIMITL		Writ	e '1' to disable interrupt for event CHOLIMITL
			Clear	1 Disa	ble



Bit r	umber			31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					V U T S R Q P O N M L K J I H G F E D C B A
Rese	et 0x000	000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
	_		Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
ı	RW	CH1LIMITH			Write '1' to disable interrupt for event CH1LIMITH
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
J	RW	CH1LIMITL			Write '1' to disable interrupt for event CH1LIMITL
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
K	RW	CH2LIMITH			Write '1' to disable interrupt for event CH2LIMITH
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
L	RW	CH2LIMITL			Write '1' to disable interrupt for event CH2LIMITL
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
М	RW	CH3LIMITH			Write '1' to disable interrupt for event CH3LIMITH
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
N	RW	CH3LIMITL			Write '1' to disable interrupt for event CH3LIMITL
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
0	RW	CH4LIMITH			Write '1' to disable interrupt for event CH4LIMITH
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
Р	RW	CH4LIMITL			Write '1' to disable interrupt for event CH4LIMITL
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
Q	RW	CH5LIMITH			Write '1' to disable interrupt for event CH5LIMITH
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
R	RW	CH5LIMITL			Write '1' to disable interrupt for event CH5LIMITL
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
S	RW	CH6LIMITH			Write '1' to disable interrupt for event CH6LIMITH
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
T	RW	CH6LIMITL			Write '1' to disable interrupt for event CH6LIMITL
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled



Bit n	umber			313	0 29 2	8 27	26 2	5 24	23	22 2:	1 20	19	18	17 1	.6 1	5 14	13	12 1	11 10	o 9	8	7	6	5	4 3	2	1 0
ID										٧	′ U	Т	S	R	Q F	0	N	М	L K	J	1	Н	G	F	E D	С	ВА
Rese	t 0x000	00000		0 (0 0	0 0	0 0	0	0	0 0	0	0	0	0	0 0	0	0	0	0 0	0	0	0	0	0	0 0	0	0 0
ID																											
U	RW	CH7LIMITH		1					Wr	te '1	' to	dis	able	e int	errı	ıpt	for e	ever	nt Cl	17LI	МΙΊ	Н					
			Clear	1					Dis	able																	
			Disabled	0					Rea	d: D	isab	oled	l														
			Enabled	1					Rea	d: E	nab	led															
V	RW	CH7LIMITL							Wr	te '1	' to	dis	able	e int	errı	ıpt	for e	ever	nt Ch	17LI	МІТ	L					
			Clear	1					Dis	able																	
			Disabled	0					Rea	d: D	isat	oled	l														
			Enabled	1					Rea	d: E	nab	led															

6.12.10.28 STATUS

Address offset: 0x400

Status

Bit n	umber			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					A
Rese	et 0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	R	STATUS			Status
			Ready	0	ADC is ready. No on-going conversion.
			Busy	1	ADC is busy. Single conversion in progress.

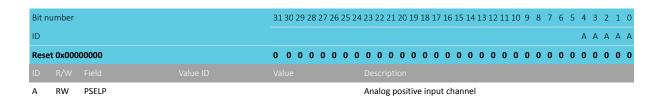
6.12.10.29 ENABLE

Address offset: 0x500 Enable or disable ADC

Bit r	umber			31 30	29 28	8 27 2	26 25	5 24	23	22 2	1 2	0 1	9 18	3 17	16	15 1	4 13	3 12	11 :	10 9	8	7	6	5	4	3 2	1	0
ID																												Α
Rese	et 0x000	00000		0 0	0 0	0	0 0	0	0	0 (0 (0 0	0	0	0	0 (0 0	0	0	0 0	0	0	0	0	0 (0	0	0
ID																												
Α	RW	ENABLE							Ena	able	or	disa	able	AD	С													
			Disabled	0					Dis	able	A C	OC																
			Enabled	1					Ena	able	AD	C																
									Wh	nen e	ena	ble	d, tl	he A	DC	will	aco	quire	e acc	ess	to t	he i	ana	log	inp	ut p	ins	
									spe	ecifie	ed i	n th	ne C	H[n].PS	ELP	and	d CH	[n].	PSEL	N r	egis	ters	s.				

6.12.10.30 CH[n].PSELP (n=0..7)

Address offset: $0x510 + (n \times 0x10)$ Input positive pin selection for CH[n]





Bit number		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			АААА
Reset 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
			Description
	NC	0	Not connected
	AnalogInput0	1	AIN0
	AnalogInput1	2	AIN1
	AnalogInput2	3	AIN2
	AnalogInput3	4	AIN3
	AnalogInput4	5	AIN4
	AnalogInput5	6	AIN5
	AnalogInput6	7	AIN6
	AnalogInput7	8	AIN7
	VDDGPIO	9	VDD_GPIO

6.12.10.31 CH[n].PSELN (n=0..7)

Address offset: $0x514 + (n \times 0x10)$

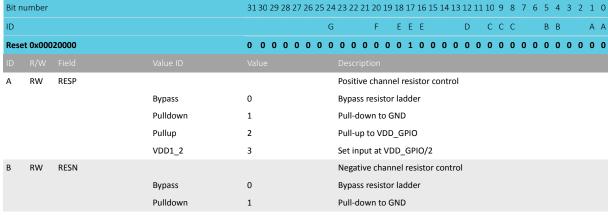
Input negative pin selection for CH[n]

Bit n	umber			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					АААА
Rese	t 0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	PSELN			Analog negative input, enables differential channel
			NC	0	Not connected
			AnalogInput0	1	AINO
			AnalogInput1	2	AIN1
			AnalogInput2	3	AIN2
			AnalogInput3	4	AIN3
			AnalogInput4	5	AIN4
			AnalogInput5	6	AIN5
			AnalogInput6	7	AIN6
			AnalogInput7	8	AIN7
			VDD_GPIO	9	VDD_GPIO

6.12.10.32 CH[n].CONFIG (n=0..7)

Address offset: $0x518 + (n \times 0x10)$

Input configuration for CH[n]



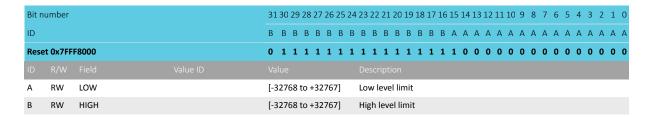


Bit nu	umber			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					G FEEE D CCC BB AA
Rese	t 0x000	20000		0 0 0 0 0 0 0	0 0 0 0 0 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
			Pullup	2	Pull-up to VDD_GPIO
			VDD1_2	3	Set input at VDD_GPIO/2
С	RW	GAIN			Gain control
			Gain1_6	0	1/6
			Gain1_5	1	1/5
			Gain1_4	2	1/4
			Gain1_3	3	1/3
			Gain1_2	4	1/2
			Gain1	5	1
			Gain2	6	2
			Gain4	7	4
D	RW	REFSEL			Reference control
			Internal	0	Internal reference (0.6 V)
			VDD1_4	1	VDD_GPIO/4 as reference
Ε	RW	TACQ			Acquisition time, the time the ADC uses to sample the input voltage
			3us	0	3 us
			5us	1	5 us
			10us	2	10 us
			15us	3	15 us
			20us	4	20 us
			40us	5	40 us
F	RW	MODE			Enable differential mode
			SE	0	Single ended, PSELN will be ignored, negative input to ADC shorted to
					GND
			Diff	1	Differential
G	RW	BURST			Enable burst mode
			Disabled	0	Burst mode is disabled (normal operation)
			Enabled	1	Burst mode is enabled. SAADC takes 2^OVERSAMPLE number of
					samples as fast as it can, and sends the average to Data RAM.

6.12.10.33 CH[n].LIMIT (n=0..7)

Address offset: $0x51C + (n \times 0x10)$

High/low limits for event monitoring a channel

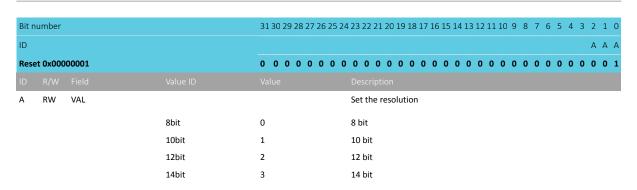


6.12.10.34 RESOLUTION

Address offset: 0x5F0
Resolution configuration



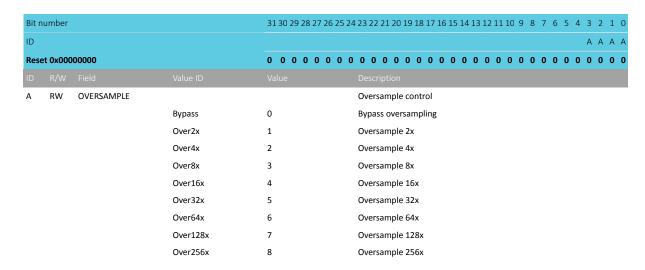




6.12.10.35 OVERSAMPLE

Address offset: 0x5F4

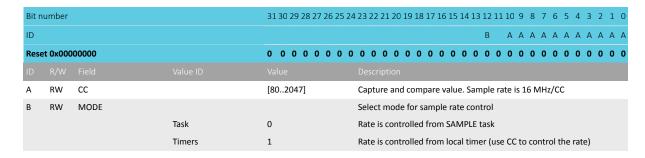
Oversampling configuration. OVERSAMPLE should not be combined with SCAN. The RESOLUTION is applied before averaging, thus for high OVERSAMPLE a higher RESOLUTION should be used.



6.12.10.36 SAMPLERATE

Address offset: 0x5F8

Controls normal or continuous sample rate

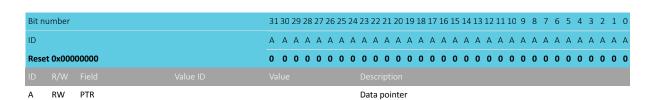


6.12.10.37 RESULT.PTR

Address offset: 0x62C

Data pointer



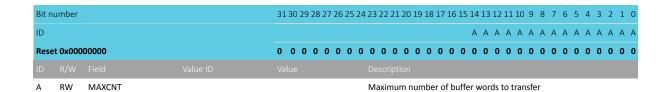


Note: See the memory chapter for details about which memories are available for EasyDMA.

6.12.10.38 RESULT.MAXCNT

Address offset: 0x630

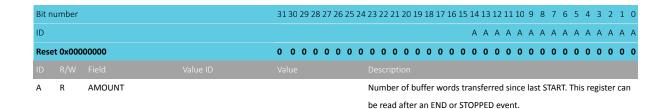
Maximum number of buffer words to transfer



6.12.10.39 RESULT.AMOUNT

Address offset: 0x634

Number of buffer words transferred since last START



6.12.11 Electrical specification

6.12.11.1 SAADC Electrical Specification

Symbol	Description	Min.	Тур.	Max.	Units
DNL ₁₀	Differential non-linearity, 10-bit resolution	-0.95	<1		LSB10b
INL ₁₀	Integral non-linearity, 10-bit resolution		1		LSB10b
V _{OS}	Differential offset error (calibrated), 10-bit resolution ^a		±2		LSB10b
C _{EG}	Gain error temperature coefficient	-0.05	0.02	0.05	%/°C
f _{SAMPLE}	Maximum sampling rate			200	kHz
t _{ACQ,10k}	Acquisition time (configurable), source Resistance <=		3		μs
	10kOhm				
t _{ACQ,40k}	Acquisition time (configurable), source Resistance <=		5		μs
	40kOhm				
t _{ACQ,100k}	Acquisition time (configurable), source Resistance <=		10		μs
	100kOhm				

^a Digital output code at zero volt differential input.



Symbol	Description	Min.	Тур.	Max.	Units
t _{ACQ,200k}	Acquisition time (configurable), source Resistance <=		15		μs
	200kOhm				
t _{ACQ,400k}	Acquisition time (configurable), source Resistance <=		20		μs
	400kOhm				
t _{ACQ,800k}	Acquisition time (configurable), source Resistance <=		40		μs
	800kOhm				
t _{CONV}	Conversion time		<2		μs
E _{G1/6}	Error ^b for Gain = 1/6	-3		3	%
E _{G1/4}	Error ^b for Gain = 1/4	-3		3	%
E _{G1/2}	Error ^b for Gain = 1/2	-3		4	%
E _{G1}	Error ^b for Gain = 1	-3		4	%
C _{SAMPLE}	Sample and hold capacitance at maximum gain 14		2.5		pF
R _{INPUT}	Input resistance		>1		ΜΩ
E _{NOB}	Effective number of bits, differential mode, 12-bit		9		Bit
	resolution, 1/1 gain, 3 μs acquisition time, HFXO, 200 ksps				
S _{NDR}	Peak signal to noise and distortion ratio, differential mode,		56		dB
	12-bit resolution, $1/1$ gain, 3 μs acquisition time, HFXO, 200				
	ksps				
S _{FDR}	Spurious free dynamic range, differential mode, 12-bit		70		dBc
	resolution, 1/1 gain, 3 μs acquisition time, HFXO, 200 ksps				
R _{LADDER}	Ladder resistance		160		kΩ

6.12.12 Performance factors

Clock jitter, affecting sample timing accuracy, and circuit noise can affect ADC performance.

Jitter can be between START tasks or from START task to acquisition. START timer accuracy and startup times of regulators and references will contribute to variability. Sources of circuit noise may include CPU activity and the DC/DC regulator. Best ADC performance is achieved using START timing based on the TIMER module, HFXO clock source, and Constant Latency mode.

6.13 SPIM — Serial peripheral interface master with EasyDMA

The SPI master can communicate with multiple slaves using individual chip select signals for each of the slave devices attached to a bus.

Listed here are the main features for the SPIM

- SPI mode 0-3
- EasyDMA direct transfer to/from RAM for both SPI Slave and SPI Master
- Individual selection of IO pin for each SPI signal



b Does not include temperature drift

 $^{^{\}rm 14}$ Maximum gain corresponds to highest capacitance.

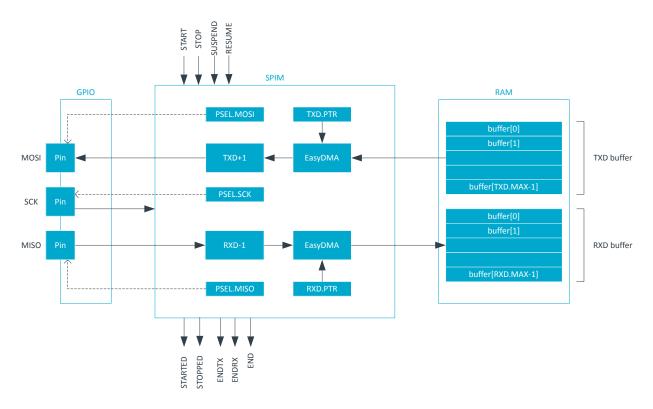


Figure 73: SPIM — SPI master with EasyDMA

The SPIM does not implement support for chip select directly. Therefore, the CPU must use available GPIOs to select the correct slave and control this independently of the SPI master. The SPIM supports SPI modes 0 through 3. The CONFIG register allows setting CPOL and CPHA appropriately.

Mode	Clock polarity	Clock phase
	CPOL	СРНА
SPI_MODE0	0 (Active High)	0 (Leading)
SPI_MODE1	0 (Active High)	1 (Trailing)
SPI_MODE2	1 (Active Low)	0 (Leading)
SPI_MODE3	1 (Active Low)	1 (Trailing)

Table 71: SPI modes

6.13.1 SPI master transaction sequence

An SPI master transaction consists of a sequence started by the START task followed by a number of events, and finally the STOP task.

An SPI master transaction is started by triggering the START task. The ENDTX event will be generated when the transmitter has transmitted all bytes in the TXD buffer as specified in the TXD.MAXCNT register. The ENDRX event will be generated when the receiver has filled the RXD buffer, i.e. received the last possible byte as specified in the RXD.MAXCNT register.

Following a START task, the SPI master will generate an END event when both ENDRX and ENDTX have been generated.

The SPI master is stopped by triggering the STOP task. A STOPPED event is generated when the SPI master has stopped.

If the ENDRX event has not already been generated when the SPI master has come to a stop, the SPI master will generate the ENDRX event explicitly even though the RX buffer is not full.

If the ENDTX event has not already been generated when the SPI master has come to a stop, the SPI master will generate the ENDTX event explicitly even though all bytes in the TXD buffer, as specified in the TXD.MAXCNT register, have not been transmitted.

The SPI master is a synchronous interface, and for every byte that is sent, a different byte will be received at the same time; this is illustrated in SPI master transaction on page 231.

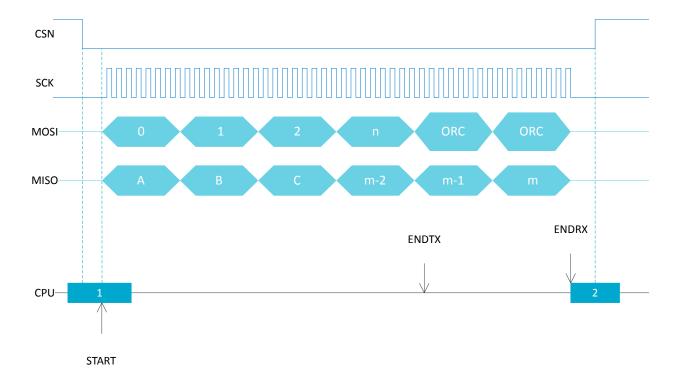


Figure 74: SPI master transaction

6.13.2 Master mode pin configuration

The SCK, MOSI, and MISO signals associated with the SPI master are mapped to physical pins according to the configuration specified in the PSEL.SCK, PSEL.MOSI, and PSEL.MISO registers respectively.

The PSEL.SCK, PSEL.MOSI, and PSEL.MISO registers and their configurations are only used as long as the SPI master is enabled, and retained only as long as the device is in ON mode. PSEL.SCK, PSEL.MOSI and PSEL.MISO must only be configured when the SPI master is disabled.

To secure correct behavior in the SPI, the pins used by the SPI must be configured in the GPIO peripheral as described in GPIO configuration on page 231 prior to enabling the SPI. This configuration must be retained in the GPIO for the selected IOs as long as the SPI is enabled.

Only one peripheral can be assigned to drive a particular GPIO pin at a time. Failing to do so may result in unpredictable behavior.

SPI master signal	SPI master pin	Direction	Output value
SCK	As specified in PSEL.SCK	Output	Same as CONFIG.CPOL
MOSI	As specified in PSEL.MOSI	Output	0
MISO	As specified in PSEL.MISO	Input	Not applicable

Table 72: GPIO configuration



6.13.3 Shared resources

The SPI shares registers and other resources with other peripherals that have the same ID as the SPI. Therefore, the user must disable all peripherals that have the same ID as the SPI before the SPI can be configured and used.

Disabling a peripheral that has the same ID as the SPI will not reset any of the registers that are shared with the SPI. It is therefore important to configure all relevant SPI registers explicitly to secure that it operates correctly.

See the Instantiation table in Instantiation on page 26 for details on peripherals and their IDs.

6.13.4 EasyDMA

The SPIM implements EasyDMA for accessing RAM without CPU involvement.

The SPIM peripheral implements the following EasyDMA channels:

Channel	Туре	Register Cluster
TXD	READER	TXD
RXD	WRITER	RXD

Table 73: SPIM EasyDMA Channels

For detailed information regarding the use of EasyDMA, see EasyDMA on page 47.

The .PTR and .MAXCNT registers are double-buffered. They can be updated and prepared for the next transmission immediately after having received the STARTED event.

The SPI master will automatically stop transmitting after TXD.MAXCNT bytes have been transmitted and RXD.MAXCNT bytes have been received. If RXD.MAXCNT is larger than TXD.MAXCNT, the remaining transmitted bytes will contain the value defined in the ORC register. If TXD.MAXCNT is larger than RXD.MAXCNT, the superfluous received bytes will be discarded.

The ENDRX/ENDTX event indicate that EasyDMA has finished accessing respectively the RX/TX buffer in RAM. The END event gets generated when both RX and TX are finished accessing the buffers in RAM.

In the case of bus congestion as described in AHB multilayer interconnect on page 49, data loss may occur.

6.13.5 Low power

When putting the system in low power and the peripheral is not needed, lowest possible power consumption is achieved by stopping, and then disabling the peripheral.

The STOP task may not be always needed (the peripheral might already be stopped), but if it is sent, software shall wait until the STOPPED event was received as a response before disabling the peripheral through the ENABLE register.



6.13.6 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x50008000	SPIM	SPIM0 : S	US	SA	SPI master 0	
0x40008000	JF IIVI	SPIM0 : NS	03	JA.	SFI master 0	
0x50009000	SPIM	SPIM1:S	US	SA	SPI master 1	
0x40009000	SPIIVI	SPIM1: NS	03	JA	Sri illaster 1	
0x5000A000	SPIM	SPIM2 : S	US	SA	SPI master 2	
0x4000A000		SPIM2 : NS	03	JA.	SFT IIIdStel 2	
0x5000B000	SPIM	SPIM3:S	US	SA	SPI master 3	
0x4000B000	JF IIVI	SPIM3 : NS	03	ЭА	SET THROUGH S	

Table 74: Instances

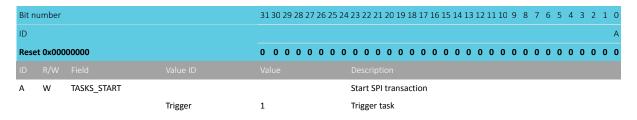
TASKS_STORP 0x01C Supper Stop Stop Styl transaction TASKS_SIDPPN 0x01C Supper Styl transaction TASKS_RESUME 0x020 Resume SPI transaction TASKS_RESUME 0x020 Resume SPI transaction SUBSCRIBE_START 0x090 Subscribe configuration for task START SUBSCRIBE_STOP 0x094 Subscribe configuration for task STOP SUBSCRIBE_SUPPEND 0x090 Subscribe configuration for task SUPPEND SUBSCRIBE_SUPPEND 0x090 Subscribe configuration for task SUPPEND SUBSCRIBE_SUPPEND 0x104 SPI transaction has stopped EVENTS_ENDRY 0x110 End of RXD Duffer reached EVENTS_ENDRY 0x110 End of RXD Duffer reached EVENTS_ENDRY 0x110 End of TXD buffer reached EVENTS_ENDRY 0x110 End of TXD buffer reached EVENTS_ENDRY 0x120 End of TXD buffer End TXD buffer TXD MAX ENDRY 0x120 End of TXD buffer TXD MAX ENDRY 0x	Register	Offset	Security	Description
TASKS_SUSPEND 0x01C Suspend SPI transaction TASKS_RESUME 0x020 Resume SPI transaction SUBSCRIBE_START 0x090 Subscribe configuration for task START SUBSCRIBE_STOP 0x094 Subscribe configuration for task STOP SUBSCRIBE_SUSPEND 0x09C Subscribe configuration for task SUSPEND SUBSCRIBE_SUSPEND 0x0A0 Subscribe configuration for task SUSPEND SUBSCRIBE_RESUME 0x0A0 Subscribe configuration for task SUSPEND SUBSCRIBE_RESUME 0x0A0 Subscribe configuration for task SUSPEND SUBSCRIBE_RESUME 0x1D SPI transaction has stopped EVENTS_STOPPED 0x11B End of RXD buffer reached EVENTS_ENDTX 0x11B End of RXD buffer reached EVENTS_STARTED 0x14C Transaction started PUBLISH_ENDTX 0x190 Publish configuration for event STOPPED PUBLISH_END 0x198 Publish configuration for event ENDTX PUBLISH_ENDTX 0x14O Publish configuration for event ENDTX PUBLISH_ENDTX 0x1AO Publish configuration for event ENDTX PUBLISH_ENDTX	TASKS_START	0x010		Start SPI transaction
TASKS_RESUME 0x020 Resume SPI transaction SUBSCRIBE_START 0x090 Subscribe configuration for task START SUBSCRIBE_STOP 0x094 Subscribe configuration for task STOP SUBSCRIBE_SUSPEND 0x040 Subscribe configuration for task SUSPEND SUBSCRIBE_RESUME 0x040 Subscribe configuration for task SUSPEND SUBSCRIBE_RESUME 0x040 Subscribe configuration for task SUSPEND EVENTS_ENDRY 0x104 SPI transaction has stopped EVENTS_ENDRY 0x118 End of RXD buffer reached EVENTS_ENDRY 0x120 End of TXD buffer reached EVENTS_STARTED 0x14C Transaction started PUBLISH_STOPPED 0x14A Publish configuration for event STOPPED PUBLISH_ENDRY 0x190 Publish configuration for event ENDRX PUBLISH_ENDRY 0x190 Publish configuration for event ENDRX PUBLISH_ENDRY 0x140 Publish configuration for event ENDRX PUBLISH_ENDRY 0x140 Publish configuration for event ENDRX PUBLISH_ENDRY 0x140 Publish configuration for event ENDRX PUBLISH_ENDRY	TASKS_STOP	0x014		Stop SPI transaction
SUBSCRIBE_START 0x090 Subscribe configuration for task START SUBSCRIBE_STOP 0x094 Subscribe configuration for task STOP SUBSCRIBE_SUSPEND 0x09C Subscribe configuration for task SUSPEND SUBSCRIBE_RESUME 0x0A0 Subscribe configuration for task RESUME EVENTS_ENDRED 0x104 SPI transaction has stopped EVENTS_ENDRED 0x110 End of RXD buffer reached EVENTS_ENDRED 0x118 End of RXD buffer reached EVENTS_ENDRED 0x120 End of TXD buffer reached EVENTS_STARTED 0x140 Publish configuration for event STOPPED PUBLISH_ENDRED 0x198 Publish configuration for event ENDRED PUBLISH_ENDRED 0x198 Publish configuration for event ENDRED PUBLISH_ENDRED 0x100 Publish configuration for event ENDRED PUBLISH_ENDRED 0x100 Publish configuration for event ENDRED PUBLISH_ENDRED 0x100 Publish configuration for event ENDRED PUBLISH_STARTED 0x100 Publish configuration for event ENDRED SHORTS 0x200 Shortcuts between local events and tasks INTENSET 0x304 Enable interrupt INTENSET 0x304 Enable interrupt INTENSET 0x306 Pin select for SCK PSEL MOSI 0x500 Enable SPIM PSELSCK 0x500 Enable SPIM PSELSCK 0x500 Pin select for MISO signal FREQUENCY 0x524 SPI frequency. Accuracy depends on the HFCLK source selected. RXD_PTR 0x534 Data pointer RXD_MAXCNT 0x538 Maximum number of bytes in receive buffer RXD_AMOUNT 0x540 EasyDMA list type TXD_MAXCNT 0x544 Data pointer TXD_MAXCNT 0x546 Maximum number of bytes in transmit buffer TXD_MAXCNT 0x540 Number of bytes transferred in the last transaction TXD_MAXCNT 0x540 Number of bytes transferred in the last transaction TXD_MAXCNT 0x540 Number of bytes in transmit buffer	TASKS_SUSPEND	0x01C		Suspend SPI transaction
SUBSCRIBE_SUSPEND 0x094 Subscribe configuration for task STOP SUBSCRIBE_SUSPEND 0x09C Subscribe configuration for task SUSPEND SUBSCRIBE_RESUME 0x00A Subscribe configuration for task RESUME EVENTS_STOPPED 0x104 SPI transaction has stopped EVENTS_ENDRX 0x110 End of RXD buffer and TXD buffer reached EVENTS_ENDR 0x118 End of RXD buffer and TXD buffer reached EVENTS_ENDTX 0x120 End of TXD buffer reached EVENTS_STARTED 0x14C Transaction started PUBLISH_STOPPED 0x184 Publish configuration for event STOPPED PUBLISH_ENDRX 0x190 Publish configuration for event ENDRX PUBLISH_ENDR 0x184 Publish configuration for event ENDR PUBLISH_ENDTX 0x1A0 Publish configuration for event ENDR PUBLISH_ENDTX 0x1A0 Publish configuration for event ENDTX PUBLISH_ENDTX 0x1A0 Publish configuration for event ENDTX PUBLISH_ENDTX 0x304 Enable interrupt INTENSET 0x304 Enable interrupt ENDAME 0x500	TASKS_RESUME	0x020		Resume SPI transaction
SUBSCRIBE_SUSPEND 0x09C Subscribe configuration for task SUSPEND SUBSCRIBE_RESUME 0x0A0 Subscribe configuration for task RESUME EVENTS_STOPPED 0x104 SPI transaction has stopped EVENTS_ENDRX 0x110 End of RXD buffer reached EVENTS_ENDRX 0x110 End of RXD buffer reached EVENTS_ENDRX 0x120 End of TXD buffer reached EVENTS_STARTED 0x14C Transaction started PUBLISH_STOPPED 0x184 Publish configuration for event STOPPED PUBLISH_ENDRX 0x190 Publish configuration for event ENDRX PUBLISH_ENDRX 0x190 Publish configuration for event ENDRX PUBLISH_ENDRX 0x1A0 Publish configuration for event ENDRX PUBLISH_STORTED 0x1CC Publish configuration for event ENDRX PUBLISH_STARTED 0x1CC Publish configuration for event STARTED SHORTS 0x300 Enable interrupt INTENCER 0x304 Enable interrupt INTENCER 0x308 Disable interrupt PERABLE 0x500 Enable SPIM PSEL.SCK 0x508 Pin select for SCK PSELMOSI 0x50C Pin select for MISO signal PSELMOSI 0x50C Pin select for MISO signal PSELMOSI 0x50C Pin select for MISO signal RRQ.DTR 0x504 Data pointer RRQ.DAMOUNT 0x50C Number of bytes in receive buffer RRQ.DAMOUNT 0x50C Number of bytes transferred in the last transaction RRQ.DTR 0x50C Assimum number of bytes in transmit buffer TXD.D.MAXCNT 0x50C Maximum number of bytes in transmit buffer TXD.D.MAXCNT 0x50C Maximum number of bytes in transmit buffer TXD.D.MAXCNT 0x50C Maximum number of bytes in transmit buffer TXD.D.MAXCNT 0x50C EasyDMA list type TXD.D.MAXCNT 0x50C Dx50C EasyDMA list type TXD.D.MAXCNT 0x50C 0x50C EasyDMA list type	SUBSCRIBE_START	0x090		Subscribe configuration for task START
SUBSCRIBE_RESUME 0x00 Subscribe configuration for task RESUME EVENTS_ENDRX 0x10 SPI transaction has stopped EVENTS_ENDRX 0x110 End of RXD buffer reached EVENTS_END 0x118 End of RXD buffer and TXD buffer reached EVENTS_ENDTX 0x120 End of TXD buffer reached EVENTS_STARED 0x14C Transaction started PUBLISH_STOPPED 0x184 Publish configuration for event STOPPED PUBLISH_ENDX 0x190 Publish configuration for event ENDRX PUBLISH_ENDTX 0x140 Publish configuration for event ENDRX PUBLISH_ENDTX 0x140 Publish configuration for event ENDRX PUBLISH_STARTED 0x1cc Publish configuration for event ENDTX PUBLISH_ENDTX 0x1cc Publish configuration for event ENDTX PUBLISH_ENDTX<	SUBSCRIBE_STOP	0x094		Subscribe configuration for task STOP
EVENTS_ENDRX 0x110 End of RXD buffer reached EVENTS_END 0x118 End of RXD buffer reached EVENTS_END 0x120 End of TXD buffer reached EVENTS_ENDTX 0x120 End of TXD buffer reached EVENTS_ENDTX 0x120 End of TXD buffer reached EVENTS_ENDTX 0x120 End of TXD buffer reached EVENTS_STARTED 0x14C Transaction started PUBLISH_STOPPED 0x184 Publish configuration for event STOPPED PUBLISH_ENDRX 0x190 Publish configuration for event ENDRX PUBLISH_ENDRX 0x190 Publish configuration for event ENDRX PUBLISH_ENDTX 0x1A0 Publish configuration for event ENDTX PUBLISH_STARTED 0x1CC Publish configuration for event ENDTX PUBLISH_STARTED 0x1CC Publish configuration for event STARTED SHORTS 0x200 Shortcuts between local events and tasks INTENSET 0x304 Enable interrupt INTENSET 0x304 Disable interrupt ENABLE 0x500 Enable SPIM PSEL.SCK 0x508 Pin select for SCK PSEL.MOSI 0x500 Pin select for MOSI signal PSEL.MISO 0x510 Pin select for MOSI signal REQUENCY 0x524 SPI frequency. Accuracy depends on the HFCLK source selected. RXD.PTR 0x534 Data pointer RXD.MAXCNT 0x538 Maximum number of bytes in receive buffer RXD.MAXCNT 0x538 Maximum number of bytes in receive buffer TXD.PTR 0x544 Data pointer TXD.MAXCNT 0x548 Maximum number of bytes in transmit buffer TXD.MAXCNT 0x548 Maximum number of bytes in transmit buffer TXD.MAXCNT 0x548 Maximum number of bytes in transmit buffer TXD.MAXCNT 0x540 Configuration register CONFIG 0x554 Configuration register	SUBSCRIBE_SUSPEND	0x09C		Subscribe configuration for task SUSPEND
EVENTS_END 0x110 End of RXD buffer reached EVENTS_END 0x118 End of RXD buffer reached EVENTS_ENDTX 0x120 End of TXD buffer reached EVENTS_STARTED 0x14C Transaction started PUBLISH_STOPPED 0x184 Publish configuration for event STOPPED PUBLISH_ENDTX 0x190 Publish configuration for event ENDTX PUBLISH_ENDT 0x140 Publish configuration for event ENDTX PUBLISH_STARTED 0x1AC Publish configuration for event STARTED SHORTS 0x200 Shortcuts between local events and tasks INTENSET 0x304 Enable interrupt INTENSET 0x304 Enable SPIM PSEL_CKS 0x508 Pin select for SCK PSEL_MOSI 0x508 Pin select for MISO signal PSEL_MISO 0x510 Pin select for MISO signal PREQUENCY 0x524 SPI frequency. Accuracy depends on the HPCLK source selected. RXD.PTR 0x534 Data pointer RXD.AMACNT 0x536 Number of bytes transferred in the last transaction TXD.PTR	SUBSCRIBE_RESUME	0x0A0		Subscribe configuration for task RESUME
EVENTS_ENDTX 0x120 End of TXD buffer reached EVENTS_STARTED 0x14C Transaction started PUBLISH_STOPPED 0x184 Publish configuration for event STOPPED PUBLISH_ENDTX 0x190 Publish configuration for event ENDTX PUBLISH_ENDTX 0x1A0 Publish configuration for event ENDTX PUBLISH_ENDTX 0x1A0 Publish configuration for event ENDTX PUBLISH_STARTED 0x1CC Publish configuration for event STARTED SHORTS 0x200 Shortcuts between local events and tasks INTENSET 0x304 Enable interrupt INTENCER 0x308 Disable interrupt ENABLE 0x500 Enable SPIM PSEL.SCK 0x508 Pin select for SCK PSEL.MISO 0x510 Pin select for MOSI signal FREQUENCY 0x534 Data pointer RXD_MAXCNT 0x536 Number of bytes in receive buffer RXD_MAXCNT 0x540 EasyDMA list type TXD_MAXCNT 0x548 Maximum number of bytes in transmit buffer TXD_MAXCNT 0x540 EasyDMA list type CONFIG 0x550 Configuration register	EVENTS_STOPPED	0x104		SPI transaction has stopped
EVENTS_STARTED 0x14C Transaction started PUBLISH_STOPPED 0x184 Publish configuration for event STOPPED PUBLISH_ENDRX 0x190 Publish configuration for event ENDRX PUBLISH_ENDRX 0x190 Publish configuration for event ENDRX PUBLISH_ENDRX 0x14C Publish configuration for event ENDRX PUBLISH_ENDRX 0x14C Publish configuration for event ENDTX PUBLISH_ENDRX 0x14C Publish configuration for event ENDTX PUBLISH_ENDRX 0x14C Publish configuration for event STARTED SHORTS 0x200 Shortcuts between local events and tasks InterNETR 10x304 Enable interrupt INTENCER 0x308 Disable interrupt INTENCER 0x308 Pin select for SCK PSEL.SCK 0x508 Pin select for SCK PSEL.MISO 0x50C Pin select for MOSI signal FREQUENCY 0x524 SPI frequency. Accuracy depends on the HFCLK source selected. RXD.PTR 0x534 Data pointer RXD.MACNT 0x536 Number of bytes in receive buffer RXD.AMOUNT 0x540 EasyDMA list type TXD.MACNT 0x548 Maximum number of bytes in reserved in the last transaction TXD.MACNT 0x548 Maximum number of bytes in transmit buffer TXD.MACNT 0x548 Maximum number of bytes in transmit buffer TXD.MACNT 0x540 EasyDMA list type TXD.MACNT 0x540 EasyDMA list type CONFIG 0x540 Configuration register	EVENTS_ENDRX	0x110		End of RXD buffer reached
EVENTS_STARTED Ox14C Transaction started PUBLISH_STOPPED Ox184 Publish configuration for event STOPPED PUBLISH_ENDRX Ox190 Publish configuration for event ENDRX PUBLISH_END Ox198 Publish configuration for event ENDR PUBLISH_ENDTX Ox1A0 Publish configuration for event ENDTX PUBLISH_STARTED Ox1CC Publish configuration for event ENDTX PUBLISH_STARTED Ox200 Shortcuts between local events and tasks INTENSET Ox304 Enable interrupt INTENCER Ox500 Enable SPIM PSEL.SCCK Ox508 Pin select for SCK PSEL.MOSI PSEL.MISO Ox50C Pin select for MOSI signal PSELMISO Ox50C Pin select for MISO signal FREQUENCY Ox524 SPI frequency. Accuracy depends on the HFCLK source selected. RXD.PTR RXD.MAXCNT Ox538 Maximum number of bytes in receive buffer RXD.AMOUNT Ox53C Number of bytes transferred in the last transaction RXD.LIST Ox540 EasyDMA list type CXD.AMOUNT Ox548 Maximum number of bytes in transmit buffer TXD.AMOUNT Ox540 EasyDMA list type CXD.AMOUNT Ox541 Ox540 Data pointer TXD.AMOUNT Ox540 Data pointer	EVENTS_END	0x118		End of RXD buffer and TXD buffer reached
PUBLISH_STOPPED 0x184 Publish configuration for event STOPPED PUBLISH_ENDRX 0x190 Publish configuration for event ENDRX PUBLISH_END 0x188 Publish configuration for event END PUBLISH_ENDTX 0x1A0 Publish configuration for event ENDTX PUBLISH_STARTED 0x1CC Publish configuration for event STARTED SHORTS 0x200 Shortcuts between local events and tasks INTENSET 0x304 Enable interrupt ENABLE 0x500 Enable SPIM ENABLE 0x500 Enable SPIM PSEL.MOSI 0x500 Pin select for SCK PSEL.MISO 0x500 Pin select for MISO signal FREQUENCY 0x524 SPI frequency. Accuracy depends on the HFCLK source selected. RXD.PTR 0x534 Data pointer RXD.AMOUNT 0x536 Maximum number of bytes in receive buffer RXD.AMOUNT 0x540 EasyDMA list type TXD.MAXCNT 0x548 Maximum number of bytes in transmit buffer TXD.AMOUNT 0x54C Number of bytes transferred in the last transaction <	EVENTS_ENDTX	0x120		End of TXD buffer reached
PUBLISH_ENDRX 0x190 Publish configuration for event ENDRX PUBLISH_ENDTX 0x1A0 Publish configuration for event END PUBLISH_ENDTX 0x1A0 Publish configuration for event ENDTX PUBLISH_STARTED 0x1CC Publish configuration for event STARTED SHORTS 0x200 Shortcuts between local events and tasks INTENSET 0x304 Enable interrupt INTENCER 0x308 Disable interrupt ENABLE 0x500 Enable SPIM PSEL.SCK 0x508 Pin select for SCK PSEL.MOSI 0x50C Pin select for MOSI signal PSEL.MISO 0x510 Pin select for MISO signal FREQUENCY 0x524 SPI frequency. Accuracy depends on the HFCLK source selected. RXD.PTR 0x534 Data pointer RXD.MAXCNT 0x538 Maximum number of bytes in receive buffer RXD.AMOUNT 0x53C Number of bytes transferred in the last transaction RXD.LIST 0x540 Data pointer TXD.PTR 0x544 Data pointer TXD.MAXCNT 0x548 Maximum number of bytes in transmit buffer TXD.MAXCNT 0x548 Maximum number of bytes in transmit buffer TXD.MAXCNT 0x548 Maximum number of bytes in transmit buffer TXD.MAXCNT 0x546 Number of bytes transferred in the last transaction TXD.MAXCNT 0x548 Maximum number of bytes in transmit buffer TXD.MAXCNT 0x540 SeasyDMA list type COLIFIC 0x550 EasyDMA list type COLIFIC 0x550 Configuration register	EVENTS_STARTED	0x14C		Transaction started
PUBLISH_END 0x198 Publish configuration for event END PUBLISH_ENDTX 0x1A0 Publish configuration for event ENDTX PUBLISH_STARTED 0x1CC Publish configuration for event STARTED SHORTS 0x200 Shortcuts between local events and tasks INTENSET 0x304 Enable interrupt INTENCLR 0x308 Disable interrupt ENABLE 0x500 Enable SPIM PSELSCK 0x508 Pin select for SCK PSELMOSI 0x50C Pin select for MISO signal PSELMISO 0x510 Pin select for MISO signal FREQUENCY 0x524 SPI frequency. Accuracy depends on the HFCLK source selected. RXD.PTR 0x534 Data pointer RXD.MAXCNT 0x538 Maximum number of bytes in receive buffer RXD.AMOUNT 0x540 EasyDMA list type TXD.PTR 0x544 Data pointer TXD.MAXCNT 0x548 Maximum number of bytes in transmit buffer TXD.MAXCNT 0x548 Maximum number of bytes in transmit buffer TXD.AMOUNT 0x54C N	PUBLISH_STOPPED	0x184		Publish configuration for event STOPPED
PUBLISH_STARTED 0x1CC Publish configuration for event ENDTX PUBLISH_STARTED 0x1CC Publish configuration for event STARTED SHORTS 0x200 Shortcuts between local events and tasks INTENSET 0x304 Enable interrupt INTENCLR 0x308 Disable interrupt ENABLE 0x500 Enable SPIM PSEL.SCK 0x508 Pin select for SCK PSEL.MOSI 0x50C Pin select for MOSI signal PSEL.MISO 0x510 Pin select for MISO signal FREQUENCY 0x524 SPI frequency. Accuracy depends on the HFCLK source selected. RXD.PTR 0x534 Data pointer RXD.MAXCNT 0x538 Maximum number of bytes in receive buffer RXD.AMOUNT 0x53C Number of bytes transferred in the last transaction RXD.PTR 0x544 Data pointer TXD.PTR 0x544 Data pointer TXD.PTR 0x544 Data pointer TXD.PTR 0x540 EasyDMA list type TXD.PTR 0x544 Data pointer TXD.MAXCNT 0x548 Maximum number of bytes in transmit buffer TXD.MAXCNT 0x548 Maximum number of bytes in transmit buffer TXD.AMOUNT 0x550 EasyDMA list type CNFIG CONFIG 0x554 Configuration register	PUBLISH_ENDRX	0x190		Publish configuration for event ENDRX
PUBLISH_STARTED 0x1CC Publish configuration for event STARTED SHORTS 0x200 Shortcuts between local events and tasks INTENSET 0x304 Enable interrupt INTENCLR 0x308 Disable interrupt ENABLE 0x500 Enable SPIM PSEL.SCK 0x508 Pin select for SCK PSEL.MOSI 0x50C Pin select for MOSI signal PSEL.MISO 0x510 Pin select for MISO signal FREQUENCY 0x524 SPI frequency. Accuracy depends on the HFCLK source selected. RXD.PTR 0x534 Data pointer RXD.MAXCNT 0x538 Maximum number of bytes in receive buffer RXD.AMOUNT 0x53C Number of bytes transferred in the last transaction RXD.PTR 0x540 EasyDMA list type TXD.PTR 0x548 Maximum number of bytes in transmit buffer TXD.MAXCNT 0x548 Maximum number of bytes in transmit buffer TXD.MAXCNT 0x548 Maximum number of bytes in transmit buffer TXD.MAXCNT 0x540 EasyDMA list type TXD.MOUNT 0x540 Number of bytes transferred in the last transaction TXD.MAXCNT 0x540 EasyDMA list type TXD.MAXCNT 0x540 EasyDMA list type CNFIG 0x550 EasyDMA list type CONFIG	PUBLISH_END	0x198		Publish configuration for event END
SHORTS 0x200 Shortcuts between local events and tasks INTENSET 0x304 Enable interrupt INTENCUR 0x308 Disable interrupt ENABLE 0x500 Enable SPIM PSEL.SCK 0x508 Pin select for SCK PSEL.MOSI 0x50C Pin select for MOSI signal PSEL.MISO 0x510 Pin select for MISO signal FREQUENCY 0x524 SPI frequency. Accuracy depends on the HFCLK source selected. RXD.PTR 0x534 Data pointer RXD.MAXCNT 0x538 Maximum number of bytes in receive buffer RXD.AMOUNT 0x540 EasyDMA list type TXD.PTR 0x544 Data pointer TXD.MAXCNT 0x548 Maximum number of bytes in transmit buffer TXD.MAXCNT 0x548 Maximum number of bytes in transmit buffer TXD.MAXCNT 0x548 Maximum number of bytes in transmit buffer TXD.AMOUNT 0x540 EasyDMA list type TXD.AMOUNT 0x540 Number of bytes transferred in the last transaction TXD.MAXCNT 0x548 Maximum number of bytes in transmit buffer TXD.AMOUNT 0x540 Number of bytes transferred in the last transaction TXD.AMOUNT 0x540 Number of bytes transferred in the last transaction TXD.AMOUNT 0x540 Number of bytes transferred in the last transaction TXD.AMOUNT 0x540 Number of bytes transferred in the last transaction TXD.AMOUNT 0x540 Number of bytes transferred in the last transaction TXD.LIST 0x550 EasyDMA list type CONFIG 0x554 Configuration register	PUBLISH_ENDTX	0x1A0		Publish configuration for event ENDTX
INTENSET N304 Enable interrupt NTENCLR Ox308 Disable interrupt ENABLE Ox500 Enable SPIM PSEL.SCK Ox508 Pin select for SCK PSEL.MOSI Ox500 Pin select for MOSI signal PSEL.MISO Ox510 Pin select for MISO signal FREQUENCY Ox524 SPI frequency. Accuracy depends on the HFCLK source selected. RXD.PTR Ox534 Data pointer RXD.MAXCNT Ox538 Maximum number of bytes in receive buffer RXD.AMOUNT Ox540 EasyDMA list type TXD.PTR Ox544 Data pointer TXD.MAXCNT Ox548 Maximum number of bytes in transmit buffer TXD.AMOUNT Ox548 Maximum number of bytes in transmit buffer TXD.AMOUNT Ox54C Number of bytes transferred in the last transaction TXD.LIST Ox550 EasyDMA list type CONFIG OX550 EasyDMA list type CONFIG	PUBLISH_STARTED	0x1CC		Publish configuration for event STARTED
INTENCLR 0x308 Disable interrupt ENABLE 0x500 Enable SPIM PSEL.SCK 0x508 Pin select for SCK PSEL.MOSI 0x50C Pin select for MOSI signal PSEL.MISO 0x510 Pin select for MISO signal FREQUENCY 0x524 SPI frequency. Accuracy depends on the HFCLK source selected. RXD.PTR 0x534 Data pointer RXD.MAXCNT 0x538 Maximum number of bytes in receive buffer RXD.AMOUNT 0x53C Number of bytes transferred in the last transaction RXD.LIST 0x540 EasyDMA list type TXD.MAXCNT 0x548 Maximum number of bytes in transmit buffer TXD.MAXCNT 0x540 Number of bytes transferred in the last transaction TXD.MAXCNT 0x548 Maximum number of bytes in transmit buffer TXD.AMOUNT 0x54C Number of bytes transferred in the last transaction TXD.LIST 0x550 EasyDMA list type CONFIG 0x550 Configuration register	SHORTS	0x200		Shortcuts between local events and tasks
ENABLE 0x500 Enable SPIM PSEL.SCK 0x508 Pin select for SCK PSEL.MOSI 0x50C Pin select for MOSI signal PSEL.MISO 0x510 Pin select for MISO signal FREQUENCY 0x524 SPI frequency. Accuracy depends on the HFCLK source selected. RXD.PTR 0x534 Data pointer RXD.MAXCNT 0x538 Maximum number of bytes in receive buffer RXD.AMOUNT 0x53C Number of bytes transferred in the last transaction RXD.LIST 0x540 EasyDMA list type TXD.PTR 0x544 Data pointer TXD.MAXCNT 0x548 Maximum number of bytes in transmit buffer TXD.AMOUNT 0x54C Number of bytes transferred in the last transaction TXD.LIST 0x550 EasyDMA list type CONFIG 0x554 Configuration register	INTENSET	0x304		Enable interrupt
PSEL.SCK PSEL.MOSI Ox50C Pin select for SCK PSEL.MISO Ox510 Pin select for MISO signal PREQUENCY Ox524 SPI frequency. Accuracy depends on the HFCLK source selected. RXD.PTR Ox534 Data pointer RXD.MAXCNT Ox538 Maximum number of bytes in receive buffer RXD.AMOUNT Ox53C Number of bytes transferred in the last transaction RXD.LIST Ox540 EasyDMA list type TXD.PTR Ox544 Data pointer TXD.MAXCNT Ox548 Maximum number of bytes in transmit buffer TXD.AMOUNT Ox546 Number of bytes transferred in the last transaction TXD.MAXCNT Ox548 Maximum number of bytes in transmit buffer TXD.AMOUNT Ox54C Number of bytes transferred in the last transaction TXD.LIST CONFIG Ox550 EasyDMA list type CONFIG	INTENCLR	0x308		Disable interrupt
PSEL.MOSI PSEL.MISO Ox510 Pin select for MISO signal FREQUENCY Ox524 SPI frequency. Accuracy depends on the HFCLK source selected. RXD.PTR Ox534 Data pointer RXD.MAXCNT Ox538 Maximum number of bytes in receive buffer RXD.AMOUNT Ox53C Number of bytes transferred in the last transaction RXD.PTR TXD.PTR Ox544 Data pointer TXD.PTR Ox545 Maximum number of bytes in transmit buffer TXD.MAXCNT Ox548 Maximum number of bytes in transmit buffer TXD.AMOUNT Ox54C Number of bytes in transmit buffer TXD.LIST Ox550 EasyDMA list type CONFIG Ox554 Configuration register	ENABLE	0x500		Enable SPIM
PSEL.MISO Ox510 Pin select for MISO signal FREQUENCY Ox524 SPI frequency. Accuracy depends on the HFCLK source selected. RXD.PTR Ox534 Data pointer RXD.MAXCNT Ox538 Maximum number of bytes in receive buffer RXD.AMOUNT Ox53C Number of bytes transferred in the last transaction RXD.LIST Ox540 EasyDMA list type TXD.PTR Ox544 Data pointer TXD.MAXCNT Ox548 Maximum number of bytes in transmit buffer TXD.AMOUNT Ox54C Number of bytes in transmit buffer TXD.AMOUNT Ox550 EasyDMA list type CONFIG Ox554 Configuration register	PSEL.SCK	0x508		Pin select for SCK
FREQUENCY Ox524 SPI frequency. Accuracy depends on the HFCLK source selected. RXD.PTR Ox534 Data pointer RXD.MAXCNT Ox538 Maximum number of bytes in receive buffer RXD.AMOUNT Ox53C Number of bytes transferred in the last transaction RXD.LIST Ox540 EasyDMA list type TXD.PTR Ox544 Data pointer TXD.MAXCNT Ox548 Maximum number of bytes in transmit buffer TXD.AMOUNT Ox54C Number of bytes transferred in the last transaction TXD.LIST Ox550 EasyDMA list type CONFIG Ox554 Configuration register	PSEL.MOSI	0x50C		Pin select for MOSI signal
RXD.PTR 0x534 Data pointer RXD.MAXCNT 0x538 Maximum number of bytes in receive buffer RXD.AMOUNT 0x53C Number of bytes transferred in the last transaction RXD.LIST 0x540 EasyDMA list type TXD.PTR 0x544 Data pointer TXD.MAXCNT 0x548 Maximum number of bytes in transmit buffer TXD.AMOUNT 0x54C Number of bytes transferred in the last transaction TXD.LIST 0x550 EasyDMA list type CONFIG 0x554 Configuration register	PSEL.MISO	0x510		Pin select for MISO signal
RXD.MAXCNT 0x538 Maximum number of bytes in receive buffer RXD.AMOUNT 0x53C Number of bytes transferred in the last transaction RXD.LIST 0x540 EasyDMA list type TXD.PTR 0x544 Data pointer TXD.MAXCNT 0x548 Maximum number of bytes in transmit buffer TXD.AMOUNT 0x54C Number of bytes transferred in the last transaction TXD.LIST 0x550 EasyDMA list type CONFIG 0x554 Configuration register	FREQUENCY	0x524		SPI frequency. Accuracy depends on the HFCLK source selected.
RXD.AMOUNT Ox53C Number of bytes transferred in the last transaction RXD.LIST Ox540 EasyDMA list type TXD.PTR Ox544 Data pointer TXD.MAXCNT Ox548 Maximum number of bytes in transmit buffer TXD.AMOUNT Ox54C Number of bytes transferred in the last transaction TXD.LIST Ox550 EasyDMA list type CONFIG Ox554 Configuration register	RXD.PTR	0x534		Data pointer
RXD.LIST Ox540 EasyDMA list type TXD.PTR Ox544 Data pointer TXD.MAXCNT Ox548 Maximum number of bytes in transmit buffer TXD.AMOUNT Ox54C Number of bytes transferred in the last transaction TXD.LIST Ox550 EasyDMA list type CONFIG Ox554 Configuration register	RXD.MAXCNT	0x538		Maximum number of bytes in receive buffer
TXD.PTR 0x544 Data pointer TXD.MAXCNT 0x548 Maximum number of bytes in transmit buffer TXD.AMOUNT 0x54C Number of bytes transferred in the last transaction TXD.LIST 0x550 EasyDMA list type CONFIG 0x554 Configuration register	RXD.AMOUNT	0x53C		Number of bytes transferred in the last transaction
TXD.MAXCNT 0x548 Maximum number of bytes in transmit buffer TXD.AMOUNT 0x54C Number of bytes transferred in the last transaction TXD.LIST 0x550 EasyDMA list type CONFIG 0x554 Configuration register	RXD.LIST	0x540		EasyDMA list type
TXD.AMOUNT 0x54C Number of bytes transferred in the last transaction TXD.LIST 0x550 EasyDMA list type CONFIG 0x554 Configuration register	TXD.PTR	0x544		Data pointer
TXD.LIST 0x550 EasyDMA list type CONFIG 0x554 Configuration register	TXD.MAXCNT	0x548		Maximum number of bytes in transmit buffer
CONFIG 0x554 Configuration register	TXD.AMOUNT	0x54C		Number of bytes transferred in the last transaction
v v	TXD.LIST	0x550		EasyDMA list type
ORC 0x5C0 Over-read character. Character clocked out in case an over-read of the TXD buffer.	CONFIG	0x554		Configuration register
	ORC	0x5C0		Over-read character. Character clocked out in case an over-read of the TXD buffer.

