

AN-1632 LP5521TMEV Programmable LED Driver

User's Guide



Literature Number: SNVA241E
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EVM Warnings and Restrictions

It is possible to feed VDD voltage from external source to connector J2. It is important to operate this EVM within the V_{DD} voltage range of 2.7 V to 5.5 V. The V_{DD} voltage must never exceed 6 V.

Exceeding the specified input range may cause unexpected operation and/or irreversible damage to the EVM. If there are questions concerning the input range, please contact a TI field representative prior to connecting the input power.

During normal operation, some circuit components may have case temperatures greater than 60°C. The EVM is designed to operate properly with certain components above 60°C as long as the input and output ranges are maintained. These components include but are not limited to LEDs, linear regulators, switching transistors, Inductors, pass transistors, and current sense resistors. These types of devices can be identified using the EVM schematic located in the EVM User's Guide.

When placing measurement probes near these devices please be aware that these devices may be very warm to the touch.

The white LEDs which are mounted on the EVM emit light which, at a high enough intensity, have the potential to be harmful to the eyes. To reduce the risk of eye damage TI recommends using engineering controls (for example, light-blocking screens or filters) or personal protection equipment (for example, light-filtering or blocking eyewear). Users should not look directly at any operating LED component regardless of LED color or intensity.

LP5521EV User Guide

1 Read This First

1.1 *About this Manual*

This user's guide describes the characteristics, operation, and use of the LP5521 evaluation module (EVM). This user's guide includes a schematic diagram and bill of materials (BOM).

1.2 *Related Documentation from Texas Instruments*

LP5521 data sheet: *LP5521 Programmable Three Channel LED Driver* ([SNVS441](#))

AN-1562 LP5521 Programming Considerations ([SNVA205](#))

1.3 *FCC Warning*

This equipment is intended for use in a laboratory test environment only. It generates, uses, and can radiate radio frequency energy and has not been tested for compliance with the limits of computing devices pursuant to subpart J of part 15 of FCC rules, which are designed to provide reasonable protection against radio frequency interference. Operation of this equipment in other environments may cause interference with radio communications, in which case the user, at his own expense, will be required to take whatever measures may be required to correct this interference.

1.4 *If You Need Assistance*

Contact your local TI sales representative.

2 Introduction

The Texas Instruments LP5521TMEV evaluation module helps designers evaluate the operation and performance of LP5521 integrated circuit (IC). The LP5521TMEV uses a high-efficiency charge pump, three independent LED channels, and program memory for creating variety of lighting sequences. More information about the LP5521 capabilities can be found in the device datasheet ([SNVS441](#)).

The EVM contains power supply connection for the V_{DD} voltage. Test points are provided for key signals. The on-board microcontroller can be used to control the digital input signals of the LP5521 and to control the device with I²C interface. A graphical user interface (GUI) is provided for fast and easy evaluation of the device.

If an external power supply is used, V_{DD} voltage must be within 2.7 V to 5.5 V. This voltage range is within the absolute maximum input range of the LP5521. Users are cautioned to evaluate their specific operating conditions and choose components with the appropriate voltage ratings before designing this support circuitry into a final product.

3 Description of the LP5521

3.1 General Description

The LP5521 is a three-channel LED driver designed to produce variety of lighting effects for mobile devices. A high-efficiency charge pump enables LED driving over full Li-Ion battery voltage range. The device has a program memory for creating variety of lighting sequences. When program memory has been loaded, LP5521 can operate autonomously without processor control allowing power savings.

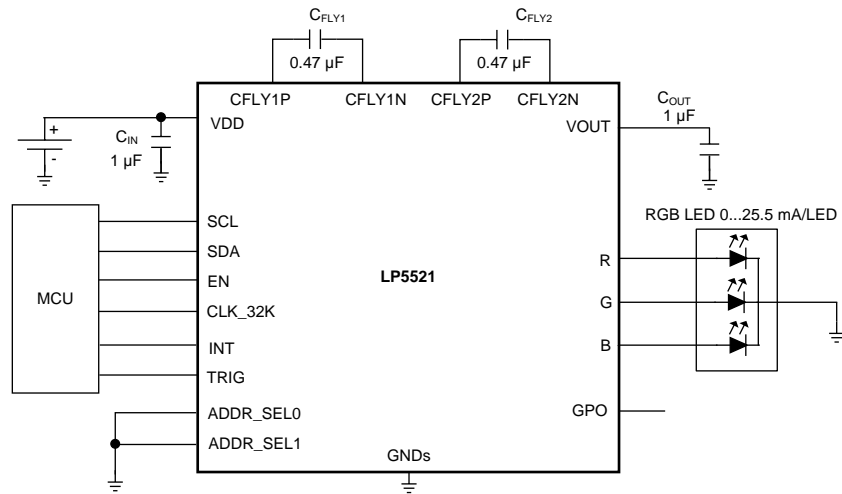
3.2 Features

- Adaptive Charge Pump With 1× and 1.5× Gain Provides Up to 95% LED Drive Efficiency
- Charge Pump with Soft Start and Overcurrent, Short-Circuit Protection
- Low Input Ripple and EMI
- Very Small Solution Size, No Inductor or Resistors Required
- 200-nA Typical Shutdown Current
- Automatic Power Save Mode
- I²C-Compatible Interface
- Independently Programmable Constant Current Outputs with 8-Bit Current Setting and 8-Bit PWM Control
- Typical LED Output Saturation Voltage 50 mV and Current Matching 1%
- Three Program Execution Engines with Flexible Instruction Set
- Autonomous Operation Without External Control
- Large SRAM Program Memory
- Two General Purpose Digital Outputs
- 36-pin DSBGA package, 2.478 mm × 2.478 mm × 0.6 mm, 0.4 mm pitch

3.3 Applications

- Fun and Indicator Lights
- LCD Sub-Display Backlighting
- Keypad RGB Backlighting and Phone Cosmetics
- Vibra, Speakers, Waveform Generator
- Blood Glucose Meter
- Handheld POS Terminals
- Electronic Access Control
- Where RGB Indication is Needed

3.4 LP5521 Typical Application Drawing



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4 LP5521EVM Hardware

Figure 1 shows how to set up shunts on LP5521TMEV. If external V_{DD} supply is used it must be connected to connector J2. Jumper J4 selects supply voltage source. This setup uses on-board microcontroller to control LP5521. LP5521TMEV must be connected to a Windows PC with USB cable. On-board LEDs are used as load.

Jumpers J1, J3, J8, and J9 select if white or RGB LEDs are used.

The LP5521 supports I2C interface. The LP5521 device is connected to the onboard microcontroller through connector J13. If user wants to use own controller to control the LP5521, shunts on connector J13 need to be removed and external controller needs to be connected to the pins on the right side of the J13.

