# **PCK953**

**20 MHz to 125 MHz PECL input, 9 CMOS output, 3.3 V PLL clock driver**

**Rev. 05 – 9 October 2008** Product data sheet

## <span id="page-0-1"></span>**1. General description**

The PCK953 is a 3.3 V compatible, PLL-based clock driver device targeted for high performance clock tree designs. With output frequencies of up to 125 MHz, and output skews of 100 ps, the PCK953 is ideal for the most demanding clock tree designs. The devices employ a fully differential PLL design to minimize cycle-to-cycle and phase jitter.

The PCK953 has a differential LVPECL reference input, along with an external feedback input. These features make the PCK953 ideal for use as a zero delay, low skew fan-out buffer. The device performance has been tuned and optimized for zero delay performance. The MR/OE input pin will reset the internal counters and 3-state the output buffers when driven HIGH.

The PCK953 is fully 3.3 V compatible and requires no external loop filter components. All control inputs accept LVCMOS or LVTTL compatible levels, while the outputs provide LVCMOS levels with the ability to drive terminated 50  $\Omega$  transmission lines. For series terminated 50  $\Omega$  lines, each of the PCK953 outputs can drive two traces, giving the device an effective fan-out of 1 : 18. The device is packaged in a 7 mm  $\times$  7 mm 32-lead LQFP package to provide the optimum combination of board density and performance.

#### <span id="page-0-0"></span>**2. Features**

- Fully integrated PLL
- Output frequency up to 125 MHz in PLL mode
- Outputs disable in high-impedance
- LQFP32 packaging
- 55 ps cycle-to-cycle jitter typical
- 9 mA quiescent current typical
- 60 ps static phase offset typical



# <span id="page-1-1"></span>**3. Ordering information**

<span id="page-1-2"></span>

Also refer to [Table 8 "Packing information"](#page-9-0).

# <span id="page-1-3"></span>**4. Functional diagram**



# <span id="page-1-4"></span><span id="page-1-0"></span>**5. Pinning information**

<span id="page-1-5"></span>

#### **5.1 Pinning**

## <span id="page-2-1"></span>**5.2 Pin description**



# <span id="page-2-3"></span><span id="page-2-2"></span>**6. Functional description**

Refer to [Figure 1 "Functional diagram"](#page-1-0).

### **6.1 Function selection**

<span id="page-2-0"></span>

# <span id="page-3-4"></span>**7. Limiting values**

<span id="page-3-2"></span>

## <span id="page-3-5"></span>**8. Static characteristics**

#### <span id="page-3-3"></span>**Table 5. Static characteristics**

 $T_{amb} = 0$  °C to 70 °C;  $V_{CC} = 3.3$  V  $\pm$  5 %, unless specified otherwise.



<span id="page-3-0"></span> $[1]$  V<sub>cm</sub> is the difference from the most positive side of the differential input signal. Normal operation is obtained when the HIGH input is within the  $V_{cm}$  range and the input swing lies within the  $V_{i(p-p)}$  specification.

<span id="page-3-1"></span>[2] The PCK953 outputs can drive series or parallel terminated 50  $\Omega$  (or 50  $\Omega$  to 0.5V<sub>CC</sub>) transmission lines on the incident edge (see [Section 11 "Application information"](#page-5-0)).

# <span id="page-4-1"></span>**9. Dynamic characteristics**

#### <span id="page-4-0"></span>**Table 6. Dynamic characteristics**

 $T_{amb}$  = 0 °C to 70 °C;  $V_{CC}$  = 3.3 V ± 5 %; unless specified otherwise.



# <span id="page-4-2"></span>**10. PLL input reference characteristics**

#### **Table 7. PLL input reference characteristics**

 $T_{amb} = 0$  °C to 70 °C.

Maximum and minimum input reference is limited by the VCO lock range and the feedback divider.