Table 75: Register overview



6.13.6.1 TASKS_START

Address offset: 0x010 Start SPI transaction



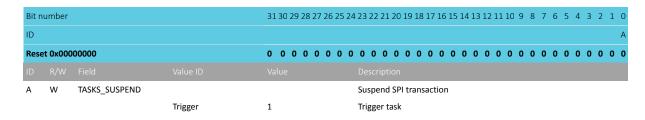
6.13.6.2 TASKS STOP

Address offset: 0x014 Stop SPI transaction

Bit n	umber			31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					А
Rese	t 0x000	00000		0 0 0 0 0 0	$0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \$
ID					
Α	W	TASKS_STOP			Stop SPI transaction
			Trigger		Trigger task

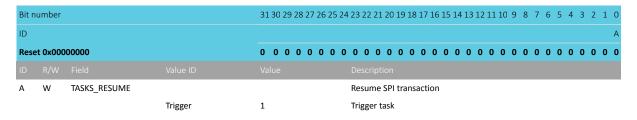
6.13.6.3 TASKS_SUSPEND

Address offset: 0x01C Suspend SPI transaction



6.13.6.4 TASKS_RESUME

Address offset: 0x020 Resume SPI transaction

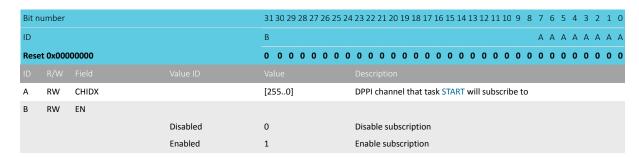


6.13.6.5 SUBSCRIBE_START

Address offset: 0x090



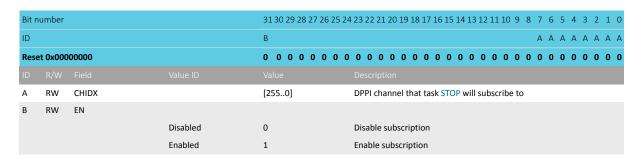
Subscribe configuration for task START



6.13.6.6 SUBSCRIBE_STOP

Address offset: 0x094

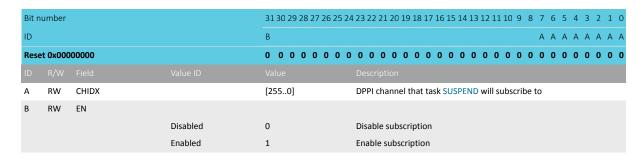
Subscribe configuration for task STOP



6.13.6.7 SUBSCRIBE_SUSPEND

Address offset: 0x09C

Subscribe configuration for task SUSPEND

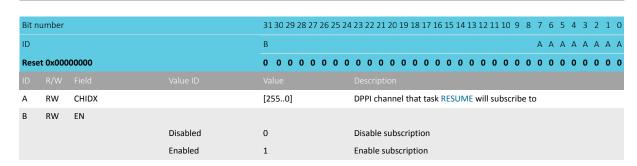


6.13.6.8 SUBSCRIBE_RESUME

Address offset: 0x0A0

Subscribe configuration for task RESUME





6.13.6.9 EVENTS_STOPPED

Address offset: 0x104

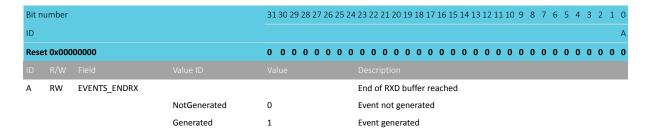
SPI transaction has stopped

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					A
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	EVENTS_STOPPED			SPI transaction has stopped
			NotGenerated	0	Event not generated
			Generated	1	Event generated

6.13.6.10 EVENTS_ENDRX

Address offset: 0x110

End of RXD buffer reached



6.13.6.11 EVENTS END

Address offset: 0x118

End of RXD buffer and TXD buffer reached

Bit n	umber			31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					A
Rese	t 0x000	00000		0 0 0 0 0 0 0	$0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \$
ID					
Α	RW	EVENTS_END			End of RXD buffer and TXD buffer reached
			NotGenerated	0	Event not generated
			Generated	1	Event generated

6.13.6.12 EVENTS_ENDTX

Address offset: 0x120

End of TXD buffer reached





Bit number	21 20 20 20 27	26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
	31 30 29 28 27	20 23 24 23 22 21 20 19 18 17 10 13 14 13 12 11 10 9 8 7 6 3 4 3 2 1 0
ID		Α
Reset 0x00000000	0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID R/W Field Value ID		
A RW EVENTS_ENDTX		End of TXD buffer reached
NotGenerated	0	Event not generated
Generated	1	Event generated

6.13.6.13 EVENTS_STARTED

Address offset: 0x14C
Transaction started

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					А
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	EVENTS_STARTED			Transaction started
			NotGenerated	0	Event not generated
			Generated	1	Event generated

6.13.6.14 PUBLISH_STOPPED

Address offset: 0x184

Publish configuration for event STOPPED

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A A
Reset 0x00000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		
ID					Description
Α	RW	CHIDX		[2550]	DPPI channel that event STOPPED will publish to
A B	RW RW	CHIDX EN		[2550]	DPPI channel that event STOPPED will publish to
		•=	Disabled	0	DPPI channel that event STOPPED will publish to Disable publishing

6.13.6.15 PUBLISH_ENDRX

Address offset: 0x190

Publish configuration for event ENDRX

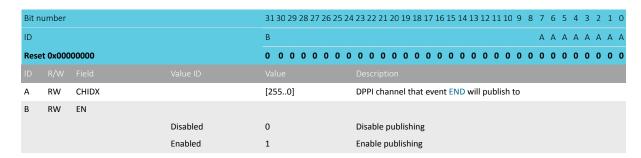
Bit n	umber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2	1 0
ID				В	ААААА	A A
Rese	Reset 0x00000000			0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0
ID						
Α	RW	CHIDX		[2550]	DPPI channel that event ENDRX will publish to	
В	RW	EN				
			Disabled	0	Disable publishing	
			Enabled	1	Enable publishing	

6.13.6.16 PUBLISH_END

Address offset: 0x198



Publish configuration for event END



6.13.6.17 PUBLISH_ENDTX

Address offset: 0x1A0

Publish configuration for event ENDTX

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A
Reset 0x00000000				0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[2550]	DPPI channel that event ENDTX will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing

6.13.6.18 PUBLISH_STARTED

Address offset: 0x1CC

Publish configuration for event STARTED

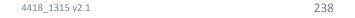
Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Rese	Reset 0x00000000 0			0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[2550]	DPPI channel that event STARTED will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing

6.13.6.19 SHORTS

Address offset: 0x200

Shortcuts between local events and tasks

Bit n	umber			31 30 29 28 27 2	6 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					А
Rese	t 0x000	00000		0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	END_START			Shortcut between event END and task START
			Disabled	0	Disable shortcut
			Enabled	1	Enable shortcut





6.13.6.20 INTENSET

Address offset: 0x304

Enable interrupt

Bit nu	ımber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					E D C B A
Reset	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	STOPPED			Write '1' to enable interrupt for event STOPPED
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
В	RW	ENDRX			Write '1' to enable interrupt for event ENDRX
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
С	RW	END			Write '1' to enable interrupt for event END
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
D	RW	ENDTX			Write '1' to enable interrupt for event ENDTX
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
E	RW	STARTED			Write '1' to enable interrupt for event STARTED
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled

6.13.6.21 INTENCLR

Address offset: 0x308

Disable interrupt

Bit r	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					E D C B A
Rese	et 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	STOPPED			Write '1' to disable interrupt for event STOPPED
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
В	RW	ENDRX			Write '1' to disable interrupt for event ENDRX
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
С	RW	END			Write '1' to disable interrupt for event END
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
D	RW	ENDTX			Write '1' to disable interrupt for event ENDTX
			Clear	1	Disable



Bit number	31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		E D C B A
Reset 0x00000000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID R/W Field Value ID		Description
Disabled	0	Read: Disabled
Enabled	1	Read: Enabled
E RW STARTED		Write '1' to disable interrupt for event STARTED
Clear	1	Disable
Disabled	0	Read: Disabled
Enabled	1	Read: Enabled

6.13.6.22 ENABLE

Address offset: 0x500

Enable SPIM

Bit n	umber			31 30 29 28 2	7 26 25 24 2	23 22 21	20 19	18 1	7 16	15 1	4 13 :	12 1:	1 10	9 8	7	6	5	4 3	3 2	1 0
ID																		Å	4 A	A A
Rese	t 0x000	00000		0 0 0 0 0	0 0 0	0 0 0	0 0	0	0 0	0 0	0	0 0	0	0 0	0	0	0	0 (0	0 0
ID																				
Α	RW	ENABLE			-	Enable o	or disa	ble S	PIM											
			Disabled	0	1	Disable :	SPIM													
			Enabled	7	1	Enable S	SPIM													

6.13.6.23 PSEL.SCK

Address offset: 0x508

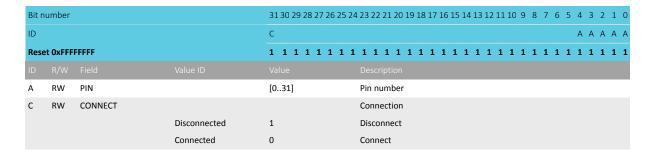
Pin select for SCK

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				С	АААА
Rese	et OxFFF	FFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID					Description
Α	RW	PIN		[031]	Pin number
С	RW	CONNECT			Connection
			Disconnected	1	Disconnect
			Connected	0	Connect

6.13.6.24 PSEL.MOSI

Address offset: 0x50C

Pin select for MOSI signal



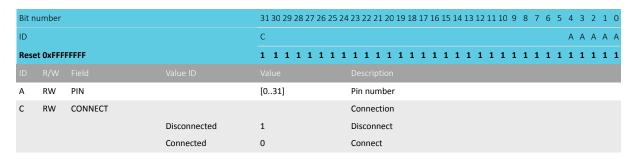




6.13.6.25 PSEL.MISO

Address offset: 0x510

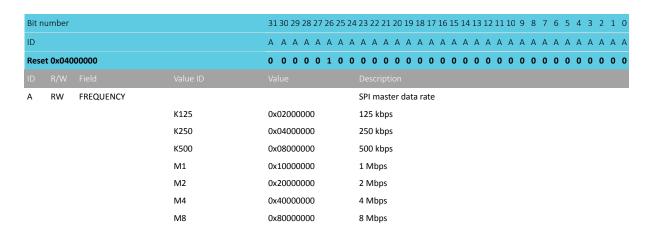
Pin select for MISO signal



6.13.6.26 FREQUENCY

Address offset: 0x524

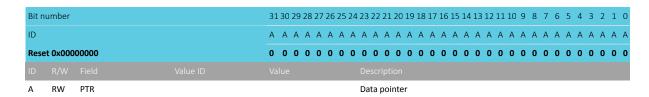
SPI frequency. Accuracy depends on the HFCLK source selected.



6.13.6.27 RXD.PTR

Address offset: 0x534

Data pointer

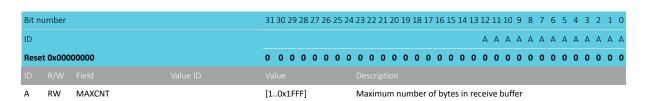


Note: See the memory chapter for details about which memories are available for EasyDMA.

6.13.6.28 RXD.MAXCNT

Address offset: 0x538

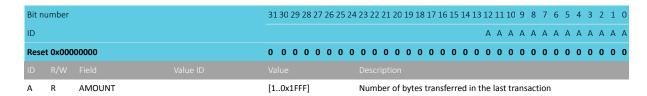
Maximum number of bytes in receive buffer



6.13.6.29 RXD.AMOUNT

Address offset: 0x53C

Number of bytes transferred in the last transaction



6.13.6.30 RXD.LIST

Address offset: 0x540 EasyDMA list type



6.13.6.31 TXD.PTR

Address offset: 0x544

Data pointer



Note: See the memory chapter for details about which memories are available for EasyDMA.

6.13.6.32 TXD.MAXCNT

Address offset: 0x548

Maximum number of bytes in transmit buffer



A RW MAXCNT	[10x1FFF] Maximum number of bytes	s in transmit buffer
ID R/W Field Value ID		
Reset 0x00000000	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	$0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \$
ID		A A A A A A A A A A A A
Bit number	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15	14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

6.13.6.33 TXD.AMOUNT

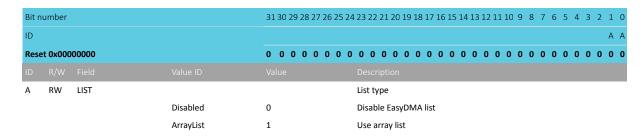
Address offset: 0x54C

Number of bytes transferred in the last transaction

Α	R	AMOUNT	[10x1FFF]	Number of bytes transferred in the last transaction
ID				
Res	et 0x000	00000	0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				A A A A A A A A A A A A A A A A A A A
Bit r	number		31 30 29 28 27 26 2	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

6.13.6.34 TXD.LIST

Address offset: 0x550 EasyDMA list type



6.13.6.35 CONFIG

Address offset: 0x554 Configuration register

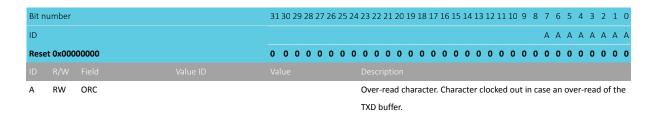
Bit r	number			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					СВА
Rese	et 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	ORDER			Bit order
			MsbFirst	0	Most significant bit shifted out first
			LsbFirst	1	Least significant bit shifted out first
В	RW	СРНА			Serial clock (SCK) phase
			Leading	0	Sample on leading edge of clock, shift serial data on trailing edge
			Trailing	1	Sample on trailing edge of clock, shift serial data on leading edge
С	RW	CPOL			Serial clock (SCK) polarity
			ActiveHigh	0	Active high
			ActiveLow	1	Active low

6.13.6.36 ORC

Address offset: 0x5C0



Over-read character. Character clocked out in case an over-read of the TXD buffer.



6.13.7 Electrical specification

6.13.7.1 SPIM master interface electrical specifications

Symbol	Description	Min.	Тур.	Max.	Units
f _{SPIM}	Bit rates for SPIM ¹⁵			8	Mbps
t _{SPIM,START}	Time from START task to transmission started		1		μs

6.13.7.2 Serial Peripheral Interface Master (SPIM) timing specifications



High bit rates may require GPIOs to be set as High Drive, see GPIO chapter for more details.

^a At 25pF load, including GPIO pin capacitance, see GPIO spec.

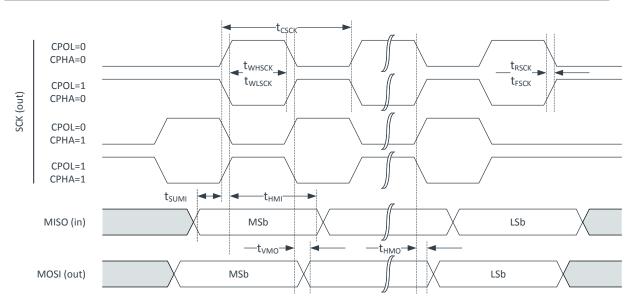


Figure 75: SPIM timing diagram

6.14 SPIS — Serial peripheral interface slave with EasyDMA

SPI slave (SPIS) is implemented with EasyDMA support for ultra low power serial communication from an external SPI master. EasyDMA in conjunction with hardware-based semaphore mechanisms removes all real-time requirements associated with controlling the SPI slave from a low priority CPU execution context.

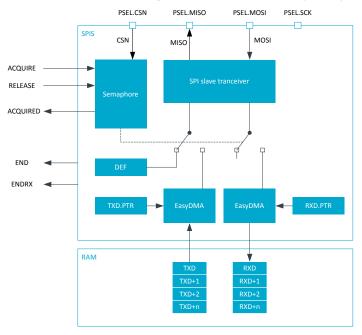


Figure 76: SPI slave

The SPIS supports SPI modes 0 through 3. The CONFIG register allows setting CPOL and CPHA appropriately.



Mode	Clock polarity	Clock phase
	CPOL	СРНА
SPI_MODE0	0 (Active High)	0 (Trailing Edge)
SPI_MODE1	0 (Active High)	1 (Leading Edge)
SPI_MODE2	1 (Active Low)	0 (Trailing Edge)
SPI_MODE3	1 (Active Low)	1 (Leading Edge)

Table 76: SPI modes

6.14.1 Shared resources

The SPI slave shares registers and other resources with other peripherals that have the same ID as the SPI slave. Therefore, you must disable all peripherals that have the same ID as the SPI slave before the SPI slave can be configured and used.

Disabling a peripheral that has the same ID as the SPI slave will not reset any of the registers that are shared with the SPI slave. It is important to configure all relevant SPI slave registers explicitly to secure that it operates correctly.

The Instantiation table in Instantiation on page 26 shows which peripherals have the same ID as the SPI slave.

6.14.2 EasyDMA

The SPIS implements EasyDMA for accessing RAM without CPU involvement.

The SPIS peripheral implements the following EasyDMA channels:

Channel	Туре	Register Cluster
TXD	READER	TXD
RXD	WRITER	RXD

Table 77: SPIS EasyDMA Channels

For detailed information regarding the use of EasyDMA, see EasyDMA on page 47.

If RXD.MAXCNT is larger than TXD.MAXCNT, the remaining transmitted bytes will contain the value defined in the ORC register.

The END event indicates that EasyDMA has finished accessing the buffer in RAM.

6.14.3 SPI slave operation

SPI slave uses two memory pointers, RXD.PTR and TXD.PTR, that point to the RXD buffer (receive buffer) and TXD buffer (transmit buffer) respectively. Since these buffers are located in RAM, which can be accessed by both the SPI slave and the CPU, a hardware based semaphore mechanism is implemented to enable safe sharing.

Before the CPU can safely update the RXD.PTR and TXD.PTR pointers it must first acquire the SPI semaphore. The CPU can acquire the semaphore by triggering the ACQUIRE task and then receiving the ACQUIRED event. When the CPU has updated the RXD.PTR and TXD.PTR pointers the CPU must release the semaphore before the SPI slave will be able to acquire it.

The CPU releases the semaphore by triggering the RELEASE task, this is illustrated in SPI transaction when shortcut between END and ACQUIRE is enabled on page 247. Triggering the RELEASE task when the semaphore is not granted to the CPU will have no effect. See Semaphore operation on page 248 for more information



If the CPU is not able to reconfigure the TXD.PTR and RXD.PTR between granted transactions, the same TX data will be clocked out and the RX buffers will be overwritten. To prevent this from happening, the END_ACQUIRE shortcut can be used. With this shortcut enabled the semaphore will be handed over to the CPU automatically after the granted transaction has completed, giving the CPU the ability to update the TXPTR and RXPTR between every granted transaction.

The ENDRX event is generated when the RX buffer has been filled.

The RXD.MAXCNT register specifies the maximum number of bytes the SPI slave can receive in one granted transaction. If the SPI slave receives more than RXD.MAXCNT number of bytes, an OVERFLOW will be indicated in the STATUS register and the incoming bytes will be discarded.

The TXD.MAXCNT parameter specifies the maximum number of bytes the SPI slave can transmit in one granted transaction. If the SPI slave is forced to transmit more than TXD.MAXCNT number of bytes, an OVERREAD will be indicated in the STATUS register and the ORC character will be clocked out.

The RXD.AMOUNT and TXD.AMOUNT registers are updated when a granted transaction is completed. The TXD.AMOUNT register indicates how many bytes were read from the TX buffer in the last transaction, that is, ORC (over-read) characters are not included in this number. Similarly, the RXD.AMOUNT register indicates how many bytes were written into the RX buffer in the last transaction.

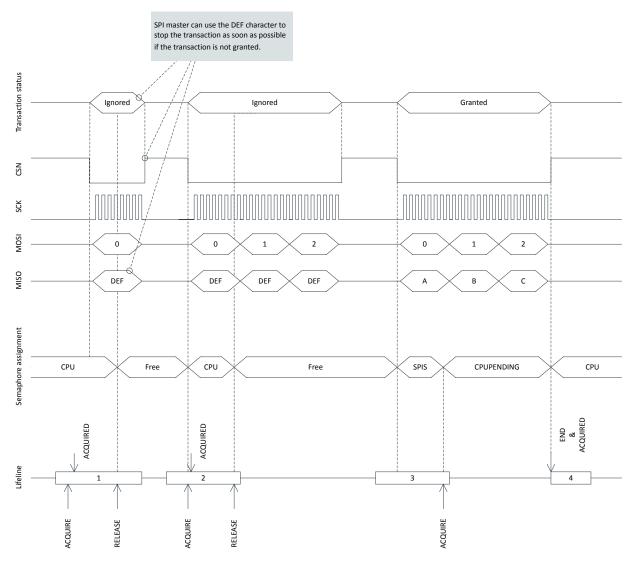


Figure 77: SPI transaction when shortcut between END and ACQUIRE is enabled



6.14.4 Semaphore operation

The semaphore is a mechanism implemented inside the SPI slave that prevents simultaneous access to the data buffers by the SPI slave and CPU.

The semaphore is by default assigned to the CPU after the SPI slave is enabled. No ACQUIRED event will be generated for this initial semaphore handover. An ACQUIRED event will be generated immediately if the ACQUIRE task is triggered while the semaphore is assigned to the CPU. The figure SPI semaphore FSM on page 248 illustrates the transitions between states in the semaphore based on the relevant tasks and events.

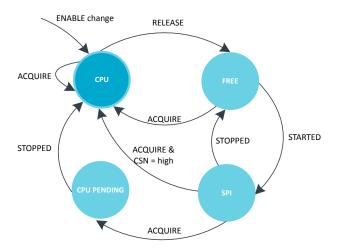


Figure 78: SPI semaphore FSM

Note: The semaphore mechanism does not, at any time, prevent the CPU from performing read or write access to the RXD.PTR register, the TXD.PTR registers, or the RAM that these pointers are pointing to. The semaphore is only telling when these can be updated by the CPU so that safe sharing is achieved.

The SPI slave will try to acquire the semaphore when STARTED event is detected, the even also indicates that CSN is currently low. If the SPI slave does not manage to acquire the semaphore at this point (i.e., it is under CPU's control), the transaction will be ignored. This means that all incoming data on MOSI will be discarded, and the DEF (default) character will be clocked out on the MISO line throughout the whole transaction. This will also be the case even if the semaphore is released by the CPU during the transaction. In case of a race condition where the CPU and the SPI slave try to acquire the semaphore at the same time, as illustrated in lifeline item 2 in figure SPI transaction when shortcut between END and ACQUIRE is enabled on page 247, the semaphore will be granted to the CPU.

If the SPI slave acquires the semaphore, the transaction will be granted. The incoming data on MOSI will be stored in the RXD buffer and the data in the TXD buffer will be clocked out on MISO.

When a granted transaction is completed and CSN goes high, the SPI slave will automatically release the semaphore and generate the END event.

As long as the semaphore is available, the SPI slave can be granted multiple transactions one after the other.

If the CPU tries to acquire the semaphore while it is assigned to the SPI slave, an immediate handover will not be granted. However, the semaphore will be handed over to the CPU as soon as the SPI slave has released the semaphore after the granted transaction is completed. If the END ACQUIRE shortcut is enabled and the CPU has triggered the ACQUIRE task during a granted transaction, only one ACQUIRE request will be served following the END event.

4418 1315 v2.1 248



6.14.5 Pin configuration

The CSN, SCK, MOSI, and MISO signals associated with the SPI slave are mapped to physical pins according to the configuration specified in the PSEL.CSN, PSEL.SCK, PSEL.MOSI, and PSEL.MISO registers respectively. If the CONNECT field of any of these registers is set to Disconnected, the associated SPI slave signal will not be connected to any physical pins.

The PSEL.CSN, PSEL.SCK, PSEL.MOSI, and PSEL.MISO registers and their configurations are only used as long as the SPI slave is enabled, and retained only as long as the device is in System ON mode, see POWER — Power control on page 68 chapter for more information about power modes. When the peripheral is disabled, the pins will behave as regular GPIOs, and use the configuration in their respective OUT bit field and PIN_CNF[n] register. PSEL.CSN, PSEL.SCK, PSEL.MOSI, and PSEL.MISO must only be configured when the SPI slave is disabled.

To secure correct behavior in the SPI slave, the pins used by the SPI slave must be configured in the GPIO peripheral as described in GPIO configuration before enabling peripheral on page 249 before enabling the SPI slave. This is to secure that the pins used by the SPI slave are driven correctly if the SPI slave itself is temporarily disabled, or if the device temporarily enters System OFF. This configuration must be retained in the GPIO for the selected I/Os as long as the SPI slave is to be recognized by an external SPI master.

The MISO line is set in high impedance as long as the SPI slave is not selected with CSN.

Only one peripheral can be assigned to drive a particular GPIO pin at a time. Failing to do so may result in unpredictable behavior.

SPI signal	SPI pin	Direction	Output value Comment
CSN	As specified in PSEL.CSN	Input	Not applicable
SCK	As specified in PSEL.SCK	Input	Not applicable
MOSI	As specified in PSEL.MOSI	Input	Not applicable
MISO	As specified in PSEL.MISO	Input	Not applicable Emulates that the SPI slave is not selected.

Table 78: GPIO configuration before enabling peripheral

6.14.6 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x50008000	CDIC	SPIS0 : S	US	SA	SPI slave 0	
0x40008000	SPIS	SPISO: NS	US	SA	SPI Slave U	
0x50009000	SPIS	SPIS1:S	US	SA	SPI slave 1	
0x40009000	3113	SPIS1 : NS	US	SA	SPI Sidve 1	
0x5000A000	SPIS	SPIS2 : S	US	SA	SPI slave 2	
0x4000A000	3113	SPIS2 : NS	US	SA	ori siave 2	
0x5000B000	SPIS	SPIS3:S	US	SA	SPI slave 3	
0x4000B000	3113	SPIS3 : NS	03	SA	ori siave o	

Table 79: Instances

Register	Offset	Security	Description
TASKS_ACQUIRE	0x024		Acquire SPI semaphore
TASKS_RELEASE	0x028		Release SPI semaphore, enabling the SPI slave to acquire it
SUBSCRIBE_ACQUIRE	0x0A4		Subscribe configuration for task ACQUIRE
SUBSCRIBE_RELEASE	0x0A8		Subscribe configuration for task RELEASE
EVENTS_END	0x104		Granted transaction completed
EVENTS_ENDRX	0x110		End of RXD buffer reached
EVENTS_ACQUIRED	0x128		Semaphore acquired





Register	Offset	Security	Description
PUBLISH_END	0x184		Publish configuration for event END
PUBLISH_ENDRX	0x190		Publish configuration for event ENDRX
PUBLISH_ACQUIRED	0x1A8		Publish configuration for event ACQUIRED
SHORTS	0x200		Shortcuts between local events and tasks
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
SEMSTAT	0x400		Semaphore status register
STATUS	0x440		Status from last transaction
ENABLE	0x500		Enable SPI slave
PSEL.SCK	0x508		Pin select for SCK
PSEL.MISO	0x50C		Pin select for MISO signal
PSEL.MOSI	0x510		Pin select for MOSI signal
PSEL.CSN	0x514		Pin select for CSN signal
PSELSCK	0x508		Pin select for SCK
			This register is deprecated.
PSELMISO	0x50C		Pin select for MISO
			This register is deprecated.
PSELMOSI	0x510		Pin select for MOSI
			This register is deprecated.
PSELCSN	0x514		Pin select for CSN
			This register is deprecated.
RXD.PTR	0x534		RXD data pointer
RXD.MAXCNT	0x538		Maximum number of bytes in receive buffer
RXD.AMOUNT	0x53C		Number of bytes received in last granted transaction
RXD.LIST	0x540		EasyDMA list type
RXDPTR	0x534		RXD data pointer
			This register is deprecated.
MAXRX	0x538		Maximum number of bytes in receive buffer
	0,000		
			This register is deprecated.
AMOUNTRX	0x53C		Number of bytes received in last granted transaction
			This register is deprecated.
TXD.PTR	0x544		TXD data pointer
TXD.MAXCNT	0x548		Maximum number of bytes in transmit buffer
TXD.AMOUNT	0x54C		Number of bytes transmitted in last granted transaction
TXD.LIST	0x550		EasyDMA list type
TXDPTR	0x544		TXD data pointer
			This register is deprecated.
MAXTX	0x548		Maximum number of bytes in transmit buffer
			This register is deprecated.
AMOUNTTX	0x54C		Number of bytes transmitted in last granted transaction
AMOUNTA	0,340		
			This register is deprecated.
CONFIG	0x554		Configuration register
DEF	0x55C		Default character. Character clocked out in case of an ignored transaction.
ORC	0x5C0		Over-read character

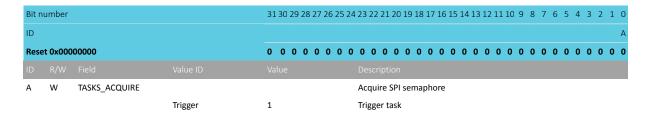
Table 80: Register overview

6.14.6.1 TASKS_ACQUIRE

Address offset: 0x024



Acquire SPI semaphore



6.14.6.2 TASKS_RELEASE

Address offset: 0x028

Release SPI semaphore, enabling the SPI slave to acquire it

Bit number ID				31 30 29 28 27 2	6 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
					А
Rese	Reset 0x00000000			0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	W	TASKS_RELEASE			Release SPI semaphore, enabling the SPI slave to acquire it
			Trigger	1	Trigger task

6.14.6.3 SUBSCRIBE_ACQUIRE

Address offset: 0x0A4

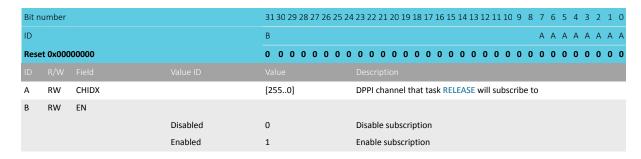
Subscribe configuration for task ACQUIRE

Bit number				31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset 0x00000000				0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[2550]	DPPI channel that task ACQUIRE will subscribe to
В	RW	EN			
			Disabled	0	Disable subscription
			Enabled	1	Enable subscription

6.14.6.4 SUBSCRIBE RELEASE

Address offset: 0x0A8

Subscribe configuration for task RELEASE



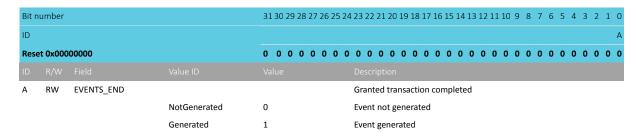
6.14.6.5 EVENTS_END

Address offset: 0x104





Granted transaction completed



6.14.6.6 EVENTS ENDRX

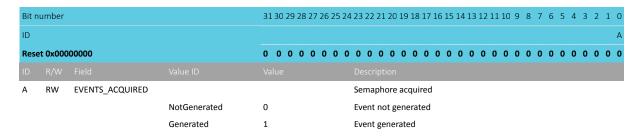
Address offset: 0x110

End of RXD buffer reached

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					A
Rese	Reset 0x00000000			0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	EVENTS_ENDRX			End of RXD buffer reached
			NotGenerated	0	Event not generated
			Generated	1	Event generated

6.14.6.7 EVENTS_ACQUIRED

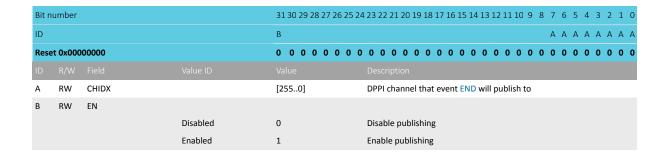
Address offset: 0x128 Semaphore acquired



6.14.6.8 PUBLISH END

Address offset: 0x184

Publish configuration for event END



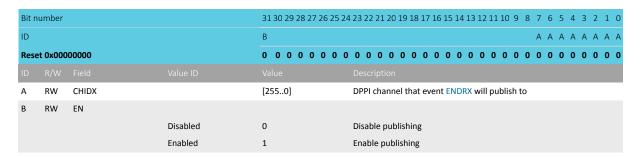




6.14.6.9 PUBLISH_ENDRX

Address offset: 0x190

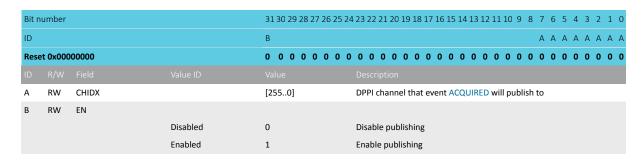
Publish configuration for event ENDRX



6.14.6.10 PUBLISH_ACQUIRED

Address offset: 0x1A8

Publish configuration for event ACQUIRED



6.14.6.11 SHORTS

Address offset: 0x200

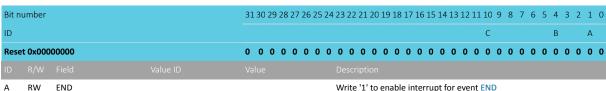
Shortcuts between local events and tasks

Bit r	umber			31 30 29 28 27	26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					A
Rese	et 0x000	00000		0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	END_ACQUIRE			Shortcut between event END and task ACQUIRE
			Disabled	0	Disable shortcut
			Enabled	1	Enable shortcut

6.14.6.12 INTENSET

Address offset: 0x304

Enable interrupt



Write '1' to enable interrupt for event END



Bit n	umber			31 30 29 28 27 26 25 24	1 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					C B A
Reset 0x00000000			0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	
					Description
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
В	RW	ENDRX			Write '1' to enable interrupt for event ENDRX
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
С	RW	ACQUIRED			Write '1' to enable interrupt for event ACQUIRED
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled

6.14.6.13 INTENCLR

Address offset: 0x308

Disable interrupt

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					C B A
Rese	Reset 0x00000000			0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	END			Write '1' to disable interrupt for event END
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
В	RW	ENDRX			Write '1' to disable interrupt for event ENDRX
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
С	RW	ACQUIRED			Write '1' to disable interrupt for event ACQUIRED
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled

6.14.6.14 SEMSTAT

Address offset: 0x400 Semaphore status register

Bit n	umber			31 30 29 28 27	26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					A A
Rese	Reset 0x00000001		0 0 0 0 0	$\begin{smallmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 $	
ID					
Α	R	SEMSTAT			Semaphore status
			Free	0	Semaphore is free
			CPU	1	Semaphore is assigned to CPU
			SPIS	2	Semaphore is assigned to SPI slave
			CPUPending	3	Semanhore is assigned to SPI but a handover to the CPII is pending





6.14.6.15 STATUS

Address offset: 0x440

Status from last transaction

Note: Individual bits are cleared by writing a '1' to the bits that shall be cleared

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					ВА
Rese	et 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	OVERREAD			TX buffer over-read detected, and prevented
			NotPresent	0	Read: error not present
			Present	1	Read: error present
			Clear	1	Write: clear error on writing '1'
В	RW	OVERFLOW			RX buffer overflow detected, and prevented
			NotPresent	0	Read: error not present
			Present	1	Read: error present
			Clear	1	Write: clear error on writing '1'

6.14.6.16 ENABLE

Address offset: 0x500

Enable SPI slave

Bit no	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					АААА
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	ENABLE			Enable or disable SPI slave
			Disabled	0	Disable SPI slave
			Enabled	2	Enable SPI slave

6.14.6.17 PSEL.SCK

Address offset: 0x508

Pin select for SCK

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				С	АААА
Rese	t OxFFF	FFFFF		1 1 1 1 1 1 1 1	. 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID					
Α	RW	PIN		[031]	Pin number
		1114		[031]	riii iluliibei
С	RW	CONNECT		[031]	Connection
С	RW		Disconnected	1	

6.14.6.18 PSEL.MISO

Address offset: 0x50C

Pin select for MISO signal





Bit n	umber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				С	АААА
Rese	t OxFFF	FFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID					
Α	RW	PIN		[031]	Pin number
С	RW	CONNECT			Connection
			Disconnected	1	Disconnect
			Connected	0	Connect

6.14.6.19 PSEL.MOSI

Address offset: 0x510

Pin select for MOSI signal

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				С	АААА
Rese	t OxFFFI	FFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID					Description
Α	RW	PIN		[031]	Pin number
С	RW	CONNECT			Connection
			Disconnected	1	Disconnect
			Connected	0	Connect

6.14.6.20 PSEL.CSN

Address offset: 0x514
Pin select for CSN signal

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				С	АААА
Rese	t OxFFF	FFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID					
Α	RW	PIN		[031]	Pin number
C	RW	PIN CONNECT		[031]	Pin number Connection
С			Disconnected	[031]	

6.14.6.21 PSELSCK (Deprecated)

Address offset: 0x508

Pin select for SCK

This register is deprecated.



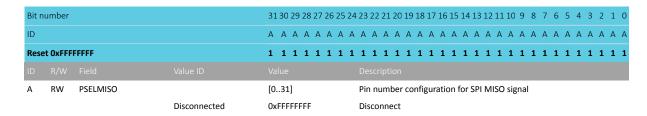




6.14.6.22 PSELMISO (Deprecated)

Address offset: 0x50C Pin select for MISO

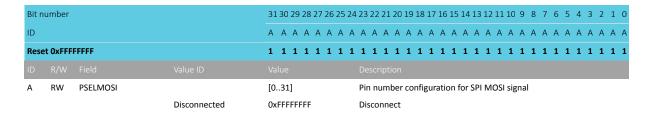
This register is deprecated.



6.14.6.23 PSELMOSI (Deprecated)

Address offset: 0x510
Pin select for MOSI

This register is deprecated.

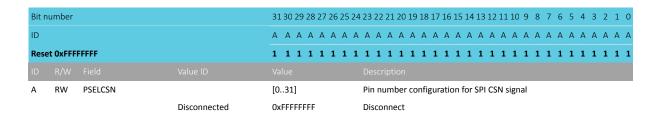


6.14.6.24 PSELCSN (Deprecated)

Address offset: 0x514

Pin select for CSN

This register is deprecated.

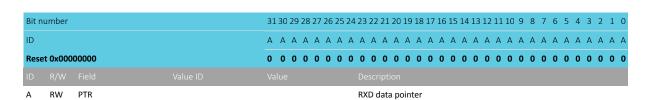


6.14.6.25 RXD.PTR

Address offset: 0x534

RXD data pointer



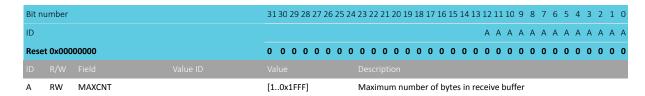


Note: See the memory chapter for details about which memories are available for EasyDMA.

6.14.6.26 RXD.MAXCNT

Address offset: 0x538

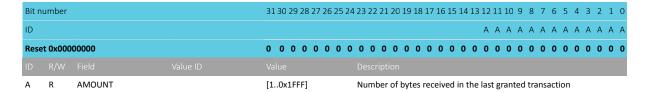
Maximum number of bytes in receive buffer



6.14.6.27 RXD.AMOUNT

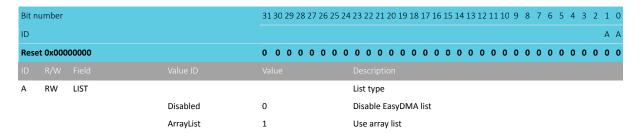
Address offset: 0x53C

Number of bytes received in last granted transaction



6.14.6.28 RXD.LIST

Address offset: 0x540 EasyDMA list type



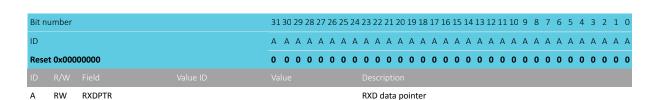
6.14.6.29 RXDPTR (Deprecated)

Address offset: 0x534

RXD data pointer

This register is deprecated.





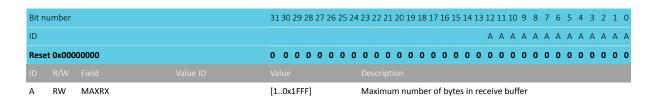
Note: See the memory chapter for details about which memories are available for EasyDMA.

6.14.6.30 MAXRX (Deprecated)

Address offset: 0x538

Maximum number of bytes in receive buffer

This register is deprecated.

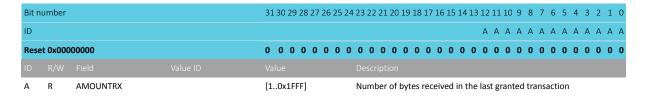


6.14.6.31 AMOUNTRX (Deprecated)

Address offset: 0x53C

Number of bytes received in last granted transaction

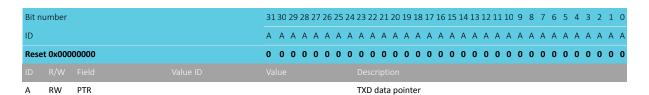
This register is deprecated.



6.14.6.32 TXD.PTR

Address offset: 0x544

TXD data pointer



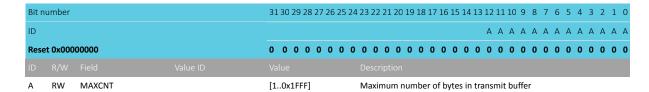
Note: See the memory chapter for details about which memories are available for EasyDMA.

6.14.6.33 TXD.MAXCNT

Address offset: 0x548



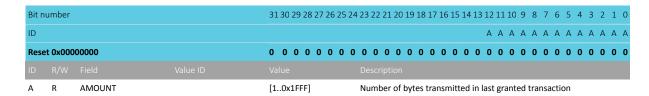
Maximum number of bytes in transmit buffer



6.14.6.34 TXD.AMOUNT

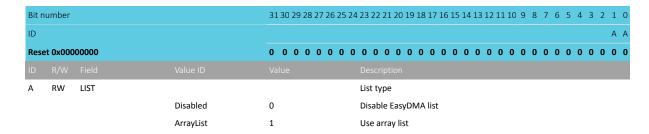
Address offset: 0x54C

Number of bytes transmitted in last granted transaction



6.14.6.35 TXD.LIST

Address offset: 0x550
EasyDMA list type

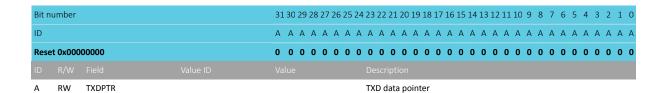


6.14.6.36 TXDPTR (Deprecated)

Address offset: 0x544

TXD data pointer

This register is deprecated.



Note: See the memory chapter for details about which memories are available for EasyDMA.

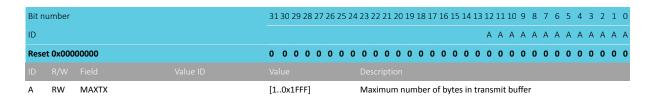
6.14.6.37 MAXTX (Deprecated)

Address offset: 0x548



Maximum number of bytes in transmit buffer

This register is deprecated.