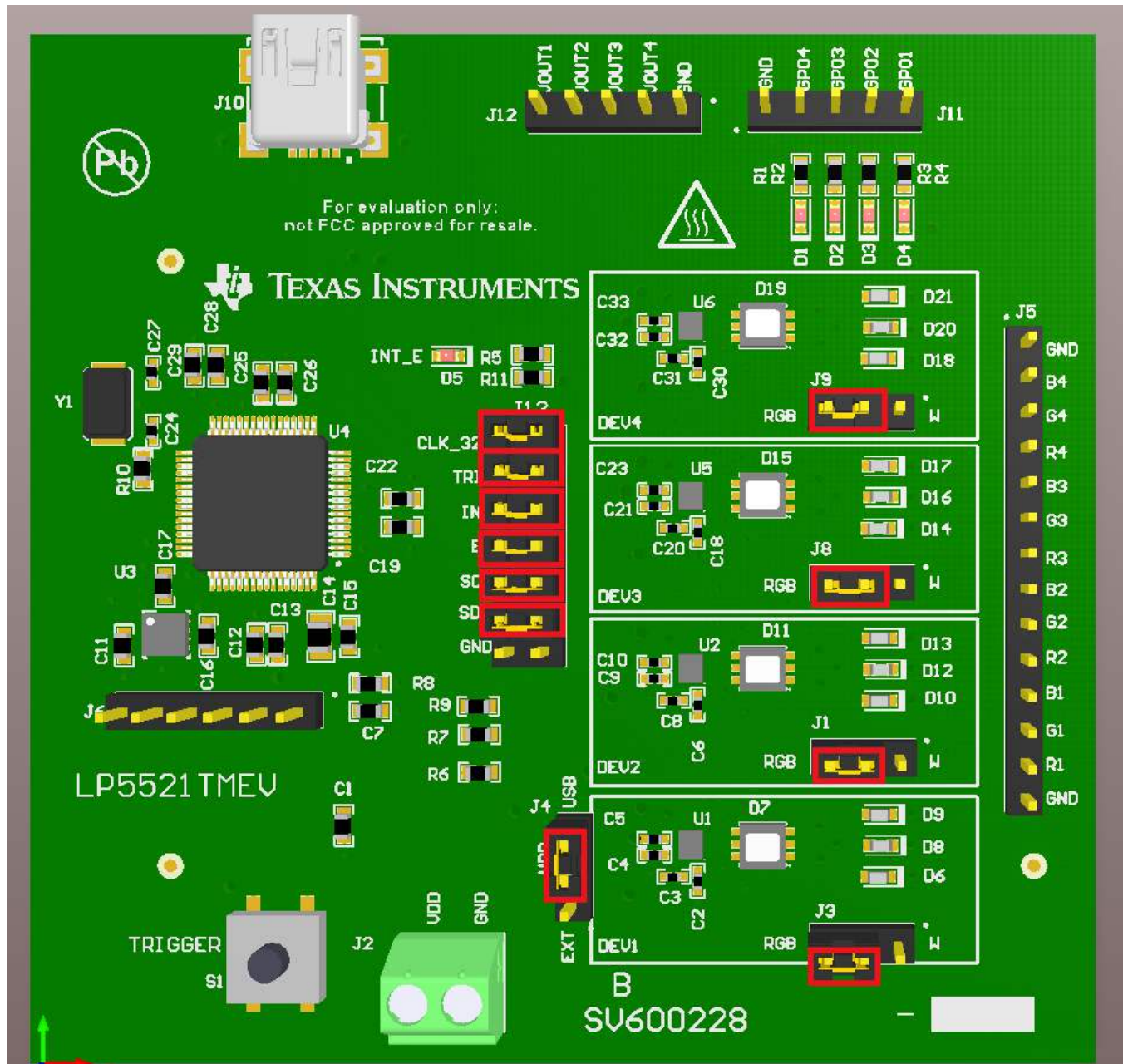


Figure 1. Evaluation Board Connectors and Setup

Figure 2 shows main parts of LP5521 EVM. The board has four LP5521 circuits with the necessary external components placed around them. Test points for the signals are on the board edges. INT and TRIG lines for the four chips are tied together to make it possible to synchronize four LP5521 and make interesting lighting effects. GPO and INT pins have indicator LEDs. Each chip has own I²C address.

Jumper J4 on the evaluation board selects supply voltage V_{DD} from either external power or USB power. If external power supply is used, the VDD and ground GND can be connected to the green power connector J2. Possible supply voltage range is from 2.7 V to 5.5 V. When the USB 5-V powering is used, onboard regulator is used to generate a 3.3-V supply voltage.

There are red indicator LEDs connected to the INT and GPO pins to detect the functionality of the pins. With INT LED time it is possible to determine to which external interrupt is sent. Interrupt can be cleared by reading the Status/INT register (offset 0Ch), or by simply pressing the Read Registers button on the evaluation software when the chip which has sent the interrupt is selected. Note that if INT pin is set to work as a CMOS output (EN_GPO_INT bit high) the functionality of the LED is reversed; that is, when GPO_INT is high then the LED is off and when GPO_INT is low, the LED is on. See Section 9 for reference.

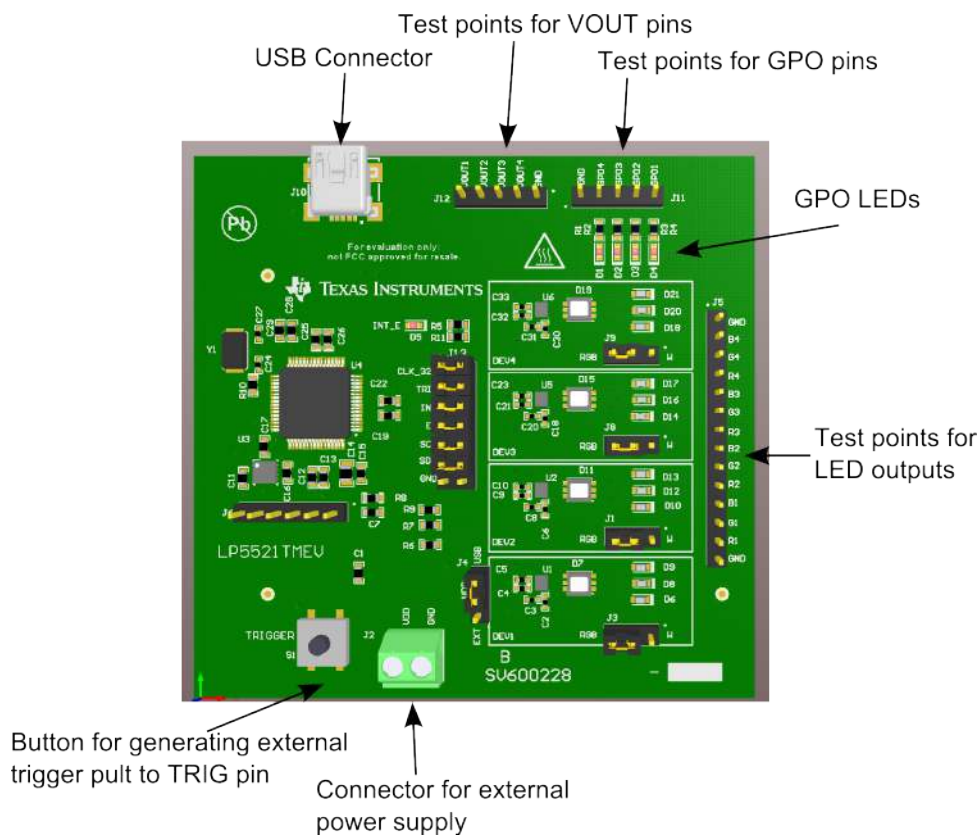


Figure 2. LP5521 Evaluation Board

5 LP5521 Evaluation Software

5.1 General

The LP5521TMEVM is connected to the computer via USB. The EVM is controlled with special evaluation software. The on-board microcontroller is used to provide easy I²C communication, as well as to control the digital inputs of the LP5521 IC. The microcontroller is powered by default from USB. The LP5521 device can be powered from the USB or from external power supply.