# <span id="page-5-2"></span><span id="page-5-0"></span>**11. Application information**

#### **11.1 Power supply filtering**

The PCK953 is a mixed analog/digital product and as such it exhibits some sensitivities that would not necessarily be seen on a fully digital product. Analog circuitry is naturally susceptible to random noise, especially if this noise is seen on the power supply pins. The PCK953 provides separate power supplies for the output buffers ( $V<sub>CCO</sub>$ ) and the phase-locked loop ( $V_{CCA}$ ) of the device. The purpose of this design technique is to try to isolate the high switching noise digital outputs from the relatively sensitive internal analog phase-locked loop. In a controlled environment such as an evaluation board, this level of isolation is sufficient. However, in a digital system environment where it is more difficult to minimize noise on the power supplies, a second level of isolation may be required. The simplest form of isolation is a power supply filter on the  $V_{CCA}$  pin for the PCK953.

[Figure](#page-5-1) 3 illustrates a typical power supply filter scheme. The PCK953 is most susceptible to noise with spectral content in the 1 kHz to 1 MHz range. Therefore, the filter should be designed to target this range. The key parameter that needs to be met in the final filter design is the DC voltage drop that will be seen between the  $V_{CC}$  supply and the  $V_{CCA}$  pin of the PCK953. The current sourced though the  $V_{CCA}$  pin is typically 15 mA (20 mA maximum), assuming that a minimum of 3.0 V must be maintained on the  $V_{CCA}$  pin, very little DC voltage drop can be tolerated when a 3.3 V  $V_{CC}$  supply is used. The resistor shown in [Figure](#page-5-1) 3 must have a resistance of 10  $\Omega$  to 15  $\Omega$  to meet the voltage drop criteria. The RC filter pictured will provide a broadband filter with approximately 100 : 1 attenuation for noise whose spectral content is above 20 kHz. As the noise frequency crosses the series resonant point of an individual capacitor, its overall impedance begins to look inductive, and thus increases with increasing frequency. The parallel capacitor combination shown ensures that a low impedance path to ground exists for frequencies well above the bandwidth of the PLL. It is recommended that the user start with an 8  $\Omega$  to 10 Ω resistor to avoid potential  $V_{CC}$  drop problems, and only move to the higher value resistors when a higher level of attenuation is shown to be needed.

Although the PCK953 has several design features to minimize the susceptibility to power supply noise (isolated power and grounds and fully differential PLL) there still may be applications in which overall performance is being degraded due to system power supply noise. The power supply filter schemes discussed in this section should be adequate to eliminate power supply noise related problems in most designs.

<span id="page-5-1"></span>

#### <span id="page-6-1"></span>**11.2 Driving transmission lines**

The PCK953 clock driver was designed to drive high speed signals in a terminated transmission line environment. To provide the optimum flexibility to the user, the output drivers were designed to exhibit the lowest impedance possible. With an output impedance of less than 20  $\Omega$ , the drivers can drive either parallel or series terminated transmission lines.

In most high performance clock networks, point-to-point distribution of signals is the method of choice. In a point-to-point scheme either series terminated or parallel terminated transmission lines can be used. The parallel technique terminates the signal at the end of the line with a 50  $\Omega$  resistance to 0.5V<sub>CC</sub>. This technique draws a fairly high level of DC current, and thus only a single terminated line can be driven by each output of the PCK953 clock driver. For the series terminated case, however, there is no DC current draw, thus the outputs can drive multiple series terminated lines. [Figure](#page-6-0) 4 illustrates an output driving a single series terminated line versus two series terminated lines in parallel. When taken to its extreme, the fan-out of the PCK953 clock driver is effectively doubled due to its capability to drive multiple lines.



<span id="page-6-0"></span>The waveform plots of [Figure](#page-7-0) 5 show the simulation results of an output driving a single line versus two lines. In both cases, the drive capability of the PCK953 output buffers is more than sufficient to drive 50 Ω transmission lines on the incident edge. Note from the delay measurements in the simulations, a delta of only 43 ps exists between the two differently loaded outputs. This suggests that the dual line driving need not be used exclusively to maintain the tight output-to-output skew of the PCK953. The output waveform in [Figure](#page-7-0) 5 shows a step in the waveform; this step is caused by the impedance mismatch seen looking into the driver. The parallel combination of the 43  $\Omega$  series resistor plus the output impedance does not match the parallel combination of the line impedances. The voltage wave launched down the two lines will equal:

$$
V_L = V_S \left(\frac{Z_o}{R_s + R_o + Z_o}\right) \tag{1}
$$

$$
Z_0 = 50 \Omega \parallel 50 \Omega
$$
  
R<sub>s</sub> = 36  $\Omega \parallel 36 \Omega$   
R<sub>o</sub> = 14  $\Omega$ 

$$
V_L = 3.0 \left(\frac{25}{18 + 14 + 25}\right) = 3.0 \left(\frac{25}{57}\right) = 1.31 \text{ V}
$$
 (2)

At the load end, the voltage will double due to the near unity reflection coefficient, to 2.62 V. It will then increment towards the quiescent 3.0 V in steps separated by one round-trip delay (in this case, 4.0 ns).