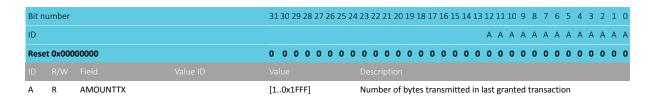


6.14.6.38 AMOUNTTX (Deprecated)

Address offset: 0x54C

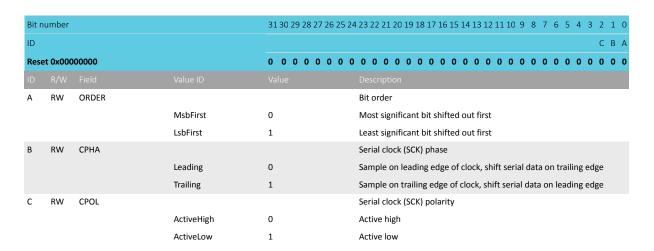
Number of bytes transmitted in last granted transaction

This register is deprecated.



6.14.6.39 CONFIG

Address offset: 0x554 Configuration register

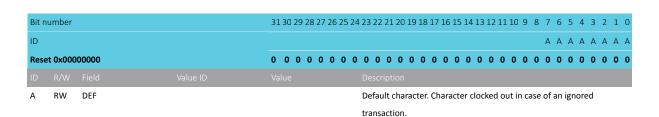


6.14.6.40 DEF

Address offset: 0x55C

Default character. Character clocked out in case of an ignored transaction.

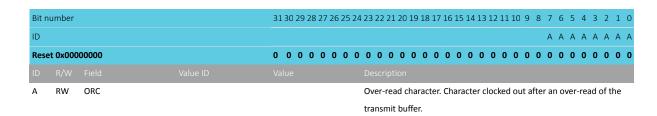




6.14.6.41 ORC

Address offset: 0x5C0

Over-read character



6.14.7 Electrical specification

6.14.7.1 SPIS slave interface electrical specifications

Symbol	Description	Min.	Тур.	Max.	Units
f _{SPIS}	Bit rates for SPIS ¹⁶			8 ¹⁷	Mbps
t _{SPIS,START}	Time from RELEASE task to receive/transmit (CSN active)		0.125		μs

6.14.7.2 Serial Peripheral Interface Slave (SPIS) timing specifications

$t_{SPIS,CSCKIN}$ SCK input period 125 ns $t_{SPIS,RFSCKIN}$ SCK input rise/fall time 30 ns	
t _{SPIS,RFSCKIN} SCK input rise/fall time 30 ns	
t _{SPIS,WHSCKIN} SCK input high time 30 ns	
t _{SPIS,WLSCKIN} SCK input low time 30 ns	
t _{SPIS,SUCSN} CSN to CLK setup time 1000 ns	
t _{SPIS,HCSN} CLK to CSN hold time 2000 ns	
t _{SPIS,ASA} CSN to MISO driven 0 ns	
t _{SPIS,ASO} CSN to MISO valid ^a 1000 ns	
t _{SPIS,DISSO} CSN to MISO disabled ^a 68 ns	
t _{SPIS,CWH} CSN inactive time 300 ns	
t _{SPIS,VSO} CLK edge to MISO valid 59 ns	
t _{SPIS,HSO} MISO hold time after CLK edge 20 ¹⁸ ns	
t _{SPIS,SUSI} MOSI to CLK edge setup time 19 ns	
t _{SPIS,HSI} CLK edge to MOSI hold time 18 ns	

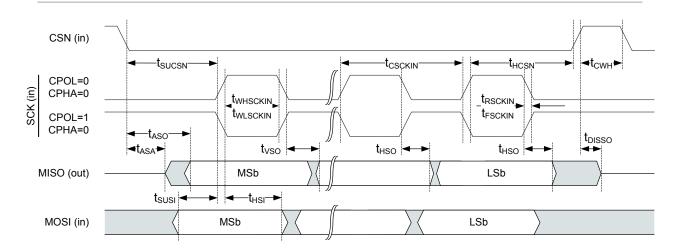
 $^{^{16}\,}$ High bit rates may require GPIOs to be set as High Drive, see GPIO chapter for more details.



The actual maximum data rate depends on the master's CLK to MISO and MOSI setup and hold timings

^a At 25pF load, including GPIO capacitance, see GPIO spec.

 $^{^{18}\,}$ This is to ensure compatibility to SPI masters sampling MISO on the same edge as MOSI is output



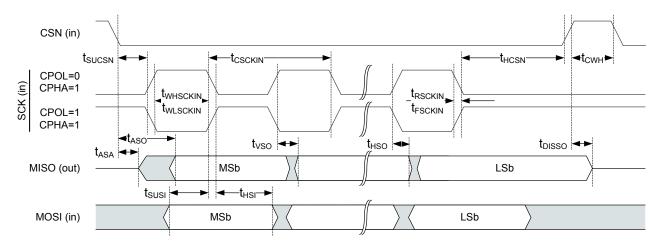


Figure 79: SPIS timing diagram

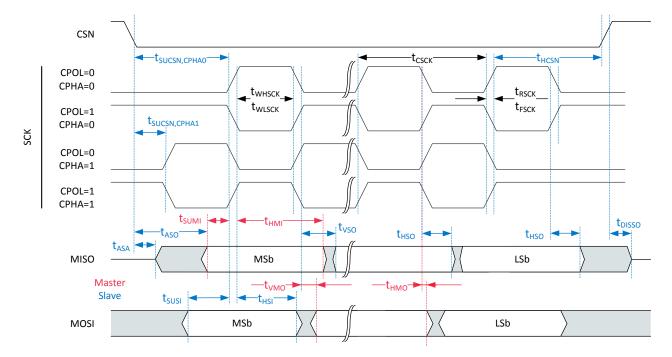


Figure 80: Common SPIM and SPIS timing diagram



6.15 SPU — System protection unit

SPU is the central point in the system to control access to memories, peripherals and other resources.

Listed here are the main features of the SPU:

- ARM TrustZone support, allowing definition of secure, non-secure and non-secure callable memory regions
- Extended ARMTrustZone, protecting memory regions and peripherals from non-CPU devices like EasyDMA transfer
- Pin access protection, preventing non-secure code and peripherals from accessing secure pin resources
- DPPI access protection, realized by preventing non-secure code and peripherals to publish from or subscribe to secured DPPI channels
- External domain access protection, controlling access rights from other MCUs

6.15.1 General concepts

SPU provides a register interface to control the various internal logic blocks that monitor access to memory-mapped slave devices (RAM, flash, peripherals, etc) and other resources (device pins, DPPI channels, etc).

For memory-mapped devices like RAM, flash and peripherals, the internal logic checks the address and attributes (e.g. read, write, execute, secure) of the incoming transfer to block it if necessary. Whether a secure resource can be accessed by a given master is defined:

For a CPU-type master

By the security state of the CPU and the security state reported by the SPU, for the address in the bus transfer

For a non-CPU master

By the security attribute of the master that initiates the transfer, defined by a SPU register The Simplified view of the protection of RAM, flash and peripherals using SPU on page 264 shows a simplified view of the SPU registers controlling several internal modules.

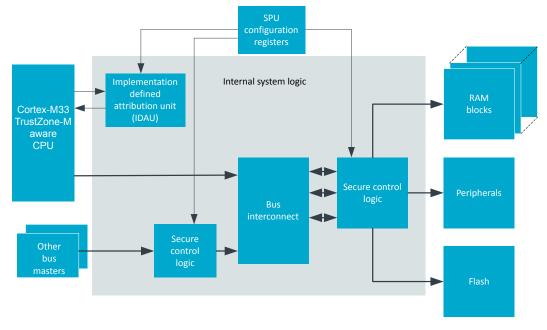


Figure 81: Simplified view of the protection of RAM, flash and peripherals using SPU

The protection logic implements a read-as-zero/write-ignore (RAZ/WI) policy:



- A blocked read operation will always return a zero value on the bus, preventing information leak
- A write operation to a forbidden region or peripheral will be ignored

An error is reported through dedicated error signals. For security state violations from an M33 master this will be a SecureFault exception, for other violations this will be an SPU event. The SPU event can be configured to generate an interrupt towards the CPU.

Other resources like pins and DPPI channels are protected by comparing the security attributes of the protected resource with the security attribute of the peripheral that wants to access it. The SPU is the only place where those security attributes can be configured.

6.15.1.1 Special considerations for ARM TrustZone for Cortex-M enabled system

For a ARM TrustZone for Cortex-M enabled CPU, the SPU also controls custom logic.

Custom logic is shown as the implementation defined attribution unit (IDAU) in figure Simplified view of the protection of RAM, flash and peripherals using SPU on page 264. Full support is provided for:

- ARM TrustZone for Cortex-M related instructions, like test target (TT) for reporting the security attributes of a region
- Non-secure callable (NSC) regions, to implement secure entry points from non-secure code

The SPU provides the necessary registers to configure the security attributes for memory regions and peripherals. However, as a requirement to use the SPU, the secure attribution unit (SAU) needs to be disabled and all memory set as non-secure in the ARM core. This will allow the SPU to control the IDAU and set the security attribution of all addresses as originally intended.

6.15.2 Flash access control

The flash memory space is divided in regions, each of them with configurable permissions settings.

The flash memory space is divided into 32 regions of 32 KiB.

For each region, four different types of permissions can be configured:

Read

Allows data read access to the region. Note that code fetch from this region is not controlled by the read permission but by the execute permission described below.

Write

Allows write or page erase access to the region

Execute

Allows code fetch from this region, even if data read is disabled

Secure

Allows only bus accesses with the security attribute set to access the region

Permissions can be set independently. For example, it is possible to configure a flash region to be accessible only through secure transfer, being read-only (no write allowed) and non-executable (no code fetch allowed). For each region, permissions can be set and then locked by using the FLASHREGION[n].PERM.LOCK bit, to prevent subsequent modifications.

Note that the debugger is able to step through execute-protected memory regions.

The following figure shows the flash memory space and the divided regions:



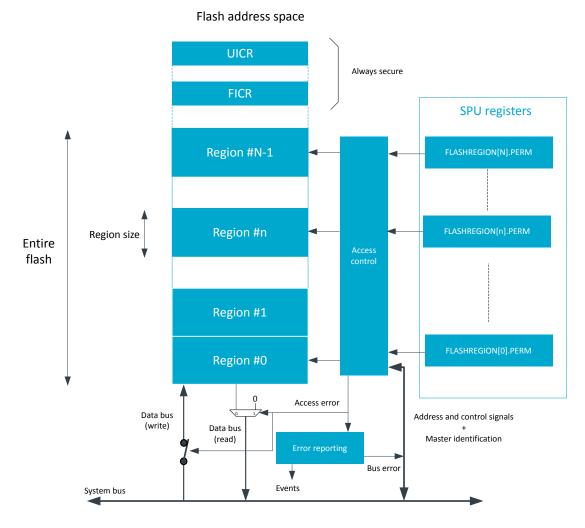


Figure 82: Definition of the N=32 regions, each of 32 KiB, in the flash memory space

6.15.2.1 Non-secure callable (NSC) region definition in flash

The SPU provides support for the definition of non-secure callable (NSC) sub-regions to allow non-secure to secure function calls.

A non-secure callable sub-region can only exist within an existing secure region and its definition is done using two registers:

- FLASHNSC[n].REGION, used to select the secure region that will contain the NSC sub-region
- FLASHNSC[n].SIZE, used to define the size of the NSC sub-region within the secure region

The NSC sub-region will be defined from the highest address in that region, going downwards. Figure below illustrates the NSC sub-regions and the registers used for their definition:



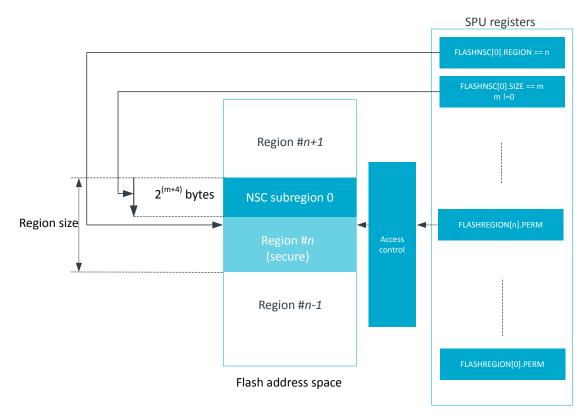


Figure 83: Non-secure callable region definition in the flash memory space

The NSC sub-region will only be defined if:

- FLASHNSC[i].SIZE value is non zero
- FLASHNSC[i].REGION defines a secure region

If FLASHNSC[i].REGION and FLASHNSC[j].REGION have the same value, there is only one sub-region defined as NSC, with the size given by the maximum of FLASHNSC[i].SIZE and FLASHNSC[j].SIZE.

If FLASHNSC[i].REGION defines a non-secure region, then there is no non-secure callable region defined and the selected region stays non-secure.

6.15.2.2 Flash access error reporting

The SPU and the logic controlled by it will respond with a certain behavior once an access violation is detected.

The following will happen once the logic controlled by the SPU detects an access violation on one of the flash ports:

- The faulty transfer will be blocked
- In case of a read transfer, the bus will be driven to zero
- Feedback will be sent to the master through specific bus error signals, if this is supported by the
 master. Moreover, the SPU will receive an event that can optionally trigger an interrupt towards the
 CPU.
- SecureFault exception will be triggered if security violation is detected for access from Cortex-M33
- BusFault exception will be triggered when read/write/execute protection violation is detected for Cortex-M33
- FLASHACCERR event will be triggered if any access violations are detected for all master types except for Cortex-M33 security violation

The following table summarizes the SPU behavior based on the type of initiator and access violation:

NORDIC*

Master type	Security violation	Read/Write/Execute protection violation
Cortex-M33	SecureFault exception	BusFault exception, FLASHACCERR event
EasyDMA	RAZ/WI, FLASHACCERR event	RAZ/WI, FLASHACCERR event
Other masters	RAZ/WI, FLASHACCERR event	RAZ/WI, FLASHACCERR event

Table 81: Error reporting for flash access errors

For a Cortex-M33 master, the SecureFault exception will take precedence over the BusFault exception if a security violation occurs simultaneously with another type of violation.

6.15.2.3 UICR and FICR protections

The user information configuration registers (UICR) and factory information configuration registers (FICR) are always considered as secure. FICR registers are read-only. UICR registers can be read and written by secure code only.

Writing new values to user information configuration registers must follow the procedure described in NVMC — Non-volatile memory controller on page 31. Code execution from FICR and UICR address spaces will always be reported as access violation, an exception to this rule applies during a debug session.

6.15.3 RAM access control

The RAM memory space is divided in regions, each of them with configurable permissions settings.

The RAM memory space is divided into 32 regions of 8 KiB.

For each region, four different types of permissions can be configured:

Read

Allows data read access to the region. Code fetch from this region is not controlled by the read permission but by the execute permission described below.

Write

Allows write access to the region

Execute

Allows code fetch from this region

Secure

Allows only bus accesses with the security attribute set to access the region

Permissions can be set independently. For example, it is possible to configure a RAM region to be accessible only through secure transfer, being read-only (no write allowed) and non-executable (no code fetch allowed). For each region, permissions can be set and then locked to prevent subsequent modifications by using the RAMREGION[n].PERM.LOCK bit.

The following figure shows the RAM memory space and the devided regions:



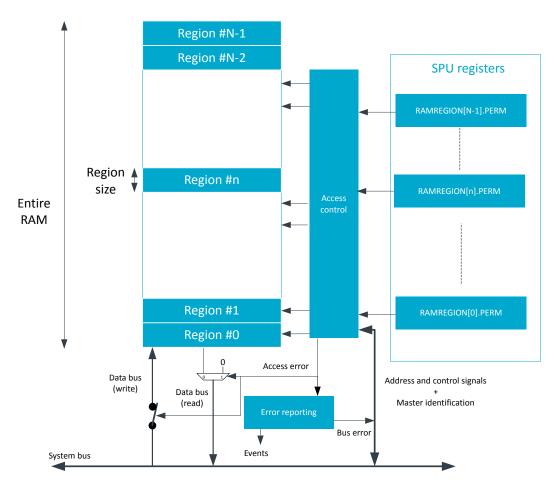


Figure 84: Definition of the N=32 regions, each of 8 KiB, in the RAM memory space

6.15.3.1 Non-secure callable (NSC) region definition in RAM

The SPU provides support for the definition of non-secure callable (NSC) sub-regions to allow non-secure to secure function calls.

A non-secure callable sub-region can only exist within an existing secure region and its definition is done using two registers:

- RAMNSC[n].REGION, used to select the secure region that will contain the NSC sub-region
- RAMNSC[n].SIZE, used to define the size of the NSC sub-region within the secure region

The NSC sub-region will be defined from the highest address in that region, going downwards. Figure below illustrates the NSC sub-regions and the registers used for their definition:



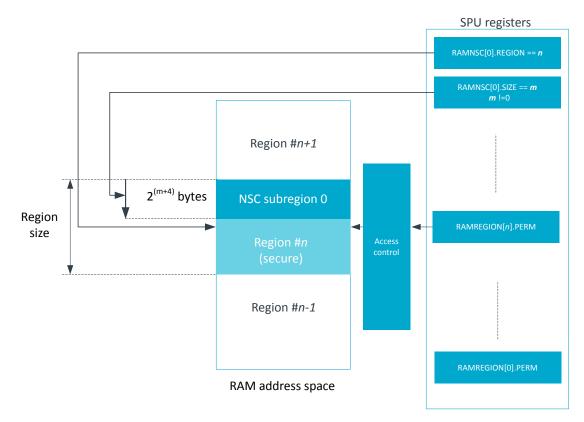


Figure 85: Non-secure callable region definition in the RAM memory space

The NSC sub-region will only be defined if:

- RAMNSC[i].SIZE value is non zero
- RAMNSC[i].REGION defines a secure region

If RAMNSC[i].REGION and RAMNSC[j].REGION have the same value, there is only one sub-region defined as NSC, with the size given by the maximum of RAMNSC[i].SIZE and RAMNSC[j].SIZE.

If RAMNSC[i].REGION defines a non-secure region, then there is no non-secure callable region defined and the selected region stays non-secure.

6.15.3.2 RAM access error reporting

The SPU and the logic controlled by it will respond with a certain behavior once an access violation is detected.

The following will happen once the logic controlled by the SPU detects an access violation on one of the RAM ports:

- The faulty transfer will be blocked
- In case of a read transfer, the bus will be driven to zero
- Feedback will be sent to the master through specific bus error signals, if this is supported by the master
- SecureFault exception will be triggered if security violation is detected for access from Cortex-M33
- BusFault exception will be triggered when read/write/execute protection violation is detected for Cortex-M33. The SPU will also generate an event that can optionally trigger an interrupt towards the CPU.
- RAMACCERR event will be triggered if any access violations are detected for all master types but for Cortex-M33 security violation

The following table summarizes the SPU behavior based on the type of initiator and access violation:



Master type	Security violation	Read/Write/Execute protection violation
Cortex-M33	SecureFault exception	BusFault exception, RAMACCERR event
EasyDMA	RAZ/WI, RAMACCERR event	RAZ/WI, RAMACCERR event
Other masters	RAZ/WI, RAMACCERR event	RAZ/WI, RAMACCERR event

Table 82: Error reporting for RAM access errors

For a Cortex-M33 master, the SecureFault exception will take precedence over the BusFault exception if a security violation occurs simultaneously with another type of violation.

6.15.4 Peripheral access control

Access controls are defined by the characteristics of the peripheral.

Peripherals can have their security attribute set as:

Always secure

For a peripheral related to system control

Always non-secure

For some general-purpose peripherals

Configurable

For general-purpose peripherals that may be configured for secure only access

The full list of peripherals and their corresponding security attributes can be found in Memory map on page 25. For each peripheral with ID n, PERIPHID[n]. PERM will show whether the security attribute for this peripheral is configurable or not.

If not hardcoded, the security attribute can configured using the PERIPHID[id].PERM.

At reset, all user-selectable and split security peripherals are set to be secure, with secure DMA where present.

Secure code can access both secure peripherals and non-secure peripherals.

The nRF9160 does not support runtime security configuration of peripherals. It is thus, advisable that all security settings on peripherals are set during boot time. Doing so will ensure the desired system security configuration is deployed simultaneously system-wide.

6.15.4.1 Peripherals with split security

Peripherals with split security are defined to handle use-cases when both secure and non-secure code needs to control the same resource.

When peripherals with split security have their security attribute set to non-secure, access to specific registers and bitfields within some registers is dependent on the security attribute of the bus transfer. For example, some registers will not be accessible for a non-secure transfer.

When peripherals with split security have their security attribute set to secure, then only secure transfers can access their registers.

See Instantiation on page 26 for an overview of split security peripherals. Respective peripheral chapters explain the specific security behavior of each peripheral.

6.15.4.2 Peripheral address mapping

Peripherals that have non-secure security mapping have their address starting with 0x4XXX_XXXX. Peripherals that have secure security mapping have their address starting with 0x5XXX_XXXX.



Peripherals with a user-selectable security mapping are available at an address starting with:

- 0x4XXX XXXX, if the peripheral security attribute is set to non-secure
- 0x5XXX_XXXX, if the peripheral security attribute is set to secure

Note: Accesses to the 0x4XXX_XXXX address range from secure or non-secure code for a peripheral marked as secure will result in a bus-error.

Secure code accessing the 0x5XXX_XXXX address range of a peripheral marked as non-secure will also result in a bus-error.

Peripherals with a split security mapping are available at an address starting with:

- 0x4XXX_XXXX for non-secure access and 0x5XXX_XXXX for secure access, if the peripheral security attribute is set to non-secure
 - Secure registers in the 0x4XXX_XXXX range are not visible for secure or non-secure code, and an attempt to access such a register will result in write-ignore, read-as-zero behavior
 - Secure code can access both non-secure and secure registers in the 0x5XXX XXXX range
- 0x5XXX_XXXX, if the peripheral security attribute is set to secure

Any attempt to access the 0x5000_0000-0x5FFF_FFFF address range from non-secure code will be ignored and generate a SecureFault exception.

The table below illustrates the address mapping for the three type of peripherals in all possible configurations

Security-features and configuration	Is mapped at 0x4XXX_XXXX?	Is mapped at 0x5XXX_XXXX?
Secure peripheral	No	Yes
Non-secure peripheral	Yes	No
Split-security peripheral, with attribute=secure	No	Yes
Split-security peripheral, with attribute=non-secure	Yes, restricted functionality	Yes

Table 83: Peripheral's address mapping in relation to its security-features and configuration

6.15.4.3 Special considerations for peripherals with DMA master

Peripherals containing a DMA master can be configured so the security attribute of the DMA transfers is different from the security attribute of the peripheral itself. This allows a secure peripheral to do non-secure data transfers to or from the system memories.

The following conditions must be met:

- The DMA field of PERIPHID[n].PERM.SECURITYMAPPING should read as "SeparateAttribute"
- The peripheral itself should be secure (PERIPHID[n].PERM.SECATTR == 1)

Then it is possible to select the security attribute of the DMA transfers using the field DMASEC (PERIPHID[n].PERM.DMASEC == Secure and PERIPHID[n].PERM.DMASEC == NonSecure) in PERIPHID[n].PERM.

6.15.4.4 Peripheral access error reporting

Peripherals send error reports once access violation is detected.

The following will happen if the logic controlled by the SPU detects an access violation on one of the peripherals:

- The faulty transfer will be blocked
- In case of a read transfer, the bus will be driven to zero



- Feedback is sent to the master through specific bus error signals, if this is supported by the master. If the master is a processor supporting ARM TrustZone for Cortex-M, a SecureFault exception will be generated for security related errors.
- The PERIPHACCERR event will be triggered

6.15.5 Pin access control

Access to device pins can be controlled by the SPU. A pin can be declared as secure so that only secure peripherals or secure code can access it. Pins declared as non-secure can be accessed by both secure and non-secure peripherals or code.

The security attribute of each pin can be individually configured in SPU's GPIOPORT[n].PERM register. When the secure attribute is set for a pin, only peripherals that have the secure attribute set will be able to read the value of the pin or change it.

Peripherals can select the pin(s) they need access to through their PSEL register(s). If a peripheral has its attribute set to non-secure, but one of its PSEL registers selects a pin with the attribute set to secure, the SPU controlled logic will ensure that the pin selection is not propagated. In addition, the pin value will always be read as zero, to prevent a non-secure peripheral from obtaining a value from a secure pin. Whereas access to other pins with attribute set as non-secure will not be blocked.

Pins can be assigned to other domains than the application domain by changing the MCUSEL value in the GPIO PIN CNF[n] register. Domains that do not have a pin assigned to them can neither control that pin nor read its status. Any pin configuration set in a domain that doesn't have ownership of that pin will not take effect until the MCUSEL is updated to assign that pin to the domain. Within each domain, pin access is controlled by that domain's local security configuration and peripheral PSEL registers. This is illustrated in the following figure:

Note: The SPU setting will still count when the APP domain accesses its local GPIO peripheral, as local registers are still writable even though MCUSEL is set to a different domain. Any changes in the APP GPIO peripheral done to a GPIO controlled by another domain will not affect the GPIO pad until MCUSEL is changed to APP.

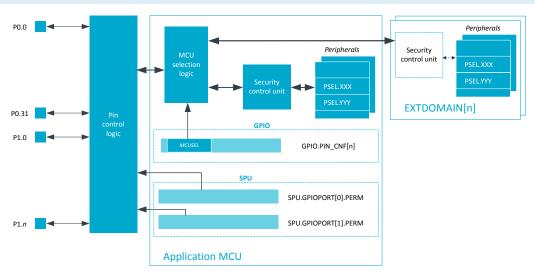


Figure 86: Pin access for domains other than the application domain

6.15.6 DPPI access control

Access to DPPI channels can be restricted. A channel can be declared as secure so that only secure peripherals can access it.

4418 1315 v2.1 273



The security attribute of a DPPI channel is configured in DPPI[n].PERM (n=0..0) on page 281. When the secure attribute is set for a channel, only peripherals that have the secure attribute set will be able to publish events to this channel or subscribe to this channel to receive tasks.

The DPPI controller peripheral (DPPIC) is a split security peripheral, i.e., its security behavior depends on the security attributes of both the DPPIC and the accessing party. See Special considerations regarding the DPPIC configuration registers on page 274 for more information about the DPPIC security behavior.

If a non-secure peripheral wants to publish an event on a secure DPPI channel, the channel will ignore the event. If a non-secure peripheral subscribes to a secure DPPI channel, it will not receive any events from this channel. The following figure illustrates the principle of operation of the security logic for a subscribed channel:

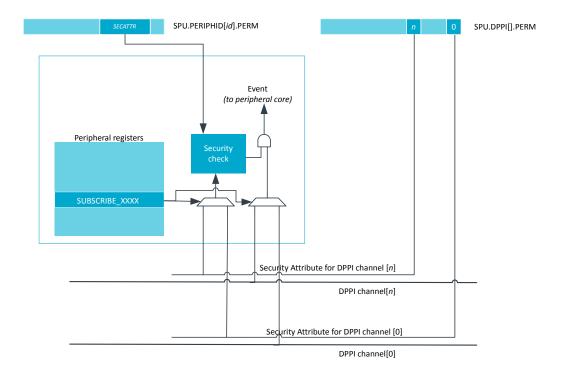


Figure 87: Subscribed channel security concept

No error reporting mechanism is associated with the DPPI access control logic.

6.15.6.1 Special considerations regarding the DPPIC configuration registers

DPPI channels can be enabled, disabled and grouped through the DPPI controller (DPPIC). The DPPIC is a split-security peripheral, and handles both secure and non-secure accesses.

A non-secure peripheral access will only be able to configure and control DPPI channels defined as non-secure in SPU's DPPI[n].PERM register(s). A secure peripheral access can control all DPPI channels, independently of the configuration in the DPPI[n].PERM register(s).

The DPPIC allows the creation of group of channels to be able to enable or disable all channels within a group simultaneously. The security attribute of a group of channels (secure or non-secure) is defined as follows:

- If all channels (enabled or not) in the group are non-secure, then the group is considered non-secure
- If at least one of the channels (enabled or not) in the group is secure, then the group is considered secure

A non-secure access to a DPPIC register, or a bitfield controlling a channel marked as secure in DPPI[n].PERM register(s), will be ignored:

• Write accesses will have no effect



Read will always return a zero value

No exceptions are thrown when a non-secure access targets a register or bitfield controlling a secure channel. For example, if the bit i is set in the DPPI[n].PERM register (declaring the DPPI channel i as secure), then:

- Non-secure write accesses to registers CHEN, CHENSET and CHENCLR will not be able to write to bit i of those registers
- Non-secure write accesses to registers TASK_CHG[j].EN and TASK_CHG[j].DIS will be ignored if the channel group j contains at least one channel defined as secure (it can be the channel i itself or any channel declared as secured)
- Non-secure read accesses to registers CHEN, CHENSET and CHENCLR will always read zero for the bit at position *i*

For the channel configuration registers (DPPIC.CHG[n]), access from non-secure code is only possible if the included channels are all non-secure, whether the channels are enabled or not. If a DPPIC.CHG[g] register included one or more secure channels, then the group gis considered as secure and only a secure transfer can read or write DPPIC.CHG[g]. A non-secure write will be ignored and a non-secure read will return zero.

The DPPIC can subscribe to secure or non-secure channels through SUBSCRIBE_CHG[n] registers in order to trigger task for enabling or disabling groups of channels. But an event from a non-secure channel will be ignored if the group subscribing to this channel is secure. An event from a secure channel can trigger both secure and non-secure tasks.

6.15.7 External domain access control

Other domains with their own CPUs can access peripherals, flash and RAM memories. The SPU allows controlling accesses from those bus masters.

The external domains can access application MCU memories and peripherals. External domains are assigned security attributes as described in register EXTDOMAIN[n].PERM.

Domain	Capability register	Permission register
LTE modem	Modem is always a non-secure domain	Not applicable

Table 84: Register mapping for external domains

The figure below illustrates how the security control units are used to assign security attributes to transfers initiated by the external domains:



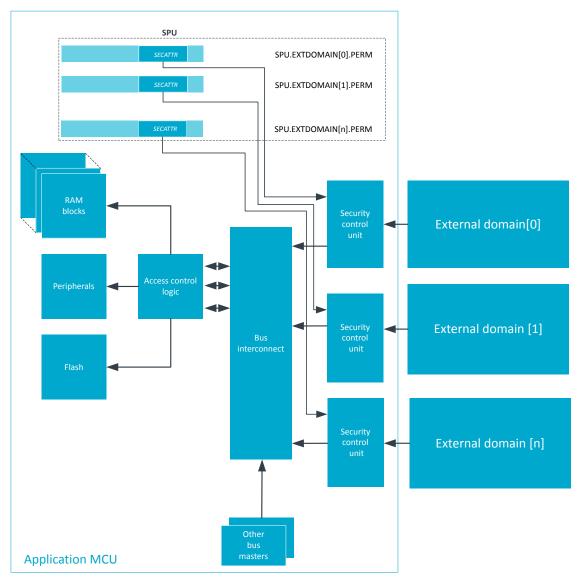


Figure 88: Access control from external domains

6.15.8 TrustZone for Cortex-M ID allocation

Flash and RAM regions, as well as non-secure and secure peripherals, are assigned unique TrustZone IDs.

Note: TrustZone ID should not be confounded with the peripheral ID used to identify peripherals.

The table below shows the TrustZone ID allocation:

Regions	TrustZone Cortex-M ID
Flash regions 031	031
RAM regions 015	6479
Non-secure peripherals	253
Secure peripherals	254

Table 85: TrustZone ID allocation



6.15.9 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x50003000	SPU	SPU	S	NA	System Protection Unit	

Table 86: Instances

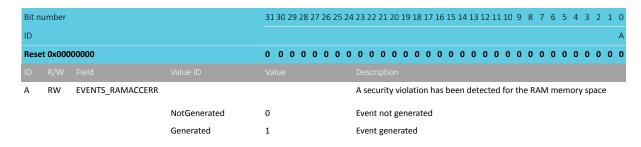
Register	Offset	Security	Description
EVENTS_RAMACCERR	0x100		A security violation has been detected for the RAM memory space
EVENTS_FLASHACCERR	0x104		A security violation has been detected for the flash memory space
EVENTS_PERIPHACCERR	0x108		A security violation has been detected on one or several peripherals
PUBLISH_RAMACCERR	0x180		Publish configuration for event RAMACCERR
PUBLISH_FLASHACCERR	0x184		Publish configuration for event FLASHACCERR
PUBLISH_PERIPHACCERR	0x188		Publish configuration for event PERIPHACCERR
INTEN	0x300		Enable or disable interrupt
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
CAP	0x400		Show implemented features for the current device
EXTDOMAIN[n].PERM	0x440		Access for bus access generated from the external domain n
			List capabilities of the external domain n
DPPI[n].PERM	0x480		Select between secure and non-secure attribute for the DPPI channels.
DPPI[n].LOCK	0x484		Prevent further modification of the corresponding PERM register
GPIOPORT[n].PERM	0x4C0		Select between secure and non-secure attribute for pins 0 to 31 of port n.
			This register is retained.
GPIOPORT[n].LOCK	0x4C4		Prevent further modification of the corresponding PERM register
FLASHNSC[n].REGION	0x500		Define which flash region can contain the non-secure callable (NSC) region n
FLASHNSC[n].SIZE	0x504		Define the size of the non-secure callable (NSC) region n
RAMNSC[n].REGION	0x540		Define which RAM region can contain the non-secure callable (NSC) region n
RAMNSC[n].SIZE	0x544		Define the size of the non-secure callable (NSC) region n
FLASHREGION[n].PERM	0x600		Access permissions for flash region n
RAMREGION[n].PERM	0x700		Access permissions for RAM region n
PERIPHID[n].PERM	0x800		List capabilities and access permissions for the peripheral with ID n

Table 87: Register overview

6.15.9.1 EVENTS_RAMACCERR

Address offset: 0x100

A security violation has been detected for the RAM memory space

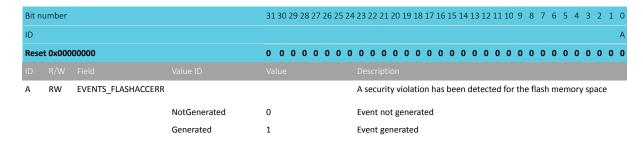


6.15.9.2 EVENTS_FLASHACCERR

Address offset: 0x104



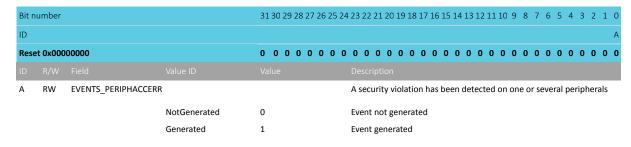
A security violation has been detected for the flash memory space



6.15.9.3 EVENTS PERIPHACCERR

Address offset: 0x108

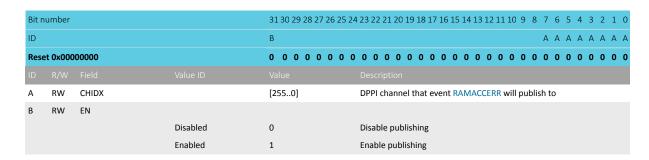
A security violation has been detected on one or several peripherals



6.15.9.4 PUBLISH RAMACCERR

Address offset: 0x180

Publish configuration for event RAMACCERR

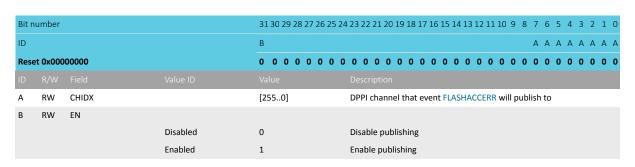


6.15.9.5 PUBLISH_FLASHACCERR

Address offset: 0x184

Publish configuration for event FLASHACCERR





6.15.9.6 PUBLISH_PERIPHACCERR

Address offset: 0x188

Publish configuration for event PERIPHACCERR

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A
Rese	et 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[2550]	DPPI channel that event PERIPHACCERR will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing

6.15.9.7 INTEN

Address offset: 0x300

Enable or disable interrupt

Bit n	umber			31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					СВА
Rese	et 0x000	00000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
					Description
Α	RW	RAMACCERR			Enable or disable interrupt for event RAMACCERR
			Disabled	0	Disable
			Enabled	1	Enable
В	RW	FLASHACCERR			Enable or disable interrupt for event FLASHACCERR
			Disabled	0	Disable
			Enabled	1	Enable
С	RW	PERIPHACCERR			Enable or disable interrupt for event PERIPHACCERR
			Disabled	0	Disable
			Enabled	1	Enable

6.15.9.8 INTENSET

Address offset: 0x304

Enable interrupt



Bit r	umber			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					СВА
Rese	et 0x000	000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	RAMACCERR			Write '1' to enable interrupt for event RAMACCERR
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
В	RW	FLASHACCERR			Write '1' to enable interrupt for event FLASHACCERR
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
С	RW	PERIPHACCERR			Write '1' to enable interrupt for event PERIPHACCERR
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled

6.15.9.9 INTENCLR

Address offset: 0x308

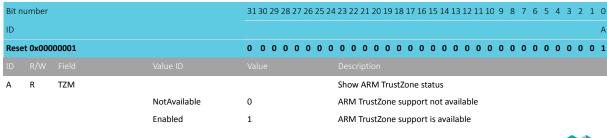
Disable interrupt

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					СВА
Rese	et 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	RAMACCERR			Write '1' to disable interrupt for event RAMACCERR
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
В	RW	FLASHACCERR			Write '1' to disable interrupt for event FLASHACCERR
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
С	RW	PERIPHACCERR			Write '1' to disable interrupt for event PERIPHACCERR
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled

6.15.9.10 CAP

Address offset: 0x400

Show implemented features for the current device





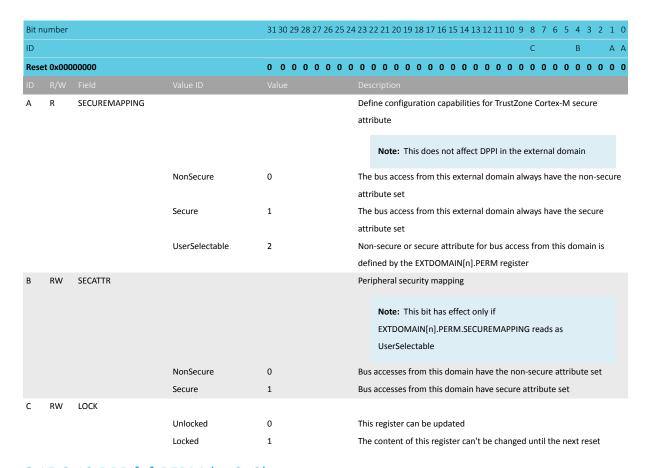


6.15.9.11 EXTDOMAIN[n].PERM (n=0..0)

Address offset: $0x440 + (n \times 0x4)$

Access for bus access generated from the external domain n

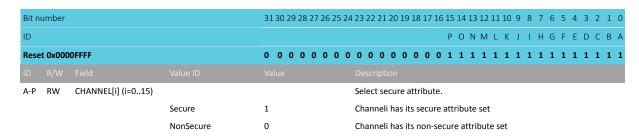
List capabilities of the external domain n



6.15.9.12 DPPI[n].PERM (n=0..0)

Address offset: $0x480 + (n \times 0x8)$

Select between secure and non-secure attribute for the DPPI channels.

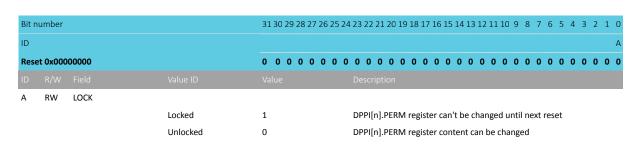


6.15.9.13 DPPI[n].LOCK (n=0..0)

Address offset: $0x484 + (n \times 0x8)$

Prevent further modification of the corresponding PERM register

NORDIC'

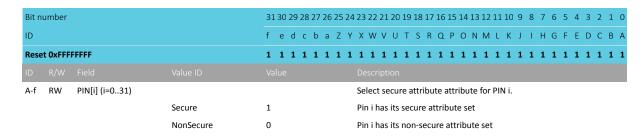


6.15.9.14 GPIOPORT[n].PERM (n=0..0) (Retained)

Address offset: $0x4C0 + (n \times 0x8)$

Select between secure and non-secure attribute for pins 0 to 31 of port n.

This register is retained.



6.15.9.15 GPIOPORT[n].LOCK (n=0..0)

Address offset: $0x4C4 + (n \times 0x8)$

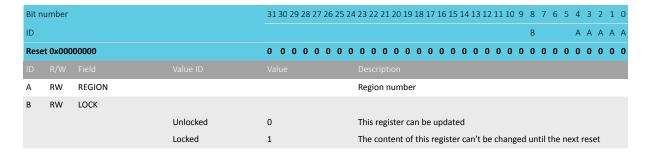
Prevent further modification of the corresponding PERM register



6.15.9.16 FLASHNSC[n].REGION (n=0..1)

Address offset: $0x500 + (n \times 0x8)$

Define which flash region can contain the non-secure callable (NSC) region n

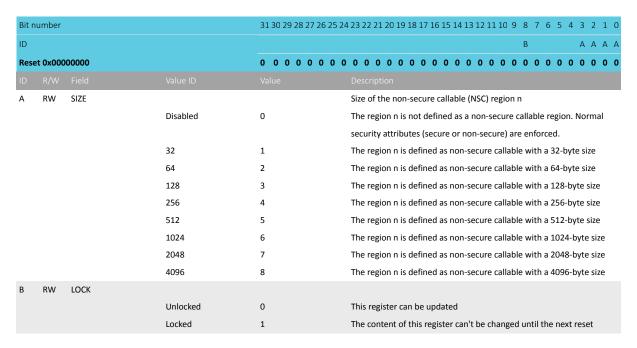


6.15.9.17 FLASHNSC[n].SIZE (n=0..1)

Address offset: $0x504 + (n \times 0x8)$



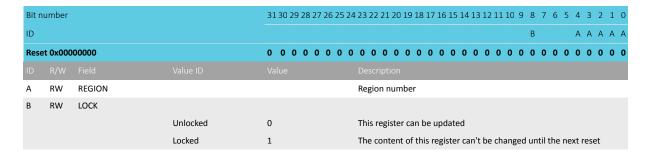
Define the size of the non-secure callable (NSC) region n



6.15.9.18 RAMNSC[n].REGION (n=0..1)

Address offset: $0x540 + (n \times 0x8)$

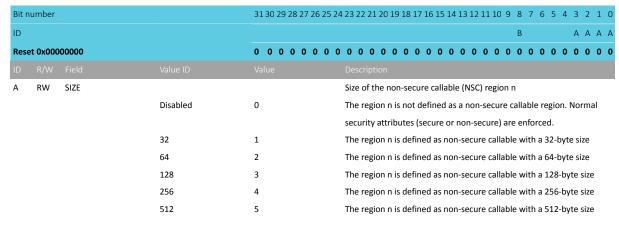
Define which RAM region can contain the non-secure callable (NSC) region n



6.15.9.19 RAMNSC[n].SIZE (n=0..1)

Address offset: $0x544 + (n \times 0x8)$

Define the size of the non-secure callable (NSC) region n





Bit number		31 30 29 28 27 26 25	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			в ааа
Reset 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID R/W Field			Description
	1024	6	The region n is defined as non-secure callable with a 1024-byte size
	2048	7	The region n is defined as non-secure callable with a 2048-byte size
	4096	8	The region n is defined as non-secure callable with a 4096-byte size
B RW LOCK			
	Unlocked	0	This register can be updated
	Locked	1	The content of this register can't be changed until the next reset

6.15.9.20 FLASHREGION[n].PERM (n=0..31)

Address offset: $0x600 + (n \times 0x4)$ Access permissions for flash region n

Bit r	umber			313	0 29	28	27 2	6 25	5 24	23	3 22	2 2 1	1 20	19	18	17 :	16 1	5 14	13	12	11 1	0 9	8	7	6	5 4	1 3	2	1	0
ID																							Ε			[)	С	В	Α
Rese	et 0x000	00017		0 (0	0	0 (0 0	0	0	0	0	0	0	0	0	0 (0	0	0	0 (0	0	0	0	0 1	0	1	1	1
Α	RW	EXECUTE								Co	onfi	iguı	re ii	nsti	ruct	ion	feto	h p	erm	issi	ons 1	ron	n fla	sh	regio	on r	1			_
			Enable	1						Αl	low	v in	stru	ıcti	on t	fetc	hes	froi	n fla	ash	regi	on n	1							
			Disable	0						Bl	ock	in	stru	ıcti	on f	etcl	nes	fror	n fla	sh	regio	on n								
В	RW	WRITE								Co	onfi	iguı	re v	vrit	ере	erm	issi	n f	or fl	ash	regi	on r	1							
			Enable	1						Αl	low	v w	rite	ор	era	tion	to	regi	on r	า										
			Disable	0						Bl	ock	WI	rite	ор	erat	tion	to	egi	on r	1										
С	RW	READ								Co	onfi	iguı	re r	eac	d pe	rmi	ssio	ns f	or fl	ash	regi	on i	n							
			Enable	1						Αl	low	v re	ead	оре	erat	ion	froi	n fla	ash	reg	on n	1								
			Disable	0						Bl	ock	re	ad	оре	erati	ion	fror	n fla	sh i	regi	on n									
D	RW	SECATTR								Se	ecur	rity	att	rib	ute	for	flas	n re	gior	n n										
			Non_Secure	0						Fla	ash	re	gio	n n	sec	urit	y at	trib	ute	is n	on-s	ecui	re							
			Secure	1						Fla	ash	re	gioi	n n	sec	urit	y at	trib	ute	is s	ecure	9								
E	RW	LOCK																												
			Unlocked	0						Th	nis r	regi	iste	r ca	an b	e u	oda	ted												
			Locked	1						Th	ne c	on	ten	t of	f thi	s re	gist	er c	an't	be	char	nged	d un	til t	he r	ext	res	et		

6.15.9.21 RAMREGION[n].PERM (n=0..31)

Address offset: $0x700 + (n \times 0x4)$ Access permissions for RAM region n

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					E D C B A
Rese	et 0x000	00017		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	EXECUTE			Configure instruction fetch permissions from RAM region n
			Enable	1	Allow instruction fetches from RAM region n
			Disable	0	Block instruction fetches from RAM region n
В	RW	WRITE			Configure write permission for RAM region n
			Enable	1	Allow write operation to RAM region n
			Disable	0	Block write operation to RAM region n
С	RW	READ			Configure read permissions for RAM region n
			Enable	1	Allow read operation from RAM region n



Bit ni	umber			31	30 2	29 2	8 27	26 2	5 24	1 23	3 22	21	20	19	18 1	7 1	6 15	5 14	13	12	11 1	10 9	8	7	6	5	4 3	2	1	0
ID																							Ε				D	С	В	Α
Rese	t 0x000	00017		0	0	0 0	0 0	0 (0 0	0	0	0	0	0	0 0) (0	0	0	0	0	0 0	0	0	0	0	1 () 1	1	1
ID																														
			Disable	0						ы	ock	rea	ad c	pe	ratio	n f	rom	RA	M r	egi	on i	า								
D	RW	SECATTR								Se	ecur	ity	attr	ribu	te fo	or F	RAIV	re	gior	n										
			Non_Secure	0						R/	٩M	reg	ion	n s	ecur	ity	attı	ibu	te i	s no	on-s	ecu	re							
			Secure	1						R/	AΜ	reg	ion	n s	ecur	ity	attı	ibu	te i	s se	cur	e								
E	RW	LOCK																												
			Unlocked	0						Th	nis r	egi	ster	r ca	n be	up	dat	ed												
			Locked	1						Th	ne c	ont	ent	of	this	reg	iste	r ca	ın't	be	cha	nge	d ur	til t	he	nex	t re	set		

6.15.9.22 PERIPHID[n].PERM (n=0..66)

Address offset: $0x800 + (n \times 0x4)$

List capabilities and access permissions for the peripheral with ID n

Note: Reset values are unique per peripheral instantation. Please refer to the peripheral instantiation table. Entries not listed in the instantiation table are undefined.