5.2 LP5521 Evaluation Software Installation

Before the LP5521 evaluation software can be used it must be installed. Open the folder containing the installation package and double click the “LP5521TMEV-1.0.0-installer.exe”. If Windows® prompts verification of the installation click “Yes”. The license agreement window opens. Read through the license agreement and click “I agree”. Next the installer prompts for components to install. Select additionally “Desktop Shortcut” if needed and click “Next>”. Then the installer prompts for installation directory. TI recommends installing the program to its default location. Click “Install” button to start installation. Evaluation software is now installed. To read release notes and/or start an application make appropriate selections and click “Finish” to exit.

5.3 Evaluation Software Uninstallation

Uninstallation of the LP5521 evaluation software is done through the Windows Control Panel. Open Control Panel → Programs and Features. Find LP5521 EVM from the list, right click it and select Uninstall.

5.4 Graphical User Interface (GUI)

When LP5521 evaluation software is run it looks like [Figure 3](#). Main parts of the GUI are:

- Menu toolbar
- Quick access toolbar
- Device controls
- Quick start/ Device/ Code/ Log Tabs
- Register access related controls
- Status bar

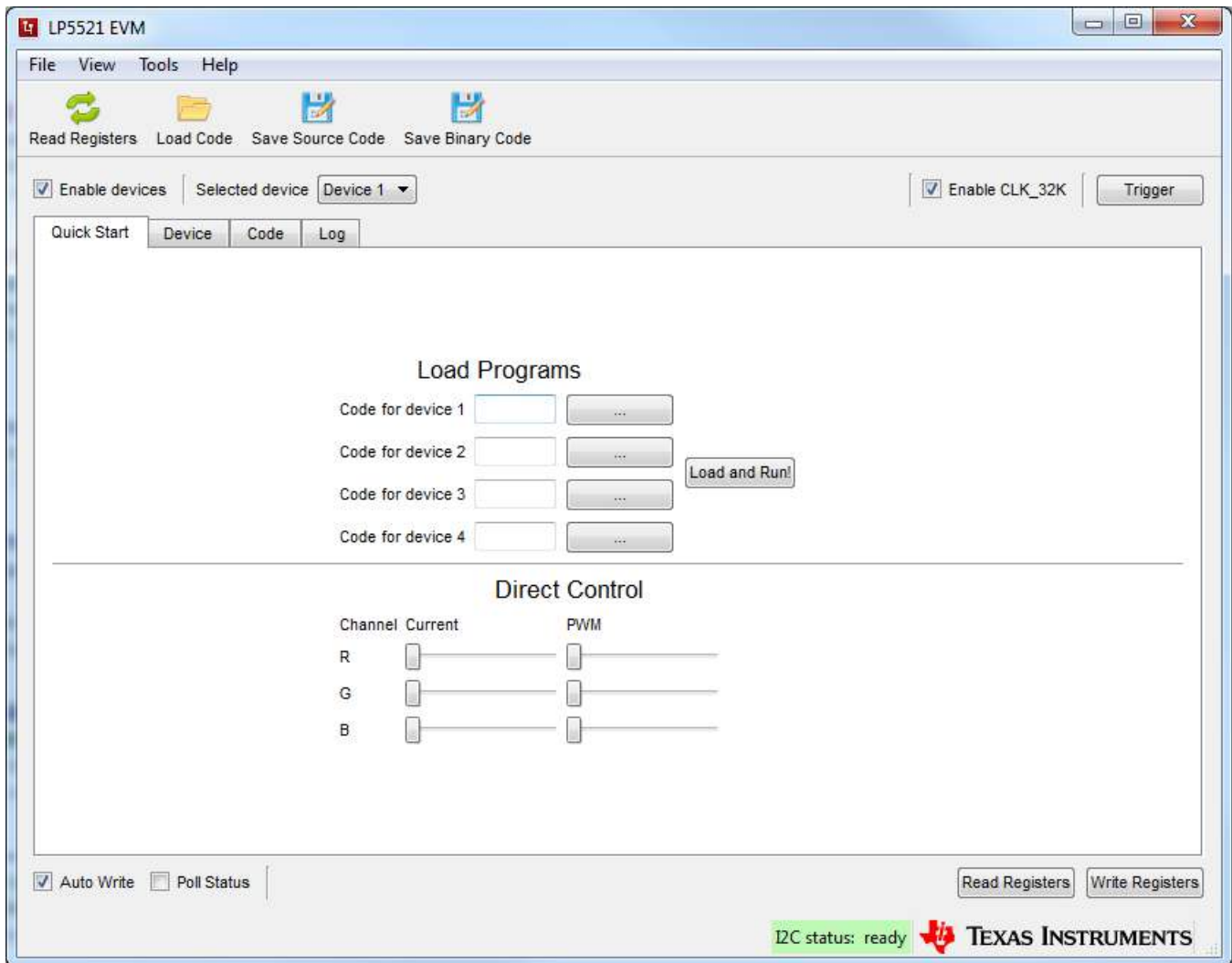


Figure 3. Evaluation Software

5.4.1 Menu Toolbar

Menu toolbar has four sub menus: File, View, Tools and Help.



- File->Load Code: loads source of binary to code editor.
- File->Save Source Code: Saves source code from code editor to a file.
- File->Save Binary File: Saves code from code editor to a file in binary format.
- File->Exit: Exits the application.
- View->Console: Opens console in the right side of the window. See [Section 5.4.8](#) for more information.
- Tools->Direct Register Access: Opens direct register access dialog. See [Section 5.4.7](#)
- Tools->Update Firmware: Can be used to update the firmware of the microcontroller on EVM.

5.4.2 Quick Access Toolbar

Quick Access toolbar contains shortcuts to features placed under File menu.



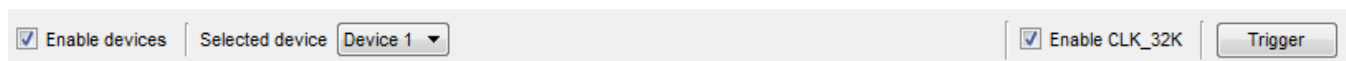
5.4.3 Device Controls

Checkbox “Enable Devices” controls the state of EN signal.

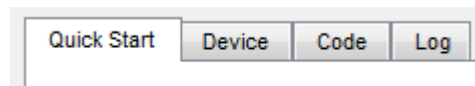
Dropdown menu is used to select to which device I²C commands are sent.

Checkbox “Enable CLK_32K” enables onboard clock signal generator .

Push button “Trigger” send short pulse to TRIGGER input.