<span id="page-7-0"></span>Since this step is well above the threshold region, it will not cause any false clock triggering, however, designers may be uncomfortable with unwanted reflections on the line. To better match the impedances when driving multiple lines, the situation in [Figure](#page-7-1) 6 should be used. In this case, the series terminating resistors are reduced such that when the parallel combination is added to the output buffer impedance, the line impedance is perfectly matched.



<span id="page-7-1"></span>SPICE level output buffer models are available for engineers who want to simulate their specific interconnect schemes. In addition, IV characteristics are in the process of being generated to support the other board-level simulators in general use.

# <span id="page-8-0"></span>**12. Package outline**



#### **Fig 7. Package outline SOT358-1 (LQFP32)**

# <span id="page-9-1"></span>**13. Packing information**

<span id="page-9-0"></span>

# <span id="page-9-2"></span>**14. Soldering of SMD packages**

This text provides a very brief insight into a complex technology. A more in-depth account of soldering ICs can be found in Application Note AN10365 "Surface mount reflow soldering description".

#### <span id="page-9-3"></span>**14.1 Introduction to soldering**

Soldering is one of the most common methods through which packages are attached to Printed Circuit Boards (PCBs), to form electrical circuits. The soldered joint provides both the mechanical and the electrical connection. There is no single soldering method that is ideal for all IC packages. Wave soldering is often preferred when through-hole and Surface Mount Devices (SMDs) are mixed on one printed wiring board; however, it is not suitable for fine pitch SMDs. Reflow soldering is ideal for the small pitches and high densities that come with increased miniaturization.

#### <span id="page-9-4"></span>**14.2 Wave and reflow soldering**

Wave soldering is a joining technology in which the joints are made by solder coming from a standing wave of liquid solder. The wave soldering process is suitable for the following:

- **•** Through-hole components
- **•** Leaded or leadless SMDs, which are glued to the surface of the printed circuit board

Not all SMDs can be wave soldered. Packages with solder balls, and some leadless packages which have solder lands underneath the body, cannot be wave soldered. Also, leaded SMDs with leads having a pitch smaller than ~0.6 mm cannot be wave soldered, due to an increased probability of bridging.

The reflow soldering process involves applying solder paste to a board, followed by component placement and exposure to a temperature profile. Leaded packages, packages with solder balls, and leadless packages are all reflow solderable.

Key characteristics in both wave and reflow soldering are:

**•** Board specifications, including the board finish, solder masks and vias

- **•** Package footprints, including solder thieves and orientation
- **•** The moisture sensitivity level of the packages
- **•** Package placement
- **•** Inspection and repair
- **•** Lead-free soldering versus SnPb soldering

#### <span id="page-10-0"></span>**14.3 Wave soldering**

Key characteristics in wave soldering are:

- **•** Process issues, such as application of adhesive and flux, clinching of leads, board transport, the solder wave parameters, and the time during which components are exposed to the wave
- **•** Solder bath specifications, including temperature and impurities

#### <span id="page-10-1"></span>**14.4 Reflow soldering**

Key characteristics in reflow soldering are:

- **•** Lead-free versus SnPb soldering; note that a lead-free reflow process usually leads to higher minimum peak temperatures (see Figure 8) than a SnPb process, thus reducing the process window
- **•** Solder paste printing issues including smearing, release, and adjusting the process window for a mix of large and small components on one board
- **•** Reflow temperature profile; this profile includes preheat, reflow (in which the board is heated to the peak temperature) and cooling down. It is imperative that the peak temperature is high enough for the solder to make reliable solder joints (a solder paste characteristic). In addition, the peak temperature must be low enough that the packages and/or boards are not damaged. The peak temperature of the package depends on package thickness and volume and is classified in accordance with Table 9 and 10

#### **Table 9. SnPb eutectic process (from J-STD-020C)**



#### **Table 10. Lead-free process (from J-STD-020C)**



Moisture sensitivity precautions, as indicated on the packing, must be respected at all times.