Bit n	umber			31	30	29	28	27	26 2	5 24	4 2	3 22	2 2 1	1 20	19	9 1	8 1	7 1	6 15	14	13	12	11	10	9 8	3 7	6	5	4	3	2	1	0
ID				F																					ı			D	С	В	В	Α	Α
Rese	t 0x000	00012		0	0	0	0	0	0 (0) (0 0	0	0	0) (0	(0	0	0	0	0	0	0 (0	0	0	1	0	0	1	0
Α	R	SECUREMAPPING										Defin Ittrib			fig	ura	itio	n c	ара	bili	ties	for	Tru	ıstZ	one	Со	rtex	-M	sec	ure			
			NonSecure	0							Т	his p	per	ripł	era	al i	s al	wa	ys a	cce	ssib	le i	as a	no	n-se	ecui	e p	erip	oher	al			
			Secure	1							Т	his p	per	ipł	era	al i	s al	wa	ys a	cce	ssib	le i	as a	sec	cure	pe	riph	nera	al				
			UserSelectable	2							Ν	lon-	sec	cur	e o	r s	ecu	re i	attr	bu	te fo	r t	his	peri	iphe	eral	is d	efir	ned	by 1	the	:	
											P	PERIF	РΗΙ	D[i	n].F	PEF	RM	reg	iste	r													
			Split	3							Т	his p	per	ripł	era	al i	mp	len	nen	ts t	he s	plit	se	curi	ty r	nec	nan	ism	. No	n-			
											S	ecur	re c	or s	ecı	ure	att	rib	ute	for	this	s pe	erip	her	al is	de	fine	d b	y th	е			
											P	PERIF	РΗΙ	D[i	n].F	PEF	RM	reg	iste	r.													
В	R	DMA									Ir	ndica	ate	if	the	p	erip	he	ral l	nas	DM	A c	ара	abili	ties	and	d if I	DM	A tr	ans	fer	cai	n
										b	e as	sig	ne	d to	о а	dif	fer	ent	sec	urit	y a	ttril	bute	e th	an t	he I	per	iphe	eral	its	elf		
		NoDMA	0							Р	erip	he	ral	ha	s n	o D	MA	A ca	pak	ility	′												
			NoSeparateAttribute	1							Р	erip	he	ral	ha	s C	MΑ	ar	nd E	MA	A tra	ns	fers	alw	ays	ha	ve t	he:	sam	e s	ecu	ırity	/
											а	ttrib	out	e a	s a	ssi	gne	d t	o th	e p	erip	he	ral										
			SeparateAttribute	2							P	erip	he	ral	ha	s D	MΑ	ar	nd E	MA	\ tra	ınsi	fers	car	n ha	ve a	dif	ffer	ent	sec	urit	ty	
											а	ttrib	out	e t	nar	ı tł	ne o	ne	ass	ign	ed t	o t	he	peri	phe	ral							
С	RW	SECATTR									P	erip	he	ral	sec	cur	ity	ma	ppi	ng													
													PE	RIF	HII	D[ı		ERI	M.S	ECl	t on JREI	•		NG	rea	ds a	ıs						
													U3	ici .	CIC		abit	. 0	Эр														
			Secure	1							Р	erip	he	ral	is r	ma	ppe	d i	n se	cui	e p	erip	ohe	ral a	add	ress	spa	ace					
		NonSecure	0								f SEC											le:	Per	iph	eral	is n	nap	ped	l in	noı	ก-		
											lf	f SEC	CUF	REN	ЛΑ	PP	NG	==	Sp	it:	Peri	phe	eral	is n	nap	pec	in	nor	ı-se	cure	e ar	nd	
											S	ecur	re p	oer	iph	er	al a	ddı	ess	spa	ace.												



Secure 1 DMA transfers initiated by this peripheral have the secure attribute set Secure 1 DMA transfers initiated by this peripheral have the secure attribute set Secure 1 DMA transfers initiated by this peripheral have the secure attribute set Secure 1 DMA transfers initiated by this peripheral have the secure attribute set Secure 1 DMA transfers initiated by this peripheral have the secure attribute set Secure 1 DMA transfers initiated by this peripheral have the secure attribute set Secure 1 DMA transfers initiated by this peripheral have the secure attribute set Secure 1 DMA transfers initiated by this peripheral have the secure attribute set Secure Secure						
Reset 0x00000012 D	Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
D R/W Field Value ID Value Description	ID				F	E DCBBAA
D RW DMASEC Security attribution for the DMA transfer Note: This bit has effect only if PERIPHID[n].PERM.SECATTR is set to secure Secure DMA transfers initiated by this peripheral have the secure attribute set NonSecure DMA transfers initiated by this peripheral have the non-secure attribute set E RW LOCK Unlocked Locked This register can be updated Locked The content of this register can't be changed until the next reset Indicate if a peripheral is present with ID n NotPresent O Peripheral is not present	Rese	et 0x000	00012		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
Note: This bit has effect only if PERIPHID[n].PERM.SECATTR is set to secure Secure 1 DMA transfers initiated by this peripheral have the secure attribute set NonSecure 0 DMA transfers initiated by this peripheral have the non-secure attribute set E RW LOCK Unlocked 0 This register can be updated Locked 1 The content of this register can't be changed until the next reset F R PRESENT NotPresent 0 Peripheral is present with ID n NotPresent	ID					
Secure 1 DMA transfers initiated by this peripheral have the secure attribute set NonSecure 0 DMA transfers initiated by this peripheral have the non-secure attribute set E RW LOCK Unlocked 0 This register can be updated Locked 1 The content of this register can't be changed until the next reset F R PRESENT NotPresent 0 Peripheral is not present	D	RW	DMASEC			Security attribution for the DMA transfer
RW LOCK Unlocked 0 This register can be updated Locked 1 The content of this register can't be changed until the next reset F R PRESENT NotPresent 0 Peripheral is not present						
E RW LOCK Unlocked 0 This register can be updated Locked 1 The content of this register can't be changed until the next reset F R PRESENT NotPresent O Peripheral is not present				Secure	1	DMA transfers initiated by this peripheral have the secure attribute set
E RW LOCK Unlocked 0 This register can be updated Locked 1 The content of this register can't be changed until the next reset F R PRESENT NotPresent 0 Peripheral is not present				NonSecure	0	DMA transfers initiated by this peripheral have the non-secure
Unlocked 0 This register can be updated Locked 1 The content of this register can't be changed until the next reset F R PRESENT Indicate if a peripheral is present with ID n NotPresent 0 Peripheral is not present						attribute set
Locked 1 The content of this register can't be changed until the next reset F R PRESENT Indicate if a peripheral is present with ID n NotPresent 0 Peripheral is not present	E	RW	LOCK			
F R PRESENT Indicate if a peripheral is present with ID n NotPresent 0 Peripheral is not present				Unlocked	0	This register can be updated
NotPresent 0 Peripheral is not present				Locked	1	The content of this register can't be changed until the next reset
	F	R	PRESENT			Indicate if a peripheral is present with ID n
IsPresent 1 Peripheral is present				NotPresent	0	Peripheral is not present
				IsPresent	1	Peripheral is present

6.16 TIMER — Timer/counter

This peripheral is a general purpose timer designed to keep track of time in user-selective time intervals, it can operate in two modes: timer and counter.

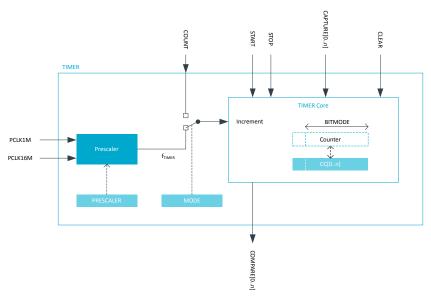


Figure 89: Block schematic for timer/counter

The timer/counter runs on the high-frequency clock source (HFCLK) and includes a four-bit (1/2X) prescaler that can divide the timer input clock from the HFCLK controller. Clock source selection between PCLK16M and PCLK1M is automatic according to TIMER base frequency set by the prescaler. The TIMER base frequency is always given as 16 MHz divided by the prescaler value.

The PPI system allows a TIMER event to trigger a task of any other system peripheral of the device. The PPI system also enables the TIMER task/event features to generate periodic output and PWM signals to any GPIO. The number of input/outputs used at the same time is limited by the number of GPIOTE channels.

TIMER can operate in two modes: Timer mode and Counter mode. In both modes, TIMER is started by triggering the START task, and stopped by triggering the STOP task. After the timer is stopped the timer can resume timing/counting by triggering the START task again. When timing/counting is resumed, the timer will continue from the value it had prior to being stopped.

NORDIC

In Timer mode, the TIMER's internal Counter register is incremented by one for every tick of the timer frequency f_{TIMER} as illustrated in Block schematic for timer/counter on page 286. The timer frequency is derived from PCLK16M as shown in the following example, using the values specified in the PRESCALER register.

```
f<sub>TIMER</sub> = 16 MHz / (2<sup>PRESCALER</sup>)
```

When $f_{TIMER} \le 1$ MHz, TIMER will use PCLK1M instead of PCLK16M for reduced power consumption.

In counter mode, the TIMER's internal Counter register is incremented by one each time the COUNT task is triggered, meaning the timer frequency and the prescaler are not utilized in counter mode. Similarly, the COUNT task has no effect in Timer mode.

The TIMER's maximum value is configured by changing the bit-width of the timer in register BITMODE on page 294.

PRESCALER on page 294 and BITMODE on page 294 must only be updated when the timer is stopped. If these registers are updated while the timer is started, unpredictable behavior may occur.

When the timer is incremented beyond its maximum value, the Counter register will overflow and the timer will automatically start over from zero.

The Counter register can be cleared by triggering the CLEAR task. This will explicitly set the internal value to zero.

TIMER implements multiple capture/compare registers.

Independent of prescaler setting, the accuracy of TIMER is equivalent to one tick of the timer frequency f_{TIMER} as illustrated in Block schematic for timer/counter on page 286.

6.16.1 Capture

TIMER implements one capture task for every available capture/compare register.

Every time the CAPTURE[n] task is triggered, the Counter value is copied to the CC[n] register.

6.16.2 Compare

TIMER implements one COMPARE event for every available capture/compare register.

A COMPARE event is generated when the Counter is incremented and then becomes equal to the value specified in one of the capture compare registers. When the Counter value becomes equal to the value specified in a capture compare register CC[n], the corresponding compare event COMPARE[n] is generated.

BITMODE on page 294 specifies how many bits of the Counter register and the capture/compare register that are used when the comparison is performed. Other bits will be ignored.

The COMPARE event can be configured to operate in one-shot mode by configuring the corresponding ONESHOTEN[n] register. COMPARE[n] event is generated the first time the Counter matches CC[n] after CC[n] has been written.

6.16.3 Task delays

After TIMER is started, the CLEAR, COUNT, and STOP tasks are guaranteed to take effect within one clock cycle of the PCLK16M.

6.16.4 Task priority



If the START task and the STOP task are triggered at the same time, meaning within the same period of PCLK16M, the STOP task will be prioritized.

If one or more of the CAPTURE tasks and the CLEAR task is triggered at the same time, that is, within the same period of PCLK16M, the CLEAR task will be prioritized. This means that the CC register for the relevant CAPTURE task will be set to 0.

6.16.5 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x5000F000	TIMER	TIMER0 : S	US	NA	Timer 0	
0x4000F000	HIVIEK	TIMER0 : NS	03	NA	Timer o	
0x50010000	TIMER	TIMER1:S	US	NA	Timer 1	
0x40010000	HIVIEK	TIMER1 : NS	03	NA	Timer 1	
0x50011000	TIMER	TIMER2 : S	US	NA	Timer 2	
0x40011000	HIVIEK	TIMER2 : NS	US	INA	Timer 2	

Table 88: Instances

Pogistor	Offset	Cocurity	Description
Register		Security	Description
TASKS_START	0x000		Start Timer
TASKS_STOP	0x004		Stop Timer
TASKS_COUNT	0x008		Increment Timer (Counter mode only)
TASKS_CLEAR	0x00C		Clear time
TASKS_SHUTDOWN	0x010		Shut down timer
			This register is deprecated.
TASKS_CAPTURE[n]	0x040		Capture Timer value to CC[n] register
SUBSCRIBE_START	0x080		Subscribe configuration for task START
SUBSCRIBE_STOP	0x084		Subscribe configuration for task STOP
SUBSCRIBE_COUNT	0x088		Subscribe configuration for task COUNT
SUBSCRIBE_CLEAR	0x08C		Subscribe configuration for task CLEAR
SUBSCRIBE_SHUTDOWN	0x090		Subscribe configuration for task SHUTDOWN
			This register is deprecated.
SUBSCRIBE_CAPTURE[n]	0x0C0		Subscribe configuration for task CAPTURE[n]
EVENTS_COMPARE[n]	0x140		Compare event on CC[n] match
PUBLISH_COMPARE[n]	0x1C0		Publish configuration for event COMPARE[n]
SHORTS	0x200		Shortcuts between local events and tasks
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
MODE	0x504		Timer mode selection
BITMODE	0x508		Configure the number of bits used by the TIMER
PRESCALER	0x510		Timer prescaler register
ONESHOTEN[n]	0x514		Enable one-shot operation for Capture/Compare channel n
CC[n]	0x540		Capture/Compare register n

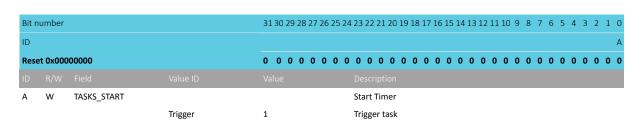
Table 89: Register overview

6.16.5.1 TASKS_START

Address offset: 0x000

Start Timer

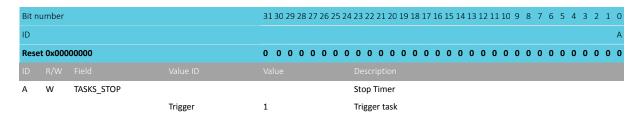




6.16.5.2 TASKS STOP

Address offset: 0x004

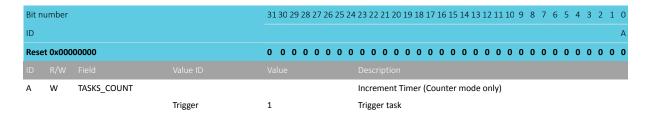
Stop Timer



6.16.5.3 TASKS_COUNT

Address offset: 0x008

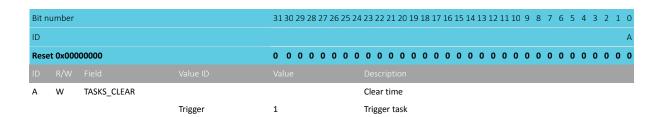
Increment Timer (Counter mode only)



6.16.5.4 TASKS_CLEAR

Address offset: 0x00C

Clear time



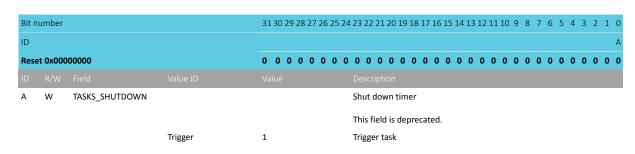
6.16.5.5 TASKS_SHUTDOWN (Deprecated)

Address offset: 0x010

Shut down timer

This register is deprecated.





6.16.5.6 TASKS_CAPTURE[n] (n=0..5)

Address offset: $0x040 + (n \times 0x4)$

Capture Timer value to CC[n] register

Bit n	umber			31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					А
Rese	et 0x000	000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	W	TASKS_CAPTURE			Capture Timer value to CC[n] register
			Trigger	1	Trigger task

6.16.5.7 SUBSCRIBE_START

Address offset: 0x080

Subscribe configuration for task START

Bit n	umber	ber		31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4	3 2 1 0
ID				В	АААА	AAAA
Rese	et 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0 0 0
ID						
Α	RW	CHIDX		[2550]	DPPI channel that task START will subscribe to	
В	RW	EN				
			Disabled	0	Disable subscription	
			Enabled	1	Enable subscription	

6.16.5.8 SUBSCRIBE_STOP

Address offset: 0x084

Subscribe configuration for task STOP

Bit n	umber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2	2 1 0
ID				В	A A A A A	ААА
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0
ID						
Α	RW	CHIDX		[2550]	DPPI channel that task STOP will subscribe to	
В	RW	EN				
			Disabled	0	Disable subscription	
			Enabled	1	Enable subscription	

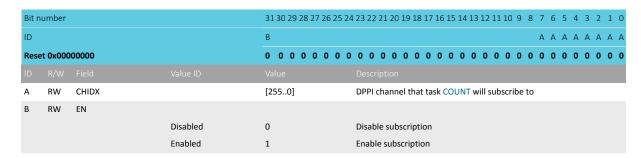
6.16.5.9 SUBSCRIBE_COUNT

Address offset: 0x088





Subscribe configuration for task COUNT



6.16.5.10 SUBSCRIBE_CLEAR

Address offset: 0x08C

Subscribe configuration for task CLEAR

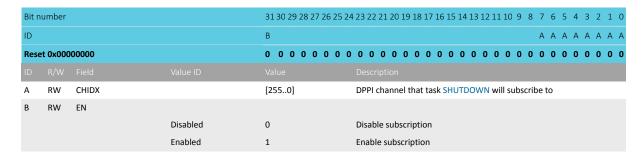
Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[2550]	DPPI channel that task CLEAR will subscribe to
В	RW	EN			
			Disabled	0	Disable subscription
			Enabled	1	Enable subscription

6.16.5.11 SUBSCRIBE_SHUTDOWN (Deprecated)

Address offset: 0x090

Subscribe configuration for task SHUTDOWN

This register is deprecated.

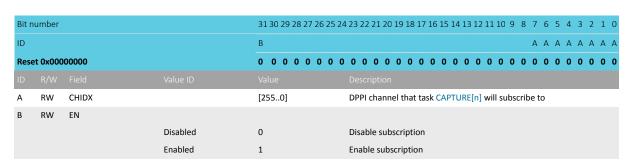


6.16.5.12 SUBSCRIBE_CAPTURE[n] (n=0..5)

Address offset: $0x0C0 + (n \times 0x4)$

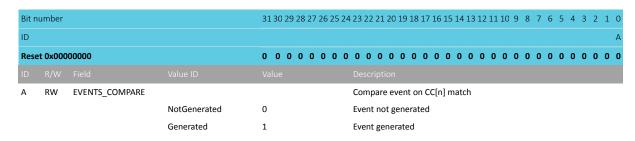
Subscribe configuration for task CAPTURE[n]





6.16.5.13 EVENTS_COMPARE[n] (n=0..5)

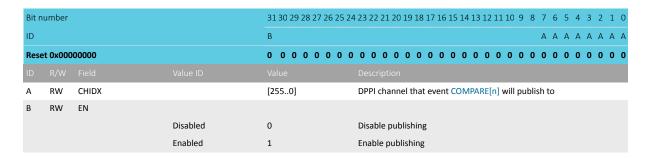
Address offset: $0x140 + (n \times 0x4)$ Compare event on CC[n] match



6.16.5.14 PUBLISH_COMPARE[n] (n=0..5)

Address offset: $0x1C0 + (n \times 0x4)$

Publish configuration for event COMPARE[n]



6.16.5.15 SHORTS

Address offset: 0x200

Shortcuts between local events and tasks



Bit numb	ber		313	80 29	28 :	27 26	25	24 2	23 :	22 2	1 2	20 19	9 18	3 17	16	15	14	13	12	11 1	10 !	9 8	7	6	5	4	3	2	1 0
ID																		L	K	J	ı ı	1 0	i		F	Ε	D	С	ВА
Reset 0x	x00000000		0	0 0	0	0 0	0	0	0	0 (0	0 0	0	0	0	0	0	0	0	0	0 (0 0	0	0	0	0	0	0	0 0
ID R/									Des																				
A-F RV	W COMPARE[i]_CLEAR								Sho	ortcı	ut k	etw	/ee	n ev	/en	t C	MC	PAF	RE[i] an	d ta	ask	CLE	AR					
	(i=05)																												
		Disabled	0					1	Dis	able	sh	orto	cut																
		Enabled	1					1	Ena	ble	sh	ortc	ut																
G-L R\	W COMPARE[i]_STOP								Sho	ortcı	ut k	etw	/ee	n ev	/en	t C	MC	PAF	RE[i] an	d t	ask	STC	P					
	(i=05)																												
		Disabled	0					-	Dis	able	sh	orto	cut																
		Enabled	1					- 1	Ena	ble	sh	ortc	ut																

6.16.5.16 INTENSET

Address offset: 0x304

Enable interrupt

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					F E D C B A
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
A-F	RW	COMPARE[i] (i=05)			Write '1' to enable interrupt for event COMPARE[i]
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled

6.16.5.17 INTENCLR

Address offset: 0x308

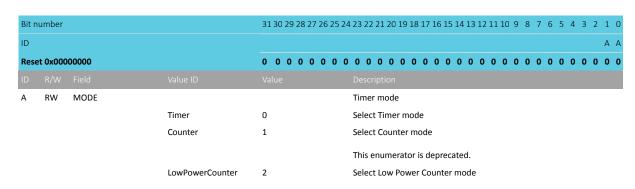
Disable interrupt

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					FEDCBA
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
A-F	RW	COMPARE[i] (i=05)			Write '1' to disable interrupt for event COMPARE[i]
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled

6.16.5.18 MODE

Address offset: 0x504
Timer mode selection

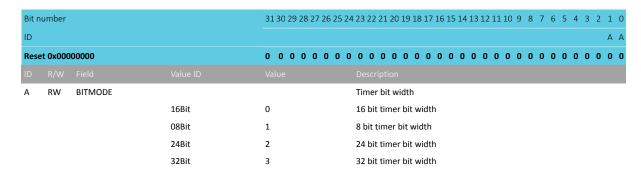




6.16.5.19 BITMODE

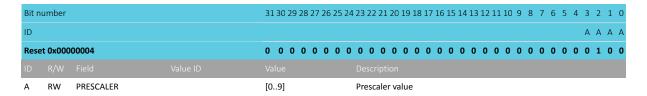
Address offset: 0x508

Configure the number of bits used by the TIMER



6.16.5.20 PRESCALER

Address offset: 0x510
Timer prescaler register

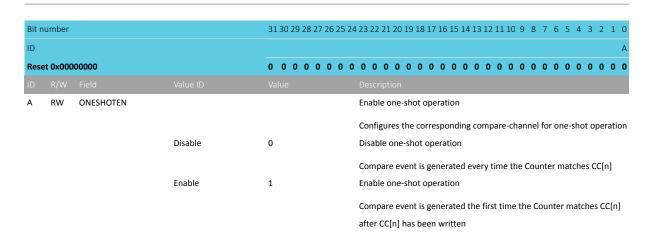


6.16.5.21 ONESHOTEN[n] (n=0..5)

Address offset: $0x514 + (n \times 0x4)$

Enable one-shot operation for Capture/Compare channel n





6.16.5.22 CC[n] (n=0..5)

Address offset: $0x540 + (n \times 0x4)$ Capture/Compare register n

Bit n	umber		31	30	29	28	27 2	26 2	25 2	4 2	3 22	2 21	. 20	19	18	17 :	16 1	15 1	4 13	3 12	11	10	9	8	7	6 5	5 4	3	2	1 0
ID			Α	Α	Α	Α	A	Α /	Δ Δ	Δ Δ	A	Α	Α	Α	Α	Α	A ,	A A	A A	Α	Α	Α	Α	A A	Δ,	A A	Δ Α	A	Α	A A
Rese	t 0x000	00000	0	0	0	0	0	0 (0 0	0	0	0	0	0	0	0	0	0 (0	0	0	0	0	0 (0	0 (0 0	0	0	0 0
ID																														
Α	RW	CC								С	apt	ure,	/Co	mp	are	val	ue													
										0	nly	the	nu	ımb	er (of b	its i	indi	cate	ed b	у В	ITN	100)E w	rill I	be ι	use	d by	the	è
										Т	IME	R.																		

6.16.6 Electrical specification

$6.17 \text{ TWIM} - I^2 \text{C}$ compatible two-wire interface master with EasyDMA

TWI master with EasyDMA (TWIM) is a two-wire half-duplex master which can communicate with multiple slave devices connected to the same bus.

Listed here are the main features for TWIM:

- I²C compatible
- Supported baud rates: 100, 250, 400 kbps
- Support for clock stretching (non I²C compliant)
- EasyDMA

The two-wire interface can communicate with a bi-directional wired-AND bus with two lines (SCL, SDA). The protocol makes it possible to interconnect up to 127 individually addressable devices. TWIM is not compatible with CBUS.

The GPIOs used for each two-wire interface line can be chosen from any GPIO on the device and are independently configurable. This enables great flexibility in device pinout and efficient use of board space and signal routing.

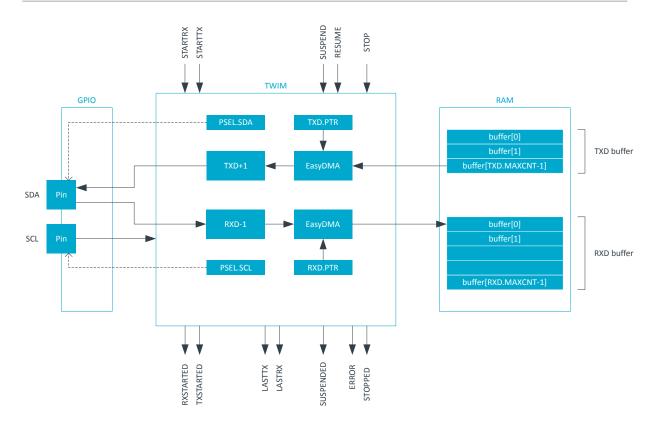


Figure 90: TWI master with EasyDMA

A typical TWI setup consists of one master and one or more slaves. For an example, see the following figure. This TWIM is only able to operate as a single master on the TWI bus. Multi-master bus configuration is not supported.

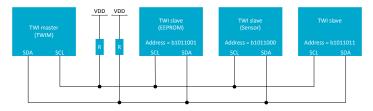


Figure 91: A typical TWI setup comprising one master and three slaves

This TWI master supports clock stretching performed by the slaves. The SCK pulse following a stretched clock cycle may be shorter than specified by the I2C specification.

The TWI master is started by triggering the STARTTX or STARTRX tasks, and stopped by triggering the STOP task. The TWI master will generate a STOPPED event when it has stopped following a STOP task.

After the TWI master is started, the STARTTX or STARTRX tasks should not be triggered again until the TWI master has issued a LASTRX, LASTTX, or STOPPED event.

The TWI master can be suspended using the SUSPEND task, this can be used when using the TWI master in a low priority interrupt context. When the TWIM enters suspend state, will automatically issue a SUSPENDED event while performing a continuous clock stretching until it is instructed to resume operation via a RESUME task. The TWI master cannot be stopped while it is suspended, thus the STOP task has to be issued after the TWI master has been resumed.

Note: Any ongoing byte transfer will be allowed to complete before the suspend is enforced. A SUSPEND task has no effect unless the TWI master is actively involved in a transfer.

If a NACK is clocked in from the slave, the TWI master will generate an ERROR event.

NORDIC SEMICONDUCTOR

6.17.1 Shared resources

The TWI master shares registers and other resources with other peripherals that have the same ID as the TWI master. Therefore, you must disable all peripherals that have the same ID as the TWI master before the TWI master can be configured and used.

Disabling a peripheral that has the same ID as the TWI master will not reset any of the registers that are shared with the TWI master. It is therefore important to configure all relevant registers explicitly to secure that the TWI master operates correctly.

The Instantiation table in Instantiation on page 26 shows which peripherals have the same ID as the TWI.

6.17.2 EasyDMA

The TWIM implements EasyDMA for accessing RAM without CPU involvement.

The TWIM peripheral implements the EasyDMA channels found in the following table.

Channel	Туре	Register Cluster
TXD	READER	TXD
RXD	WRITER	RXD

Table 90: TWIM EasyDMA Channels

For detailed information regarding the use of EasyDMA, see EasyDMA on page 47.

The .PTR and .MAXCNT registers are double-buffered. They can be updated and prepared for the next RX/TX transmission immediately after having received the RXSTARTED/TXSTARTED event.

The STOPPED event indicates that EasyDMA has finished accessing the buffer in RAM.

6.17.3 Master write sequence

A TWI master write sequence is started by triggering the STARTTX task. After the STARTTX task has been triggered, the TWI master will generate a start condition on the TWI bus, followed by clocking out the address and the READ/WRITE bit set to 0 (WRITE=0, READ=1).

The address must match the address of the slave device that the master wants to write to. The READ/WRITE bit is followed by an ACK/NACK bit (ACK=0 or NACK=1) generated by the slave.

After receiving the ACK bit, the TWI master will clock out the data bytes found in the transmit buffer located in RAM at the address specified in the TXD.PTR register. Each byte clocked out from the master will be followed by an ACK/NACK bit clocked in from the slave.

A typical TWI master write sequence is shown in the following figure. Occurrence 2 in the figure illustrates clock stretching performed by the TWI master following a SUSPEND task.

A SUSPENDED event indicates that the SUSPEND task has taken effect. This event can be used to synchronize the software.

The TWI master will generate a LASTTX event when it starts to transmit the last byte, this is shown in the following figure.



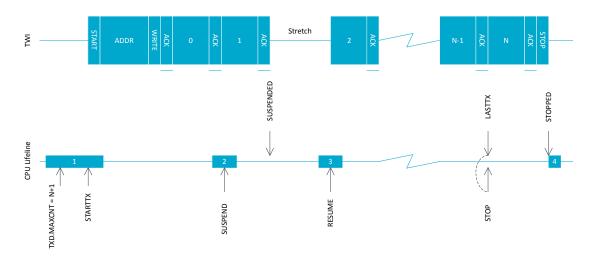


Figure 92: TWI master writing data to a slave

The TWI master is stopped by triggering the STOP task. This task should be triggered during the transmission of the last byte to secure that the TWI master will stop as fast as possible after sending the last byte. The shortcut between LASTTX and STOP can alternatively be used to accomplish this.

Note: The TWI master does not stop by itself when the entire RAM buffer has been sent, or when an error occurs. The STOP task must be issued, through the use of a local or PPI shortcut, or in software as part of the error handler.

6.17.4 Master read sequence

A TWI master read sequence is started by triggering the STARTRX task. After the STARTRX task has been triggered, the TWI master will generate a start condition on the TWI bus, followed by clocking out the address and the READ/WRITE bit set to 1 (WRITE = 0, READ = 1). The address must match the address of the slave device that the master wants to read from. The READ/WRITE bit is followed by an ACK/NACK bit (ACK=0 or NACK = 1) generated by the slave.

After sending the ACK bit, the TWI slave will send data to the master using the clock generated by the master.

Data received will be stored in RAM at the address specified in the RXD.PTR register. The TWI master will generate an ACK after all but the last byte have been received from the slave. The TWI master will generate a NACK after the last byte received to indicate that the read sequence shall stop.

A typical TWI master read sequence is illustrated in The TWI master reading data from a slave on page 299. Occurrence 2 in the figure illustrates clock stretching performed by the TWI master following a SUSPEND task.

A SUSPENDED event indicates that the SUSPEND task has taken effect. This event can be used to synchronize the software.

The TWI master will generate a LASTRX event when it is ready to receive the last byte, as shown in The TWI master reading data from a slave on page 299. If RXD.MAXCNT > 1, the LASTRX event is generated after sending the ACK of the previously received byte. If RXD.MAXCNT = 1, the LASTRX event is generated after receiving the ACK following the address and READ bit.

The TWI master is stopped by triggering the STOP task. This task must be triggered before the NACK bit is supposed to be transmitted. The STOP task can be triggered at any time during the reception of the last byte. It is recommended to use the shortcut between LASTRX and STOP to accomplish this.

The TWI master does not stop by itself when the RAM buffer is full, or when an error occurs. The STOP task must be issued, through the use of a local or PPI shortcut, or in software as part of the error handler.

NORDIC SEMICONDUCTOR

The TWI master cannot be stopped while suspended, so the STOP task must be issued after the TWI master has been resumed.

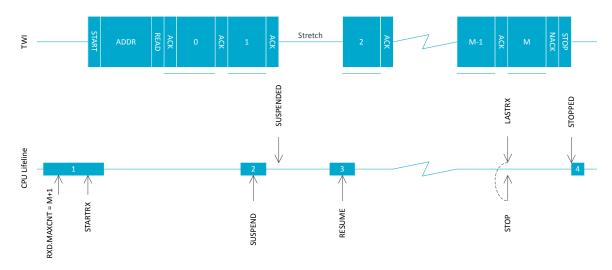


Figure 93: The TWI master reading data from a slave

6.17.5 Master repeated start sequence

A typical repeated start sequence is one in which the TWI master writes two bytes to the slave followed by reading four bytes from the slave. This example uses shortcuts to perform the simplest type of repeated start sequence, i.e. one write followed by one read. The same approach can be used to perform a repeated start sequence where the sequence is read followed by write.

The following figure shows an example of a repeated start sequence where the TWI master writes two bytes followed by reading four bytes from the slave.

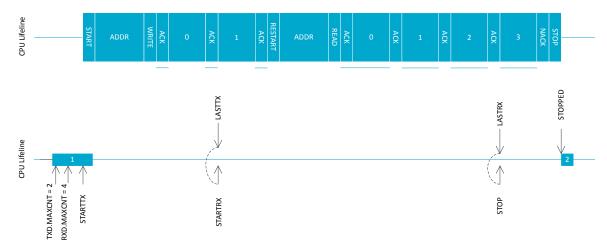


Figure 94: Master repeated start sequence

If a more complex repeated start sequence is needed, and the TWI firmware drive is serviced in a low priority interrupt, it may be necessary to use the SUSPEND task and SUSPENDED event to guarantee that the correct tasks are generated at the correct time. A double repeated start sequence using the SUSPEND task to secure safe operation in low priority interrupts is shown in the following figure.



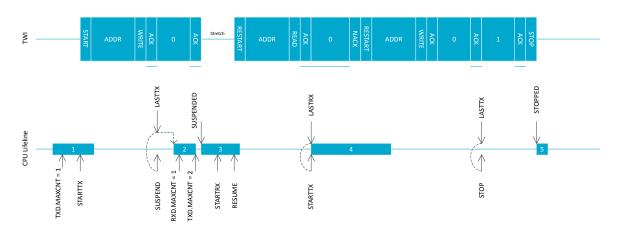


Figure 95: Double repeated start sequence

6.17.6 Low power

When putting the system in low power and the peripheral is not needed, lowest possible power consumption is achieved by stopping, and then disabling the peripheral.

When the STOP task is sent, the software shall wait until the STOPPED event is received as a response before disabling the peripheral through the ENABLE register. If the peripheral is already stopped, the STOP task is not required.

6.17.7 Master mode pin configuration

The SCL and SDA signals associated with the TWI master are mapped to physical pins according to the configuration specified in the PSEL.SCL and PSEL.SDA registers respectively.

The PSEL.SCL and PSEL.SDA registers and their configurations are only used as long as the TWI master is enabled, and retained only as long as the device is in ON mode. When the peripheral is disabled, the pins will behave as regular GPIOs, and use the configuration in their respective OUT bit field and PIN_CNF[n] register. PSEL.SCL, PSEL.SDA must only be configured when the TWI master is disabled.

To secure correct signal levels on the pins used by the TWI master when the system is in OFF mode, and when the TWI master is disabled, these pins must be configured in the GPIO peripheral as described in the following table.

Only one peripheral can be assigned to drive a particular GPIO pin at a time. Failing to do so may result in unpredictable behavior.

TWI master signal	TWI master pin	Direction	Output value	Drive strength
SCL	As specified in PSEL.SCL	Input	Not applicable	SOD1
SDA	As specified in PSEL.SDA	Input	Not applicable	SOD1

Table 91: GPIO configuration before enabling peripheral



6.17.8 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x50008000	TWIM	TWIM0 : S	US	SA	Two-wire interface master 0	
0x40008000	I WIIVI	TWIM0 : NS	03	SA	TWO-WITE IIITETTACE THASTET O	
0x50009000	TWIM	TWIM1:S	US	SA	Two-wire interface master 1	
0x40009000	I WIIVI	TWIM1 : NS	03	SA	TWO-WITE IIITETTACE THASTEL 1	
0x5000A000	TWIM	TWIM2 : S	US	SA	Two-wire interface master 2	
0x4000A000	1 441141	TWIM2 : NS	03	JA.	Two wire interface master 2	
0x5000B000	TWIM	TWIM3 : S	US	SA	Two-wire interface master 3	
0x4000B000	I VVIIVI	TWIM3 : NS	03	SA	TWO-WITE IIITETTACE THASTEL 3	

Table 92: Instances

Register	Offset	Security	Description
TASKS_STARTRX	0x000		Start TWI receive sequence
TASKS_STARTTX	0x008		Start TWI transmit sequence
TASKS_STOP	0x014		Stop TWI transaction. Must be issued while the TWI master is not suspended.
TASKS_SUSPEND	0x01C		Suspend TWI transaction
TASKS_RESUME	0x020		Resume TWI transaction
SUBSCRIBE_STARTRX	0x080		Subscribe configuration for task STARTRX
SUBSCRIBE_STARTTX	0x088		Subscribe configuration for task STARTTX
SUBSCRIBE_STOP	0x094		Subscribe configuration for task STOP
SUBSCRIBE_SUSPEND	0x09C		Subscribe configuration for task SUSPEND
SUBSCRIBE_RESUME	0x0A0		Subscribe configuration for task RESUME
EVENTS_STOPPED	0x104		TWI stopped
EVENTS_ERROR	0x124		TWI error
EVENTS_SUSPENDED	0x148		SUSPEND task has been issued, TWI traffic is now suspended.
EVENTS_RXSTARTED	0x14C		Receive sequence started
EVENTS_TXSTARTED	0x150		Transmit sequence started
EVENTS_LASTRX	0x15C		Byte boundary, starting to receive the last byte
EVENTS_LASTTX	0x160		Byte boundary, starting to transmit the last byte
PUBLISH_STOPPED	0x184		Publish configuration for event STOPPED
PUBLISH_ERROR	0x1A4		Publish configuration for event ERROR
PUBLISH_SUSPENDED	0x1C8		Publish configuration for event SUSPENDED
PUBLISH_RXSTARTED	0x1CC		Publish configuration for event RXSTARTED
PUBLISH_TXSTARTED	0x1D0		Publish configuration for event TXSTARTED
PUBLISH_LASTRX	0x1DC		Publish configuration for event LASTRX
PUBLISH_LASTTX	0x1E0		Publish configuration for event LASTTX
SHORTS	0x200		Shortcuts between local events and tasks
INTEN	0x300		Enable or disable interrupt
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
ERRORSRC	0x4C4		Error source
ENABLE	0x500		Enable TWIM
PSEL.SCL	0x508		Pin select for SCL signal
PSEL.SDA	0x50C		Pin select for SDA signal
FREQUENCY	0x524		TWI frequency. Accuracy depends on the HFCLK source selected.
RXD.PTR	0x534		Data pointer
RXD.MAXCNT	0x538		Maximum number of bytes in receive buffer
RXD.AMOUNT	0x53C		Number of bytes transferred in the last transaction
RXD.LIST	0x540		EasyDMA list type
TXD.PTR	0x544		Data pointer



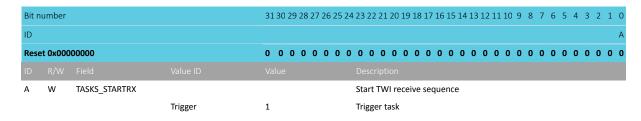
Register	Offset	Security	Description
TXD.MAXCNT	0x548		Maximum number of bytes in transmit buffer
TXD.AMOUNT	0x54C		Number of bytes transferred in the last transaction
TXD.LIST	0x550		EasyDMA list type
ADDRESS	0x588		Address used in the TWI transfer

Table 93: Register overview

6.17.8.1 TASKS_STARTRX

Address offset: 0x000

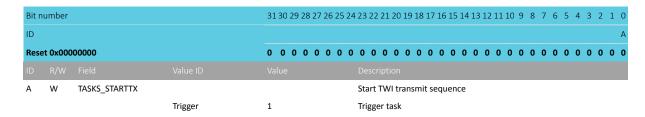
Start TWI receive sequence



6.17.8.2 TASKS STARTTX

Address offset: 0x008

Start TWI transmit sequence



6.17.8.3 TASKS_STOP

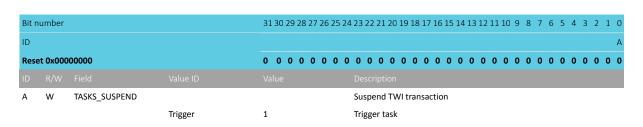
Address offset: 0x014

Stop TWI transaction. Must be issued while the TWI master is not suspended.

Bit r	umber			31 30 29 28 27	26 25 24	23 22	2 21 2	0 19	18 17	7 16	15 3	14 13	12 1	1 10	9 8	3 7	6	5	4 3	2	1 0
ID																					Α
Res	et 0x000	00000		0 0 0 0 0	0 0 0	0 0	0	0 0	0 0	0	0	0 0	0 (0 0	0 (0 0	0	0	0 0	0	0 0
ID																					
Α	W	TASKS_STOP				Stop	TWI	trans	actio	n. N	1ust	be is	sued	whil	e th	e TV	VI m	ıaste	er is	not	
						suspe	ende	d.													
			Trigger	1		Trigg	ger ta	sk													

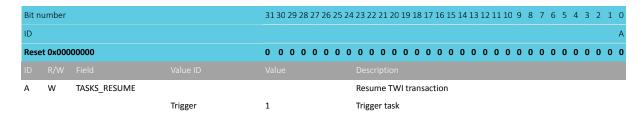
6.17.8.4 TASKS_SUSPEND

Address offset: 0x01C Suspend TWI transaction



6.17.8.5 TASKS_RESUME

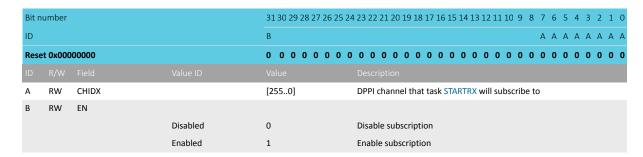
Address offset: 0x020
Resume TWI transaction



6.17.8.6 SUBSCRIBE_STARTRX

Address offset: 0x080

Subscribe configuration for task STARTRX



6.17.8.7 SUBSCRIBE STARTTX

Address offset: 0x088

Subscribe configuration for task STARTTX

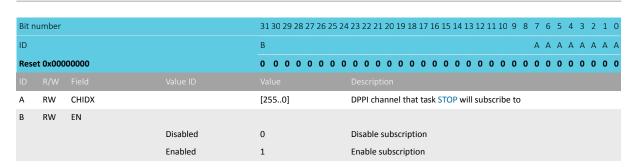
Bit n	umber			31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0											
ID				B A A A A											
Rese	et 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0										
ID															
Α	RW	CHIDX		[2550]	DPPI channel that task STARTTX will subscribe to										
В	RW	EN													
			Disabled	0	Disable subscription										
			Enabled	1	Enable subscription										

6.17.8.8 SUBSCRIBE_STOP

Address offset: 0x094

Subscribe configuration for task STOP





6.17.8.9 SUBSCRIBE_SUSPEND

Address offset: 0x09C

Subscribe configuration for task SUSPEND

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[2550]	DPPI channel that task SUSPEND will subscribe to
В	RW	EN			
			Disabled	0	Disable subscription
			Enabled	1	Enable subscription

6.17.8.10 SUBSCRIBE_RESUME

Address offset: 0x0A0

Subscribe configuration for task RESUME

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[2550]	DPPI channel that task RESUME will subscribe to
В	RW	EN			
			Disabled	0	Disable subscription
			Enabled	1	Enable subscription

6.17.8.11 EVENTS_STOPPED

Address offset: 0x104

TWI stopped



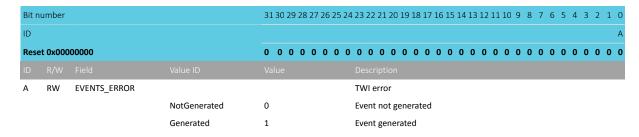




6.17.8.12 EVENTS_ERROR

Address offset: 0x124

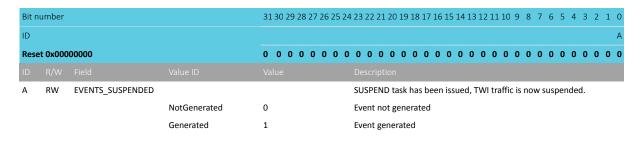
TWI error



6.17.8.13 EVENTS SUSPENDED

Address offset: 0x148

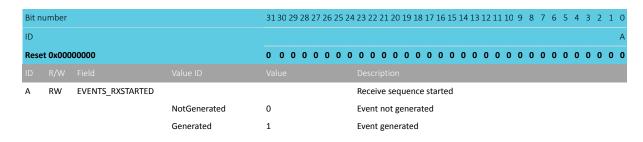
SUSPEND task has been issued, TWI traffic is now suspended.