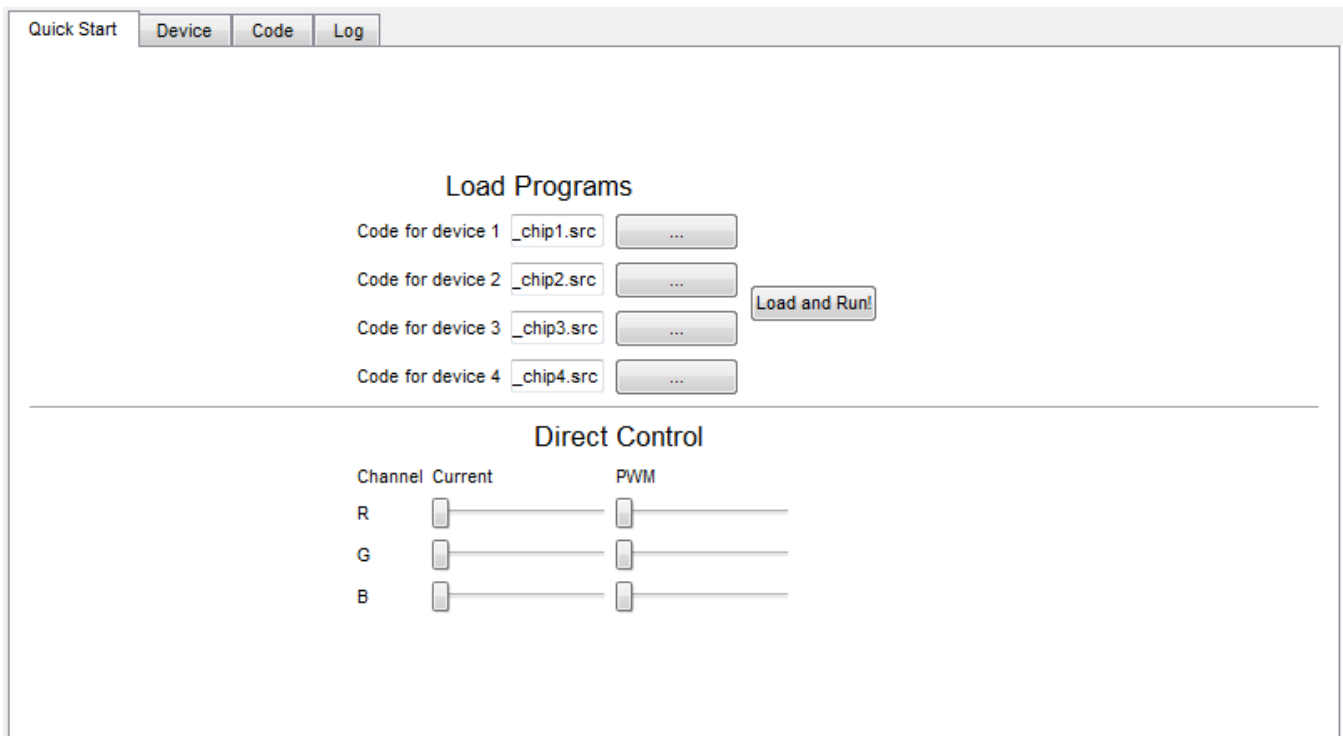
5.4.4 Tabs



There are four separate tabs. See [Section 5.4.4.1](#) to [Section 5.4.4.4](#) for more detailed description.

5.4.4.1 Quick Start Tab

Quick Start tab can be used to quickly load example code files to the program memory or to control directly current and PWM of the LEDS.

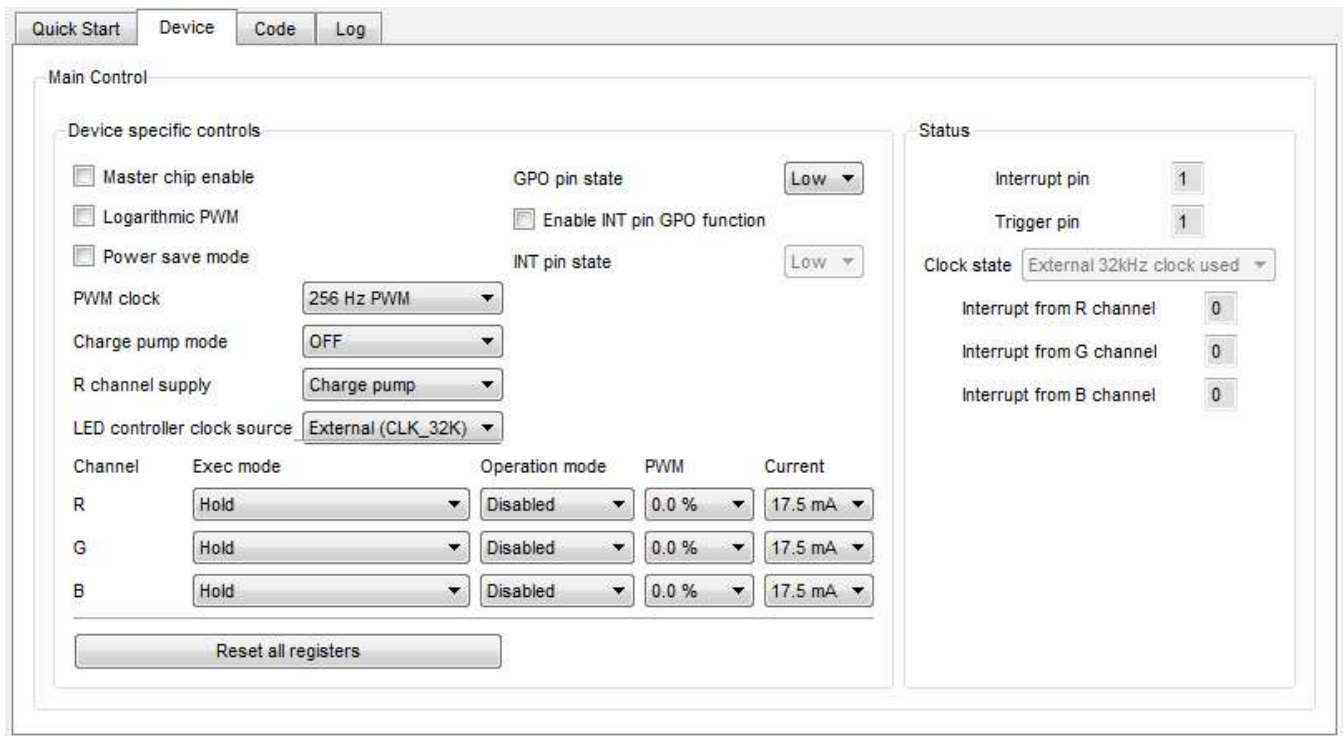


Click “...” button to select code file to be loaded for each device and click “Load and Run!” button. The evaluation software is provided with several example programs. They can be found in “program_examples” directory. Some of the examples wait for TRIGGER signal before they start. TRIGGER signal can be toggled by clicking “Trigger” button or pressing button S1 on EVM.

Alternatively LEDs can be controlled directly by using sliders on the lower part of the tab. Each LED has separate slider for current and PWM value. Device to be controlled is selected by dropdown menu labeled “Selected device”. Notice that LED currents can be adjusted while programs are running, but adjusting PWM stops the execution of the current programs.

5.4.4.2 Device Tab

Device Tab contains most of the register controls. Change to any control is written immediately to the selected device unless “Auto Write” checkbox is unchecked. Refer to LP5521 datasheet for more detailed information.



On the left side there are controls covering most of the device functions.

Master Chip Enable—Enables device internal start-up sequence.

GPO Pin State—Controls the state of the GPO pin.

Logarithmic PWM—Checking this sets INT pin to function as GPO pin.

Enable INT pin GPO function—Selected register is read from the selected device.

INT Pin State—Controls the state of the INT pin. (it must be in GPO mode).

Power-Save Mode—Enabled power-save mode.

PWM Clock—Selects between 256 Hz (source external 32-kHz clock) and 558-Hz clock (source internal oscillator).