Studies have shown that small packages reach higher temperatures during reflow soldering, see Figure 8.

For further information on temperature profiles, refer to Application Note AN10365 "Surface mount reflow soldering description".

# <span id="page-11-0"></span>**15. Abbreviations**



# <span id="page-12-0"></span>**16. Revision history**



# <span id="page-13-1"></span>**17. Legal information**

#### <span id="page-13-2"></span>**17.1 Data sheet status**



[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the Internet at URL <http://www.nxp.com>.

#### <span id="page-13-3"></span>**17.2 Definitions**

**Draft —** The document is a draft version only. The content is still under internal review and subject to formal approval, which may result in modifications or additions. NXP Semiconductors does not give any representations or warranties as to the accuracy or completeness of information included herein and shall have no liability for the consequences of use of such information.

**Short data sheet —** A short data sheet is an extract from a full data sheet with the same product type number(s) and title. A short data sheet is intended for quick reference only and should not be relied upon to contain detailed and full information. For detailed and full information see the relevant full data sheet, which is available on request via the local NXP Semiconductors sales office. In case of any inconsistency or conflict with the short data sheet, the full data sheet shall prevail.

#### <span id="page-13-0"></span>**17.3 Disclaimers**

**General —** Information in this document is believed to be accurate and reliable. However, NXP Semiconductors does not give any representations or warranties, expressed or implied, as to the accuracy or completeness of such information and shall have no liability for the consequences of use of such information.

**Right to make changes —** NXP Semiconductors reserves the right to make changes to information published in this document, including without limitation specifications and product descriptions, at any time and without notice. This document supersedes and replaces all information supplied prior to the publication hereof.

**Suitability for use —** NXP Semiconductors products are not designed, authorized or warranted to be suitable for use in medical, military, aircraft, space or life support equipment, nor in applications where failure or

#### malfunction of an NXP Semiconductors product can reasonably be expected to result in personal injury, death or severe property or environmental damage. NXP Semiconductors accepts no liability for inclusion and/or use of NXP Semiconductors products in such equipment or applications and therefore such inclusion and/or use is at the customer's own risk.

**Applications —** Applications that are described herein for any of these products are for illustrative purposes only. NXP Semiconductors makes no representation or warranty that such applications will be suitable for the specified use without further testing or modification.

**Limiting values —** Stress above one or more limiting values (as defined in the Absolute Maximum Ratings System of IEC 60134) may cause permanent damage to the device. Limiting values are stress ratings only and operation of the device at these or any other conditions above those given in the Characteristics sections of this document is not implied. Exposure to limiting values for extended periods may affect device reliability.

**Terms and conditions of sale —** NXP Semiconductors products are sold subject to the general terms and conditions of commercial sale, as published at <http://www.nxp.com/profile/terms>, including those pertaining to warranty, intellectual property rights infringement and limitation of liability, unless explicitly otherwise agreed to in writing by NXP Semiconductors. In case of any inconsistency or conflict between information in this document and such terms and conditions, the latter will prevail.

**No offer to sell or license —** Nothing in this document may be interpreted or construed as an offer to sell products that is open for acceptance or the grant, conveyance or implication of any license under any copyrights, patents or other industrial or intellectual property rights.

#### <span id="page-13-4"></span>**17.4 Trademarks**

Notice: All referenced brands, product names, service names and trademarks are the property of their respective owners.

# <span id="page-13-5"></span>**18. Contact information**

For more information, please visit: **http://www.nxp.com**

For sales office addresses, please send an email to: **salesaddresses@nxp.com**

# **NXP Semiconductors PCK953**

**20 MHz to 125 MHz PECL input, 9 CMOS output, 3.3 V PLL clock driver**

# <span id="page-14-0"></span>**19. Contents**



Please be aware that important notices concerning this document and the product(s) described herein, have been included in section 'Legal information'.

**© NXP B.V. 2008. All rights reserved.**

For more information, please visit: http://www.nxp.com For sales office addresses, please send an email to: salesaddresses@nxp.com

**Date of release: 9 October 2008 Document identifier: PCK953\_5**