6.17.8.14 EVENTS RXSTARTED

Address offset: 0x14C

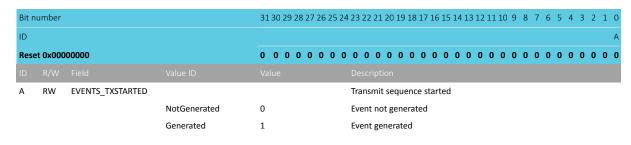
Receive sequence started



6.17.8.15 EVENTS TXSTARTED

Address offset: 0x150

Transmit sequence started

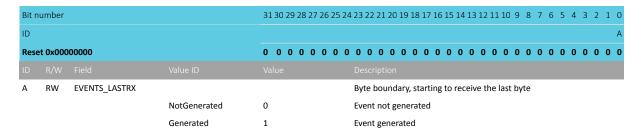




6.17.8.16 EVENTS_LASTRX

Address offset: 0x15C

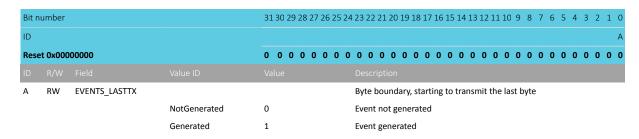
Byte boundary, starting to receive the last byte



6.17.8.17 EVENTS LASTTX

Address offset: 0x160

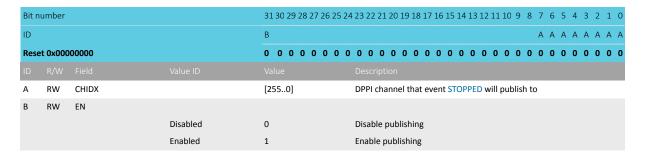
Byte boundary, starting to transmit the last byte



6.17.8.18 PUBLISH STOPPED

Address offset: 0x184

Publish configuration for event STOPPED

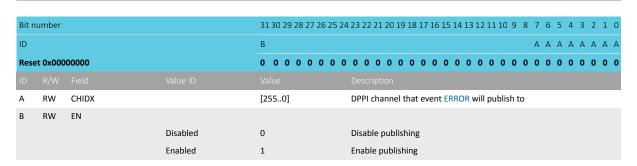


6.17.8.19 PUBLISH ERROR

Address offset: 0x1A4

Publish configuration for event ERROR

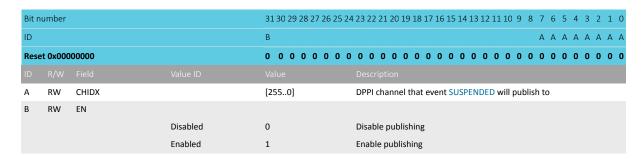




6.17.8.20 PUBLISH SUSPENDED

Address offset: 0x1C8

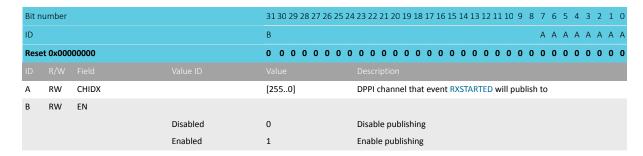
Publish configuration for event SUSPENDED



6.17.8.21 PUBLISH_RXSTARTED

Address offset: 0x1CC

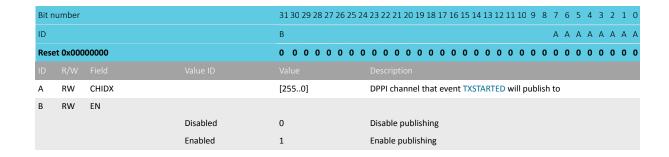
Publish configuration for event RXSTARTED



6.17.8.22 PUBLISH TXSTARTED

Address offset: 0x1D0

Publish configuration for event TXSTARTED



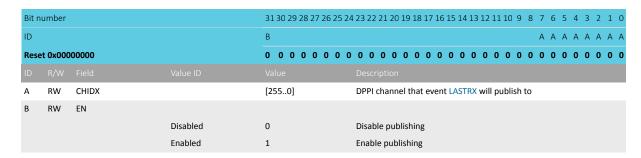




6.17.8.23 PUBLISH_LASTRX

Address offset: 0x1DC

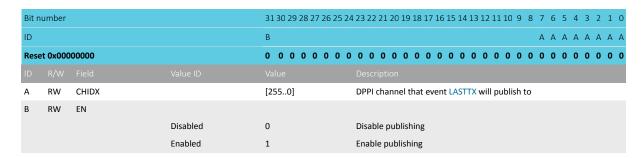
Publish configuration for event LASTRX



6.17.8.24 PUBLISH_LASTTX

Address offset: 0x1E0

Publish configuration for event LASTTX



6.17.8.25 SHORTS

Address offset: 0x200

Shortcuts between local events and tasks

Bit r	number			31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					F DCBA
Res	et 0x000	000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	LASTTX_STARTRX			Shortcut between event LASTTX and task STARTRX
			Disabled	0	Disable shortcut
			Enabled	1	Enable shortcut
В	RW	LASTTX_SUSPEND			Shortcut between event LASTTX and task SUSPEND
			Disabled	0	Disable shortcut
			Enabled	1	Enable shortcut
С	RW	LASTTX_STOP			Shortcut between event LASTTX and task STOP
			Disabled	0	Disable shortcut
			Enabled	1	Enable shortcut
D	RW	LASTRX_STARTTX			Shortcut between event LASTRX and task STARTTX
			Disabled	0	Disable shortcut
			Enabled	1	Enable shortcut
F	RW	LASTRX_STOP			Shortcut between event LASTRX and task STOP
			Disabled	0	Disable shortcut
			Enabled	1	Enable shortcut



6.17.8.26 INTEN

Address offset: 0x300

Enable or disable interrupt

Dit	umber			24 20 20 20 27 26 25 2	4 22 22 24 20 40 40 47 46 46 44 42 42 44 40 0 0 7 6 - 5 4 2 2 4 2
	umber				4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				J	II H G F D A
Rese	et 0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
					Description
Α	RW	STOPPED			Enable or disable interrupt for event STOPPED
			Disabled	0	Disable
			Enabled	1	Enable
D	RW	ERROR			Enable or disable interrupt for event ERROR
			Disabled	0	Disable
			Enabled	1	Enable
F	RW	SUSPENDED			Enable or disable interrupt for event SUSPENDED
			Disabled	0	Disable
			Enabled	1	Enable
G	RW	RXSTARTED			Enable or disable interrupt for event RXSTARTED
			Disabled	0	Disable
			Enabled	1	Enable
Н	RW	TXSTARTED			Enable or disable interrupt for event TXSTARTED
			Disabled	0	Disable
			Enabled	1	Enable
1	RW	LASTRX			Enable or disable interrupt for event LASTRX
			Disabled	0	Disable
			Enabled	1	Enable
J	RW	LASTTX			Enable or disable interrupt for event LASTTX
			Disabled	0	Disable
			Enabled	1	Enable

6.17.8.27 INTENSET

Address offset: 0x304

Enable interrupt

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				J	I H G F D A
Rese	et 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	STOPPED			Write '1' to enable interrupt for event STOPPED
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
D	RW	ERROR			Write '1' to enable interrupt for event ERROR
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
F	RW	SUSPENDED			Write '1' to enable interrupt for event SUSPENDED
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
G	RW	RXSTARTED			Write '1' to enable interrupt for event RXSTARTED



Bit n	umber			31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					JI H G F D A
	et 0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
Н	RW	TXSTARTED			Write '1' to enable interrupt for event TXSTARTED
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
1	RW	LASTRX			Write '1' to enable interrupt for event LASTRX
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
J	RW	LASTTX			Write '1' to enable interrupt for event LASTTX
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled

6.17.8.28 INTENCLR

Address offset: 0x308

Disable interrupt

Bit r	umber			31 30 2	29 28	3 27 20	6 25	24	23 2	22 2	21 2	20 19	9 1	8 17	16	15	14	13 1	2 1	.1 10	9	8	7	6 5	4	3	2	1 0
ID								J	T		ŀ	НЭ	i F								D							A
Rese	et 0x000	00000		0 0	0 0	0 0	0 0	0	0	0 (0 (0 0	0	0	0	0	0	0 (0 (0 0	0	0	0	0 0	0	0	0	0 0
Α	RW	STOPPED							Wri	ite '	1' t	o di	sak	ole i	nte	rru	ot fo	or ev	ven	t ST	ОР	PED						
			Clear	1					Dis	able	9																	
			Disabled	0					Rea	ad: [Disa	able	d															
			Enabled	1					Rea	ad: E	Ena	ble	d															
D	RW	ERROR							Wri	ite ':	1' t	o di	sak	ole i	nte	rru	ot fo	or ev	ven	t EF	RRO	R						
			Clear	1					Dis	able	9																	
			Disabled	0					Rea	ad: [Disa	able	d															
			Enabled	1					Rea	ad: E	Ena	ble	b															
F	RW	SUSPENDED							Wri	ite '	1' t	o di	sak	ole i	nte	rru	ot fo	or ev	ven	t SL	JSP	END	ED					
			Clear	1					Dis	able	9																	
			Disabled	0					Rea	ad: [Disa	able	d															
			Enabled	1					Rea	ad: E	Ena	ble	b															
G	RW	RXSTARTED							Wri	ite '	1' t	o di	sak	ole i	nte	rru	ot fo	or ev	ven	t R>	(ST/	ARTE	D					
			Clear	1					Dis	able	9																	
			Disabled	0					Rea	ad: [Disa	able	d															
			Enabled	1					Rea	ad: E	Ena	ble	b															
Н	RW	TXSTARTED							Wri	ite '	1' t	o di	sak	ole i	nte	rru	ot fo	or ev	ven	t TX	STA	ARTE	D					
			Clear	1					Dis	able	9																	
			Disabled	0					Rea	ad: [Disa	able	d															
			Enabled	1					Rea	ad: E	Ena	ble	b															
I	RW	LASTRX							Wri	ite '	1' t	o di	sak	ole i	nte	rru	ot fo	or ev	ven	t LA	STI	RX						
			Clear	1					Dis	able	9																	
			Disabled	0					Rea	ad: [Disa	able	d															
			Enabled	1					Rea	ad: E	Ena	ble	d															



Bit number	31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		JI HGF D A
Reset 0x00000000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID R/W Field Value ID		Description
J RW LASTTX		Write '1' to disable interrupt for event LASTTX
Clear	1	Disable
Disabled	0	Read: Disabled
Enabled	1	Read: Enabled

6.17.8.29 ERRORSRC

Address offset: 0x4C4

Error source

Bit r	umber			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					СВА
Rese	et 0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	OVERRUN			Overrun error
					A new byte was received before previous byte got transferred into RXD
					buffer. (Previous data is lost)
			NotReceived	0	Error did not occur
			Received	1	Error occurred
В	RW	ANACK			NACK received after sending the address (write '1' to clear)
			NotReceived	0	Error did not occur
			Received	1	Error occurred
С	RW	DNACK			NACK received after sending a data byte (write '1' to clear)
			NotReceived	0	Error did not occur
			Received	1	Error occurred

6.17.8.30 ENABLE

Address offset: 0x500

Enable TWIM

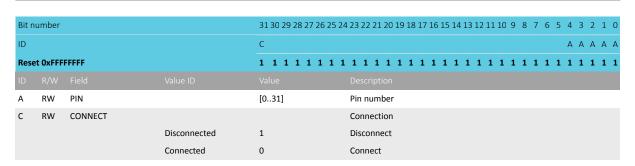
Bit n	umber			31 30 29 28 27	26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					ААА
Rese	et 0x000	00000		0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
Α	RW	ENABLE			Enable or disable TWIM
			Disabled	0	Disable TWIM
			Enabled	6	Enable TWIM

6.17.8.31 PSEL.SCL

Address offset: 0x508

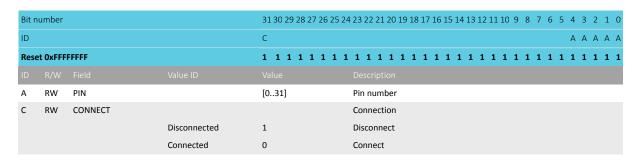
Pin select for SCL signal





6.17.8.32 PSEL.SDA

Address offset: 0x50C Pin select for SDA signal



6.17.8.33 FREQUENCY

Address offset: 0x524

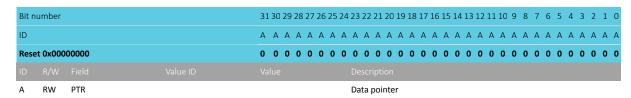
TWI frequency. Accuracy depends on the HFCLK source selected.

Bit n	umber			31 30	29	28 2	7 26	5 25	24	23	22	21	20	19	18	17	16	15	14	13 1	2 11	10	9	8	7 6	5 5	5 4	3	2	1 0
ID				A A	Α	A A	4 Α	A	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	A A	A A	Α	A	Δ /	4 <i>A</i>	۸ ۸	4 A	Α	Α	А А
Rese	t 0x040	00000		0 0	0	0 (0 1	0	0	0	0	0	0	0	0	0	0	0	0	0 (0	0	0	0 () () (0 0	0	0	0 0
ID																														
Α	RW	FREQUENCY					Т	Т		TV	VIr	nas	ter	clo	ck t	frec	que	ency	У						Т	Т				
A	RW	FREQUENCY	K100	0x01	9800	000	Π					nas bps		clo	ock t	frec	que	ency	У											
A	RW	FREQUENCY	K100 K250	0x019						10	0 k		S	clo	ock t	frec	que	ency	у											

6.17.8.34 RXD.PTR

Address offset: 0x534

Data pointer



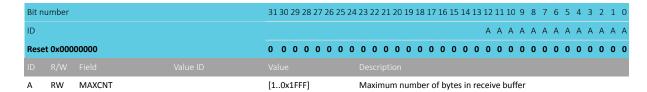
See the memory chapter for details about which memories are available for EasyDMA.



6.17.8.35 RXD.MAXCNT

Address offset: 0x538

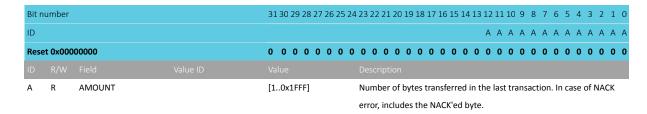
Maximum number of bytes in receive buffer



6.17.8.36 RXD.AMOUNT

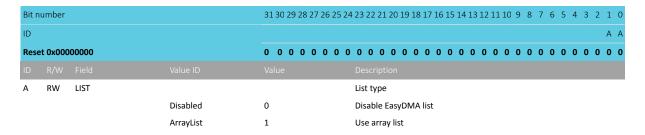
Address offset: 0x53C

Number of bytes transferred in the last transaction



6.17.8.37 RXD.LIST

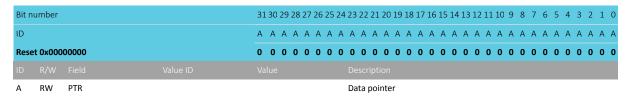
Address offset: 0x540 EasyDMA list type



6.17.8.38 TXD.PTR

Address offset: 0x544

Data pointer



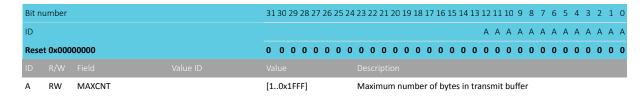
See the memory chapter for details about which memories are available for EasyDMA.



6.17.8.39 TXD.MAXCNT

Address offset: 0x548

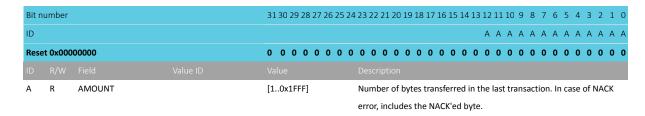
Maximum number of bytes in transmit buffer



6.17.8.40 TXD.AMOUNT

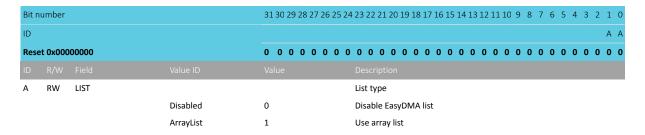
Address offset: 0x54C

Number of bytes transferred in the last transaction



6.17.8.41 TXD.LIST

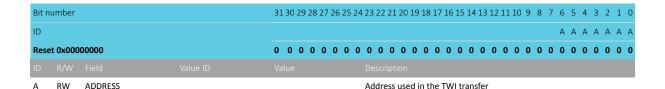
Address offset: 0x550 EasyDMA list type



6.17.8.42 ADDRESS

Address offset: 0x588

Address used in the TWI transfer





6.17.9 Electrical specification

6.17.9.1 TWIM interface electrical specifications

Symbol	Description	Min.	Тур.	Max.	Units
f _{TWIM,SCL}	Bit rates for TWIM ¹⁹	100		400	kbps
t _{TWIM,START}	Time from STARTRX/STARTTX task to transmission started		1.615		μs

6.17.9.2 Two Wire Interface Master (TWIM) timing specifications

Symbol	Description	Min.	Тур.	Max.	Units
t _{TWIM,SU_DAT}	Data setup time before positive edge on SCL – all modes	300			ns
t _{TWIM,HD_DAT}	Data hold time after negative edge on SCL $-$ 100, 250 and	500			ns
	400 kbps				
t _{TWIM,HD_STA,100kbps}	TWIM master hold time for START and repeated START	10000			ns
	condition, 100 kbps				
$t_{\text{TWIM},\text{HD_STA},250\text{kbps}}$	TWIM master hold time for START and repeated START	4000			ns
	condition, 250 kbps				
$t_{\text{TWIM},\text{HD_STA},400\text{kbps}}$	TWIM master hold time for START and repeated START	2500			ns
	condition, 400 kbps				
$t_{TWIM,SU_STO,100kbps}$	TWIM master setup time from SCL high to STOP condition,	5000			ns
	100 kbps				
$t_{\text{TWIM,SU_STO,250kbps}}$	TWIM master setup time from SCL high to STOP condition,	2000			ns
	250 kbps				
$t_{\text{TWIM,SU_STO,400kbps}}$	TWIM master setup time from SCL high to STOP condition,	1250			ns
	400 kbps				
$t_{\text{TWIM},\text{BUF},\text{100kbps}}$	TWIM master bus free time between STOP and START	5800			ns
	conditions, 100 kbps				
t _{TWIM,BUF,250kbps}	TWIM master bus free time between STOP and START	2700			ns
	conditions, 250 kbps				
t _{TWIM,BUF,400kbps}	TWIM master bus free time between STOP and START	2100			ns
	conditions, 400 kbps				

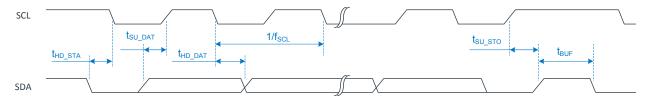


Figure 96: TWIM timing diagram, 1 byte transaction



¹⁹ High bit rates or stronger pull-ups may require GPIOs to be set as High Drive, see GPIO — General purpose input/output on page 102 for more details.

6.17.10 Pullup resistor

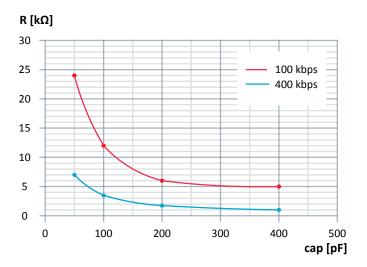


Figure 97: Recommended TWIM pullup value vs. line capacitance

- The I2C specification allows a line capacitance of 400 pF at most.
- The value of internal pullup resistor (R_{PU}) for nRF9160 can be found in GPIO General purpose input/output on page 102.

$6.18 \text{ TWIS} - I^2 \text{C}$ compatible two-wire interface slave with EasyDMA

TWI slave with EasyDMA (TWIS) is compatible with I^2C operating at 100 kHz and 400 kHz. The TWI transmitter and receiver implement EasyDMA.

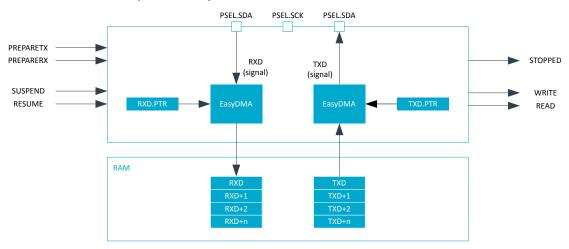


Figure 98: TWI slave with EasyDMA

316

A typical TWI setup consists of one master and one or more slaves. For an example, see the following figure. TWIS is only able to operate with a single master on the TWI bus.

NORDIC^{*}

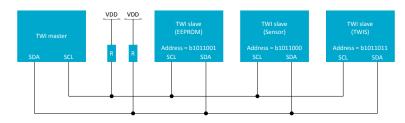


Figure 99: A typical TWI setup comprising one master and three slaves

The following figure shows the TWI slave state machine.

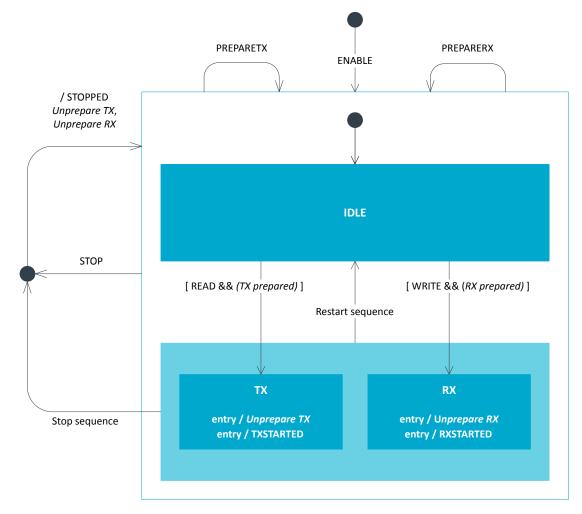


Figure 100: TWI slave state machine

The following table contains descriptions of the symbols used in the state machine.



Symbol	Туре	Description
ENABLE	Register	The TWI slave has been enabled via the ENABLE register.
PREPARETX	Task	The TASKS_PREPARETX task has been triggered.
STOP	Task	The TASKS_STOP task has been triggered.
PREPARERX	Task	The TASKS_PREPARERX task has been triggered.
STOPPED	Event	The EVENTS_STOPPED event was generated.
RXSTARTED	Event	The EVENTS_RXSTARTED event was generated.
TXSTARTED	Event	The EVENTS_TXSTARTED event was generated.
TX prepared	Internal	Internal flag indicating that a TASKS_PREPARETX task has been triggered. This flag is not visible to the
		user.
RX prepared	Internal	Internal flag indicating that a TASKS_PREPARERX task has been triggered. This flag is not visible to the
		user.
Unprepare TX	Internal	Clears the internal 'TX prepared' flag until next TASKS_PREPARETX task.
Unprepare RX	Internal	Clears the internal 'RX prepared' flag until next TASKS_PREPARERX task.
Stop condition	TWI protocol	A TWI stop condition was detected.
Restart condition	TWI protocol	A TWI restart condition was detected.

Table 94: TWI slave state machine symbols

The TWI slave can perform clock stretching, with the premise that the master is able to support it.

The TWI slave operates in a low power mode while waiting for a TWI master to initiate a transfer. As long as the TWI slave is not addressed, it will remain in this low power mode.

To secure correct behavior of the TWI slave, PSEL.SCL, PSEL.SDA, CONFIG, and the ADDRESS[n] registers must be configured prior to enabling the TWI slave through the ENABLE register. Similarly, changing these settings must be performed while the TWI slave is disabled. Failing to do so may result in unpredictable behavior.

6.18.1 Shared resources

The TWI slave shares registers and other resources with other peripherals that have the same ID as the TWI slave.

Therefore, you must disable all peripherals that have the same ID as the TWI slave before the TWI slave can be configured and used. Disabling a peripheral that has the same ID as the TWI slave will not reset any of the registers that are shared with the TWI slave. It is therefore important to configure all relevant registers explicitly to secure that the TWI slave operates correctly.

The Instantiation table in Instantiation on page 26 shows which peripherals have the same ID as the TWI slave.

6.18.2 EasyDMA

The TWIS implements EasyDMA for accessing RAM without CPU involvement.

The following table shows the Easy DMA channels that the TWIS peripheral implements.

Channel	Туре	Register Cluster
TXD	READER	TXD
RXD	WRITER	RXD

Table 95: TWIS EasyDMA Channels

For detailed information regarding the use of EasyDMA, see EasyDMA on page 47.

The STOPPED event indicates that EasyDMA has finished accessing the buffer in RAM.



6.18.3 TWI slave responding to a read command

Before the TWI slave can respond to a read command, the TWI slave must be configured correctly and enabled via the ENABLE register. When enabled, the TWI slave will be in its IDLE state. .

A read command is started when the TWI master generates a start condition on the TWI bus, followed by clocking out the address and the READ/WRITE bit set to 1 (WRITE=0, READ=1). The READ/WRITE bit is followed by an ACK/NACK bit (ACK=0 or NACK=1) response from the TWI slave.

The TWI slave is able to listen for up to two addresses at the same time. This is configured in the ADDRESS registers and the CONFIG register.

The TWI slave will only acknowledge (ACK) the read command if the address presented by the master matches one of the addresses the slave is configured to listen for. The TWI slave will generate a READ event when it acknowledges the read command.

The TWI slave is only able to detect a read command from the IDLE state.

The TWI slave will set an internal 'TX prepared' flag when the PREPARETX task is triggered.

When the read command is received, the TWI slave will enter the TX state if the internal 'TX prepared' flag is set.

If the internal 'TX prepared' flag is not set when the read command is received, the TWI slave will stretch the master's clock until the PREPARETX task is triggered and the internal 'TX prepared' flag is set.

The TWI slave will generate the TXSTARTED event and clear the 'TX prepared' flag ('unprepare TX') when it enters the TX state. In this state the TWI slave will send the data bytes found in the transmit buffer to the master using the master's clock.

The TWI slave will go back to the IDLE state if the TWI slave receives a restart command when it is in the TX state.

The TWI slave is stopped when it receives the stop condition from the TWI master. A STOPPED event will be generated when the transaction has stopped. The TWI slave will clear the 'TX prepared' flag ('unprepare TX') and go back to the IDLE state when it has stopped.

The transmit buffer is located in RAM at the address specified in the TXD.PTR register. The TWI slave will only be able to send TXD.MAXCNT bytes from the transmit buffer for each transaction. If the TWI master forces the slave to send more than TXD.MAXCNT bytes, the slave will send the byte specified in the ORC register to the master instead. If this happens, an ERROR event will be generated.

The EasyDMA configuration registers, see TXD.PTR etc., are latched when the TXSTARTED event is generated.

The TWI slave can be forced to stop by triggering the STOP task. A STOPPED event will be generated when the TWI slave has stopped. The TWI slave will clear the 'TX prepared' flag and go back to the IDLE state when it has stopped, see also Terminating an ongoing TWI transaction on page 322.

Each byte sent from the slave will be followed by an ACK/NACK bit sent from the master. The TWI master will generate a NACK following the last byte that it wants to receive to tell the slave to release the bus so that the TWI master can generate the stop condition. The TXD.AMOUNT register can be queried after a transaction to see how many bytes were sent.

A typical TWI slave read command response is shown in the following figure. Occurrence 2 in the figure illustrates clock stretching performed by the TWI slave following a SUSPEND task.



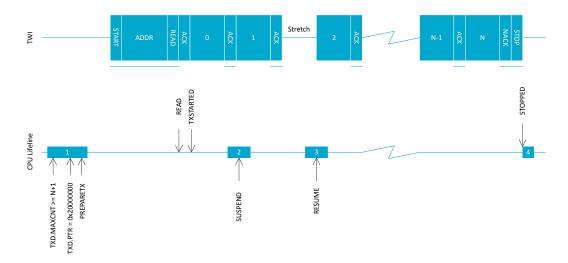


Figure 101: The TWI slave responding to a read command

6.18.4 TWI slave responding to a write command

Before the TWI slave can respond to a write command, the TWI slave must be configured correctly and enabled via the ENABLE register. When enabled, the TWI slave will be in its IDLE state.

A write command is started when the TWI master generates a start condition on the TWI bus, followed by clocking out the address and the READ/WRITE bit set to 0 (WRITE=0, READ=1). The READ/WRITE bit is followed by an ACK/NACK bit (ACK=0 or NACK=1) response from the slave.

The TWI slave is able to listen for up to two addresses at the same time. This is configured in the ADDRESS registers and the CONFIG register.

The TWI slave will only acknowledge (ACK) the write command if the address presented by the master matches one of the addresses the slave is configured to listen for. The TWI slave will generate a WRITE event if it acknowledges the write command.

The TWI slave is only able to detect a write command from the IDLE state.

The TWI slave will set an internal 'RX prepared' flag when the PREPARERX task is triggered.

When the write command is received, the TWI slave will enter the RX state if the internal 'RX prepared' flag is set.

If the internal 'RX prepared' flag is not set when the write command is received, the TWI slave will stretch the master's clock until the PREPARERX task is triggered and the internal 'RX prepared' flag is set.

The TWI slave will generate the RXSTARTED event and clear the internal 'RX prepared' flag ('unprepare RX') when it enters the RX state. In this state, the TWI slave will be able to receive the bytes sent by the TWI master.

The TWI slave will go back to the IDLE state if the TWI slave receives a restart command when it is in the RX state.

The TWI slave is stopped when it receives the stop condition from the TWI master. A STOPPED event will be generated when the transaction has stopped. The TWI slave will clear the internal 'RX prepared' flag ('unprepare RX') and go back to the IDLE state when it has stopped.

The receive buffer is located in RAM at the address specified in the RXD.PTR register. The TWI slave will only be able to receive as many bytes as specified in the RXD.MAXCNT register. If the TWI master tries to send more bytes to the slave than it can receive, the extra bytes are discarded and NACKed by the slave. If this happens, an ERROR event will be generated.

The EasyDMA configuration registers, see RXD.PTR etc., are latched when the RXSTARTED event is generated.

NORDIC

The TWI slave can be forced to stop by triggering the STOP task. A STOPPED event will be generated when the TWI slave has stopped. The TWI slave will clear the internal 'RX prepared' flag and go back to the IDLE state when it has stopped, see also Terminating an ongoing TWI transaction on page 322.

The TWI slave will generate an ACK after every byte received from the master. The RXD.AMOUNT register can be queried after a transaction to see how many bytes were received.

A typical TWI slave write command response is show in the following figure. Occurrence 2 in the figure illustrates clock stretching performed by the TWI slave following a SUSPEND task.

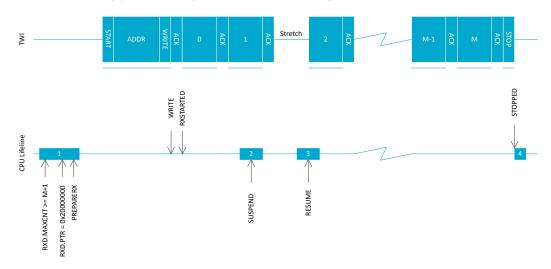


Figure 102: The TWI slave responding to a write command

6.18.5 Master repeated start sequence

An example of a repeated start sequence is one in which the TWI master writes two bytes to the slave followed by reading four bytes from the slave.

This is illustrated in the following figure.

In this example, the receiver does not know what the master wants to read in advance. This information is in the first two received bytes of the write in the repeated start sequence. To guarantee that the CPU is able to process the received data before the TWI slave starts to reply to the read command, the SUSPEND task is triggered via a shortcut from the READ event generated when the read command is received. When the CPU has processed the incoming data and prepared the correct data response, the CPU will resume the transaction by triggering the RESUME task.

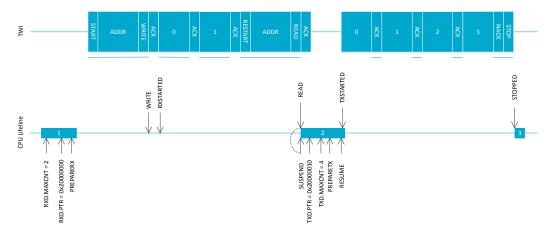


Figure 103: Repeated start sequence



6.18.6 Terminating an ongoing TWI transaction

In some situations, e.g. if the external TWI master is not responding correctly, it may be required to terminate an ongoing transaction.

This can be achieved by triggering the STOP task. In this situation, a STOPPED event will be generated when the TWI has stopped independent of whether or not a STOP condition has been generated on the TWI bus. The TWI slave will release the bus when it has stopped and go back to its IDLE state.

6.18.7 Low power

When putting the system in low power and the peripheral is not needed, lowest possible power consumption is achieved by stopping, and then disabling the peripheral.

The STOP task may not be always needed (the peripheral might already be stopped), but if it is sent, software shall wait until the STOPPED event was received as a response before disabling the peripheral through the ENABLE register.

6.18.8 Slave mode pin configuration

The SCL and SDA signals associated with the TWI slave are mapped to physical pins according to the configuration specified in the PSEL.SCL and PSEL.SDA registers respectively.

The PSEL.SCL and PSEL.SDA registers and their configurations are only used as long as the TWI slave is enabled, and retained only as long as the device is in ON mode. When the peripheral is disabled, the pins will behave as regular GPIOs, and use the configuration in their respective OUT bit field and PIN_CNF[n] register. PSEL.SCL and PSEL.SDA must only be configured when the TWI slave is disabled.

To secure correct signal levels on the pins used by the TWI slave when the system is in OFF mode, and when the TWI slave is disabled, these pins must be configured in the GPIO peripheral as described in the following table.

Only one peripheral can be assigned to drive a particular GPIO pin at a time. Failing to do so may result in unpredictable behavior.

TWI slave signal	TWI slave pin	Direction	Output value	Drive strength
SCL	As specified in PSEL.SCL	Input	Not applicable	S0D1
SDA	As specified in PSEL.SDA	Input	Not applicable	SOD1

Table 96: GPIO configuration before enabling peripheral

6.18.9 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x50008000	TWIS	TWIS0 : S	US	SA	Two-wire interface slave 0	
0x40008000	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	TWIS0 : NS	03	3A	TWO-WIFE IIILEFFACE STAVE O	
0x50009000	TWIS	TWIS1:S	US	SA	Two-wire interface slave 1	
0x40009000	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	TWIS1 : NS	03	3A	TWO-WIFE IIITEFFACE STAVE 1	
0x5000A000	TWIS	TWIS2 : S	LIC	54	Two-wire interface slave 2	
0x4000A000	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	TWIS2 : NS	US	SA	Two-wire interface slave 2	
0x5000B000	TIME	TWIS3 : S	uc	54	Two-wire interface slave 3	
0x4000B000	TWIS	TWIS3 : NS	US	SA	TWO-WITE ITILETTACE STAVE 3	

Table 97: Instances

Register	Offset	Security	Description
TASKS_STOP	0x014		Stop TWI transaction



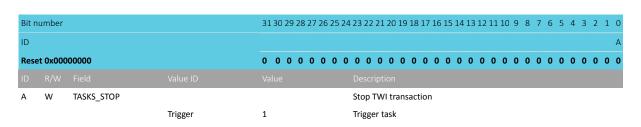
Register	Offset	Security	Description
TASKS_SUSPEND	0x01C		Suspend TWI transaction
TASKS_RESUME	0x020		Resume TWI transaction
TASKS_PREPARERX	0x030		Prepare the TWI slave to respond to a write command
TASKS_PREPARETX	0x034		Prepare the TWI slave to respond to a read command
SUBSCRIBE_STOP	0x094		Subscribe configuration for task STOP
SUBSCRIBE_SUSPEND	0x09C		Subscribe configuration for task SUSPEND
SUBSCRIBE_RESUME	0x0A0		Subscribe configuration for task RESUME
SUBSCRIBE_PREPARERX	0x0B0		Subscribe configuration for task PREPARERX
SUBSCRIBE_PREPARETX	0x0B4		Subscribe configuration for task PREPARETX
EVENTS_STOPPED	0x104		TWI stopped
EVENTS_ERROR	0x124		TWI error
EVENTS_RXSTARTED	0x14C		Receive sequence started
EVENTS_TXSTARTED	0x150		Transmit sequence started
EVENTS_WRITE	0x164		Write command received
EVENTS_READ	0x168		Read command received
PUBLISH_STOPPED	0x184		Publish configuration for event STOPPED
PUBLISH_ERROR	0x1A4		Publish configuration for event ERROR
PUBLISH_RXSTARTED	0x1CC		Publish configuration for event RXSTARTED
PUBLISH_TXSTARTED	0x1D0		Publish configuration for event TXSTARTED
PUBLISH_WRITE	0x1E4		Publish configuration for event WRITE
PUBLISH_READ	0x1E8		Publish configuration for event READ
SHORTS	0x200		Shortcuts between local events and tasks
INTEN	0x300		Enable or disable interrupt
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
ERRORSRC	0x4D0		Error source
MATCH	0x4D4		Status register indicating which address had a match
ENABLE	0x500		Enable TWIS
PSEL.SCL	0x508		Pin select for SCL signal
PSEL.SDA	0x50C		Pin select for SDA signal
RXD.PTR	0x534		RXD Data pointer
RXD.MAXCNT	0x538		Maximum number of bytes in RXD buffer
RXD.AMOUNT	0x53C		Number of bytes transferred in the last RXD transaction
RXD.LIST	0x540		EasyDMA list type
TXD.PTR	0x544		TXD Data pointer
TXD.MAXCNT	0x548		Maximum number of bytes in TXD buffer
TXD.AMOUNT	0x54C		Number of bytes transferred in the last TXD transaction
TXD.LIST	0x550		EasyDMA list type
ADDRESS[n]	0x588		TWI slave address n
CONFIG	0x594		Configuration register for the address match mechanism
ORC	0x5C0		Over-read character. Character sent out in case of an over-read of the transmit buffer.

Table 98: Register overview

6.18.9.1 TASKS_STOP

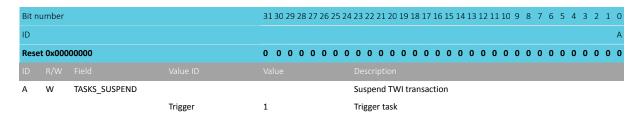
Address offset: 0x014
Stop TWI transaction





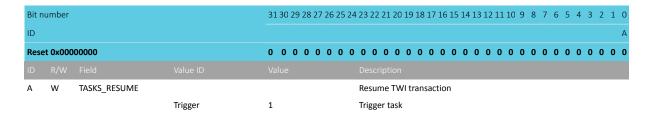
6.18.9.2 TASKS SUSPEND

Address offset: 0x01C
Suspend TWI transaction



6.18.9.3 TASKS RESUME

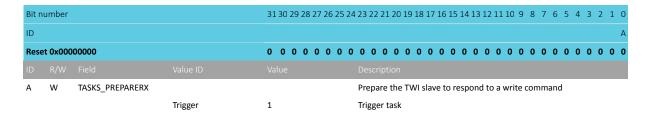
Address offset: 0x020
Resume TWI transaction



6.18.9.4 TASKS PREPARERX

Address offset: 0x030

Prepare the TWI slave to respond to a write command

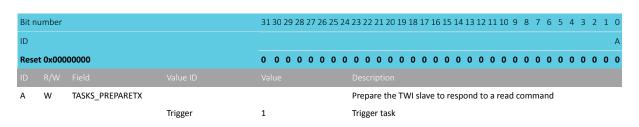


6.18.9.5 TASKS_PREPARETX

Address offset: 0x034

Prepare the TWI slave to respond to a read command





6.18.9.6 SUBSCRIBE_STOP

Address offset: 0x094

Subscribe configuration for task STOP

Bit n	umber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1	0
ID				В	A A A A A	Α
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0
ID						
Α	RW	CHIDX		[2550]	DPPI channel that task STOP will subscribe to	
В	RW	EN				
			Disabled	0	Disable subscription	
			Enabled	1	Enable subscription	

6.18.9.7 SUBSCRIBE_SUSPEND

Address offset: 0x09C

Subscribe configuration for task SUSPEND

Bit n	umber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[2550]	DPPI channel that task SUSPEND will subscribe to
В	RW	EN			
			Disabled	0	Disable subscription
			Enabled	1	Enable subscription

6.18.9.8 SUBSCRIBE_RESUME

Address offset: 0x0A0

Subscribe configuration for task RESUME

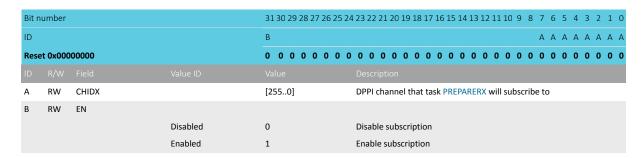
Bit n	umber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1
ID				В	AAAAA
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[2550]	DPPI channel that task RESUME will subscribe to
В	RW	EN			
			Disabled	0	Disable subscription
			Enabled	1	Enable subscription

6.18.9.9 SUBSCRIBE_PREPARERX

Address offset: 0x0B0



Subscribe configuration for task PREPARERX



6.18.9.10 SUBSCRIBE_PREPARETX

Address offset: 0x0B4

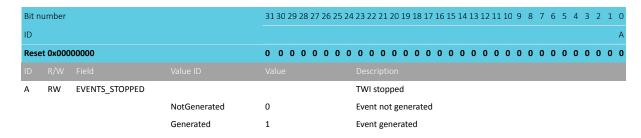
Subscribe configuration for task PREPARETX

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[2550]	DPPI channel that task PREPARETX will subscribe to
В	RW	EN			
			Disabled	0	Disable subscription
			Enabled	1	Enable subscription

6.18.9.11 EVENTS_STOPPED

Address offset: 0x104

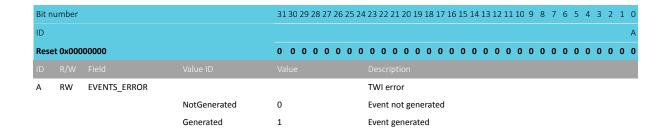
TWI stopped



6.18.9.12 EVENTS_ERROR

Address offset: 0x124

TWI error







6.18.9.13 EVENTS_RXSTARTED

Address offset: 0x14C

Receive sequence started

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					A
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	EVENTS_RXSTARTED			Receive sequence started
			NotGenerated	0	Event not generated
			Generated	1	Event generated

6.18.9.14 EVENTS_TXSTARTED

Address offset: 0x150

Transmit sequence started

Bit n	umber			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					A
Rese	t 0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	EVENTS_TXSTARTED			Transmit sequence started
			NotGenerated	0	Event not generated
			Generated	1	Event generated

6.18.9.15 EVENTS_WRITE

Address offset: 0x164

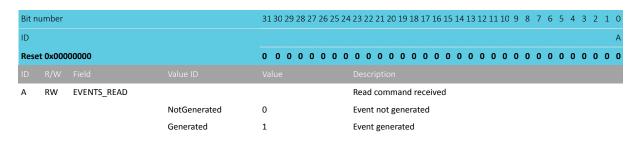
Write command received

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					А
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	EVENTS_WRITE			Write command received
			NotGenerated	0	Event not generated
			Generated	1	Event generated

6.18.9.16 EVENTS_READ

Address offset: 0x168

Read command received

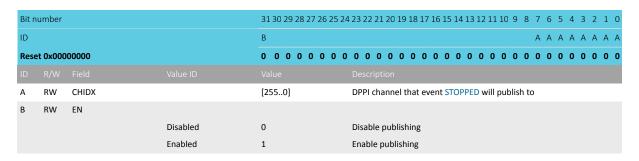




6.18.9.17 PUBLISH_STOPPED

Address offset: 0x184

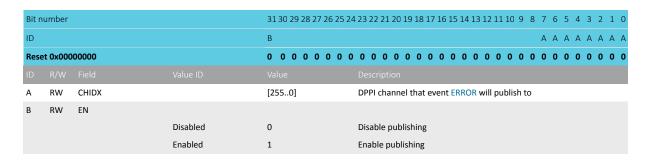
Publish configuration for event STOPPED



6.18.9.18 PUBLISH_ERROR

Address offset: 0x1A4

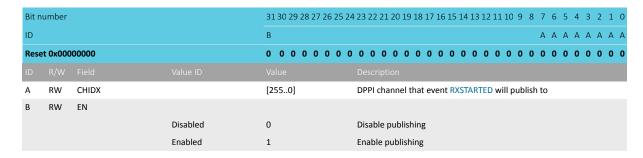
Publish configuration for event ERROR



6.18.9.19 PUBLISH RXSTARTED

Address offset: 0x1CC

Publish configuration for event RXSTARTED

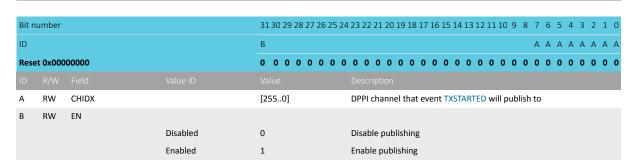


6.18.9.20 PUBLISH_TXSTARTED

Address offset: 0x1D0

Publish configuration for event TXSTARTED





6.18.9.21 PUBLISH_WRITE

Address offset: 0x1E4

Publish configuration for event WRITE

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[2550]	DPPI channel that event WRITE will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing

6.18.9.22 PUBLISH_READ

Address offset: 0x1E8

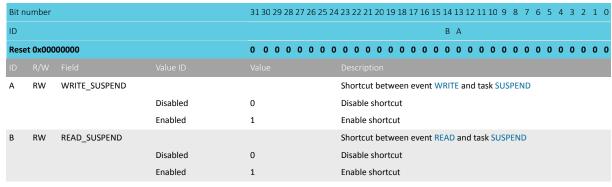
Publish configuration for event READ

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1
ID				В	A A A A A A
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[2550]	DPPI channel that event READ will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing

6.18.9.23 SHORTS

Address offset: 0x200

Shortcuts between local events and tasks







6.18.9.24 INTEN

Address offset: 0x300

Enable or disable interrupt

Bit r	umber			313	30 2	9 28	3 27 2	26 25	5 24	23	22 2	1 2	20 1	.9 18	3 17	16	15 3	14 :	13 1	12 1	11 10	o 9	8	7	6 5	5 4	3	2	1 (
ID								H G	i				F	E								В							Α
Res	et 0x000	00000		0	0 0	0	0	0 0	0	0	0 (0	0 (0 0	0	0	0	0	0	0	0 0	0	0	0	0 (0 0	0	0	0 0
Α	RW	STOPPED								En	able	or	dis	able	e int	err	upt	for	eve	ent	STO	PPE	D						
			Disabled	0						Dis	sable	è																	
			Enabled	1						En	able																		
В	RW	ERROR								En	able	or	dis	able	e int	err	upt	for	eve	ent	ERR	OR							
			Disabled	0						Dis	sable	9																	
			Enabled	1						En	able																		
Ε	RW	RXSTARTED								En	able	or	dis	able	e int	err	upt	for	eve	ent	RXS	TAF	RTEC)					
			Disabled	0						Dis	sable	è																	
			Enabled	1						En	able																		
F	RW	TXSTARTED								En	able	or	dis	able	int	err	upt	for	eve	ent	TXS	TAR	TED)					
			Disabled	0						Dis	sable	è																	
			Enabled	1						En	able																		
G	RW	WRITE								En	able	or	dis	able	int	err	upt	for	eve	ent	WR	ITE							
			Disabled	0						Dis	sable	è																	
			Enabled	1						En	able																		
Н	RW	READ								En	able	or	dis	able	e int	err	upt	for	eve	ent	REA	D							
			Disabled	0						Dis	sable	9																	
			Enabled	1						En	able																		

6.18.9.25 INTENSET

Address offset: 0x304

Enable interrupt

Bit n	umber			31	30 2	29 2	8 2	7 26	6 25	24	23	22 2	21 :	20 1	19 1	8 17	7 16	15	14	13 1	12 1	111	0 9	8	7	6	5 4	3	2	1 0
ID								Н	I G					F	Е								В							Α
Rese	t 0x000	00000		0	0	0 0	0 0	0	0	0	0	0	0	0	0 (0 0	0	0	0	0	0	0 (0	0	0	0	0 0	0	0	0 0
ID																														
Α	RW	STOPPED									Wr	rite '	'1'	to e	enak	ole i	nte	rrup	t fo	or e	ven	t ST	OP	PED						
			Set	1							En	able	2																	
			Disabled	0							Re	ad: I	Dis	abl	ed															
			Enabled	1							Re	ad: I	Ena	able	ed															
В	RW	ERROR									Wr	rite '	1'	to e	enak	ole i	nte	rup	t fo	or e	ven	t EF	RO	R						
			Set	1							En	able																		
			Disabled	0							Re	ad: I	Dis	abl	ed															
			Enabled	1							Re	ad: I	Ena	able	ed															
Е	RW	RXSTARTED									Wr	rite '	1'	to e	enak	ole i	nte	rup	t fo	or e	ven	t R)	ST/	ARTE	D					
			Set	1							En	able	•																	
			Disabled	0							Re	ad: I	Dis	abl	ed															
			Enabled	1							Re	ad: I	Ena	able	ed															
F	RW	TXSTARTED									Wr	rite '	1'	to e	enat	ole i	nte	rrup	t fo	or e	ven	t TX	STA	RTE	D					
			Set	1							En	able	2																	
			Disabled	0							Re	ad: I	Dis	abl	ed															
			Enabled	1							Re	ad: I	Ena	able	ed															
				-										_~.																



7 6 5 4 3 2 1 A 0 0 0 0 0 0 0
0 0 0 0 0 0 0

6.18.9.26 INTENCLR

Address offset: 0x308

Disable interrupt

Bit n	umber			313	30 29	28	27 2	6 25	5 24	23	3 22	21	. 20	19	18	17	16	15	14	13 1	12 :	11 1	LO :	9 8	7	6	5	4	3 :	2 1	. 0
ID							ŀ	H G					F	Ε										В						Δ	
Rese	et 0x000	00000		0	0 0	0	0 (0	0	0	0 (0	0	0	0	0	0	0	0	0	0	0	0	0 0	0	0	0	0	0 (0 0	0
Α	RW	STOPPED								W	Vrite	'1'	' to	dis	ab	le ir	ntei	rup	ot fo	or e	ver	nt S	TO	PPE	D						
			Clear	1						D	isab	le																			
			Disabled	0						R	ead:	Di	sab	ole	t																
			Enabled	1						R	ead:	Er	nabl	led																	
В	RW	ERROR								W	Vrite	'1'	' to	dis	sab	le ir	ntei	rup	ot fo	or e	ver	nt E	RR	OR							
			Clear	1						D	isab	le																			
			Disabled	0						R	ead:	Di	sab	ole	b																
			Enabled	1						R	ead:	Er	nabl	led																	
E	RW	RXSTARTED								W	Vrite	'1'	' to	dis	sab	le ir	ntei	rup	ot fo	or e	ver	nt R	XS	ΓAR	ΓED						
			Clear	1						D	isab	le																			
			Disabled	0						R	ead:	Di	sab	ole	b																
			Enabled	1						R	ead:	Er	nabl	led																	
F	RW	TXSTARTED								W	Vrite	'1'	' to	dis	ab	le ir	nte	rup	ot fo	or e	ver	nt T	XST	AR	ED						
			Clear	1						D	isab	le																			
			Disabled	0						R	ead:	Di	sab	ole	b																
			Enabled	1						R	ead:	Er	nabl	led																	
G	RW	WRITE								W	Vrite	'1'	' to	dis	ab	le ir	ntei	rup	ot fo	or e	ver	nt V	VRI	TE							
			Clear	1						D	isab	le																			
			Disabled	0						R	ead:	Di	sab	ole	t																
			Enabled	1						R	ead:	Er	nabl	led																	
Н	RW	READ								W	Vrite	'1'	' to	dis	sab	le ir	ntei	rup	ot fo	or e	ver	nt R	EA	D							
			Clear	1						D	isab	le																			
			Disabled	0						R	ead:	Di	sab	ole	t																
			Enabled	1						R	ead:	Er	nabl	led																	

6.18.9.27 ERRORSRC

Address offset: 0x4D0

Error source

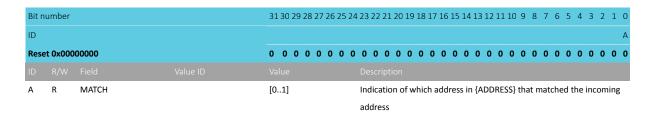


Bit r	umber			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					СВА
Rese	et 0x000	000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	OVERFLOW			RX buffer overflow detected, and prevented
			NotDetected	0	Error did not occur
			Detected	1	Error occurred
В	RW	DNACK			NACK sent after receiving a data byte
			NotReceived	0	Error did not occur
			Received	1	Error occurred
С	RW	OVERREAD			TX buffer over-read detected, and prevented
			NotDetected	0	Error did not occur
			Detected	1	Error occurred

6.18.9.28 MATCH

Address offset: 0x4D4

Status register indicating which address had a match



6.18.9.29 ENABLE

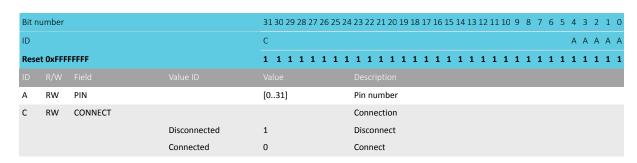
Address offset: 0x500

Enable TWIS

Bit r	umber			31 30 29 2	28 27 2	26 25	24 23 2	2 21 2	20 19	18	17 10	6 15	14 13	3 12	11 1	.0 9	8	7 6	5 5	4	3	2	1 0
ID																					Α	A	A A
Rese	et 0x000	00000		0 0 0	0 0 (0 0	0 0 0	0 (0 0	0	0 0	0	0 0	0	0 (0 0	0	0 (0	0	0	0	0 0
ID																							
Α	RW	ENABLE					Enal	le or	disa	ble 1	WIS	;											
			Disabled	0			Disa	ble TV	NIS														
			Enabled	9			Enal	le TV	VIS														

6.18.9.30 PSEL.SCL

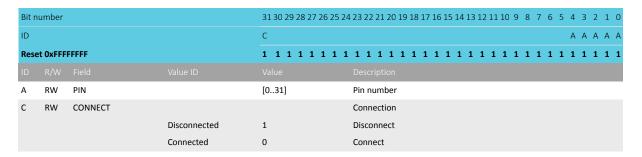
Address offset: 0x508
Pin select for SCL signal





6.18.9.31 PSEL.SDA

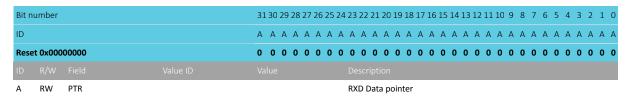
Address offset: 0x50C Pin select for SDA signal



6.18.9.32 RXD.PTR

Address offset: 0x534

RXD Data pointer

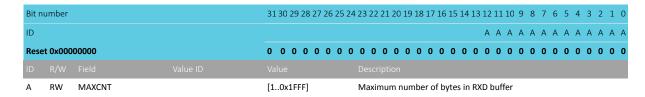


See the memory chapter for details about which memories are available for EasyDMA.