Charge Pump Mode—Sets mode of the charge pump to OFF, forced bypass mode, forced 1.5× mode or automatic mode.

R Channel Supply—Selects between charge pump and battery.

LED-Controller Clock Source—Options: external 32-kHz or internal clock or automatic selection.

Exec Mode—Selects the execution mode of each engine. Options: Hold, Step, Run and Step, but not increment PC.

Operation Mode—Selects the operation mode of each engine. Options: Disabled, Load program, Run program and Direct control.

PWM— Sets the PWM value for each output.

Current— Sets the LED current for each output.

On the right side are status indicators for interrupt and trigger pin and various status bits.

INTERRUPT Pin—Shows the state of the INTERRUPT pin.

TRIGGER Pin—Shows the state of the TRIGGER pin.

Clock State—Shows currently selected clock source.

Interrupt from X Channel—Shows which channel(s) triggered interrupt.

NT Pin State—Controls the state of the INT pin. (it must be in GPO mode).

Power-Save Mode—Enabled power-save mode.

Current— Sets the LED current for each output.

5.4.4.3 Code Tab

The Code tab is divided to source code editor (left side) and binary view (right side). Code file (source or binary) can be loaded by clicking “Load Code” button in Quick Access toolbar or in the File menu. File format is automatically detected. “Assemble>>” button is used for compiling code in the source code editor. Results are shown in binary view. It is possible to disassemble contents of binary view by clicking “<<Disassemble” button. Source or binary code can be saved to a file by clicking corresponding button in Quick Access toolbar.

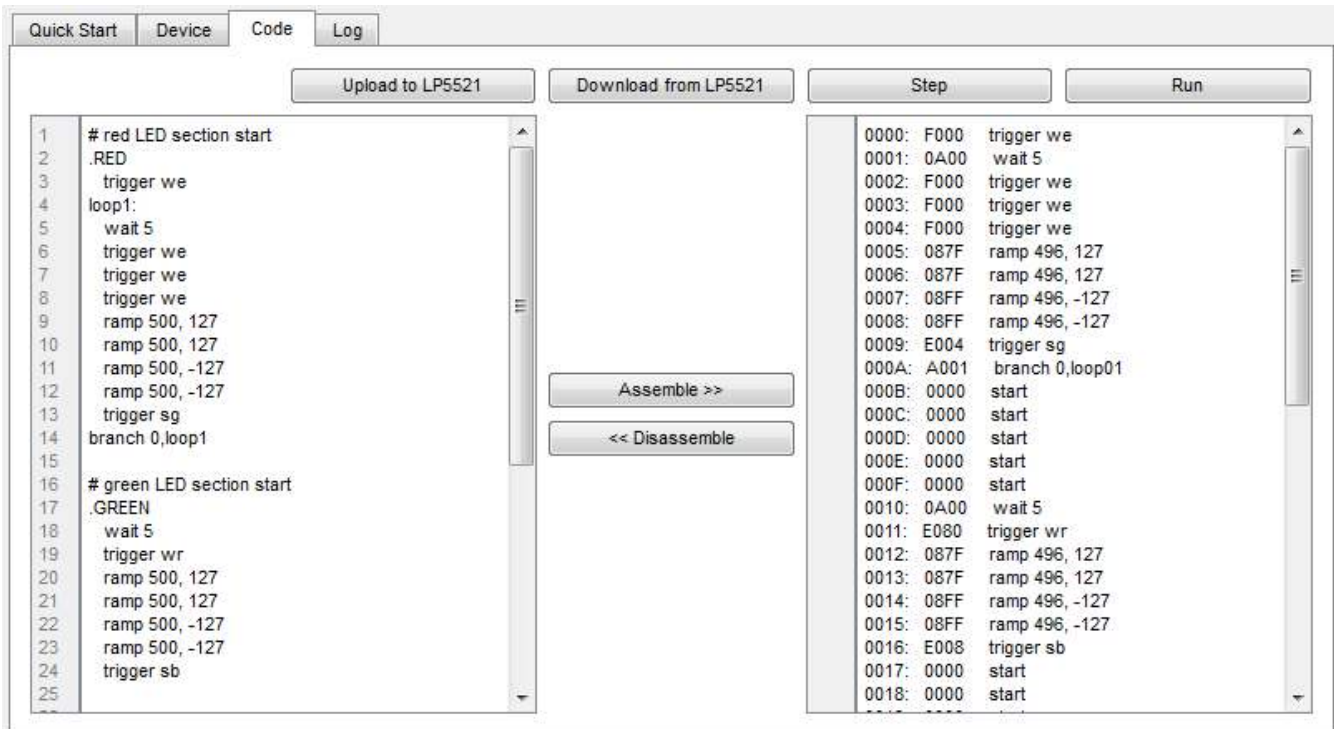
“Upload to LP5521” button sends compiled program code to selected device.

“Download from LP5521” button reads program code from selected device and show results in binary view.

“Step” button executes loaded code one instruction at time. When code is stepped, instruction pointers of each engine are shown in the left side of the binary view.

“Run” button starts the execution of loaded code. When code is running, it can be stopped by clicking “Stop” button.

For more information about LP5521 assembly language, see [Section 8.1](#).



The screenshot shows the Code Tab interface with the following components:

- Navigation Tabs:** Quick Start, Device, Code (selected), Log.
- Buttons:** Upload to LP5521, Download from LP5521, Step, Run, Assemble >>, << Disassemble.
- Source Code Editor (Left):**

```

1 # red LED section start
2 .RED
3 trigger we
4 loop1:
5 wait 5
6 trigger we
7 trigger we
8 trigger we
9 ramp 500, 127
10 ramp 500, 127
11 ramp 500, -127
12 ramp 500, -127
13 trigger sg
14 branch 0,loop1
15
16 # green LED section start
17 .GREEN
18 wait 5
19 trigger wr
20 ramp 500, 127
21 ramp 500, 127
22 ramp 500, -127
23 ramp 500, -127
24 trigger sb
25

```
- Binary View (Right):**

```

0000: F000 trigger we
0001: 0A00 wait 5
0002: F000 trigger we
0003: F000 trigger we
0004: F000 trigger we
0005: 087F ramp 496, 127
0006: 087F ramp 496, 127
0007: 08FF ramp 496, -127
0008: 08FF ramp 496, -127
0009: E004 trigger sg
000A: A001 branch 0,loop01
000B: 0000 start
000C: 0000 start
000D: 0000 start
000E: 0000 start
000F: 0000 start
0010: 0A00 wait 5
0011: E080 trigger wr
0012: 087F ramp 496, 127
0013: 087F ramp 496, 127
0014: 08FF ramp 496, -127
0015: 08FF ramp 496, -127
0016: E008 trigger sb
0017: 0000 start
0018: 0000 start

```


5.4.4.4 Log Tab

The Log tab shows the commands that have been sent to the LP5521. Log can be cleared by clicking the clear Log button.



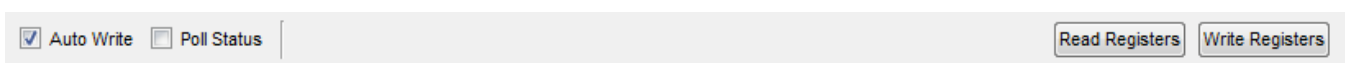
5.4.5 Register Access Related Controls

“Auto Write” checkbox controls if changes are written immediately to the device or not.