6.18.9.33 RXD.MAXCNT

Address offset: 0x538

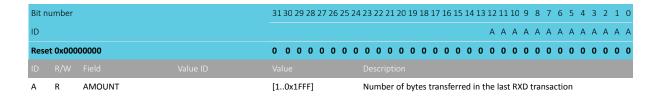
Maximum number of bytes in RXD buffer



6.18.9.34 RXD.AMOUNT

Address offset: 0x53C

Number of bytes transferred in the last RXD transaction

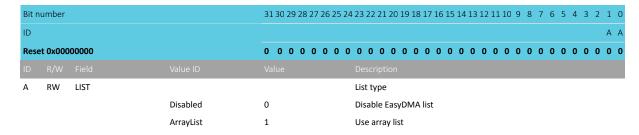




6.18.9.35 RXD.LIST

Address offset: 0x540

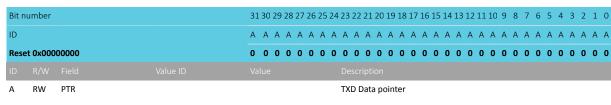
EasyDMA list type



6.18.9.36 TXD.PTR

Address offset: 0x544

TXD Data pointer

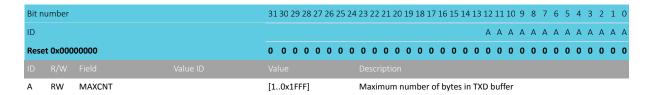


See the memory chapter for details about which memories are available for EasyDMA.

6.18.9.37 TXD.MAXCNT

Address offset: 0x548

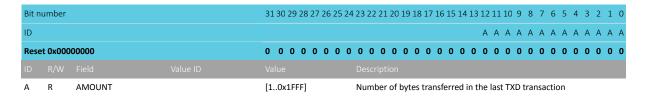
Maximum number of bytes in TXD buffer



6.18.9.38 TXD.AMOUNT

Address offset: 0x54C

Number of bytes transferred in the last TXD transaction

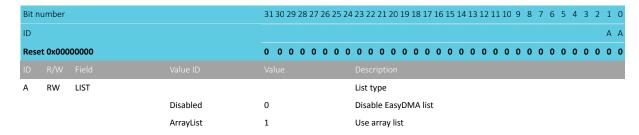


6.18.9.39 TXD.LIST

Address offset: 0x550



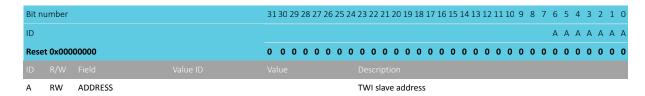
EasyDMA list type



6.18.9.40 ADDRESS[n] (n=0..1)

Address offset: $0x588 + (n \times 0x4)$

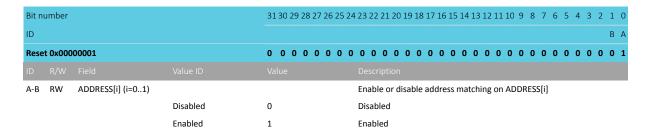
TWI slave address n



6.18.9.41 CONFIG

Address offset: 0x594

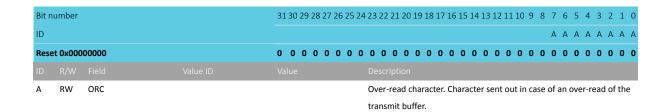
Configuration register for the address match mechanism



6.18.9.42 ORC

Address offset: 0x5C0

Over-read character. Character sent out in case of an over-read of the transmit buffer.





6.18.10 Electrical specification

6.18.10.1 TWIS slave timing specifications

Symbol	Description	Min.	Тур.	Max.	Units
f _{TWIS,SCL}	Bit rates for TWIS ²⁰	100		400	kbps
t _{TWIS,START}	Time from PREPARERX/PREPARETX task to ready to receive/		1.5		μs
	transmit				
t _{TWIS,SU_DAT}	Data setup time before positive edge on SCL – all modes	300			ns
t _{TWIS,HD_DAT}	Data hold time after negative edge on SCL – all modes	500			ns
$t_{\text{TWIS},\text{HD_STA},100\text{kbps}}$	TWI slave hold time from for START condition (SDA low to	5200			ns
	SCL low), 100 kbps				
$t_{\text{TWIS},\text{HD_STA},400\text{kbps}}$	TWI slave hold time from for START condition (SDA low to	1300			ns
	SCL low), 400 kbps				
$t_{\text{TWIS},\text{SU_STO},100\text{kbps}}$	TWI slave setup time from SCL high to STOP condition, 100	5200			ns
	kbps				
$t_{TWIS,SU_STO,400kbps}$	TWI slave setup time from SCL high to STOP condition, 400	1300			ns
	kbps				
t _{TWIS,BUF,100kbps}	TWI slave bus free time between STOP and START		4700		ns
	conditions, 100 kbps				
t _{TWIS,BUF,400kbps}	TWI slave bus free time between STOP and START		1300		ns
	conditions, 400 kbps				

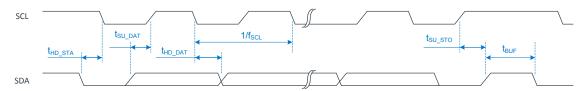


Figure 104: TWIS timing diagram, 1 byte transaction

6.19 UARTE — Universal asynchronous receiver/ transmitter with EasyDMA

The Universal asynchronous receiver/transmitter with EasyDMA (UARTE) offers fast, full-duplex, asynchronous serial communication with built-in flow control (CTS, RTS) support in hardware at a rate up to 1 Mbps, and EasyDMA data transfer from/to RAM.

Listed here are the main features for UARTE:

- Full-duplex operation
- · Automatic hardware flow control
- Optional even parity bit checking and generation
- EasyDMA
- Up to 1 Mbps baudrate
- · Return to IDLE between transactions supported (when using HW flow control)
- One or two stop bit
- · Least significant bit (LSB) first



High bit rates or stronger pull-ups may require GPIOs to be set as High Drive, see GPIO chapter for more details.

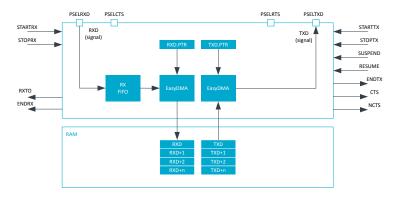


Figure 105: UARTE configuration

The GPIOs used for each UART interface can be chosen from any GPIO on the device and are independently configurable. This enables great flexibility in device pinout and efficient use of board space and signal routing.

Note: The external crystal oscillator must be enabled to obtain sufficient clock accuracy for stable communication. See CLOCK — Clock control on page 74 for more information.

6.19.1 EasyDMA

The UARTE implements EasyDMA for reading and writing to and from the RAM.

If the TXD.PTR and the RXD.PTR are not pointing to the Data RAM region, an EasyDMA transfer may result in a HardFault or RAM corruption. See Memory on page 23 for more information about the different memory regions.

The .PTR and .MAXCNT registers are double-buffered. They can be updated and prepared for the next RX/TX transmission immediately after having received the RXSTARTED/TXSTARTED event.

The ENDRX and ENDTX events indicate that the EasyDMA is finished accessing the RX or TX buffer in RAM.

6.19.2 Transmission

The first step of a DMA transmission is storing bytes in the transmit buffer and configuring EasyDMA. This is achieved by writing the initial address pointer to TXD.PTR, and the number of bytes in the RAM buffer to TXD.MAXCNT. The UARTE transmission is started by triggering the STARTTX task.

After each byte has been sent over the TXD line, a TXDRDY event will be generated.

When all bytes in the TXD buffer, as specified in the TXD.MAXCNT register, have been transmitted, the UARTE transmission will end automatically and an ENDTX event will be generated.

A UARTE transmission sequence is stopped by triggering the STOPTX task. A TXSTOPPED event will be generated when the UARTE transmitter has stopped.

If the ENDTX event has not already been generated when the UARTE transmitter has come to a stop, the UARTE will generate the ENDTX event explicitly even though all bytes in the TXD buffer, as specified in the TXD.MAXCNT register, have not been transmitted.

If flow control is enabled through the HWFC field in the CONFIG register, a transmission will be automatically suspended when CTS is deactivated and resumed when CTS is activated again, as shown in the following figure. A byte that is in transmission when CTS is deactivated will be fully transmitted before the transmission is suspended.



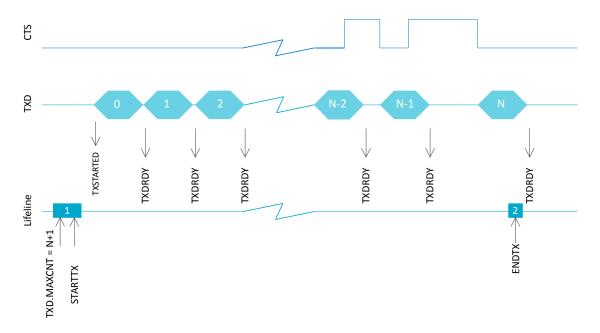


Figure 106: UARTE transmission

The UARTE transmitter will be in its lowest activity level, and consume the least amount of energy, when it is stopped, i.e. before it is started via STARTTX or after it has been stopped via STOPTX and the TXSTOPPED event has been generated. See POWER — Power control on page 68 for more information about power modes.

6.19.3 Reception

The UARTE receiver is started by triggering the STARTRX task. The UARTE receiver is using EasyDMA to store incoming data in an RX buffer in RAM.

The RX buffer is located at the address specified in the RXD.PTR register. The RXD.PTR register is double-buffered and it can be updated and prepared for the next STARTRX task immediately after the RXSTARTED event is generated. The size of the RX buffer is specified in the RXD.MAXCNT register. The UARTE generates an ENDRX event when it has filled up the RX buffer, as seen in the following figure.

For each byte received over the RXD line, an RXDRDY event will be generated. This event is likely to occur before the corresponding data has been transferred to Data RAM.

The RXD.AMOUNT register can be queried following an ENDRX event to see how many new bytes have been transferred to the RX buffer in RAM since the previous ENDRX event.



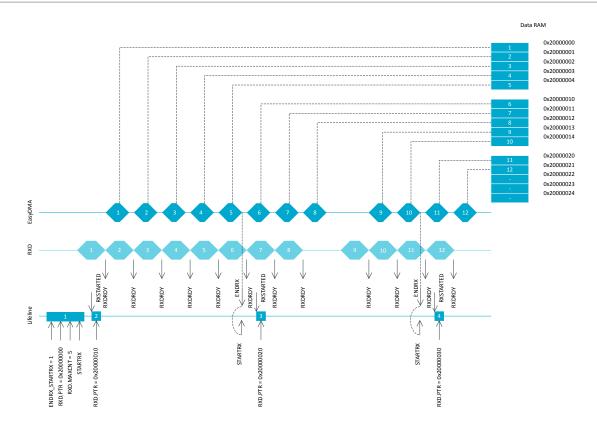


Figure 107: UARTE reception

The UARTE receiver is stopped by triggering the STOPRX task. An RXTO event is generated when the UARTE has stopped. The UARTE will make sure that an impending ENDRX event will be generated before the RXTO event is generated. This means that the UARTE will guarantee that no ENDRX event will be generated after RXTO, unless the UARTE is restarted or a FLUSHRX command is issued after the RXTO event is generated.

Note: If the ENDRX event has not been generated when the UARTE receiver stops, indicating that all pending content in the RX FIFO has been moved to the RX buffer, the UARTE will generate the ENDRX event explicitly even though the RX buffer is not full. In this scenario the ENDRX event will be generated before the RXTO event is generated.

To determine the amount of bytes the RX buffer has received, the CPU can read the RXD.AMOUNT register following the ENDRX event or the RXTO event.

The UARTE is able to receive up to four bytes after the STOPRX task has been triggered, as long as these are sent in succession immediately after the RTS signal is deactivated. After the RTS is deactivated, the UART is able to receive bytes for a period of time equal to the time needed to send four bytes on the configured baud rate.

After the RXTO event is generated the internal RX FIFO may still contain data, and to move this data to RAM the FLUSHRX task must be triggered. To make sure that this data does not overwrite data in the RX buffer, the RX buffer should be emptied or the RXD.PTR should be updated before the FLUSHRX task is triggered. To make sure that all data in the RX FIFO is moved to the RX buffer, the RXD.MAXCNT register must be set to RXD.MAXCNT > 4, as seen in the following figure. The UARTE will generate the ENDRX event after completing the FLUSHRX task even if the RX FIFO was empty or if the RX buffer does not get filled up. To be able to know how many bytes have actually been received into the RX buffer in this case, the CPU can read the RXD.AMOUNT register following the ENDRX event.



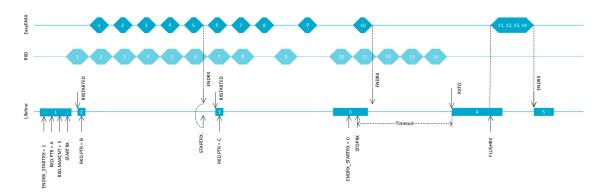


Figure 108: UARTE reception with forced stop via STOPRX

If HW flow control is enabled through the HWFC field in the CONFIG register, the RTS signal will be deactivated when the receiver is stopped via the STOPRX task or when the UARTE is only able to receive four more bytes in its internal RX FIFO.

With flow control disabled, the UARTE will function in the same way as when the flow control is enabled except that the RTS line will not be used. This means that no signal will be generated when the UARTE has reached the point where it is only able to receive four more bytes in its internal RX FIFO. Data received when the internal RX FIFO is filled up, will be lost.

The UARTE receiver will be in its lowest activity level, and consume the least amount of energy, when it is stopped, i.e. before it is started via STARTRX or after it has been stopped via STOPRX and the RXTO event has been generated. See POWER — Power control on page 68 for more information about power modes.

6.19.4 Frror conditions

An ERROR event, in the form of a framing error, will be generated if a valid stop bit is not detected in a frame. Another ERROR event, in the form of a break condition, will be generated if the RXD line is held active low for longer than the length of a data frame. Effectively, a framing error is always generated before a break condition occurs.

An ERROR event will not stop reception. If the error was a parity error, the received byte will still be transferred into Data RAM, and so will following incoming bytes. If there was a framing error (wrong stop bit), that specific byte will NOT be stored into Data RAM, but following incoming bytes will.

6.19.5 Using the UARTE without flow control

If flow control is not enabled, the interface will behave as if the CTS and RTS lines are kept active all the time.

6.19.6 Parity and stop bit configuration

Automatic even parity generation for both transmission and reception can be configured using the register CONFIG on page 358. See the register description for details.

The amount of stop bits can also be configured through the register CONFIG on page 358.

6.19.7 Low power

When putting the system in low power and the peripheral is not needed, lowest possible power consumption is achieved by stopping, and then disabling the peripheral.

The STOPTX and STOPRX tasks may not be always needed (the peripheral might already be stopped), but if STOPTX and/or STOPRX is sent, software shall wait until the TXSTOPPED and/or RXTO event is received in response, before disabling the peripheral through the ENABLE register.



6.19.8 Pin configuration

The different signals RXD, CTS (Clear To Send, active low), RTS (Request To Send, active low), and TXD associated with the UARTE are mapped to physical pins according to the configuration specified in the PSEL.RXD, PSEL.RTS, and PSEL.TXD registers respectively.

The PSEL.RXD, PSEL.CTS, PSEL.RTS, and PSEL.TXD registers and their configurations are only used as long as the UARTE is enabled, and retained only for the duration the device is in ON mode. PSEL.RXD, PSEL.RTS, PSEL.RTS, and PSEL.TXD must only be configured when the UARTE is disabled.

To secure correct signal levels on the pins by the UARTE when the system is in OFF mode, the pins must be configured in the GPIO peripheral as described in the following table.

Only one peripheral can be assigned to drive a particular GPIO pin at a time. Failing to do so may result in unpredictable behavior.

UARTE signal	UARTE pin	Direction	Output value
RXD	As specified in PSEL.RXD	Input	Not applicable
CTS	As specified in PSEL.CTS	Input	Not applicable
RTS	As specified in PSEL.RTS	Output	1
TXD	As specified in PSEL.TXD	Output	1

Table 99: GPIO configuration before enabling peripheral

6.19.9 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x50008000		UARTE0 : S			Universal asynchronous	
0x40008000	UARTE	UARTEO : NS	US	SA	receiver/transmitter with	
0x40006000		UARTEU . NS			EasyDMA 0	
0x50009000		UARTE1:S			Universal asynchronous	
0x40009000	UARTE	UARTE1:3	US	SA	receiver/transmitter with	
0x40009000		UARTEL: NS			EasyDMA 1	
0x5000A000		UARTE2 : S			Universal asynchronous	
0x4000A000	UARTE	UARTE2 : NS	US	SA	receiver/transmitter with	
0x4000A000		UARTEZ : NS			EasyDMA 2	
0x5000B000		UARTE3 : S			Universal asynchronous	
	UARTE		US	SA	receiver/transmitter with	
0x4000B000		UARTE3 : NS			EasyDMA 3	

Table 100: Instances

Register	Offset	Security	Description
TASKS_STARTRX	0x000		Start UART receiver
TASKS_STOPRX	0x004		Stop UART receiver
TASKS_STARTTX	0x008		Start UART transmitter
TASKS_STOPTX	0x00C		Stop UART transmitter
TASKS_FLUSHRX	0x02C		Flush RX FIFO into RX buffer
SUBSCRIBE_STARTRX	0x080		Subscribe configuration for task STARTRX
SUBSCRIBE_STOPRX	0x084		Subscribe configuration for task STOPRX
SUBSCRIBE_STARTTX	0x088		Subscribe configuration for task STARTTX
SUBSCRIBE_STOPTX	0x08C		Subscribe configuration for task STOPTX
SUBSCRIBE_FLUSHRX	0x0AC		Subscribe configuration for task FLUSHRX
EVENTS_CTS	0x100		CTS is activated (set low). Clear To Send.
EVENTS_NCTS	0x104		CTS is deactivated (set high). Not Clear To Send.



	Offset	Security	Description
EVENTS_RXDRDY	0x108		Data received in RXD (but potentially not yet transferred to Data RAM)
EVENTS_ENDRX	0x110		Receive buffer is filled up
EVENTS_TXDRDY	0x11C		Data sent from TXD
EVENTS_ENDTX	0x120		Last TX byte transmitted
EVENTS_ERROR	0x124		Error detected
EVENTS_RXTO	0x144		Receiver timeout
EVENTS_RXSTARTED	0x14C		UART receiver has started
EVENTS_TXSTARTED	0x150		UART transmitter has started
EVENTS_TXSTOPPED	0x158		Transmitter stopped
PUBLISH_CTS	0x180		Publish configuration for event CTS
PUBLISH_NCTS	0x184		Publish configuration for event NCTS
PUBLISH_RXDRDY	0x188		Publish configuration for event RXDRDY
PUBLISH_ENDRX	0x190		Publish configuration for event ENDRX
PUBLISH_TXDRDY	0x19C		Publish configuration for event TXDRDY
PUBLISH_ENDTX	0x1A0		Publish configuration for event ENDTX
PUBLISH_ERROR	0x1A4		Publish configuration for event ERROR
PUBLISH_RXTO	0x1C4		Publish configuration for event RXTO
PUBLISH_RXSTARTED	0x1CC		Publish configuration for event RXSTARTED
PUBLISH_TXSTARTED	0x1D0		Publish configuration for event TXSTARTED
PUBLISH_TXSTOPPED	0x1D8		Publish configuration for event TXSTOPPED
SHORTS	0x200		Shortcuts between local events and tasks
INTEN	0x300		Enable or disable interrupt
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
ERRORSRC	0x480		Error source
			This register is read/write one to clear.
ENABLE	0x500		Enable UART
PSEL.RTS	0x508		Pin select for RTS signal
PSEL.TXD	0x50C		Pin select for TXD signal
PSEL.CTS	0x510		Pin select for CTS signal
PSEL.RXD	0x514		Pin select for RXD signal
BAUDRATE	0x524		Baud rate. Accuracy depends on the HFCLK source selected.
RXD.PTR	0x534		Data pointer
RXD.MAXCNT	0x538		Maximum number of bytes in receive buffer
RXD.AMOUNT	0x53C		Number of bytes transferred in the last transaction
TXD.PTR	0x544		Data pointer
TXD.MAXCNT	0x548		Maximum number of bytes in transmit buffer
	0x54C		Number of bytes transferred in the last transaction
TXD.AMOUNT	0/13-10		,

Table 101: Register overview

6.19.9.1 TASKS_STARTRX

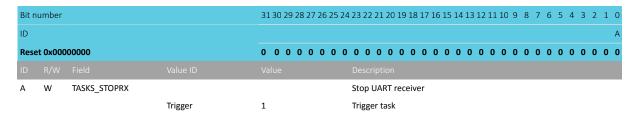
Address offset: 0x000 Start UART receiver

Bit n	umber			31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					A
Rese	t 0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	W	TASKS_STARTRX			Start UART receiver
			Trigger	1	Trigger task



6.19.9.2 TASKS_STOPRX

Address offset: 0x004 Stop UART receiver



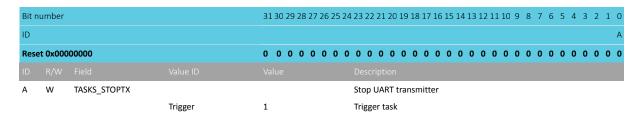
6.19.9.3 TASKS STARTTX

Address offset: 0x008 Start UART transmitter

Bit n	umber			31 30 29 28 27 26 2	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					A
Rese	et 0x000	00000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	W	TASKS_STARTTX			Start UART transmitter
			Trigger	1	Trigger task

6.19.9.4 TASKS_STOPTX

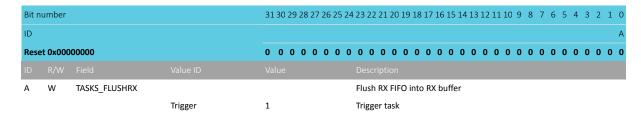
Address offset: 0x00C Stop UART transmitter



6.19.9.5 TASKS_FLUSHRX

Address offset: 0x02C

Flush RX FIFO into RX buffer

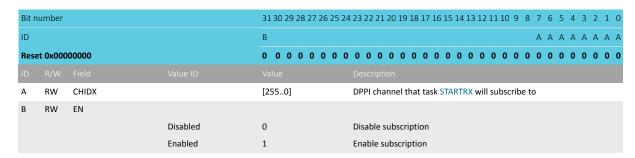


6.19.9.6 SUBSCRIBE_STARTRX

Address offset: 0x080



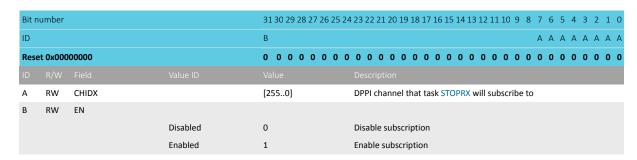
Subscribe configuration for task STARTRX



6.19.9.7 SUBSCRIBE_STOPRX

Address offset: 0x084

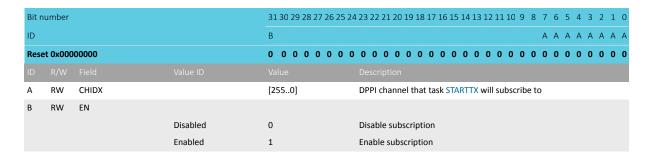
Subscribe configuration for task STOPRX



6.19.9.8 SUBSCRIBE_STARTTX

Address offset: 0x088

Subscribe configuration for task STARTTX

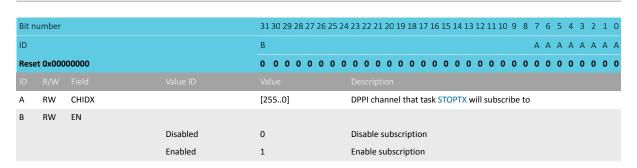


6.19.9.9 SUBSCRIBE_STOPTX

Address offset: 0x08C

Subscribe configuration for task STOPTX





6.19.9.10 SUBSCRIBE_FLUSHRX

Address offset: 0x0AC

Subscribe configuration for task FLUSHRX

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[2550]	DPPI channel that task FLUSHRX will subscribe to
В	RW	EN			
			Disabled	0	Disable subscription
			Enabled	1	Enable subscription

6.19.9.11 EVENTS_CTS

Address offset: 0x100

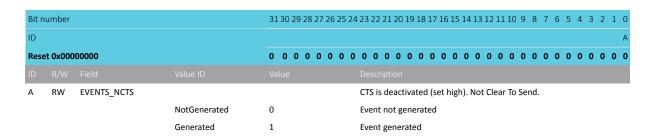
CTS is activated (set low). Clear To Send.

Bit n	umber			31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					A
Rese	t 0x000	00000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	EVENTS_CTS			CTS is activated (set low). Clear To Send.
			NotGenerated	0	Event not generated
			Generated	1	Event generated

6.19.9.12 EVENTS_NCTS

Address offset: 0x104

CTS is deactivated (set high). Not Clear To Send.

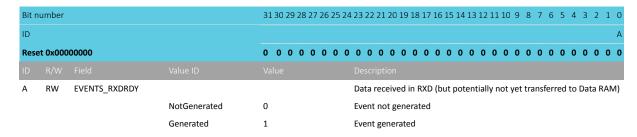


6.19.9.13 EVENTS_RXDRDY

Address offset: 0x108



Data received in RXD (but potentially not yet transferred to Data RAM)



6.19.9.14 EVENTS ENDRX

Address offset: 0x110 Receive buffer is filled up

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					А
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	EVENTS_ENDRX			Receive buffer is filled up
			NotGenerated	0	Event not generated
			Generated	1	Event generated

6.19.9.15 EVENTS_TXDRDY

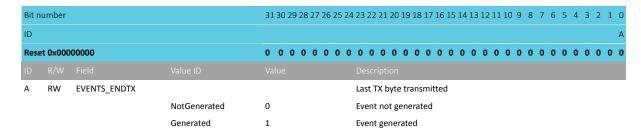
Address offset: 0x11C

Data sent from TXD

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					A
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	EVENTS_TXDRDY			Data sent from TXD
			NotGenerated	0	Event not generated
			Generated	1	Event generated

6.19.9.16 EVENTS ENDTX

Address offset: 0x120 Last TX byte transmitted

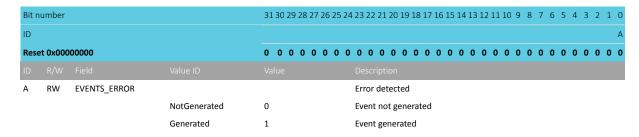


6.19.9.17 EVENTS_ERROR

Address offset: 0x124



Error detected



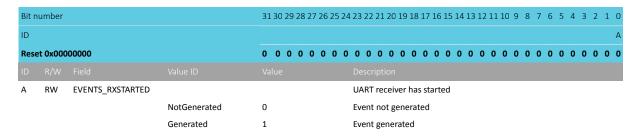
6.19.9.18 EVENTS RXTO

Address offset: 0x144
Receiver timeout

Bit n	umber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					А
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	EVENTS_RXTO			Receiver timeout
			NotGenerated	0	Event not generated
			Generated	1	Event generated

6.19.9.19 EVENTS RXSTARTED

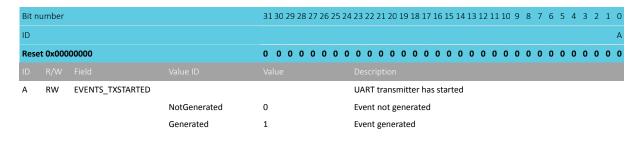
Address offset: 0x14C
UART receiver has started



6.19.9.20 EVENTS TXSTARTED

Address offset: 0x150

UART transmitter has started



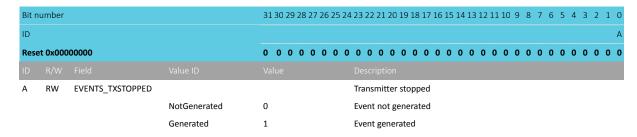
6.19.9.21 EVENTS_TXSTOPPED

Address offset: 0x158





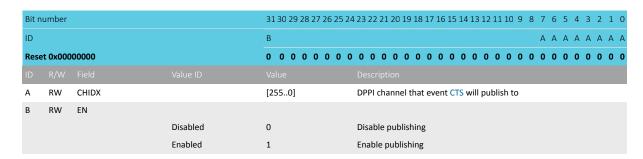
Transmitter stopped



6.19.9.22 PUBLISH CTS

Address offset: 0x180

Publish configuration for event CTS



6.19.9.23 PUBLISH_NCTS

Address offset: 0x184

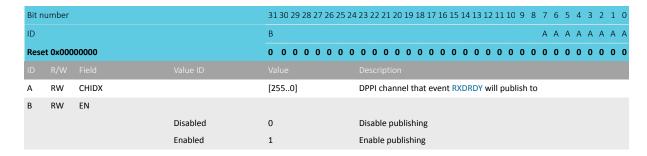
Publish configuration for event NCTS

Bit n	umber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2	1 0
ID				В	ААААА	A A
Rese	et 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0
ID						
Α	RW	CHIDX		[2550]	DPPI channel that event NCTS will publish to	
В	RW	EN				
			Disabled	0	Disable publishing	
			Enabled	1	Enable publishing	

6.19.9.24 PUBLISH_RXDRDY

Address offset: 0x188

Publish configuration for event RXDRDY

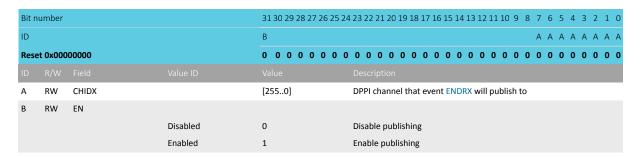




6.19.9.25 PUBLISH_ENDRX

Address offset: 0x190

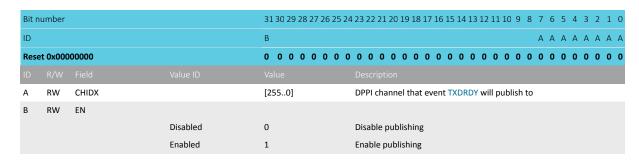
Publish configuration for event ENDRX



6.19.9.26 PUBLISH_TXDRDY

Address offset: 0x19C

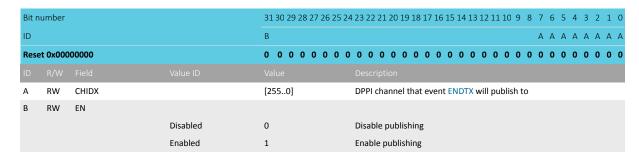
Publish configuration for event TXDRDY



6.19.9.27 PUBLISH ENDTX

Address offset: 0x1A0

Publish configuration for event ENDTX

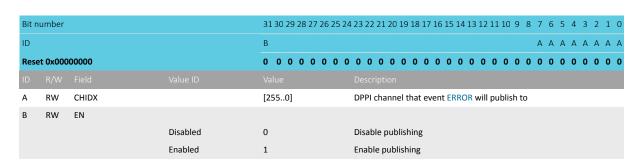


6.19.9.28 PUBLISH_ERROR

Address offset: 0x1A4

Publish configuration for event ERROR

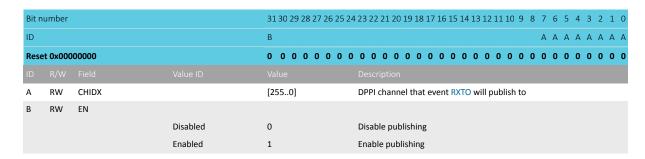




6.19.9.29 PUBLISH_RXTO

Address offset: 0x1C4

Publish configuration for event RXTO



6.19.9.30 PUBLISH_RXSTARTED

Address offset: 0x1CC

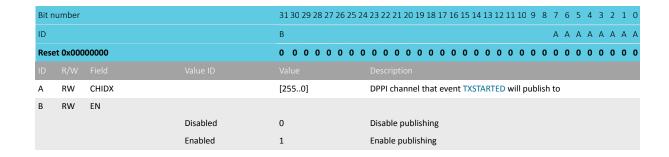
Publish configuration for event RXSTARTED

Bit n	number			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3	2 1 0
ID				В	АААА	A A A
Rese	et 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0 0
ID						
Α	RW	CHIDX		[2550]	DPPI channel that event RXSTARTED will publish to	
_						
В	RW	EN				
В	RW	EN	Disabled	0	Disable publishing	

6.19.9.31 PUBLISH_TXSTARTED

Address offset: 0x1D0

Publish configuration for event TXSTARTED



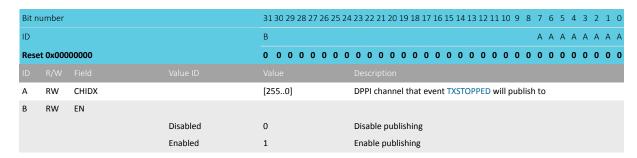




6.19.9.32 PUBLISH_TXSTOPPED

Address offset: 0x1D8

Publish configuration for event TXSTOPPED



6.19.9.33 SHORTS

Address offset: 0x200

Shortcuts between local events and tasks

Bit n	umber			3	313	0 2	29 2	8 2	7 2	6 25	5 24	123	3 2	22 2	1 2	20 1	9 2	L8 1	.7 1	6 :	15 :	14	13	12	11 :	LO	9 8	3 7	6	5	4	3	2	1 (
ID																													D	С					
Rese	et 0x000	00000		() (0	0 (0 (0 0	0	0	0) (0 0) (0	0	0	0	0	0	0	0	0	0	0	0 (0	0	0	0	0	0	0 0	
ID																																			
С	RW	ENDRX_STARTRX										Sł	ho	rtcu	ıt k	bet	we	en	eve	nt	EN	DR	Ха	nd	tas	k S	TAR	TRX							
			Disabled	()							D	isa	ble	sh	nor	cu	t																	
			Enabled	:	L							Er	na	ble	sh	ort	cut																		
D	RW	ENDRX_STOPRX										Sł	ho	rtcu	ıt k	bet	we	en	eve	nt	EN	DR	X a	nd	tas	k S	ГОР	RX							
			Disabled	()							D	isa	ble	sh	nor	cu	t																	
			Enabled	:	L							Er	na	ble	sh	ort	cut																		

6.19.9.34 INTEN

Address offset: 0x300

Enable or disable interrupt

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					L J I H G F E D C B A
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CTS			Enable or disable interrupt for event CTS
			Disabled	0	Disable
			Enabled	1	Enable
В	RW	NCTS			Enable or disable interrupt for event NCTS
			Disabled	0	Disable
			Enabled	1	Enable
С	RW	RXDRDY			Enable or disable interrupt for event RXDRDY
			Disabled	0	Disable
			Enabled	1	Enable
D	RW	ENDRX			Enable or disable interrupt for event ENDRX
			Disabled	0	Disable
			Enabled	1	Enable
E	RW	TXDRDY			Enable or disable interrupt for event TXDRDY



Bit n	umber			313	0 29 2	28 27	7 26 2	5 24	123	22 2	21 2	0 1	9 18	3 17	16	15 1	L4 1	3 1:	2 11	10	9 8	3 7	6	5	4	3 2	1	0
ID										L		J	ı	Н							G I	E			D	C	В	Α
Rese	t 0x000	00000		0 (0 0	0 0	0 (0 0	0	0 (0 (0 (0 0	0	0	0	0 (0	0	0	0 (0 0	0	0	0	0 0	0	0
ID																												
			Disabled	0					Dis	able	9																	
			Enabled	1					Ena	able																		
F	RW	ENDTX							Ena	able	or	dis	able	e int	err	upt 1	for e	eve	nt El	NDT	Χ							
			Disabled	0					Dis	able	2																	
			Enabled	1					Ena	able																		
G	RW	ERROR							Ena	able	or	dis	able	e int	erri	ıpt 1	for e	eve	nt EF	RRO	R							
			Disabled	0					Dis	able	9																	
			Enabled	1					Ena	able																		
Н	RW	RXTO							Ena	able	or	dis	able	int	erri	upt 1	for e	eve	nt R	кто								
			Disabled	0					Dis	able	9																	
			Enabled	1					Ena	able																		
1	RW	RXSTARTED							Ena	able	or	dis	able	e int	erri	ıpt 1	for e	eve	nt R)	KST/	RTI	D						
			Disabled	0					Dis	able	9																	
			Enabled	1					Ena	able																		
J	RW	TXSTARTED							Ena	able	or	dis	able	e int	erri	ıpt 1	for e	eve	nt T	(STA	RTI	D						
			Disabled	0					Dis	able	9																	
			Enabled	1					Ena	able																		
L	RW	TXSTOPPED							Ena	able	or	dis	able	e int	erri	ıpt 1	for e	eve	nt T	(STC	PP	ED						
			Disabled	0					Dis	able	9																	
			Enabled	1					Ena	able																		

6.19.9.35 INTENSET

Address offset: 0x304

Enable interrupt

Bit r	number			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					L J I H G F E D C B A
Res	et 0x000	000000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CTS			Write '1' to enable interrupt for event CTS
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
В	RW	NCTS			Write '1' to enable interrupt for event NCTS
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
С	RW	RXDRDY			Write '1' to enable interrupt for event RXDRDY
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
D	RW	ENDRX			Write '1' to enable interrupt for event ENDRX
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
Е	RW	TXDRDY			Write '1' to enable interrupt for event TXDRDY
			Set	1	Enable
			Disabled	0	Read: Disabled



Bit r	umber			3:	13	0 2	9 28	8 2	7 26	25	24	23	3 22	21	1 2	20 1	9 1	18	17 :	16	15	14	13	12 1	111	10 9	9	8	7	6 !	5	4	3 :	2	1 (
ID													L			J	I		Н							(ŝ	F I	E			D	(0 1	В
Rese	et 0x000	00000		0	C	0 (0 0	0	0	0	0	0	0	0)	0 (0	0	0	0	0	0	0	0	0	0 ()	0 (0	0 (0	0	0 () () (
			Enabled	1								Re	ead	: Eı	na	ble	d																		
F	RW	ENDTX										W	rite	'1	l' t	:о е	na	ble	int	er	rup	t fo	r e	ven	t E	NDT	ГХ								
			Set	1								En	nabl	le																					
			Disabled	0								Re	ead	: D	isa	able	ed																		
			Enabled	1								Re	ead	: Eı	na	ble	d																		
G	RW	ERROR										W	rite	'1	l' t	:о е	na	ble	int	er	rup	t fo	r e	ven	t E	RRC	DR								
			Set	1								En	nabl	le																					
			Disabled	0								Re	ead	: D	isa	able	ed																		
			Enabled	1								Re	ead	: Eı	na	ble	d																		
Н	RW	RXTO										W	rite	'1	l' t	:о е	na	ble	int	er	rup	t fo	r e	ven	t R	XTC)								
			Set	1								En	nabl	le																					
			Disabled	0								Re	ead:	: D	isa	able	ed																		
			Enabled	1								Re	ead:	: Eı	na	ble	d																		
I	RW	RXSTARTED										W	rite	'1	l' t	:о е	na	ble	int	er	rup	t fo	r e	ven	t R	XST	AR	TEC)						
			Set	1								En	nabl	le																					
			Disabled	0								Re	ead	: D	isa	able	ed																		
			Enabled	1								Re	ead	: Eı	na	ble	d																		
J	RW	TXSTARTED										W	rite	· '1	l' t	:о е	na	ble	int	er	rup	t fc	r e	ven	t T	XST	AR	TEC)						
			Set	1								En	nabl	le																					
			Disabled	0								Re	ead	: D	isa	able	ed																		
			Enabled	1								Re	ead:	: Eı	na	ble	d																		
L	RW	TXSTOPPED										W	rite	'1	l' t	:о е	na	ble	int	er	rup	t fc	r e	ven	t T	XST	OP	PE)						
			Set	1								En	nabl	le																					
			Disabled	0								Re	ead:	: D	isa	able	ed																		
			Enabled	1								Re	ead:	: Eı	na	ble	d																		

6.19.9.36 INTENCLR

Address offset: 0x308

Disable interrupt

Bit r	number			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					L J I H G F E D C B A
Res	et 0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CTS			Write '1' to disable interrupt for event CTS
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
В	RW	NCTS			Write '1' to disable interrupt for event NCTS
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
С	RW	RXDRDY			Write '1' to disable interrupt for event RXDRDY
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
D	RW	ENDRX			Write '1' to disable interrupt for event ENDRX
			Clear	1	Disable



Dit n	umber			21	20	20.1	າດາ	777	י זר	24	22	22.	11	20	10 -	10.1	171	C 1	г 1	111	2 1	2 1	1 10		0	7	_	_	1	າ າ	1	C
	ımber			31	. 30	29 2	20 Z	27 26	25	24	23							.0 .1	.D J	.4]	. J	.21	1 10				О					
ID												L		J			Н								F				D		В	
Rese	t 0x000						0 (0 0	0	0					0	0	0 ()	0	0	י כ	0 (0	0	0	0	0	0	0 (0 0	0	C
ID	R/W	Field	Value ID		lue							scri																				
			Disabled	0								ad:																				
			Enabled	1								ad:																				
E	RW	TXDRDY										rite '		to	disa	ble	int	err	up	t fo	r e	ven	t TX	DRI	DΥ							
			Clear	1								sable																				
			Disabled	0								ad:																				
			Enabled	1							Re	ad:	Ena	abl	ed																	
F	RW	ENDTX									Wr	rite '	'1'	to	disa	ble	int	err	up	t fo	r e	ven	t EN	DT	X							
			Clear	1							Dis	sable	е																			
			Disabled	0							Re	ad:	Dis	ab	led																	
			Enabled	1							Re	ad:	Ena	abl	ed																	
G	RW	ERROR									Wr	rite '	'1'	to	disa	ble	int	err	up	t fo	r e	ven	t ER	RO	R							
			Clear	1							Dis	sable	е																			
			Disabled	0							Re	ad:	Dis	ab	led																	
			Enabled	1							Re	ad:	En	abl	ed																	
Н	RW	RXTO									Wr	rite '	'1'	to	disa	ble	int	err	up	t fo	r e	ven	t RX	то								
			Clear	1							Dis	sable	е																			
			Disabled	0							Re	ad:	Dis	ab	led																	
			Enabled	1							Re	ad:	En	abl	ed																	
I	RW	RXSTARTED									W	rite '	'1'	to	disa	ble	int	err	up	t fo	r e	ven	t RX	STA	RTE	ED						
			Clear	1							Dis	sable	е																			
			Disabled	0							Re	ad:	Dis	ab	led																	
			Enabled	1							Re	ad:	En	abl	ed																	
J	RW	TXSTARTED									ıW	rite '	'1'	to	disa	ble	int	err	up	t fo	r e	ven	t TX	STA	RTE	D						
			Clear	1							Dis	sable	е																			
			Disabled	0							Re	ad:	Dis	ab	led																	
			Enabled	1							Re	ad:	En	abl	ed																	
L	RW	TXSTOPPED									Wr	rite '	1'	to	disa	ble	int	err	up	t fo	r e	ven	t TX	STC	PPI	ED						
			Clear	1							Dis	sable	е																			
			Disabled	0							Re	ad:	Dis	ab	led																	
			Enabled	1							Re	ad:	Ena	abl	ed																	

6.19.9.37 ERRORSRC

Address offset: 0x480

Error source

This register is read/write one to clear.

Bit n	umber			313	0 29	28 2	27 2	6 25	5 24	23	3 22	21	20	19 1	l8 1	7 16	15	14 1	3 1:	2 11	10	9 8	3 7	6	5	4	3	2	1 0
ID																											D	С	ВА
Rese	Reset 0x00000000			0	0 0	0	0 (0 0	0	0	0	0	0	0	0 0	0	0	0	0	0	0	0 (0	0	0	0	0	0	0 0
ID																													
Α	RW	OVERRUN								٥١	verr	run	erro	or															
											star ata i			rec	eive	d w	hile	the	pre	viou	ıs d	ata s	till	lies	in f	RXD	. (P	rev	ious
			NotPresent	0						Re	ead:	: er	ror ı	not	pre	ent													
			Present	1						Re	ead:	: er	ror p	ore	sent														
В	RW	PARITY								Pa	arity	er /	ror																
										Α	cha	ırac	ter	witl	n ba	d pa	arity	is r	ecei	ved	, if I	HW	oari	ty c	hec	k is	en	able	ed.





Bit n	umber			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					D C B A
Rese	t 0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
			NotPresent	0	Read: error not present
			Present	1	Read: error present
С	RW	FRAMING			Framing error occurred
					A valid stop bit is not detected on the serial data input after all bits in a
					character have been received.
			NotPresent	0	Read: error not present
			Present	1	Read: error present
D	RW	BREAK			Break condition
					The serial data input is '0' for longer than the length of a data frame.
					(The data frame length is 10 bits without parity bit, and 11 bits with
					parity bit).
			NotPresent	0	Read: error not present
			Present	1	Read: error present

6.19.9.38 ENABLE

Address offset: 0x500

Enable UART

Bit n	umber			31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					АААА
Rese	et 0x000	00000		0 0 0 0 0 0 0	$0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \$
ID					
Α	RW	ENABLE			Enable or disable UARTE
			Disabled	0	Disable UARTE
			Enabled	8	Enable UARTE

6.19.9.39 PSEL.RTS

Address offset: 0x508

Pin select for RTS signal

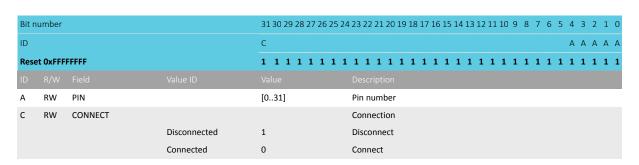
Bit n	Bit number			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				С	АААА
Rese	Reset 0xFFFFFFF			1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID					Description
Α	RW	PIN		[031]	Pin number
A C	RW RW	PIN CONNECT		[031]	Pin number Connection
A C			Disconnected	[031]	

6.19.9.40 PSEL.TXD

Address offset: 0x50C

Pin select for TXD signal





6.19.9.41 PSEL.CTS

Address offset: 0x510 Pin select for CTS signal

Bit n	Bit number			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				С	АААА
Rese	t OxFFF	FFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID					Description
Α	RW	PIN		[031]	Pin number
С	RW	CONNECT			Connection
			Disconnected	1	Disconnect
			Connected	0	Connect

6.19.9.42 PSEL.RXD

Address offset: 0x514

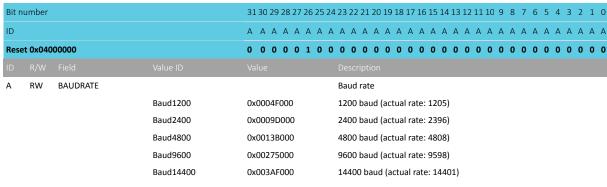
Pin select for RXD signal

Bit n	Bit number			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				С	АААА
Rese	t OxFFF	FFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID					
۸	D) 4 /	DINI		[0, 24]	Dia guarda a
Α	RW	PIN		[031]	Pin number
С	RW	CONNECT		[031]	Connection
С			Disconnected	1	

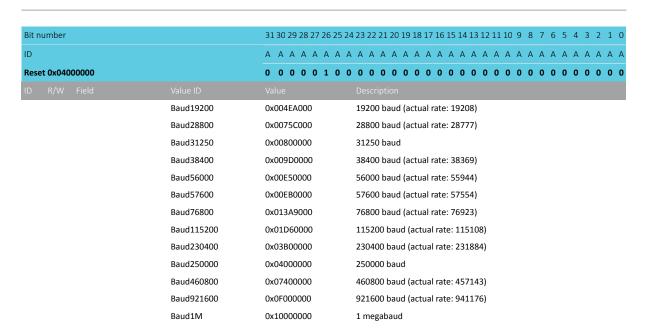
6.19.9.43 BAUDRATE

Address offset: 0x524

Baud rate. Accuracy depends on the HFCLK source selected.



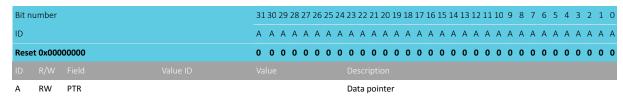




6.19.9.44 RXD.PTR

Address offset: 0x534

Data pointer

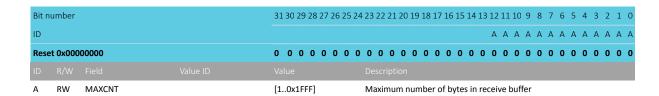


See the memory chapter for details about which memories are available for EasyDMA.

6.19.9.45 RXD.MAXCNT

Address offset: 0x538

Maximum number of bytes in receive buffer



6.19.9.46 RXD.AMOUNT

Address offset: 0x53C

Number of bytes transferred in the last transaction

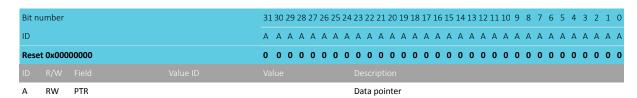


Α	R	AMOUNT	[10x1FFF] N	Number of bytes transferred in the last transaction
ID				Description
Res	et 0x000	00000	0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				A A A A A A A A A A A A A A A A A A A
Bit r	number		31 30 29 28 27 26 25 24 2	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

6.19.9.47 TXD.PTR

Address offset: 0x544

Data pointer

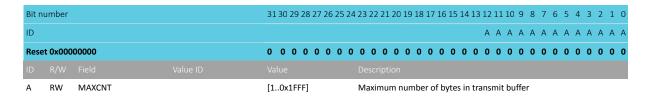


See the memory chapter for details about which memories are available for EasyDMA.