“Poll Status” checkbox controls if status registers are polled repeatedly.

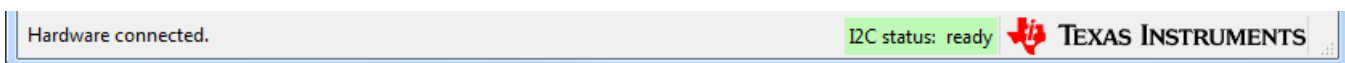
“Read Registers” push button reads all registers of the device.

“Write Registers” push button writes values from the GUI to the device. This is useful only if “Auto Write” checkbox is unchecked.



5.4.6 Status Bar

Status bar shows the connection status of the EVM and the status of the last I²C operation.



5.4.7 Direct Register Access Dialog

Register map can be opened from Tools menu -> Direct Register Access. This gives an easy way to show content of all the registers. Direct register access can also be used to change the content of any of the registers. Register contents of the selected device are read when Direct Register Access Dialog is opened.

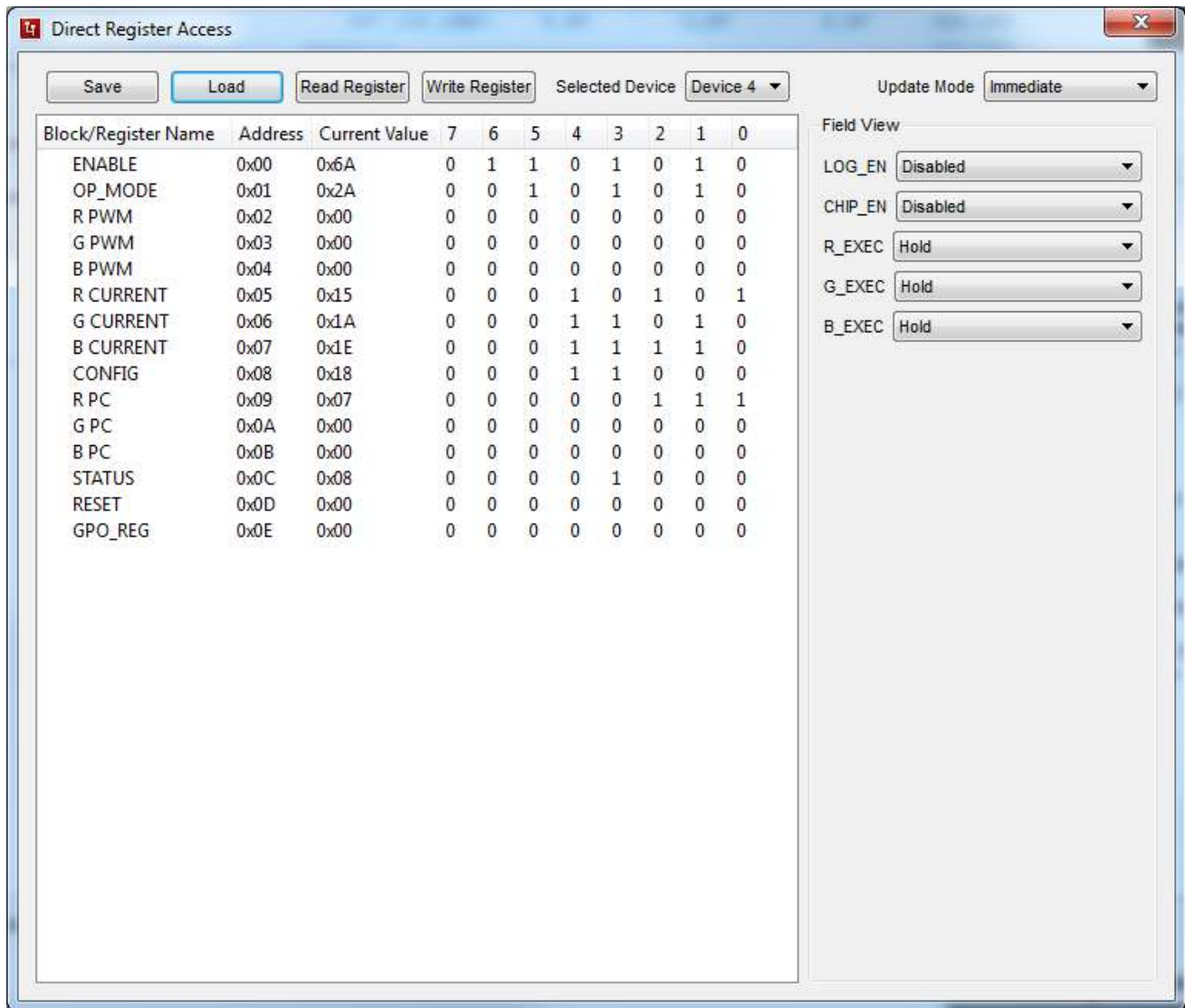


Figure 4. Direct Register Access Dialog

In the top part of the dialog there are the following controls:

Save— All registers are saved to a file.

Load— Register contents are restored from a file.

Read Register— Selected register is read from the selected device.

Write Register— Selected register is read from the selected device.

Selected Register— Selects the device to be controlled.

Update Mode— Immediate = changes are written to the selected device immediately.
Manual = “Write Register” button has to be used to write change to the device.

5.4.8 Console

The console window can be used to read and write any of the registers. A register can be read by giving register address, for example 0x00. Register value can be changed by giving register address followed by data, for example 0x00 = 0x05.

Console can also be used to run predefined script files. Script file needs to be located in the same folder as the LP5521 evaluation software. Script files are described with more details in the Script files chapter

Console can be enabled by clicking View → Console

```

> STATUS
STATUS = 0x08 ( 0000 1000 )
> CONFIG
CONFIG = 0x18 ( 0001 1000 )
> 0x00
0x00 = 0x6A ( 0110 1010 )
> 0x00 = 0x6a
>
  
```

6 Examples

This section describes how to do some basic operations with LP5521EV software.

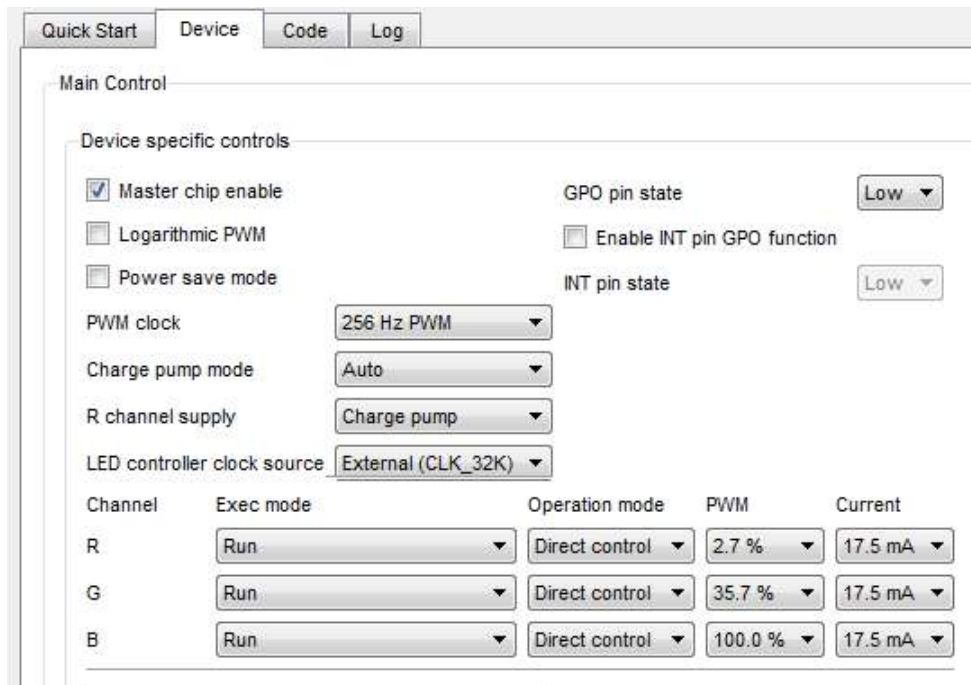
6.1 Starting up the LP5521

To start up the LP5521 and to be able to communicate with the device follow these steps:

- Connect and set up the EVM hardware as described in chapter LP5521TMEV Hardware and turn on the power supply if external supply is used.
- Set EN pin high by checking “Enable devices”. LP5521 is now in normal mode and all the registers can be read and written.
- Use “Selected Device” dropdown menu to select right device.

6.2 Set R, G, and B LEDs ON

- Start up the device as described in chapter [Section 6.1](#).
- In Device tab, check checkbox “Master chip enable”.
- Set operation mode for each channel to “Direct control”.
- Set charge pump mode to “auto”.
- Increase PWM values of each LED.



7 Using Scripts

Script file is a text file that contains number of different register write/read operations. Script files also support simple looping, wait command and can take parameters as inputs. Script file can be used to set up LP5521. They can also be used to generate brightness ramps etc.

Script file can be run by typing the name of the script file to the console window. To be able to run the script file it needs to be stored into the LP5521 evaluation software installation folder. If LP5521 evaluation software was installed to default location it can be found in "C:\Program Files\Texas Instruments\LP5521 EVM".

7.1 Register Access

Registers can be accessed by register name or by direct address. It is also possible to limit access to specific bit field to keep other bits in same register address unaltered.

7.1.1 Example: Read contents of ENABLE register in address 0h.

By direct address:

```
> 0x0
0x0 = 0x6A ( 0110 1010 )
```

By register name:

```
> ENABLE
ENABLE = 0x6A ( 0110 1010 )
```

7.1.2 Example: Write value AAh to R_PWM register in address 02h.

By direct address:

```
> 0x02=0xaa
```

By register name:

```
> R_PWM = 0xaa
```

7.1.3 Example: Read bit field R_EXEC (bits [5:4]) from ENABLE register in address 0h.

By direct address:

```
> 0x0[5:4]
0x0[5:4] = 0x02 ( 0000 0010 )
```

By bit name:

```
> R_EXEC
R_EXEC = 0x02 ( 0000 0010 )
```

7.1.4 Example: Write 02h to bit field R_EXEC (bits [5:4]) in ENABLE register, address 0h.

By direct address:

```
> 0x0[5:4] = 0x02
```

By bit name:

```
> R_EXEC
R_EXEC = 0x02 ( 0000 0010 )
```

When writing to registers or bit fields, values can be given in several formats. The following example shows commands which do effectively same thing.

```
> 0x02=0xaa
> 0x02=aaH
> 0x02=170
> 0x02=10101010b
```

7.2 Parameters

It is possible to execute a script with parameters. Scripts can also call other scripts and give them parameters.

7.2.1 Example: Call “example2.txt” script with three parameters.

```
> example2.txt 10 0x100 0xaa
> |
```

Example: Call “example2.txt” script with three parameters:

```
// variables example
// execute this script by giving it
parameter:
// example2.txt <time> <addr in hex>
<data>

// input parameters
// $0 wait time
// $1 address
// $2 data to write

wait($0)

$1 = $2
```

It is possible to call script with up to 7 parameters.

7.3 Loops

It is possible to create simple for-loops in script files. Example below shows how to use for-loops.

```
// for-loop example

// incrementing variable

for i=0:10:100
    wait($i)
end

// decrementing
for i=100:-10:0
    wait($i)
end

// nested loop

for i=0:1:5
    for j=0:10:100
        wait($j)
    end
end
```

7.4 Command Reference

| | |
|--------|--------------------|
| wait() | Programmable delay |
|--------|--------------------|

wait(N)

Creates N milliseconds long delay. N can be between 1 and 10000.

example: wait(1000)

8 Command Compiler

Command compiler is used to write LED sequences for the LP5521. It is simple to use tool integrated to GUI application. User can write own memory files by using source editor in Code tab. Compiling can be done by clicking “Assemble>>” button.

8.1 Instruction Reference

8.1.1 ramp

Ramp command generates a PWM ramp from current value. Ramp command has two parameters – first is time in milliseconds (maximum time = 1000 ms x number of steps) and second is number of steps (positive or negative integer, 2-128) separated by comma.

Example: ramp 100,50

8.1.2 wait

With wait command, program execution stops for time defined. Command has one parameter, time in milliseconds. (1-999)

Example: wait 500

8.1.3 branch

Branch command can be used to loop certain sequences in program. Command loads step number to program counter. It has two parameters, loop count (0-63, 0 means infinite loop) and label separated with comma, Label must be defined before using in a branch command. The following example loops 5 times between label1 and branch command.

Example: label1: ...

...

...

branch 5, label1

8.1.4 set_pwm

set_pwm command sets PWM output value. Command has one parameter, PWM value (0-255).

Example: set_pwm 23

8.1.5 start

start command resets program counter and continues executing from the beginning of the section.

Example: start

8.1.6 trigger

trigger command waits or sends trigger. Command has two parameters, wait channel and send channel. Channels are defined as: r = red, g = green, b = blue and e = external.

Examples: trigger sr => Send trigger to red channel

trigger sg => Send trigger to green channel

trigger sb => Send trigger to blue channel

trigger se => Send trigger to external channel

trigger sgb => Send trigger to green and blue channel

trigger wr => Wait for trigger from red channel

trigger sr,wb => Send trigger to red channel and wait for trigger from blue channel.

8.1.7 end

end command ends program execution. Optionally interrupt signal can be sent or program counter can be reset. Command can have up to two parameters. I = send interrupt to INT pin, R = reset program counter.

Examples:

```
end I
end R
end R,I
end I,R
end
```

8.1.8 Comment

Comment lines must start with “#” or “/” character.

Example: # red LED section start

8.1.9 Sections

Red, green and blue LED engine sections start with .RED, .GREEN or .BLUE.

Example: .RED

8.1.10 Labels

Any words with colon (:) as last character.