6.19.9.48 TXD.MAXCNT

Address offset: 0x548

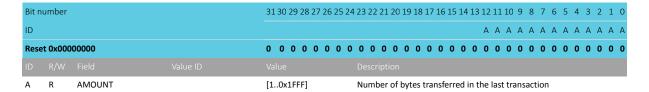
Maximum number of bytes in transmit buffer



6.19.9.49 TXD.AMOUNT

Address offset: 0x54C

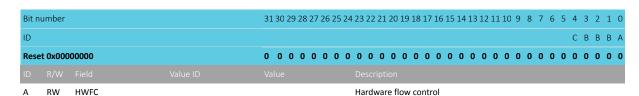
Number of bytes transferred in the last transaction



6.19.9.50 CONFIG

Address offset: 0x56C

Configuration of parity and hardware flow control





Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					СВВВА
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
			Disabled	0	Disabled
			Enabled	1	Enabled
В	RW	PARITY			Parity
			Excluded	0x0	Exclude parity bit
			Included	0x7	Include even parity bit
С	RW	STOP			Stop bits
			One	0	One stop bit
			Two	1	Two stop bits

6.19.10 Electrical specification

6.19.10.1 UARTE electrical specification

Symbol	Description	Min.	Тур.	Max.	Units
f _{UARTE}	Baud rate for UARTE ²¹ .			1000	kbps
t _{UARTE,CTSH}	CTS high time	1			μs
t _{UARTE,START}	Time from STARTRX/STARTTX task to transmission started		0.25		μs

6.20 WDT — Watchdog timer

A countdown watchdog timer using the low-frequency clock source (LFCLK) offers configurable and robust protection against application lock-up.

The watchdog timer is started by triggering the START task.

The watchdog can be paused during long CPU sleep periods for low power applications and when the debugger has halted the CPU. The watchdog is implemented as a down-counter that generates a TIMEOUT event when it wraps over after counting down to 0. When the watchdog timer is started through the START task, the watchdog counter is loaded with the value specified in the CRV register. This counter is also reloaded with the value specified in the CRV register when a reload request is granted.

The watchdog's timeout period is given by:

```
timeout [s] = ( CRV + 1 ) / 32768
```

When started, the watchdog will automatically force the 32.768 kHz RC oscillator on as long as no other 32.768 kHz clock source is running and generating the 32.768 kHz system clock, see chapter CLOCK — Clock control on page 74.

6.20.1 Reload criteria

The watchdog has eight separate reload request registers, which shall be used to request the watchdog to reload its counter with the value specified in the CRV register. To reload the watchdog counter, the special value 0x6E524635 needs to be written to all enabled reload registers.

One or more RR registers can be individually enabled through the RREN register.

NORDIC*

High baud rates may require GPIOs to be set as High Drive, see GPIO chapter for more details.

6.20.2 Temporarily pausing the watchdog

By default, the watchdog will be active counting down the down-counter while the CPU is sleeping and when it is halted by the debugger. It is however possible to configure the watchdog to automatically pause while the CPU is sleeping as well as when it is halted by the debugger.

6.20.3 Watchdog reset

A TIMEOUT event will automatically lead to a watchdog reset.

See Reset on page 60 for more information about reset sources. If the watchdog is configured to generate an interrupt on the TIMEOUT event, the watchdog reset will be postponed with two 32.768 kHz clock cycles after the TIMEOUT event has been generated. Once the TIMEOUT event has been generated, the impending watchdog reset will always be effectuated.

The watchdog must be configured before it is started. After it is started, the watchdog's configuration registers, which comprise registers CRV, RREN, and CONFIG, will be blocked for further configuration.

The watchdog can be reset from several reset sources, see Reset behavior on page 61.

When the device starts running again, after a reset, or waking up from OFF mode, the watchdog configuration registers will be available for configuration again.

6.20.4 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x50018000	WOT	WDT:S	HC	NIA	Matchdog times	
0x40018000	WDT	WDT : NS	US	NA	Watchdog timer	

Table 102: Instances

Register	Offset	Security	Description
TASKS_START	0x000		Start the watchdog
SUBSCRIBE_START	0x080		Subscribe configuration for task START
EVENTS_TIMEOUT	0x100		Watchdog timeout
PUBLISH_TIMEOUT	0x180		Publish configuration for event TIMEOUT
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
RUNSTATUS	0x400		Run status
REQSTATUS	0x404		Request status
CRV	0x504		Counter reload value
RREN	0x508		Enable register for reload request registers
CONFIG	0x50C		Configuration register
RR[n]	0x600		Reload request n

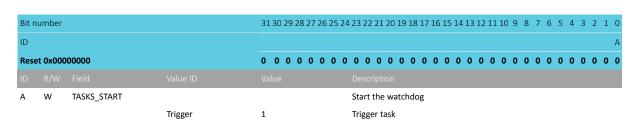
Table 103: Register overview

6.20.4.1 TASKS_START

Address offset: 0x000

Start the watchdog





6.20.4.2 SUBSCRIBE_START

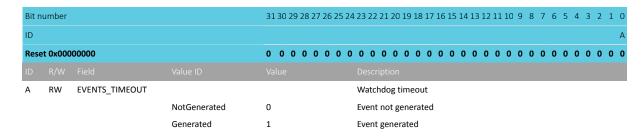
Address offset: 0x080

Subscribe configuration for task START

Bit n	umber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1	0
ID				В	A A A A A A	Α
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0
ID						
Α	RW	CHIDX		[2550]	DPPI channel that task START will subscribe to	
В	RW	EN				
			Disabled	0	Disable subscription	
			Enabled	1	Enable subscription	

6.20.4.3 EVENTS_TIMEOUT

Address offset: 0x100 Watchdog timeout



6.20.4.4 PUBLISH_TIMEOUT

Address offset: 0x180

Publish configuration for event TIMEOUT

Bit n	umber			31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0							
ID				В	АААААА						
Rese	Reset 0x00000000			0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0						
ID											
Α	RW	CHIDX		[2550]	DPPI channel that event TIMEOUT will publish to						
В	RW	EN									
			Disabled	0	Disable publishing						
			Enabled	1	Enable publishing						

6.20.4.5 INTENSET

Address offset: 0x304

Enable interrupt





Bit nu	3it number					7 26 25	5 24 2	23 22	21 2	20 19	18 1	17 10	6 15	14 1	3 12	11	10 9	8	7	6 5	5 4	3	2	1 0
ID	ID																							Α
Reset 0x00000000			0 0 0	0 0	0 0	0	0 0	0	0 0	0	0 0	0	0 (0	0	0 0	0	0	0 (0	0	0	0 0	
ID																								
Α	RW	TIMEOUT					,	Write	'1' t	o en	able	inte	errup	t for	eve	nt T	IMEC	DUT						
			Set	1			1	Enabl	е															
			Disabled	0			1	Read:	Disa	able	d													
			Enabled	1			- 1	Read:	Ena	bled	ı													

6.20.4.6 INTENCLR

Address offset: 0x308

Disable interrupt

Bit n	umber			31 30 29 28 27 26 2	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					А
Rese	Reset 0x00000000			0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	TIMEOUT			Write '1' to disable interrupt for event TIMEOUT
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled

6.20.4.7 RUNSTATUS

Address offset: 0x400

Run status

Bit n	umber			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0	
ID					A	
Rese	Reset 0x00000000			0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	
ID						
Α	R	RUNSTATUSWDT			Indicates whether or not the watchdog is running	
			NotRunning	0	Watchdog not running	
			Running	1	Watchdog is running	

6.20.4.8 REQSTATUS

Address offset: 0x404

Request status

Bit number		31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0				
ID			HGFEDCBA				
Reset 0x00000001		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0				
ID R/W Field							
A-H R RR[i] (i=07)		Request status for RR[i] register					
DisabledOrRequested		0	RR[i] register is not enabled, or are already requesting reload				
	EnabledAndUnrequeste	ed1	RR[i] register is enabled, and are not yet requesting reload				

6.20.4.9 CRV

Address offset: 0x504



Counter reload value



6.20.4.10 RREN

Address offset: 0x508

Enable register for reload request registers

Bit numbe	lit number			26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0			
ID	ID			HGFEDCBA			
Reset 0x00000001			0 0 0 0 0	$\begin{smallmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 $			
ID R/W							
A-H RW	RR[i] (i=07)			Enable or disable RR[i] register			
		Disabled	0	Disable RR[i] register			
		Enabled	1	Enable RR[i] register			

6.20.4.11 CONFIG

Address offset: 0x50C Configuration register

Bit number		31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0			
ID			C A			
Reset 0x00000001 0 0 0		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0			
ID R/W Field			Description			
A RW SLEEP			Configure the watchdog to either be paused, or kept running, while t			
			CPU is sleeping			
	Pause	0	Pause watchdog while the CPU is sleeping			
	Run	1	Keep the watchdog running while the CPU is sleeping			
C RW HALT			Configure the watchdog to either be paused, or kept running, while the			
			CPU is halted by the debugger			
	Pause	0	Pause watchdog while the CPU is halted by the debugger			
	Run	1	Keep the watchdog running while the CPU is halted by the debugger			

6.20.4.12 RR[n] (n=0..7)

Address offset: $0x600 + (n \times 0x4)$

Reload request n

Reload		0x6E524635	Value to request a reload of the watchdog timer		
Α	W	RR			Reload request register
ID					
Reset 0x00000000				0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID	ID			A A A A A A	A A A A A A A A A A A A A A A A A A A
Bit nu	umber			31 30 29 28 27 26 2	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0





6.20.5 Electrical specification

6.20.5.1 Watchdog Timer Electrical Specification

Symbol	Description	Min.	Тур.	Max.	Units
t _{WDT}	Time out interval	31 µs		36 h	



7 LTE modem

The long term evolution (LTE) modem consists of baseband processing and RF parts, which together implement a complete 3GPP LTE release 13 (Rel-13) Cat-M1 and Cat-NB1 and LTE release 14 (Rel-14) Cat-NB1 and Cat-NB2 capable product.

Note: The LTE modem hardware supports Cat-NB2, but needs modem firmware support to get enabled. For information on Cat-NB2 feature support, see the *nRF9160 Modem Firmware Release Notes* included in the latest nRF9160 modem firmware.

As shown in the following figure, the parts of the LTE modem are:

- RF transceiver
- Modem baseband (BB)
- Embedded flash/RAM
- Modem host processor and peripherals

The modem baseband and host processor provide functions for the LTE L1, L2, and L3 (layers 1, 2, and 3 respectively) as well as IP communication layers. Modem peripherals provide hardware services for the modem operating system and the modem secure execution environment.

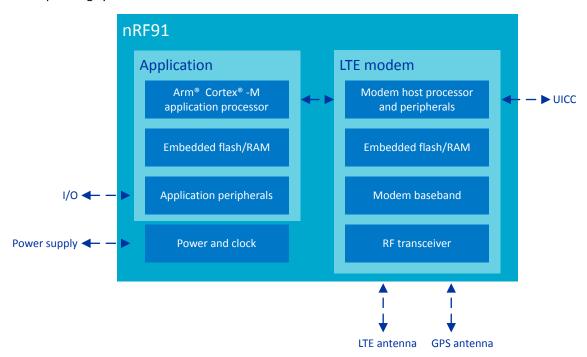


Figure 109: LTE modem within the nRF91

Application and modem domains interact through the interprocessor communication (IPC) mechanism. The LTE modem is accessible to users through the modem API.

The application processor is the system master and is responsible for starting and stopping the modem. The LTE modem enables the clocks and power required for its own operation. The platform handles shared resources, such as clocks, and does not need user participation. In cases where a hard fault is detected in the modem, the application domain will perform a hard reset for the modem.

Note: For details regarding the modem API, see nRF Connect SDK API documentation and nRF91 AT Commands.



The key features of the LTE modem are:

- Complete modem with baseband and RF transceiver
- 3GPP release 13 compliant LTE categories:
 - Cat-M1 (eMTC enhanced machine type communication)
 - Cat-NB1 (NB-IoT narrowband internet of things (IoT))
- 3GPP release 14 compliant LTE categories:
 - Cat-NB1 (NB-IoT)
 - Cat-NB2 (NB-IoT)
- · Power saving modes
- Supports LTE bands from 700 MHz to 2.2 GHz through a single typical 50 Ω antenna pin
 - ANT antenna pin is DC grounded
- RX sensitivity: -108 dBm for Cat-M1 and -114 dBm for Cat-NB1 and Cat-NB2
 - As defined in 3GPP conformance test specification TS 36.521-1
- 1.8 V MIPI RFFE (RF front-end) digital control interface and MAGPIO control interface for external RF applications.
- LTE modem internal ADC that is also used for some AT command interface services, for example, for battery monitoring
- 1.8 V UICC (universal integrated circuit card) interface, based on ISO/IEC 7816-3 and compliant with:
 - ICC (ETSI TS 102 221)
 - eUICC (ETSI TS 103 383)

Note: nRF9160 can run different modem firmware builds that define the final modem feature set in a specific nRF9160 based application.

Note: For details on services provided by the modem AT command interface, see nRF Connect SDK AT interface and nRF91 AT Commands.

7.1 SIM card interface

The LTE modem supports the universal integrated circuit card (UICC) interface.

Only UICCs with electrical interfaces specified in ISO/IEC 7816-3 are supported. UICCs with IC-USB, CLF or MMC interfaces are not supported.

The supported UICC/eUICC interface is compliant with:

- ETSI TS 102 221: Smart Cards; UICC-Terminal interface; Physical and logical characteristics
- ETSI TS 103 383: Smart Cards; Embedded UICC; Requirements Specification

The physical interface towards the eUICC is the same as towards the removable UICC.

Only the class C (supply voltage 1.8 V nominal) operation is supported. Support for the legacy class B (supply voltage 3.0 V nominal) operation must be built with external components, including the external power supply and the level shifters towards the LTE modem UICC interface.

The LTE modem supports powering down the UICC during PSM and eDRX idle mode if the UICC supports this feature as specified in 3GPP TS 24.301. To reach the lowest total power consumption of the complete cellular IoT product, only UICCs supporting power down mode during PSM and eDRX idle mode sleep intervals should be considered.

The LTE modem controls the physical interfaces towards the UICC and implements the transport protocol over the four-pin ISO/IEC 7816-3 interface:



- VCC (power supply) LTE modem drives this
- CLK (clock signal) LTE modem drives this
- RST (reset signal) LTE modem drives this
- I/O (input/output serial data) Bi-directional

The interface and the connections between the LTE modem, UICC connector, and the ESD device is shown in the following figure.

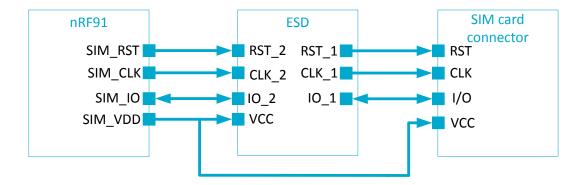


Figure 110: Connections between LTE modem, card connector, and the ESD device

Only standard transmission speeds are supported as specified in ETSI TS 102 221.

Note: Stop the LTE modem through the modem API before removing the UICC.

An electrostatic discharge (ESD) protection device compatible with UICC cards must be used between the removable card and the LTE modem, to protect LTE modem against harmful ESD from the card connector.

7.2 LTE modem coexistence interface

The LTE modem uses a dedicated three-pin interface for RF interference avoidance towards a companion radio device such as an external positioning device or Bluetooth Low Energy device.

The inputs and outputs for this interface are the following:

- COEXO Input to the LTE modem from the external device. When active high, indicates that the
 external device transceiver is turned on. When internal GPS is used, COEXO can be used as active high
 control for the external LNA component.
- COEX1 Output from the LTE modem to the external device. Active high time mark pulse, which is synchronous to LTE system time. When internal GPS is used, COEX1 delivers the GPS 1PPS (one pulse per second) time mark pulse.
- COEX2 Output from the LTE modem to the external device. When active high, indicates that the LTE
 modem transceiver is turned on. COEX2 can also be treated as active low grant from LTE modem to the
 external device, indicating grant to transmit and receive.

Note: Using the COEX2 pin requires an external pull-down resistor in the 100 k Ω size range.

Note: For information on COEX signaling feature support, see the *nRF9160 Modem Firmware Release Notes* included in the latest nRF9160 modem firmware.

The COEX interface timing in relation to modem state is shown in the following figure.



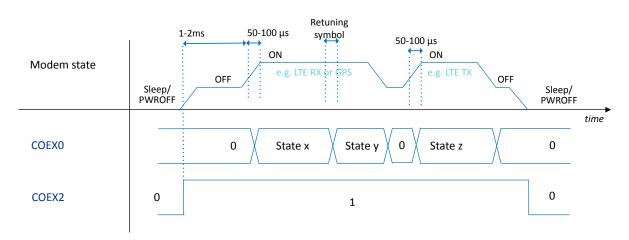


Figure 111: COEX interface timing

7.3 LTE modem RF control external interface

The LTE modem provides dedicated 1.8 V digital interfaces for controlling external RF applications, such as antenna tuner devices.

The LTE modem supports the following pins:

- MIPI RFFE interface pins VIO, SCLK, SDATA
- MAGPIO interface pins MAGPIO0, MAGPIO1, MAGPIO2

The LTE modem drives these outputs timing accurately according to LTE protocol timing to set, for example, the correct antenna tuner settings per used frequency. The user needs to inform the LTE modem through the modem API about the particular RF application, such as antenna tuner device configuration, so that LTE modem knows how to drive it.

Note: For details regarding the modem API and supported RF external control features, see nRF91 AT Commands.

Note: The MIPI RFFE capacitive load at SCLK or SDATA pins shall not exceed 15 pF.

The MIPI RFFE interface timing in relation to modem state is shown in the following figure.

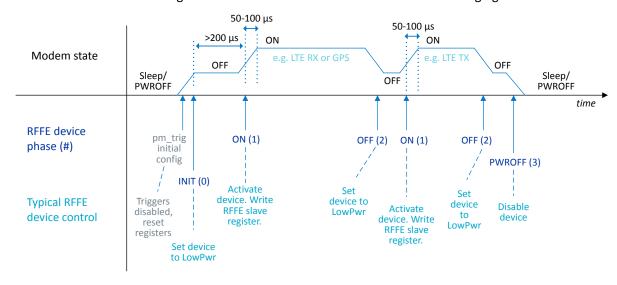


Figure 112: MIPI RFFE interface timing



The MAGPIO interface timing in relation to modem state is shown in the following figure.

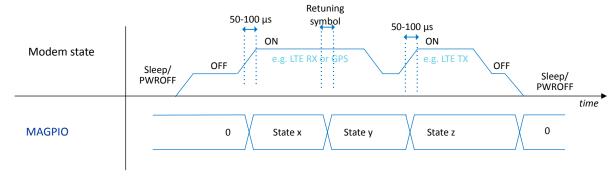


Figure 113: MAGPIO interface timing

7.4 RF front-end interface

nRF9160 has a single-ended (SE) 50 Ω antenna interface to connect directly to antenna.

7.5 Registers

7.6 Electrical specification

7.6.1 Key RF parameters for Cat-M1

Note: For certification status, please refer to Regulatory information on page 403.

Symbol	Description	Min.	Тур.	Max.	Units
Supported LTE	Supported LTE standards		LTE		
			Rel-13		
			Cat-M1		
			HD-FDD		
Bands supported	Bands supported		B1, B2,		
			B3, B4,		
			B5, B8,		
			B12,		
			B13,		
			B14,		
			B18,		
			B19,		
			B20,		
			B25,		
			B26,		
			B28, B66	i	
Transmission	Maximum bandwidth		1.4		MHz
bandwidth					



7.6.2 Key RF parameters for Cat-NB1 and Cat-NB2

Note: For certification status, please refer to Regulatory information on page 403.

Note: There is no foreseen NB-IoT network deployment for FCC bands closer than 200 kHz from band edge, hence our device will not transmit in FCC bands on channels that are closer than 200kHz to band edge.

Symbol	Description	Min.	Тур.	Max.	Units
Supported LTE	Supported LTE standards		LTE		
			Rel-13		
			Cat-		
			NB1 HD-		
			FDD, LTE		
			Rel-14		
			Cat-NB1		
			and Cat-		
			NB2 HD-		
			FDD		
Bands supported	Bands supported		B1, B2,		
			B3, B4,		
			B5, B8,		
			B12,		
			B13,		
			B17, B19,		
			B19, B20,		
			B20, B25,		
			B25, B26,		
			B28, B66		
Transmission	Maximum bandwidth		200		kHz
bandwidth			_00		

7.6.3 Receiver parameters for Cat-M1

Symbol	Description	Min.	Тур.	Max.	Units
Freq _{range_ANT_RX}	RX operation frequency range at ANT (pin 61)	729		2200	MHz
Z _{in}	Input impedance, single-ended		50		Ω
Sensitivity, low	LTE 1.4 MHz without coverage extension	-103	-108		dBm
band					
Sensitivity, mid	LTE 1.4 MHz without coverage extension	-103	-107		dBm
band					



7.6.4 Receiver parameters for Cat-NB1 and Cat-NB2

Symbol	Description	Min.	Тур.	Max.	Units
Freq _{range_ANT_RX}	RX operation frequency range at ANT (pin 61)	729		2200	MHz
Z _{in}	Input impedance, single-ended		50		Ω
Sensitivity, low	NB 200 kHz without coverage extension	-108	-114		dBm
band					
Sensitivity, mid	NB 200 kHz without coverage extension	-108	-113		dBm
band					

7.6.5 Transmitter parameters for Cat-M1

Symbol	Description	Min.	Тур.	Max.	Units
$Freq_{range_ANT_TX}$	TX operation frequency range at ANT (pin 61)	699		1980	MHz
Z _{out}	Output impedance, single-ended		50		Ω
Maximum output	Maximum output power		23		dBm
power					
Minimum output	Minimum output power		-40		dBm
power					
Pout maximum	Pout maximum accuracy		+-2		dB
accuracy					

7.6.6 Transmitter parameters for Cat-NB1 and Cat-NB2

Symbol	Description	Min.	Тур.	Max.	Units
Freq _{range_ANT_TX}	TX operation frequency range at ANT (pin 61)	699		1980	MHz
Z _{out}	Output impedance, single-ended		50		Ω
Maximum output	Maximum output power		23		dBm
power					
Minimum output	Minimum output power		-40		dBm
power					
Pout maximum	Pout maximum accuracy		+-2		dB
accuracy					



8 GPS receiver

The GPS receiver supports GPS L1 C/A and QZSS L1 C/A reception. Operation is time multiplexed with LTE modem, and it is possible to use the GPS and QZSS receiver to obtain position either while the LTE is in RRC Idle mode or power saving mode (PSM), or when the LTE modem is completely deactivated.

The application processor is the master in the system and responsible for starting and stopping of the GPS receiver. GPS can be run standalone or concurrently with QZSS. GPS and QZSS receiver configuration is accessible to user through the GNSS interface API.

Note: For details regarding the GNSS API, please refer to nRF Connect SDK API documentation.

Key features of the GPS receiver are:

- GPS L1 C/A supported
- QZSS L1 C/A supported
- · Optimized for low-power and low-cost IoT applications
- Modes of operation:
 - Single shot (cold start mode by default)
 - Position fix per fixed interval, configurable between 10 s 0.5 hour: first start with cold start, sequential fixes with hot start if interval less than 0.5 hour and enough satellites have been found in the first start
 - Continuous tracking
- Power saving mode:
 - Duty-cycled continuous tracking operation
- One pulse per second (1PPS) signal:
 - A pulse repeating once per second, extremely accurately synchronized to coordinated universal time (UTC) full seconds
 - For more details on 1PPS programmability and power vs. accuracy trade-offs, see GNSS API documentation
 - Available on device COEX1 pin
 - For more details, please see LTE modem on page 365, coexistence interface
- Antenna interface:
 - External low-noise amplifier (LNA) with SAW filter recommended on the GPS antenna input
 - Dedicated GPS antenna, or shared antenna with LTE
 - · GPS antenna pin is DC grounded

Note: There must be minumum 27dB attenuation to out of band power to avoid blocking high power RF signals to GPS receiver input. This can be achieved for example by a SAW filter at the output of the external LNA.

8.1 Electrical specification

Summary of GPS receiver performance parameters.



Condition	Value
Environment	Open sky
Temperature	25 °C
GPS sleep clock source	тсхо

Table 104: Common typical conditions

Note: Local and temporal conditions may lead to considerable variation in TTFF, positioning accuracy, 1PPS signal accuracy.

Symbol	Description	Value	Unit
Sensitivity, cold	Acquisition sensitivity, cold start	-145.5	dBm
Sensitivity, hot	Acquisition sensitivity, hot start	-147	dBm
Sensitivity, tracking	Tracking sensitivity	-155	dBm
TTFF, cold	Acquisition time (time to first fix (TTFF)), cold start	36	S
TTFF, hot	Acquisition time (TTFF), hot start	1.3	S
Accuracy, 2D, periodic	Positioning accuracy (CEP50), periodic tracking	5	m
Accuracy, 2D, continuous	Positioning accuracy (CEP50), continuous tracking	3	m
1PPS accuracy	1PPS signal accuracy, continous tracking	±40	ns

Table 105: GPS electrical specification

9 Debug and trace

The debug and trace system offers a flexible and powerful mechanism for non-intrusive debugging.

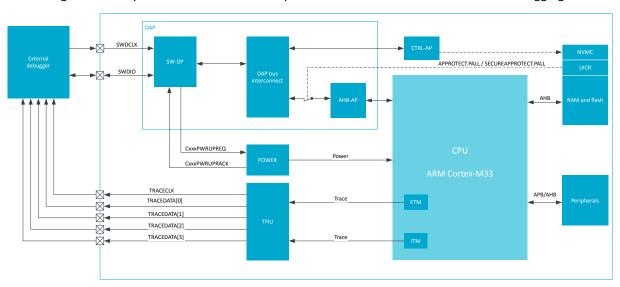


Figure 114: Debug and trace overview

The main features of the debug and trace system include:

- Two-pin serial wire debug (SWD) interface, protocol version 1
- Access port connection
 - Breakpoint unit (BPU) supports eight hardware breakpoint comparators
 - Data watchpoint and trace (DWT) unit supports four watchpoint comparators
 - Instrumentation trace macrocell (ITM)
 - Embedded trace macrocell (ETM)
 - Access protection through APPROTECT, ERASEPROTECT and SECUREAPPROTECT
- Trace port interface unit (TPIU)
 - 4-bit parallel trace of ITM and ETM trace data

Note: When a system contains multiple CPU domains, it is important to notice that if one domain (subsystem A) has master rights on another domain (subsystem B), the master subsystem can have access to data from the slave subsytem. In this example, even if subsystem B is locked by APPROTECT or ERASEPROTECT, subsystem A can access some data for subsystem B. Consequently, even if the security permissions are managed per subsystem, it is mandatory to have a global approach to the protection. Protecting a slave subsystem does not guarantee system security if the master subsystem is not protected.

9.1 Special consideration regarding debugger access

A debugger, if desired, can be restricted to debug non-secure code only, and access non-secure memory regions and peripherals using register SECUREAPPROTECT on page 45. Register APPROTECT on page 43 will block all debugger access.

Debugger accesses are controlled as described in table below.



Debugging capability	UICR.APPROTECT.PALL	UICR.SECUREAPPROTECT.PALL
Secure and non-secure code	Unprotected	Unprotected
Non-secure code only	Unprotected	Protected
No debugging possible	Protected	-

Table 106: Debugger access control

If a RAM or flash region has its permission set to allow code execution, the content of this region will be visible to the debugger even if the read permission is not set. This allows a debugger to display the content of the code being executed. For more about how to configure permissions, please refer to SPU — System protection unit on page 264.

9.2 DAP - Debug access port

An external debugger can access the device via the debug access port (DAP).

The DAP implements a standard ARM CoreSight serial wire debug port (SW-DP). The SW-DP implements the serial wire debug (SWD) protocol that is a two-pin serial interface, see SWDCLK and SWDIO illustrated in figure Debug and trace overview on page 374.

In addition to the default access port in the application CPU (AHB-AP), the DAP includes a custom control access port (CTRL-AP), described in more detail in CTRL-AP - Control access port on page 377.

Note:

- The SWDIO line has an internal pull-up resistor.
- The SWDCLK line has an internal pull-down resistor.

There are several access ports that connect to different parts of the system. An overview is given in the table below.

AP ID	Туре	Description
0	AHB-AP	Application subsystem access port
3	APB-AP	CoreSight subsystem access port
4	CTRL-AP	Application subsystem control access port

Table 107: Access port overview

The standard ARM components are documented in *ARM CoreSight SoC-400 Technical Reference Manual, revision r3p2*. The control access port (CTRL-AP) is proprietary, and described in more detail in CTRL-AP - Control access port on page 377.

9.3 Debug interface mode

Before the external debugger can access the CPU's access port (AHB-AP) or the control access port (CTRL-AP), the debugger must first request the device to power up via CxxxPWRUPREQ in the SWJ-DP.

As long as the debugger is requesting power via CxxxPWRUPREQ, the device will be in debug interface mode. Otherwise, the device is in normal mode. When a debug session is over, the external debugger must make sure to put the device back into normal mode and then a pin reset should be performed. The



reason is that the overall power consumption is higher in debug interface mode compared to normal mode.

Some peripherals behave differently in debug interface mode compared to normal mode. The differences are described in more detail in the chapters of the affected peripherals.

For details on how to use the debug capabilities, please read the debug documentation of your IDE.

If the device is in System OFF when power is requested via CxxxPWRUPREQ, the system will wake up and the DIF flag in RESETREAS on page 72 will be set.

9.4 Real-time debug

The device supports real-time debugging, which allows interrupts to execute to completion in real time when breakpoints are set in thread mode or lower priority interrupts.

Real-time debugging thus enables the developer to set a breakpoint and single-step through their code without a failure of the real-time event-driven threads running at higher priority. For example, this enables the device to continue to service the high-priority interrupts of an external controller or sensor without failure or loss of state synchronization while the developer steps through code in a low-priority thread.

9.5 Trace

The device supports ETM and ITM trace.

Trace data from the ETM and the ITM is sent to an external debugger via a 4-bit wide parallel trace port (TPIU), see TRACEDATA[0] through TRACEDATA[3], and TRACECLK in Debug and trace overview on page 374.

For details on how to use the trace capabilities, please read the debug documentation of your IDE.

TPIU's trace pins are multiplexed with GPIOs, see Pin assignments on page 390 for more information.

Note: To configure the trace data delivery to the device trace port, use the MDK system start-up file included as of MDK version 8.26.0.

Trace speed is configured in the TRACEPORTSPEED (Retained) on page 388 register. The speed of the trace pins depends on the DRIVE setting of the GPIOs that the trace pins are multiplexed with. See GPIO — General purpose input/output on page 102 for information about how to set drive settings. Only SOS1 and H0H1 drives are suitable for debugging. SOS1 is the default DRIVE at reset. If parallel or serial trace port signals are not fast enough in the debugging conditions, all GPIOs in use for tracing should be set to high drive (H0H1). The user shall make sure that DRIVE setting for these GPIOs is not overwritten by software during the debugging session.

9.6 Registers

Register	Offset	Security	Description
TARGETID	0x042		The TARGETID register provides information about the target when the host is connected to a
			single device.
			The TARGETID register is accessed by a read of DP register 0x4 when the DPBANKSEL bit in
			the SELECT register is set to 0x2.

Table 108: Register overview

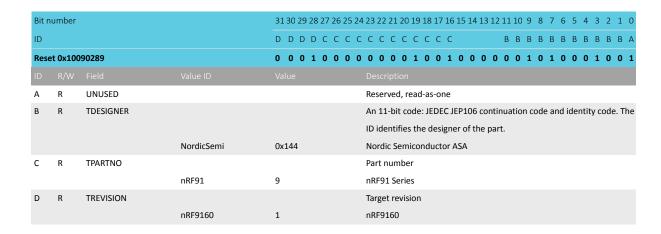


9.6.1 TARGETID

Address offset: 0x042

The TARGETID register provides information about the target when the host is connected to a single device.

The TARGETID register is accessed by a read of DP register 0x4 when the DPBANKSEL bit in the SELECT register is set to 0x2.



9.7 Electrical specification

9.7.1 Trace port

Symbol	Description	Min.	Тур.	Max.	Units		
T _{cyc}	Clock period, as defined by ARM (See ARM Infocenter,	62.5			ns		
	Embedded Trace Macrocell Architecture Specification, Trace						
	Port Physical Interface, Timing specifications)						

9.8 CTRL-AP - Control access port

The control access port (CTRL-AP) is a custom access port that enables control of the device when other debug access ports (DAP) have been disabled by the access port protection.

For an overview of the other debug access ports, see DAP - Debug access port on page 375.



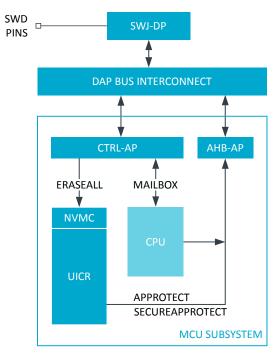


Figure 115: Control access port details

Access port protection (APPROTECT) blocks the debugger access to the AHB-AP, and prevents read and write access to all CPU registers and memory-mapped addresses. To enable port protection access for both secure and non-secure modes, use the registers SECUREAPPROTECT on page 45 and APPROTECT on page 43 respectively. The debugger can use the register APPROTECT.STATUS on page 381 to read the status of secure and non-secure access port protection.

CTRL-AP has the following features:

- Soft reset
- Erase all
- · Mailbox interface
- Debug of protected devices

9.8.1 Reset request

The debugger can request the device to perform a soft reset.

Use the register RESET on page 380 to request a soft reset. Once the soft reset is performed, the reset reason is accessible on the on-chip firmware through the RESETREAS register. For more information about the soft reset, see Reset on page 60.

9.8.2 Erase all

The Erase all function lets the debugger trigger an erase of flash, user information configuration registers (UICR), RAM, all peripheral settings, and also removes the access port protection.

To trigger an erase all function, the debugger writes to the register ERASEALL on page 380. The register ERASEALLSTATUS on page 381 will read as busy for the duration of the operation. After the next reset, the access port protection is removed.

If the debugger performs an erase all function on a slave MCU, the erase sequence will always erase the application MCU first, independently of how the application is protected, before erasing the slave MCU.



Erase all protection

It is possible to prevent the debugger from performing an erase all operation by writing to the UICR.ERASEPROTECT register. Once the register is configured and the device is reset, the CTRL-AP ERASEALL operation is disabled, and all flash write and erase operations are restricted to the firmware. In addition, it is still possible to write/erase from the debugger as long as the UICR.APPROTECT register is not set.

Note: Setting the UICR.ERASEPROTECT register only affects the erase all operation and not the debugger access.

The register ERASEPROTECT.STATUS on page 381 holds the status for erase protection.

9.8.3 Mailbox interface

CTRL-AP implements a mailbox interface which enables the CPU to communicate with a debugger over the SWD interface.

The mailbox interface consists of a transmit register MAILBOX.TXDATA on page 382 with its corresponding status register MAILBOX.TXSTATUS on page 382, and a receive register MAILBOX.RXDATA on page 382 with its corresponding status register MAILBOX.RXSTATUS on page 383. Status bits in the TXSTATUS/RXSTATUS registers are set and cleared automatically when the TXDATA/RXDATA registers are written to and read from, independently of the direction.

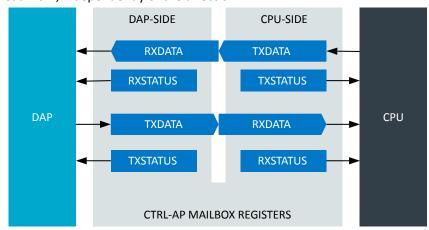


Figure 116: Mailbox register interface

Mailbox transfer sequence

- 1. Sender writes TXDATA.
- 2. Hardware sets sender's TXSTATUS to DataPending.
- 3. Hardware sets receiver's RXSTATUS to DataPending.
- 4. Receiver reads RXDATA.
- 5. Hardware sets receiver's RXSTATUS to NoDataPending.
- 6. Hardware sets sender's TXSTATUS to NoDataPending.

9.8.4 Disabling erase protection

The erase protection mechanism can be disabled to return a device to factory default settings on next reset.

The debugger can read the erase protection status in the register ERASEPROTECT.STATUS on page 381.

If ERASEPROTECT has been enabled, both the debugger and on-chip firmware must write the same non-zero 32-bit KEY value into their respective ERASEPROTECT.DISABLE registers to disable the erase

NORDIC*

protection. When both registers have been written with the same non-zero 32-bit KEY value, the device is automatically erased as described in Erase all on page 378. The access ports will be re-enabled on the next reset once the secure erase sequence has completed.

The write-once register ERASEPROTECT.LOCK on page 385 should be set to *Locked* as early as possible in the start-up sequence, preferably as soon as the on-chip firmware has determined it does not need to communicate with a debugger over the CTRL-AP mailbox interface. Once written, it will not be possible to remove the erase protection until the next reset.

9.8.5 Debugger registers

CTRL-AP has a set of registers that can only be accessed from the debugger over the SWD interface. These are not accessible from the CPU.

9.8.5.1 Registers

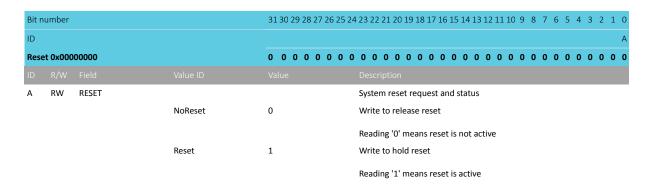
Register	Offset	Description
RESET	0x000	System reset request
ERASEALL	0x004	Perform a secure erase of the device, where flash, SRAM and UICR will be erased in sequence. The
		device will be returned to factory default settings upon next reset.
ERASEALLSTATUS	0x008	This is the status register for the ERASEALL operation.
APPROTECT.STATUS	0x00C	This is the status register for the UICR access port protection.
ERASEPROTECT.STATUS	0x018	This is the status register for the UICR ERASEPROTECT configuration.
ERASEPROTECT.DISABLE	0x01C	This register disables ERASEPROTECT and performs ERASEALL.
MAILBOX.TXDATA	0x020	Data sent from the debugger to the CPU.
MAILBOX.TXSTATUS	0x024	This register shows a status that indicates if data sent from the debugger to the CPU has been read.
MAILBOX.RXDATA	0x028	Data sent from the CPU to the debugger.
MAILBOX.RXSTATUS	0x02C	This register shows a status that indicates if data sent from the CPU to the debugger has been read.
IDR	0x0FC	CTRL-AP Identification Register, IDR

Table 109: Register overview

9.8.5.1.1 RESET

Address offset: 0x000 System reset request

This register is automatically deactivated by writing Erase to ERASEALL, it is then kept inactive until a reset source affecting the debug system is asserted. See Reset behavior on page 61.

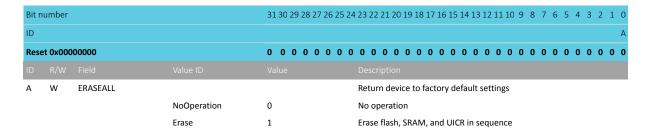


9.8.5.1.2 ERASEALL

Address offset: 0x004



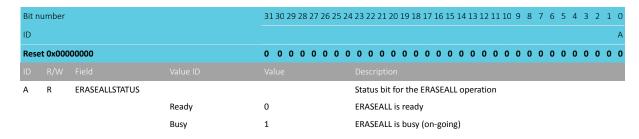
Perform a secure erase of the device, where flash, SRAM and UICR will be erased in sequence. The device will be returned to factory default settings upon next reset.



9.8.5.1.3 ERASEALLSTATUS

Address offset: 0x008

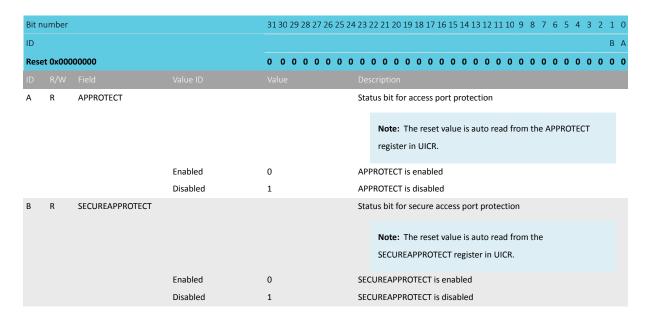
This is the status register for the ERASEALL operation.



9.8.5.1.4 APPROTECT.STATUS

Address offset: 0x00C

This is the status register for the UICR access port protection.

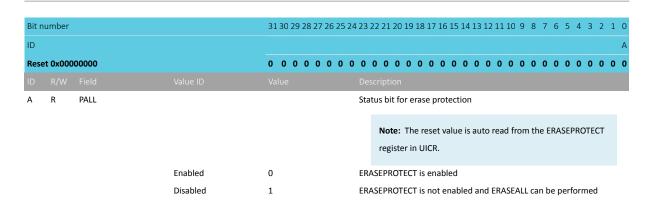


9.8.5.1.5 ERASEPROTECT.STATUS

Address offset: 0x018

This is the status register for the UICR ERASEPROTECT configuration.

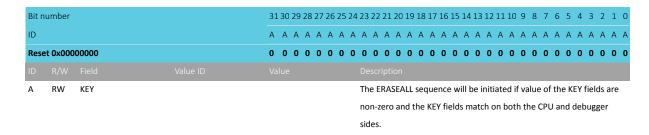




9.8.5.1.6 ERASEPROTECT.DISABLE

Address offset: 0x01C

This register disables ERASEPROTECT and performs ERASEALL.

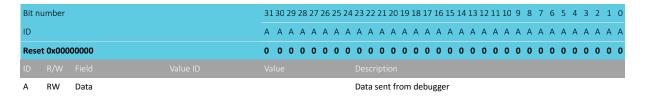


9.8.5.1.7 MAILBOX.TXDATA

Address offset: 0x020

Data sent from the debugger to the CPU.

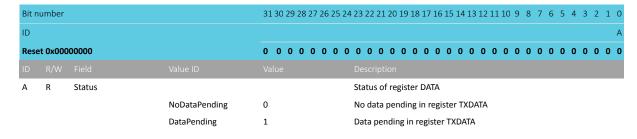
Writing to this register will automatically set a DataPending value in the TXSTATUS register.



9.8.5.1.8 MAILBOX.TXSTATUS

Address offset: 0x024

This register shows a status that indicates if data sent from the debugger to the CPU has been read.



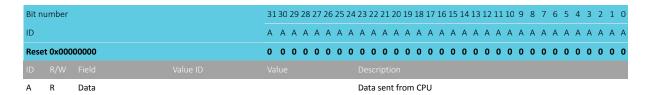
9.8.5.1.9 MAILBOX.RXDATA

Address offset: 0x028



Data sent from the CPU to the debugger.

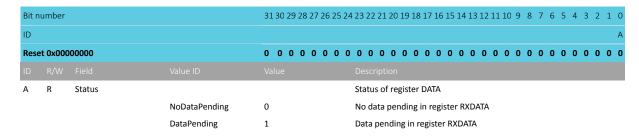
Reading from this register will automatically set a NoDataPending value in the RXSTATUS register.



9.8.5.1.10 MAILBOX.RXSTATUS

Address offset: 0x02C

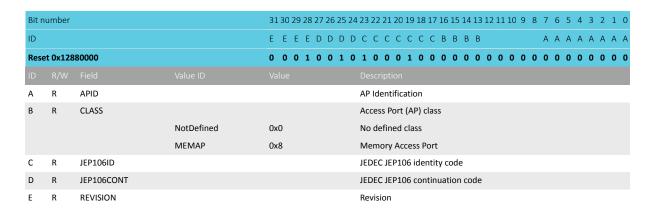
This register shows a status that indicates if data sent from the CPU to the debugger has been read.



9.8.5.1.11 IDR

Address offset: 0x0FC

CTRL-AP Identification Register, IDR



9.8.6 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0x50006000	CTRLAPPERI	CTRL_AP_PER	I S	NA	CTRL-AP-PERI	

Table 110: Instances

Register	Offset	Security	Description
MAILBOX.RXDATA	0x400		Data sent from the debugger to the CPU.
MAILBOX.RXSTATUS	0x404		This register shows a status that indicates if data sent from the debugger to the CPU has been
			read.



Register	Offset	Security	Description
MAILBOX.TXDATA	0x480		Data sent from the CPU to the debugger.
MAILBOX.TXSTATUS	0x484		This register shows a status that indicates if the data sent from the CPU to the debugger has been read.
ERASEPROTECT.LOCK	0x500		$This \ register \ locks \ the \ ERASEPROTECT. DISABLE \ register \ from \ being \ written \ until \ next \ reset.$
ERASEPROTECT.DISABLE	0x504		This register disables the ERASEPROTECT register and performs an ERASEALL operation.

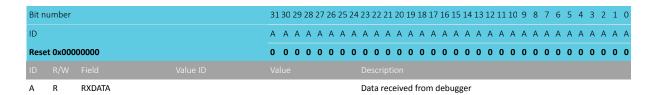
Table 111: Register overview

9.8.6.1 MAILBOX.RXDATA

Address offset: 0x400

Data sent from the debugger to the CPU.

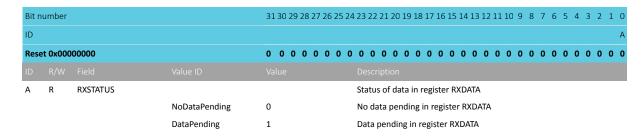
Reading from this register will automatically set a NoDataPending value in the RXSTATUS register.



9.8.6.2 MAILBOX.RXSTATUS

Address offset: 0x404

This register shows a status that indicates if data sent from the debugger to the CPU has been read.

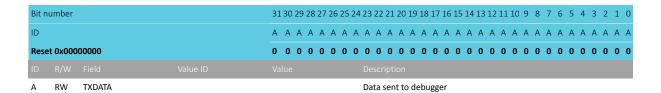


9.8.6.3 MAILBOX.TXDATA

Address offset: 0x480

Data sent from the CPU to the debugger.

Writing to this register will automatically set a DataPending value in the TXSTATUS register.

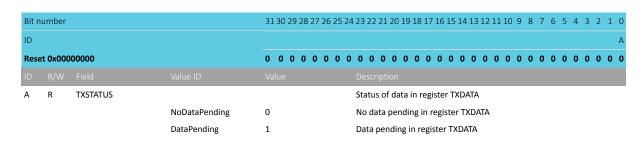


9.8.6.4 MAILBOX.TXSTATUS

Address offset: 0x484

This register shows a status that indicates if the data sent from the CPU to the debugger has been read.

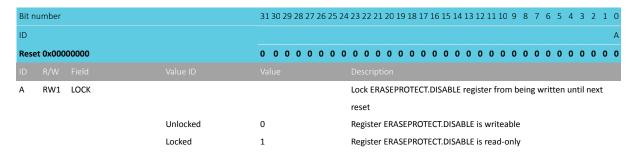




9.8.6.5 ERASEPROTECT.LOCK

Address offset: 0x500

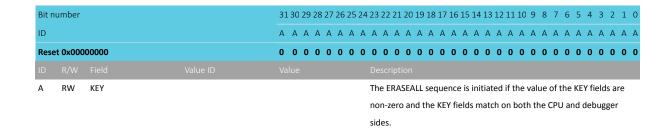
This register locks the ERASEPROTECT.DISABLE register from being written until next reset.



9.8.6.6 ERASEPROTECT.DISABLE

Address offset: 0x504

This register disables the ERASEPROTECT register and performs an ERASEALL operation.



9.9 TAD - Trace and debug control

Configuration interface for trace and debug

Please refer to the Trace section for more information about how to configure the trace and debug interface.

Note: Although there are PSEL registers for the trace port, each function can only be mapped to a single pin due to pin speed requirements. Setting the PIN field to anything else will not have any effect. See Pin assignment chapter for more information



9.9.1 Registers

Base address	Peripheral	Instance	Secure mapping	DMA security	Description	Configuration
0xE0080000	TAD	TAD	S	NA	Trace and debug control	

Table 112: Instances

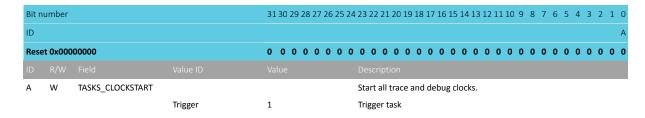
Register	Offset	Security	Description
TASKS_CLOCKSTART	0x000		Start all trace and debug clocks.
TASKS_CLOCKSTOP	0x004		Stop all trace and debug clocks.
ENABLE	0x500		Enable debug domain and aquire selected GPIOs
PSEL.TRACECLK	0x504		Pin configuration for TRACECLK
PSEL.TRACEDATA0	0x508		Pin configuration for TRACEDATA[0]
PSEL.TRACEDATA1	0x50C		Pin configuration for TRACEDATA[1]
PSEL.TRACEDATA2	0x510		Pin configuration for TRACEDATA[2]
PSEL.TRACEDATA3	0x514		Pin configuration for TRACEDATA[3]
TRACEPORTSPEED	0x518		Clocking options for the Trace Port debug interface
			Reset behavior is the same as debug components
			This register is retained.

Table 113: Register overview

9.9.1.1 TASKS_CLOCKSTART

Address offset: 0x000

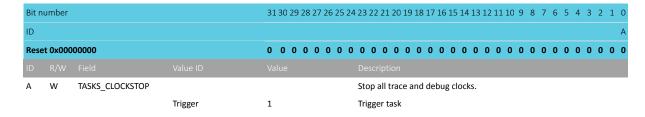
Start all trace and debug clocks.



9.9.1.2 TASKS_CLOCKSTOP

Address offset: 0x004

Stop all trace and debug clocks.

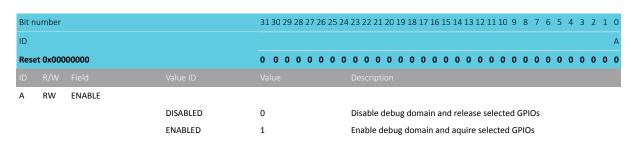


9.9.1.3 ENABLE

Address offset: 0x500

Enable debug domain and aquire selected GPIOs

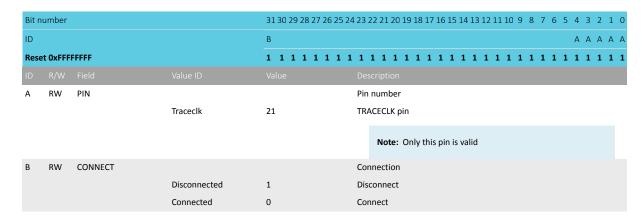




9.9.1.4 PSEL.TRACECLK

Address offset: 0x504

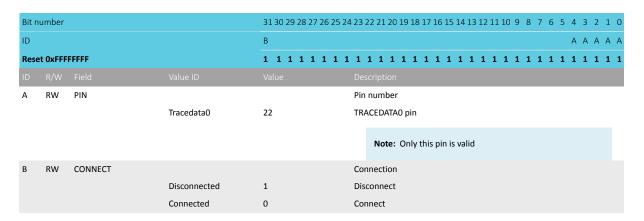
Pin configuration for TRACECLK



9.9.1.5 PSEL.TRACEDATAO

Address offset: 0x508

Pin configuration for TRACEDATA[0]



9.9.1.6 PSEL.TRACEDATA1

Address offset: 0x50C

Pin configuration for TRACEDATA[1]



Bit n	umber			31 30 29 28 27 26 25 24	1 23 2	2 21 2	20 19	18 1	7 16	5 15	14 13	3 12	11 10	9	8	7 6	5	4	3 :	2 1	L O
ID				В														Α	Α ,	4 4	A A
Rese	t OxFFF	FFFF		1 1 1 1 1 1 1 1	1 1	1 1	1 1	1 1	l 1	1	1 1	1	1 1	1	1	1 1	. 1	1	1 :	1 1	i 1
ID																					
Α	RW	PIN			Pin r	numb	er														
			Tracedata1	23	TRA	CEDA	TA1 p	in													
						Note	e: Or	ıly th	iis p	in is	valid										
В	RW	CONNECT			Coni	nectio	on														
			Disconnected	1	Disc	onne	ct														
			Connected	0	Coni	nect															

9.9.1.7 PSEL.TRACEDATA2

Address offset: 0x510

Pin configuration for TRACEDATA[2]

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 (
ID				В	АААА
Rese	t OxFFF	FFFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID					
Α	RW	PIN			Pin number
			Tracedata2	24	TRACEDATA2 pin
					Note: Only this pin is valid
В	RW	CONNECT			Connection
			Disconnected	1	Disconnect
			Connected	0	Connect

9.9.1.8 PSEL.TRACEDATA3

Address offset: 0x514

Pin configuration for TRACEDATA[3]

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	АААА
Rese	t OxFFF	FFFF		1 1 1 1 1 1 1 1	. 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID					
Α	RW	PIN			Pin number
			Tracedata3	25	TRACEDATA3 pin
					Note: Only this pin is valid
В	RW	CONNECT			Connection
			Disconnected	1	Disconnect
			Connected	0	Connect

9.9.1.9 TRACEPORTSPEED (Retained)

Address offset: 0x518

Clocking options for the Trace Port debug interface

Reset behavior is the same as debug components



This register is retained.

Bit n	umber			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					АА
Rese	et 0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	TRACEPORTSPEED			Speed of Trace Port clock. Note that the TRACECLK pin output will be
					divided again by two from the Trace Port clock.
			32MHz	0	Trace Port clock is:
					32MHz
			16MHz	1	Trace Port clock is:
					16MHz
			8MHz	2	Trace Port clock is:
					8MHz
			4MHz	3	Trace Port clock is:
					4MHz



10 Hardware and layout

The following sections describe nRF9160 hardware and layout specifications.

10.1 Pin assignments

This section describes the pin assignment and the pin functions.

This device provides flexibility when it comes to routing and configuration of the GPIO pins. However, some pins have recommendations for how the pin should be configured or what it should be used for. See LGA pin assignments on page 390 for more information about this.

10.1.1 LGA pin assignments

The pin assignment table and figure describe the assignments.

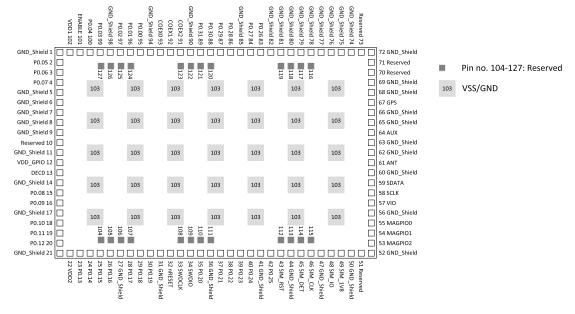


Figure 117: LGA pin assignments, top view

Pin no	Pin name	Function	Description
1	GND_Shield	Power	Ground
2	P0.05	Digital I/O (SoC)	General purpose I/O
3	P0.06	Digital I/O (SoC)	General purpose I/O
4	P0.07	Digital I/O (SoC)	General purpose I/O
5	GND_Shield	Power	Ground
6	GND_Shield	Power	Ground
7	GND_Shield	Power	Ground
8	GND_Shield	Power	Ground
9	GND_Shield	Power	Ground
10	Reserved		Do not connect/reserved for future use
11	GND_Shield	Power	Ground
12	VDD_GPIO	Power	GPIO power supply input and logic level
13	DEC0	Power	Power supply decoupling. Reserved for Nordic use.
14	GND_Shield	Power	Ground



	Pin no	Pin name	Function	Description
16 80.09 Digital VO (SoC) General purpose VO 17 GNO_Shield Power Clound 18 80.00 Digital VO (SoC) General purpose VO 19 P0.11 Digital VO (SoC) General purpose VO 21 OND_Shield Power Ground 22 VDD2 Power Supply votinge Input 23 ND.31 Digital VO (SoC) General purpose VO 24 AIRO Analog input Analog input. 24 P0.14 Digital VO (SoC) General purpose VO 25 AIRO Analog input Analog input. 26 AIRO Analog input Analog input. 27 AIRO Analog input Analog input. 28 AIRO Analog input Analog input. 29 AIRO Analog input Analog input. 29 P0.18 Analog input Analog input. 29 P0.18 Analog input. Analog input. 31 AIRO				
17 GNO_Shield Power Ground 18 Po.10 Biglial I/O (ScC) General purpose I/O 19 NO.11 Deglat I/O (ScC) General purpose I/O 20 PO.12 Deglat I/O (ScC) General purpose I/O 21 ORD_Shield Power Supply voltage input 22 VODC Power Supply voltage input 23 PO.13 Deglat I/O (ScC) General purpose I/O. 24 AINO Analog input Analog input. 24 PO.14 Digital I/O (ScC) General purpose I/O. 25 PO.15 Digital I/O (ScC) General purpose I/O. 26 AIN2 Analog input Analog input 26 PO.15 Deglat I/O (ScC) General purpose I/O. 27 AINA Analog input Analog input 28 PO.15 Deglat I/O (ScC) General purpose I/O. 29 AINA Analog input Analog input 30 PO.13 Deglat I/O (ScC) General purpose I/O. <td></td> <td></td> <td></td> <td></td>				
18 P0.10 Digital I/O (SoC) General purpose I/O 19 P0.12 Digital I/O (SoC) General purpose I/O 21 R0.12 Digital I/O (SoC) General purpose I/O 21 KND. Shield Power Ground 22 VDO2 Power Sipply voltage input AlNO Analog input Analog input. 4 P0.14 Digital I/O (SoC) General purpose I/O AlNI Analog input Analog input. 25 P0.15 Digital I/O (SoC) General purpose I/O AlN2 Analog input Analog input. 26 P0.15 Digital I/O (SoC) General purpose I/O AlN3 Analog input Analog input. 27 ANA Analog input Analog input. 28 P0.17 Digital I/O (SoC) General purpose I/O AlN4 Analog input Analog input. 29 P0.18 Digital I/O (SoC) General purpose I/O AlN6 Analog input Analog input.				
19 PO.12 Digital VO (SoC) General purpose VO 20 PO.22 Digital VO (SoC) General purpose VO 21 NOD. Shield Power Ground 22 VOD.2 Power Supply voltage Input 23 PO.13 Digital VO (SoC) General purpose VO. 24 PO.14 Digital VO (SoC) General purpose VO. 24 ANIA Analog input Analog input. 25 ANIA Analog input Analog input. 26 PO.16 Digital VO (SoC) General purpose VO. 27 ANIA Analog input Analog input. 28 PO.17 Digital VO (SoC) General purpose VO. 29 ANIA Analog input Analog input. 20 ANIA Analog input Analog input. 30 PO.19 Digital VO (SoC) General purpose VO. ANIA Analog input Analog input. 31 GRO JSheld Power General purpose VO. ANIA		_		
28 B P0.12 Diptal VO (SOC) General purpose I/O 21 C ROD, Shield Power Ground 22 N P013 Diptal VO (SoC) General purpose I/O. 23 A RO13 Diptal VO (SoC) General purpose I/O. 24 A RO14 Diptal VO (SoC) General purpose I/O. 25 A RO15 Diptal VO (SoC) General purpose I/O. 26 A RO16 Diptal VO (SoC) General purpose I/O. 27 A ANS Analog input Analog input. 28 A RO16 Diptal VO (SoC) General purpose I/O. 29 A ANS Analog input Analog input. 29 A RO17 Diptal VO (SoC) General purpose I/O. 29 A PO18 Analog input Analog input. 29 A PO18 Analog input Analog input. 30 A SANCA Analog input Analog input. 31 A SNDO Analog input Analog input. 31 A SNDO Diptal VO (SoC) General purpos			•	
21 GND_Shield Power Ground 22 VDD2 Power Supply voltage input 24 VDD2 Power Supply voltage input 24 PD.14 Digital IV/GSCJ General purpose IV.D. 24 PD.15 Digital IV/GSCJ General purpose IV.D. 25 PD.15 Digital IV/GSCJ General purpose IV.D. 28 PD.15 Digital IV/GSCJ General purpose IV.D. 28 PD.18 Digital IV/GSCJ General purpose IV.D. 28 PD.19 Digital IV.GSCJ General purpose IV.D. 28 PD.17 Digital IV.GSCJ General purpose IV.D. 28 PD.17 Digital IV.GSCJ General purpose IV.D. 29 PD.18 Digital IV.GSCJ General purpose IV.D. 30 PD.19 Digital IV.GSCJ General purpose IV.D. 31 AING Analog input Analog input. 31 SVD.Shield Power Ground 31 SVD.Shield Power Ground </td <td></td> <td></td> <td></td> <td></td>				
22 VDD2 Power Supply voltage input 23 PD.13 Digital VO (SOC) General purpose VO. AlNO Analog input Analog input. 24 PD.13 Digital VO (SOC) General purpose VO. AlN1 Analog input Analog input. 25 PD.15 Digital VO (SOC) General purpose VO. AlN2 Analog input Analog input. 26 PD.16 Digital VO (SOC) General purpose VO. AlN3 Analog input Analog input. 27 GND, Shield Pover Ground 28 PD.17 Digital VO (SOC) General purpose VO. AlN4 Analog input Analog input. 29 PD.18 Digital VO (SOC) General purpose VO. AlN6 Analog input Analog input. 31 SWDO Digital VO (SOC) General purpose VO. 31 SWDOLX Digital VO (SOC) Serial wire debug dock input for debug and programming 32 WD.2 Digital VO (SOC) <t< td=""><td></td><td></td><td></td><td></td></t<>				
23 Po.3.3 Digital I/O (SoC) General purpose I/O. 24 Po.1.4 Digital I/O (SoC) General purpose I/O. 24 Po.1.4 Digital I/O (SoC) General purpose I/O. 25 Po.1.5 Digital I/O (SoC) General purpose I/O. 26 Po.1.6 Digital I/O (SoC) General purpose I/O. 27 GND, Shield Poover Ground 28 Po.1.7 Digital I/O (SoC) General purpose I/O. 28 Po.1.7 Digital I/O (SoC) General purpose I/O. 29 Po.1.8 Digital I/O (SoC) General purpose I/O. 30 Po.1.9 Digital I/O (SoC) General purpose I/O. 31 AlNS Analogi input Analogi input. 30 Po.1.9 Digital I/O (SoC) General purpose I/O. 31 AlNS Analogi input Analogi input. 32 Bristal Po.1.9 Digital I/O (SoC) SoC system reset 33 SWDCLK Digital I/O (SoC) General purpose I/O. 34 <td></td> <td>_</td> <td></td> <td></td>		_		
AlNO				
AN1				
25 P0.15 Digital I/O (soc) General purpose I/O. 26 P0.16 Digital I/O (soc) General purpose I/O. 27 GND, Shield Power Ground 28 P0.17 Digital I/O (soc) General purpose I/O. 28 P0.17 Digital I/O (soc) General purpose I/O. 29 AINA Analog input Analog input. 30 P0.19 Digital I/O (soc) General purpose I/O. AINS Analog input Analog input. 31 GND, Shield Power Ground 32 RESET Digital I/O (soc) Soc system reset Note: External pull-up not allowed. 33 SWDCLK Digital I/O (soc) General purpose I/O. 34 SWDIO Digital I/O (soc) General purpose I/O. 35 PO.20 Digital I/O (soc) General purpose I/O. 36 GND, Shield Power Ground 37 PO.20 Digital I/O (soc) General purpose I/O. 38 PO.	24	P0.14	Digital I/O (SoC)	General purpose I/O.
Analog input		AIN1	Analog input	Analog input.
26 P0.16 Digital I/O (SoC) General purpose I/O. AIN3 Analog input Analog input. 27 GND_Shield Power Ground 28 P0.17 Digital I/O (SoC) General purpose I/O. AIN4 Analog input Analog input. 29 P0.18 Digital I/O (SoC) General purpose I/O. AIN6 Analog input Analog input. 31 GND_Shield Power Ground 32 RREST Digital I/O (SoC) Serial wire debug clock input for debug and programming 33 SWDCLK Digital I/O (SoC) Serial wire debug I/O for debug and programming 34 SWDIO Digital I/O (SoC) General purpose I/O. 35 PO.20 Digital I/O (SoC) General purpose I/O. 36 GND_Shield Power Ground 37 PO.21 Digital I/O (SoC) General purpose I/O. 38 PO.22 Digital I/O (SoC) General purpose I/O. 39 PO.23 Digital I/O (SoC) General purpose I/O	25	P0.15	Digital I/O (SoC)	General purpose I/O.
Analog Input Analog Input Pour Ground Power Biglial I/O (Soc) General purpose I/O. AlN4 Analog input Analog input. Note: External pull-up not allowed. Serial wire debug clock input for debug and programming of experiments of		AIN2	Analog input	Analog input.
27 QND_Shield Power Ground 28 P0.17 Digital I/O (SoC) General purpose I/O. 29 P0.18 Digital I/O (SoC) General purpose I/O. 30 P0.19 Digital I/O (SoC) General purpose I/O. 30 P0.19 Digital I/O (SoC) General purpose I/O. 31 QND_Shield Power Ground 32 RESET Digital I/O (SoC) SoC system reset 34 SWDOLK Digital I/O (SoC) Serial wire debug clock input for debug and programming 34 SWDIO Digital I/O (SoC) General purpose I/O. AIN7 Analog input Analog input. 36 GND_Shield Power Ground 37 P0.20 Digital I/O (SoC) General purpose I/O. 38 P0.21 Digital I/O (SoC) General purpose I/O. 38 P0.22 Digital I/O (SoC) General purpose I/O. 39 P0.23 Digital I/O (SoC) General purpose I/O. 30 TRACEDATA1 Trace data <td>26</td> <td>P0.16</td> <td>Digital I/O (SoC)</td> <td>General purpose I/O.</td>	26	P0.16	Digital I/O (SoC)	General purpose I/O.
28 P0.17 Digital I/O (soc) General purpose I/O. 29 P0.18 Digital I/O (soc) General purpose I/O. 30 P0.19 Digital I/O (soc) General purpose I/O. 31 AING Analog input Analog input. 31 AING Analog input Analog input. 31 OND_Shield Power Ground 32 Interpretation of the purpose I/O. Soc system reset Note: External pull-up not allowed. 33 SWOCK Digital I/O (soc) Serial wire debug clock input for debug and programming 34 SWODIO Digital I/O (soc) General purpose I/O. 35 P0.20 Digital I/O (soc) General purpose I/O. 36 GND_Shield Power Ground 37 P0.21 Digital I/O (soc) General purpose I/O. 38 P0.22 Digital I/O (soc) General purpose I/O. 39 P0.23 Digital I/O (soc) General purpose I/O. 40 P0.24 Digital I/O (soc) General purpo		AIN3	Analog input	Analog input.
AlN4 Analog input Analog input. 29 P0.18 Digital I/O (SoC) General purpose I/O. AlN5 Analog input Analog input. 30 P0.19 Digital I/O (SoC) General purpose I/O. AlN6 Analog input Analog input. 31 GND_Shield Power Ground 32 NRESET Digital I/O (SoC) SoC system reset Note: External pull-up not allowed. 33 SWDCLK Digital I/O (SoC) General purpose I/O. AlN7 Analog input Serial wire debug clock input for debug and programming Digital I/O (SoC) General purpose I/O. AlN7 Analog input Analog input. 36 GND_Shield Power Ground 37 P0.21 Digital I/O (SoC) General purpose I/O. TRACECLK Trace clock Trace buffer rlock (optional). 38 P0.22 Digital I/O (SoC) General purpose I/O. TRACECLK Trace data Trace buffer TRACEDATA(I) (optional). 40 P0.23 Digital I/O (SoC) General purpose I/O. TRACEDATA1 Trace data Trace buffer TRACEDATA(I) (optional). 40 P0.24 Digital I/O (SoC) General purpose I/O. TRACEDATA2 Trace data Trace buffer TRACEDATA(I) (optional). 41 GND_Shield Power Ground 42 P0.25 Digital I/O (SoC) General purpose I/O. TRACEDATA3 Trace data Trace buffer TRACEDATA(I) (optional). 43 SIM_RST Digital I/O (SoC) General purpose I/O. TRACEDATA3 Trace data Trace buffer TRACEDATA(I) (optional). 44 GND_Shield Power Ground 45 SIM_RST Digital I/O (SoC) General purpose I/O. TRACEDATA3 Trace data Trace buffer TRACEDATA(I) (optional). 46 GND_Shield Power Ground 47 GND_Shield Power Ground 48 GND_Shield Power Ground 49 GND_Shield Power Ground 40 GND_Shield Power Ground 41 GND_Shield Power Ground 42 GND_Shield Power Ground	27	GND_Shield	Power	Ground
P0.18 Digital I/O (SoC) General purpose I/O. AINS Analog input Analog input. Analog input Analog input. Analog input Analog input. Analog input Analog input. SoC system reset Note: External pull-up not allowed. SoC system reset Note: External pull-up not allowed. SoC system reset Note: External pull-up not allowed. Analog input. Serial wire debug clock input for debug and programming debug system programming. Analog input.	28	P0.17	Digital I/O (SoC)	General purpose I/O.
Analog input Analog input. PD.19 Digital /O (soc) General purpose I/O. AlN6 Analog input Analog input. Borund Coround Coround Coround Coround Coround Coround Soc system reset Note: External pull-up not allowed. Note: External pull-up not allowed. Note: External pull-up not		AIN4	Analog input	Analog input.
P0.19 Digital /O (SoC) General purpose /O.	29	P0.18	Digital I/O (SoC)	General purpose I/O.
P0.19 Digital /O (SoC) General purpose /O.		AIN5	Analog input	Analog input.
AlN6 Analog input Analog input. GND_Shield Power Ground RESET Digital I/O (SoC) SoC system reset Note: External pull-up not allowed. Serial wire debug clock input for debug and programming debug lock input for debug and programming deput prose I/O. Final pull-up of allowed. Analog input Analog input Analog input. Analog input	30			
SIN_Shield Power Ground				
Note: External pull-up not allowed. Serial wire debug (lock input for debug and programming Serial wire debug (lock input for debug and programming Note: External pull-up not allowed. Note: External pull-up not allowed. Serial wire debug (lock input for debug and programming Note: Analog input.	21		- 1	
Note: External pull-up not allowed. Note: External pull-up not allowed. Note: External pull-up not allowed.				
34 SWDIO Digital I/O Serial wire debug I/O for debug and programming 35 P0.20 Digital I/O (SoC) General purpose I/O. AlN7 Analog input Analog input. 36 GND_Shield Power Ground 37 P0.21 Digital I/O (SoC) General purpose I/O. 38 P0.22 Digital I/O (SoC) General purpose I/O. 39 P0.23 Digital I/O (SoC) General purpose I/O. 39 P0.23 Digital I/O (SoC) General purpose I/O. 39 P0.23 Digital I/O (SoC) General purpose I/O. 40 P0.24 Digital I/O (SoC) General purpose I/O. 40 P0.24 Digital I/O (SoC) General purpose I/O. 41 GND_Shield Power Ground 42 P0.25 Digital I/O (SoC) General purpose I/O. 43 SIM_RST Digital I/O (SoC) SIM reset 44 GND_Shield Power Ground 45 SIM_DET Digital I/O (SoC) SIM detect Kot used. Needs to be left floating. Not used. Needs to be left floating.	32	INCSCI	Digital I/O (SOC)	
P0.20 Digital I/O (SoC) General purpose I/O.	33	SWDCLK	Digital input	Serial wire debug clock input for debug and programming
Analog input. Analog input. Analog input. Analog input. Ground ROND_Shield Power Digital I/O (SoC) RACECLK Trace clock Trace buffer clock (optional). RACEDATA0 Trace data Trace buffer TRACEDATA[0] (optional). RACEDATA1 Trace data Trace buffer TRACEDATA[1] (optional). RACEDATA2 Trace data Trace buffer TRACEDATA[1] (optional). RACEDATA2 Trace data Trace buffer TRACEDATA[2] (optional). RACEDATA2 Trace data Trace buffer TRACEDATA[2] (optional). RACEDATA2 Trace data Trace buffer TRACEDATA[2] (optional). RACEDATA2 Trace data Trace buffer TRACEDATA[3] (optional). RACEDATA3 Trace data Trace buffer TRACEDATA[3] (optional). RACEDATA3 Trace data Trace buffer TRACEDATA[3] (optional). RACEDATA3 Trace data Trace buffer TRACEDATA[3] (optional). SIM_RST Digital I/O (SoC) SIM reset Ground SIM_DET Digital I/O (SoC) SIM detect Not used. Needs to be left floating.	34	SWDIO	Digital I/O	Serial wire debug I/O for debug and programming
GND_Shield Power Ground RACECLK Trace clock Trace buffer clock (optional). RACECLK Trace data Trace buffer TRACEDATA[0] (optional). RACECDATA0 Trace data Trace buffer TRACEDATA[1] (optional). RACEDATA1 Trace data Trace buffer TRACEDATA[1] (optional). RACEDATA1 Trace data Trace buffer TRACEDATA[1] (optional). PO.24 Digital I/O (SoC) General purpose I/O. RACEDATA2 Trace data Trace buffer TRACEDATA[1] (optional). RACEDATA2 Trace data Trace buffer TRACEDATA[1] (optional). RACEDATA2 Trace data Trace buffer TRACEDATA[2] (optional). RACEDATA2 Trace data Trace buffer TRACEDATA[2] (optional). RACEDATA3 Trace data Trace buffer TRACEDATA[3] (optional). SIM_RST Digital I/O (SoC) SIM reset Ground SIM_DET Digital I/O (SoC) SIM detect Not used. Needs to be left floating.	35	P0.20	Digital I/O (SoC)	General purpose I/O.
TRACECLK Trace clock Trace buffer clock (optional). TRACECLK Trace clock Trace buffer clock (optional). TRACEDATA0 Trace data Trace buffer TRACEDATA[0] (optional). TRACEDATA0 Trace data Trace buffer TRACEDATA[0] (optional). TRACEDATA1 Trace data Trace buffer TRACEDATA[1] (optional). TRACEDATA1 Trace data Trace buffer TRACEDATA[1] (optional). TRACEDATA2 Trace data Trace buffer TRACEDATA[1] (optional). TRACEDATA2 Trace data Trace buffer TRACEDATA[2] (optional). TRACEDATA2 Trace data Trace buffer TRACEDATA[2] (optional). TRACEDATA2 Trace data Trace buffer TRACEDATA[3] (optional). TRACEDATA3 Trac		AIN7	Analog input	Analog input.
TRACECLK Trace clock Trace clock Trace buffer clock (optional). Beneral purpose I/O. TRACEDATAO Trace data Trace buffer TRACEDATA[0] (optional). PO.23 Digital I/O (SoC) General purpose I/O. TRACEDATA1 Trace data Trace buffer TRACEDATA[1] (optional). TRACEDATA1 Trace data Trace buffer TRACEDATA[1] (optional). PO.24 Digital I/O (SoC) General purpose I/O. TRACEDATA2 Trace data Trace buffer TRACEDATA[2] (optional). Trace buffer TRACEDATA[2] (optional). Ground Ground General purpose I/O. TRACEDATA3 Trace data Trace buffer TRACEDATA[2] (optional). Trace buffer TRACEDATA[3] (optional). SIM_RST Digital I/O (SoC) SIM reset Ground Ground SIM_DET Digital I/O (SoC) SIM detect Not used. Needs to be left floating.	36	GND_Shield	Power	Ground
P0.22 Digital I/O (SoC) General purpose I/O.	37	P0.21	Digital I/O (SoC)	General purpose I/O.
TRACEDATAO Trace data Trace buffer TRACEDATA[0] (optional). P0.23 Digital I/O (SoC) General purpose I/O. TRACEDATA1 Trace data Trace buffer TRACEDATA[1] (optional). P0.24 Digital I/O (SoC) General purpose I/O. TRACEDATA2 Trace data Trace buffer TRACEDATA[2] (optional). GND_Shield Power Ground P0.25 Digital I/O (SoC) General purpose I/O. TRACEDATA3 Trace data Trace buffer TRACEDATA[2] (optional). SIM_RST Digital I/O (SoC) General purpose I/O. GRACEDATA3 Trace data Trace buffer TRACEDATA[3] (optional). SIM_reset GND_Shield Power Ground SIM_reset GND_Shield Power Ground SIM_DET Digital I/O (SoC) SIM detect Not used. Needs to be left floating.		TRACECLK	Trace clock	Trace buffer clock (optional).
39 P0.23 Digital I/O (SoC) General purpose I/O. TRACEDATA1 Trace data Trace buffer TRACEDATA[1] (optional). 40 P0.24 Digital I/O (SoC) General purpose I/O. TRACEDATA2 Trace data Trace buffer TRACEDATA[2] (optional). 41 GND_Shield Power Ground 42 P0.25 Digital I/O (SoC) General purpose I/O. TRACEDATA3 Trace data Trace buffer TRACEDATA[3] (optional). 43 SIM_RST Digital I/O (SoC) SIM reset 44 GND_Shield Power Ground 45 SIM_DET Digital I/O (SoC) SIM detect Not used. Needs to be left floating. 46 SIM_CLK Digital I/O (SoC) SIM clock	38	P0.22	Digital I/O (SoC)	General purpose I/O.
TRACEDATA1 Trace data Trace buffer TRACEDATA[1] (optional). 40 P0.24 Digital I/O (SoC) General purpose I/O. TRACEDATA2 Trace data Trace buffer TRACEDATA[2] (optional). 41 GND_Shield Power Ground 42 P0.25 Digital I/O (SoC) General purpose I/O. TRACEDATA3 Trace data Trace buffer TRACEDATA[3] (optional). 43 SIM_RST Digital I/O (SoC) SIM reset 44 GND_Shield Power Ground 45 SIM_DET Digital I/O (SoC) SIM detect Not used. Needs to be left floating. 46 SIM_CLK Digital I/O (SoC) SIM clock		TRACEDATA0	Trace data	Trace buffer TRACEDATA[0] (optional).
P0.24 Digital I/O (SoC) General purpose I/O. TRACEDATA2 Trace data Trace buffer TRACEDATA[2] (optional). 41 GND_Shield Power Ground 42 P0.25 Digital I/O (SoC) General purpose I/O. TRACEDATA3 Trace data Trace buffer TRACEDATA[3] (optional). 43 SIM_RST Digital I/O (SoC) SIM reset 44 GND_Shield Power Ground 45 SIM_DET Digital I/O (SoC) SIM detect Not used. Needs to be left floating. 46 SIM_CLK Digital I/O (SoC) SIM clock	39	P0.23	Digital I/O (SoC)	General purpose I/O.
TRACEDATA2 Trace data Trace buffer TRACEDATA[2] (optional). 41 GND_Shield Power Ground 42 P0.25 Digital I/O (SoC) General purpose I/O. TRACEDATA3 Trace data Trace buffer TRACEDATA[3] (optional). 43 SIM_RST Digital I/O (SoC) SIM reset 44 GND_Shield Power Ground 45 SIM_DET Digital I/O (SoC) SIM detect Not used. Needs to be left floating. 46 SIM_CLK Digital I/O (SoC) SIM clock		TRACEDATA1	Trace data	Trace buffer TRACEDATA[1] (optional).
41 GND_Shield Power Ground 42 P0.25 Digital I/O (SoC) General purpose I/O. TRACEDATA3 Trace data Trace buffer TRACEDATA[3] (optional). 43 SIM_RST Digital I/O (SoC) SIM reset 44 GND_Shield Power Ground 45 SIM_DET Digital I/O (SoC) SIM detect Not used. Needs to be left floating. 46 SIM_CLK Digital I/O (SoC) SIM clock	40	P0.24	Digital I/O (SoC)	General purpose I/O.
P0.25 Digital I/O (SoC) General purpose I/O. TRACEDATA3 Trace data Trace buffer TRACEDATA[3] (optional). SIM_RST Digital I/O (SoC) SIM reset GROUD_Shield Power Ground SIM_DET Digital I/O (SoC) SIM detect Not used. Needs to be left floating. SIM_CLK Digital I/O (SoC) SIM clock		TRACEDATA2	Trace data	Trace buffer TRACEDATA[2] (optional).
TRACEDATA3 Trace data Trace buffer TRACEDATA[3] (optional). 43 SIM_RST Digital I/O (SoC) SIM reset 44 GND_Shield Power Ground 45 SIM_DET Digital I/O (SoC) SIM detect Not used. Needs to be left floating. 46 SIM_CLK Digital I/O (SoC) SIM clock	41	GND_Shield	Power	Ground
43 SIM_RST Digital I/O (SoC) SIM reset 44 GND_Shield Power Ground 45 SIM_DET Digital I/O (SoC) SIM detect Not used. Needs to be left floating. 46 SIM_CLK Digital I/O (SoC) SIM clock	42	P0.25	Digital I/O (SoC)	General purpose I/O.
44 GND_Shield Power Ground 45 SIM_DET Digital I/O (SoC) SIM detect Not used. Needs to be left floating. 46 SIM_CLK Digital I/O (SoC) SIM clock		TRACEDATA3	Trace data	Trace buffer TRACEDATA[3] (optional).
45 SIM_DET Digital I/O (SoC) SIM detect Not used. Needs to be left floating. 46 SIM_CLK Digital I/O (SoC) SIM clock	43	SIM_RST	Digital I/O (SoC)	SIM reset
Not used. Needs to be left floating. 46 SIM_CLK Digital I/O (SoC) SIM clock	44	GND_Shield	Power	Ground
46 SIM_CLK Digital I/O (SoC) SIM clock	45	SIM_DET	Digital I/O (SoC)	SIM detect
				Not used. Needs to be left floating.
47 GND_Shield Power Ground	46	SIM_CLK	Digital I/O (SoC)	SIM clock
	47	GND_Shield	Power	Ground





Pin no	Pin name	Function	Description
48	SIM_IO	Digital I/O (SoC)	SIM data
49	SIM_1V8	Power	SIM 1.8 V power supply output
50	GND_Shield	Power	Ground
51	Reserved		Do not connect/reserved for future use
52	GND_Shield	Power	Ground
53	MAGPIO2	Digital I/O (SoC)	1.8 V general purpose I/O
54	MAGPIO1	Digital I/O (SoC)	1.8 V general purpose I/O
55	MAGPIO0	Digital I/O (SoC)	1.8 V general purpose I/O
56	GND_Shield	Power	Ground
57	VIO	Power	MIPI RFFE control interface
58	SCLK	Digital I/O (SoC)	MIPI RFFE control interface
59	SDATA	Digital I/O (SoC)	MIPI RFFE control interface
60	GND_Shield	Power	Ground
61	ANT	RF	Single-ended 50 Ω LTE antenna pin
62	GND_Shield	Power	Ground
63	GND_Shield	Power	Ground
64	AUX	RF	Single-ended 50 Ω ANT loop-back pin
65	GND_Shield	Power	Ground
66	GND_Shield	Power	Ground
67	GPS	RF	Single-ended 50 Ω GPS input pin
68	GND_Shield	Power	Ground
69	GND_Shield	Power	Ground
70	Reserved		Do not connect/reserved for future use
71	Reserved		Do not connect/reserved for future use
72	GND_Shield	Power	Ground
73	Reserved		Do not connect/reserved for future use
74	GND_Shield	Power	Ground
75	GND_Shield	Power	Ground
76	GND_Shield	Power	Ground
77	GND_Shield	Power	Ground
78	GND_Shield	Power	Ground
79	GND Shield	Power	Ground
80	GND_Shield	Power	Ground
81	GND_Shield	Power	Ground
82	GND_Shield	Power	Ground
83	P0.26	Digital I/O (SoC)	General purpose I/O
84	P0.27	Digital I/O (SoC)	General purpose I/O
85	GND_Shield	Power	Ground
86	P0.28	Digital I/O (SoC)	General purpose I/O
87	P0.29	Digital I/O (SoC)	General purpose I/O
88	P0.30	Digital I/O (SoC)	General purpose I/O
89	P0.31	Digital I/O (SoC)	General purpose I/O
90	GND_Shield	Power	Ground
91	COEX2	Digital I/O (SoC)	Coexistence interface
92	COEX1	Digital I/O (SoC)	Coexistence interface
93	COEXO	Digital I/O (SoC)	Coexistence interface
94	GND_Shield	Power	Ground
95	P0.00	Digital I/O (SoC)	General purpose I/O
96	P0.01	Digital I/O (SoC)	General purpose I/O
97	P0.02	Digital I/O (SoC)	General purpose I/O
98	GND_Shield	Power	Ground
99	P0.03	Digital I/O (SoC)	General purpose I/O
100	P0.04	Digital I/O (SoC)	General purpose I/O
100	. 0.04	51 ₆ .ta. 1/ 0 (300/	General parpose I/O



Pin no	Pin name	Function	Description
101	ENABLE		Enable for the SiP internal regulator for the nRF91 SoC.
			Note: The nRF91 will not start until this pin is enabled.
102	VDD1	Power	Supply voltage
103	VSS	Power	Ground
104-127	Reserved		Do not connect/reserved for future use

Table 114: LGA pin assignments

10.2 Mechanical specifications

The mechanical specifications for the packages show the dimensions in millimeters.

10.2.1 16.00 x 10.50 mm package

Dimensions in millimeters for the nRF9160 LGA 16.00 x 10.50 mm package.

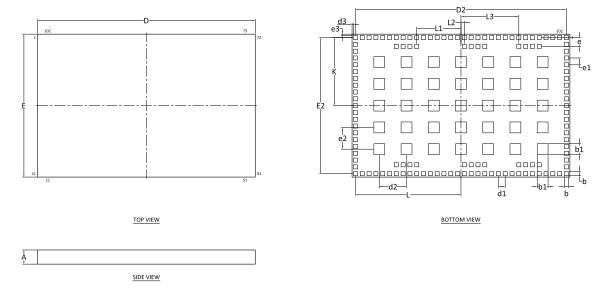


Figure 118: LGA 16.00 x 10.50 mm package

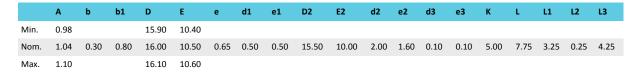


Table 115: LGA dimensions in millimeters

10.3 Reference circuitry

To ensure good RF performance when designing PCBs, it is highly recommended using the PCB layouts and component values provided by Nordic Semiconductor.

Documentation for the different package reference circuits, including Altium Designer files, PCB layout files, and PCB production files can be downloaded from the product page at www.nordicsemi.com.



In this section, there are reference circuits for SIxA to show the components and component values to support on-chip features in a design.

Note: This is not a complete list of configurations, but all required circuitry is shown for further configurations.

10.3.1 Schematic SIxA LGA127

Circuit configuration for SIxA LGA127, showing the schematic and the Bill of Materials (BOM) table.

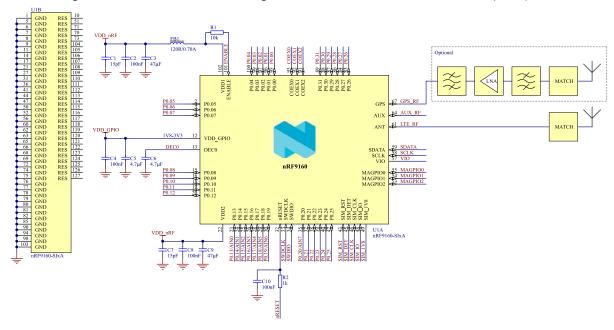


Figure 119: Schematic SIxA with antenna details

Designator	Value	Description	Footprint
C1, C7	15 pF	Capacitor, NPO, ±0.1pF, 25 V	0201
C2, C4, C8, C10	100 nF	Capacitor, X5R, ±10%	0201
C3, C9	47 μF	Capacitor, X5R, ±20%, 10 V	0805
C5	4.7 μF	Capacitor, X5R, ±20%	0402
C6	4.7 μF	Capacitor, X5R, ±10%, 16 V	0805
R1	10 kΩ	Resistor, ±1%, 0.05 W	0201
R2	1 k	Resistor, ±1%, 0.05 W	0201
FB1	120 R / 0.70 A	Ferrite Bead, 120 Ω @ 100 MHz, 700 mA, 130 m Ω Max	0402
U1	nRF9160-SIxA	Low power System- in-Package (SiP) with integrated LTE-M/NB-IoT modem and GPS	LGA

Table 116: BOM for SIxA LGA127

For PCB reference layouts, see the product page for the nRF9160 at www.nordicsemi.com.

10.4 Reflow conditions

The recommended reflow profile is JEDEC J-STD-020D. The maximum amount of reflows is three.

10.5 Shelf and floor life

If floor life is exceeded, see Shelf Life of Dry Packed Integrated Circuits for shelf and floor life and recommended baking (drying of parts) requirements.



11 Operating conditions

The operating conditions are the physical parameters that the chip can operate within.

Symbol	Parameter	Notes	Min.	Nom.	Max.	Units
VDD	Battery input voltage	Including voltage drop, ripple and	1 3.0	3.8	5.5	V
		spikes.				
		RF 3GPP compliancy requires 3.3				
		V.				
VDD_GPIO	GPIO input voltage		1.7		3.6	V
GPIO _H	GPIO high level voltage				VDD_GPIO	V
$MAGPIO_H$	MAGPIO high level voltage	Supply from internal LDO	1.7	1.8	1.9	V
VIO	VIO high level voltage	Supply from internal LDO	1.7	1.8	1.9	V
TA	Operating temperature		-40	25	85	°C
COEX	COEX high level voltage				VDD_GPIO	٧
SIMIF	SIMIF output high level voltage	Supply from internal LDO	1.7	1.8	1.9	V

Table 117: Operating conditions

Note: There can be excessive leakage at VDD and/or VDD_GPIO if any of these supply voltages is outside its range given in the table above.

Note: It is not recommended to use high voltage, high drive GPIO outputs ($V_{OH,HDH}$ and $V_{OH,HDL}$) with high frequency, high capacitance loads unless needed, as this may increase noise level and affect radio receiver performance. High drive/high load should especially be avoided on GPIO pins close to the radio front end.

11.1 VDD_GPIO considerations

VDD_GPIO is the supply to the general purpose I/O.

The following restrictions should be taken into considerations:

- VDD GPIO should be applied after VDD has been supplied
- VDD_GPIO should be removed before removing VDD
- If VDD is supplied and VDD_GPIO is grounded, an extra current consumption can be generated on VDD
- If ENABLE is low, VDD_GPIO should also be low



12 Absolute maximum ratings

Maximum ratings are the extreme limits to which the chip can be exposed for a limited amount of time without permanently damaging it. Exposure to absolute maximum ratings for prolonged periods of time may affect the reliability of the device.

	Note	Min.	Max.	Unit
Supply voltages				
VDD		-0.3	5.5 ²²	V
VDD_GPIO		-0.3	3.9	V
SIM_1V8		1.65	1.95	V
VSS			0	V
I/O pin voltage				
V _{I/O} , VDD_GPIO ≤ 3.6 V		-0.3	VDD_GPIO + 0.3	V
V _{I/O} , VDD_GPIO > 3.6 V		-0.3	3.9	V
Radio				
ANT antenna input level			10	dBm
GPS antenna input level	LNA turned on, max gain		-15	dBm
RF port ruggedness	Maximum deviation from		10:1	VSWR
	50Ω without damaging the			
	module			
Environmental (LGA package)				
Storage temperature		-40	95	°C
MSL	Moisture Sensitivity Level		3	
ESD HBM	Human Body Model		1.5	kV
ESD HBM Class	Human Body Model Class		1C	
ESD CDM	Charged Device Model		250	V
Flash memory				
Endurance		10 000		Write/erase cycles
Retention		10 years at 85°C		
ATEX compliance				
Ci			83	μF
Ü			9.0	μН
Ui			5.0	V
li			600	mA
Thermal conductivity			35	C/W
No internal voltage boost converters				

Table 118: Absolute maximum ratings



²² ATEX compliance requires a maximum of 5.0 V.

13 Ordering information

This chapter contains information on IC marking, ordering codes, and container sizes.

13.1 IC marking

The nRF9160 IC package is marked like described below.

N	9	1	6	0	
<p< th=""><th>P></th><th><></th><th>V></th><th>+</th><th><p></p></th></p<>	P>	<>	V>	+	<p></p>
<y< th=""><th>Y></th><th><w< th=""><th>W></th><th><l< th=""><th>L></th></l<></th></w<></th></y<>	Y>	<w< th=""><th>W></th><th><l< th=""><th>L></th></l<></th></w<>	W>	<l< th=""><th>L></th></l<>	L>

Figure 120: Package marking

13.2 Box labels

Here are the box labels used for the nRF9160.

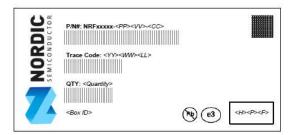


Figure 121: Inner box label



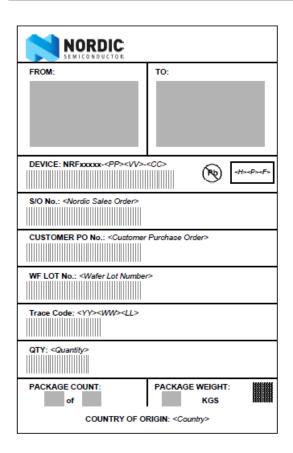


Figure 122: Outer box label

13.3 Order code

Here are the nRF9160 order codes and definitions.

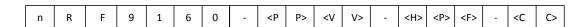


Figure 123: Order code



Abbreviation	Definition and implemented codes
N91/nRF91	nRF91 Series product
60	Part code
<pp></pp>	Package variant code
<vv></vv>	Function variant code
<h><p><f></f></p></h>	Build code H - Hardware version code P - Production configuration code (production site, etc.) F - Firmware version code (only visible on shipping container label)
<yy><ww><ll></ll></ww></yy>	Tracking code YY - Year code WW - Assembly week number LL - Wafer lot code
<cc></cc>	Container code

Table 119: Abbreviations

13.4 Code ranges and values

Defined here are the nRF9160 code ranges and values.

<pp></pp>	Package	Size (mm)	Pin/Ball count	Pitch (mm)
SI	LGA	16.00 x 10.50	127	0.50

Table 120: Package variant codes

<vv></vv>	LTE-M/NB-IoT/GPS	Flash (kB)	RAM (kB)
CA	LTE-M/NB-IoT/GPS	1024	256
AA	LTE-M only		
ВА	NB-IoT only		

Table 121: Function variant codes

<h>></h>	Description
[A Z]	Hardware version/revision identifier (incremental)

Table 122: Hardware version codes



<p></p>	Description
[09]	Production device identifier (incremental)
[A Z]	Engineering device identifier (incremental)

Table 123: Production configuration codes

<f></f>	Description
[A N, P Z]	Version of preprogrammed firmware
[0]	Delivered without preprogrammed firmware

Table 124: Production version codes

<yy></yy>	Description
[1599]	Production year: 2015 to 2099

Table 125: Year codes

<ww></ww>	Description
[152]	Week of production

Table 126: Week codes

<ll></ll>	Description
[AA ZZ]	Wafer production lot identifier

Table 127: Lot codes

<cc></cc>	Description
R7	7" Reel
R	13" Reel
Т	Tray

Table 128: Container codes

13.5 Product options

Defined here are the nRF9160 product options.



Order code	Minimum ordering quantity (MOQ)	Comment
nRF9160-SICA-B1A-R	2500	LTE-M/NB-IoT/GPS product
nRF9160-SICA-B1A-R7	100	LTE-M/NB-IoT/GPS product
nRF9160-SIAA-B1A-R	2500	LTE-M only product
nRF9160-SIAA-B1A-R7	100	LTE-M only product
nRF9160-SIBA-B1A-R	2500	NB-IoT only product
nRF9160-SIBA-B1A-R7	100	NB-IoT only product

Table 129: nRF9160 order codes

Order code	Description	
nRF9160-DK	nRF9160 Development Kit	
nRF6943	Nordic Thingy:91	

Table 130: Development tools order code

14 Regulatory information

The nRF9160 undergoes a number of regulatory certifications, ensuring both regional compliancies and compatibility with the LTE 3GPP specification.

For information about certified bands, and status for the ongoing certifications, see nRF9160 Certifications.



15 Legal notices

By using this documentation you agree to our terms and conditions of use. Nordic Semiconductor may change these terms and conditions at any time without notice.

Liability disclaimer

Nordic Semiconductor ASA reserves the right to make changes without further notice to the product to improve reliability, function, or design. Nordic Semiconductor ASA does not assume any liability arising out of the application or use of any product or circuits described herein.

Nordic Semiconductor ASA does not give any representations or warranties, expressed or implied, as to the accuracy or completeness of such information and shall have no liability for the consequences of use of such information. If there are any discrepancies, ambiguities or conflicts in Nordic Semiconductor's documentation, the Product Specification prevails.

Nordic Semiconductor ASA reserves the right to make corrections, enhancements, and other changes to this document without notice.

Customer represents that, with respect to its applications, it has all the necessary expertise to create and implement safeguards that anticipate dangerous consequences of failures, monitor failures and their consequences, and lessen the likelihood of failures that might cause harm, and to take appropriate remedial actions.

Nordic Semiconductor ASA assumes no liability for applications assistance or the design of customers' products. Customers are solely responsible for the design, validation, and testing of its applications as well as for compliance with all legal, regulatory, and safety-related requirements concerning its applications.

Nordic Semiconductor ASA's products are not designed for use in life-critical medical equipment, support appliances, devices, or systems where malfunction of Nordic Semiconductor ASA's products can reasonably be expected to result in personal injury. Customer may not use any Nordic Semiconductor ASA's products in life-critical medical equipment unless adequate design and operating safeguards by customer's authorized officers have been made. Customer agrees that prior to using or distributing any life-critical medical equipment that include Nordic Semiconductor ASA's products, customer will thoroughly test such systems and the functionality of such products as used in such systems.

Customer will fully indemnify Nordic Semiconductor ASA and its representatives against any damages, costs, losses, and/or liabilities arising out of customer's non-compliance with this section.

RoHS and REACH statement

Refer to www.nordicsemi.com for complete hazardous substance reports, material composition reports, and latest version of Nordic's RoHS and REACH statements.

Trademarks

All trademarks, service marks, trade names, product names, and logos appearing in this documentation are the property of their respective owners.

Copyright notice

© Nordic Semiconductor ASA. All rights are reserved. Reproduction in whole or in part is prohibited without the prior written permission of the copyright holder.