Example: label1:

8.2 Example Code

```
# red LED section
start
.RED
ramp 20.5,6
ramp 10,-15
wait 10
# green LED section
start
.GREEN
ramp 10,-15
start
# blue LED section
start
.BLUE
ramp 10,15
end R
```


9 Evaluation Board Schematics

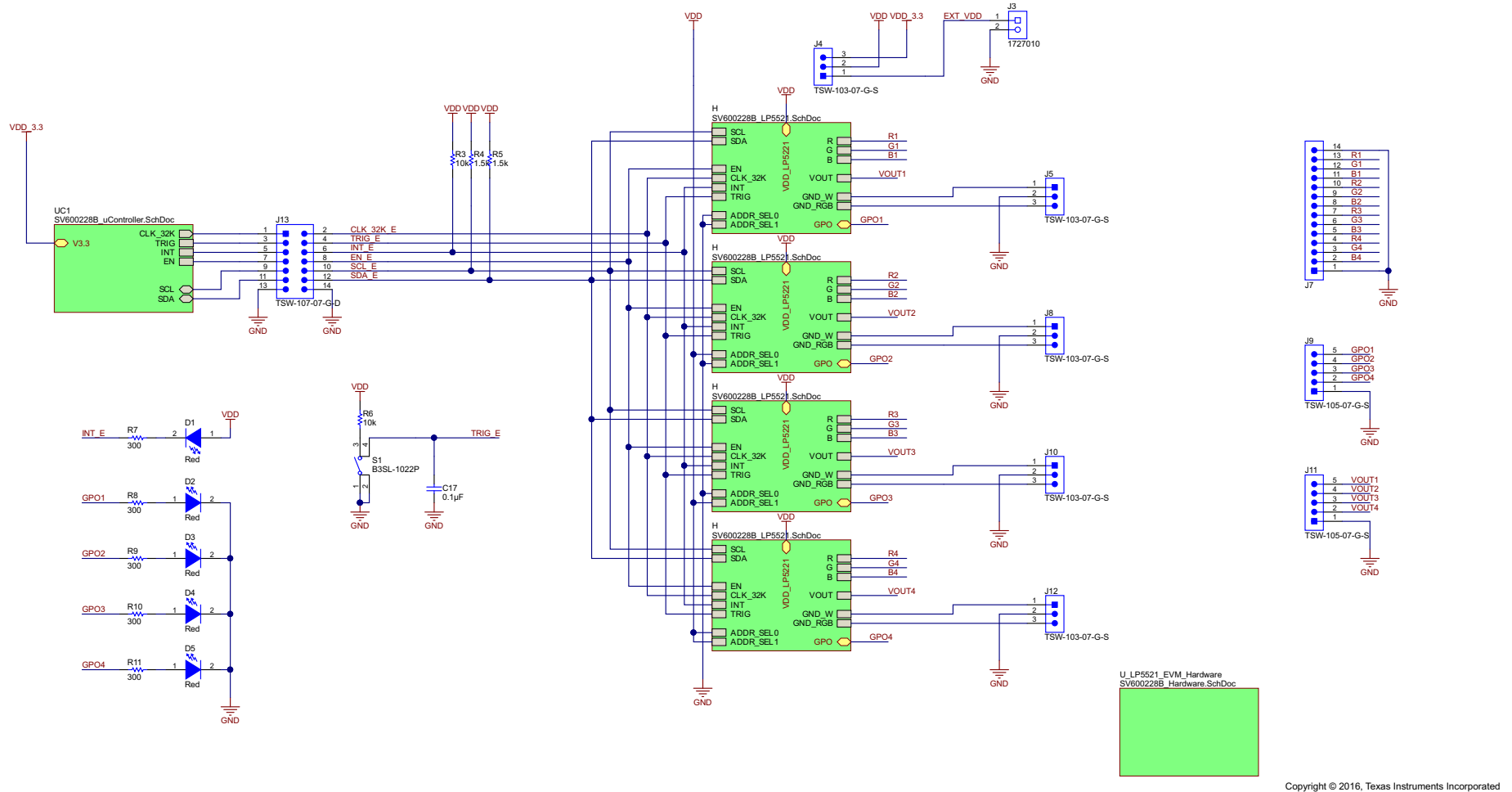


Figure 5. Top Level

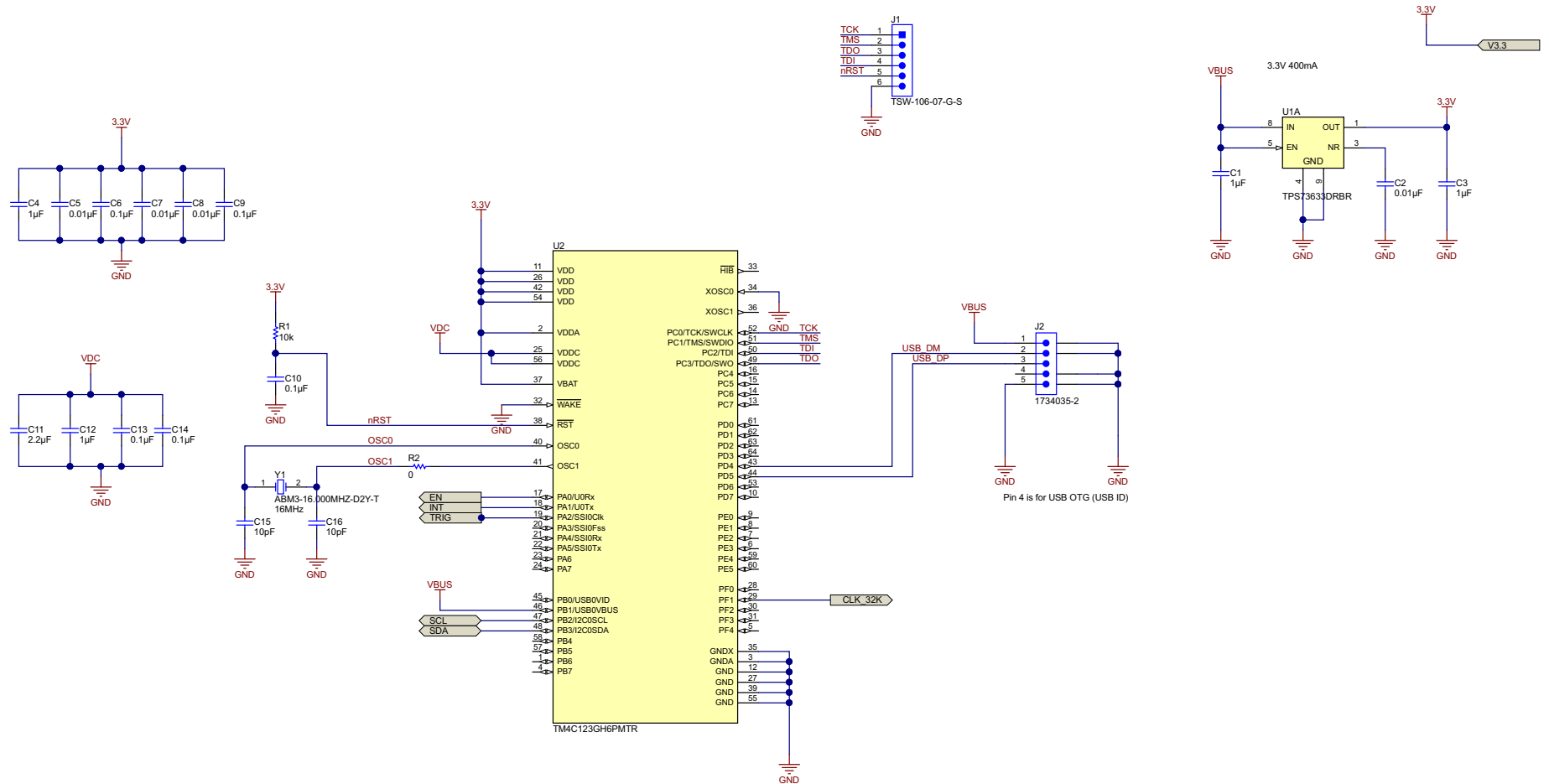
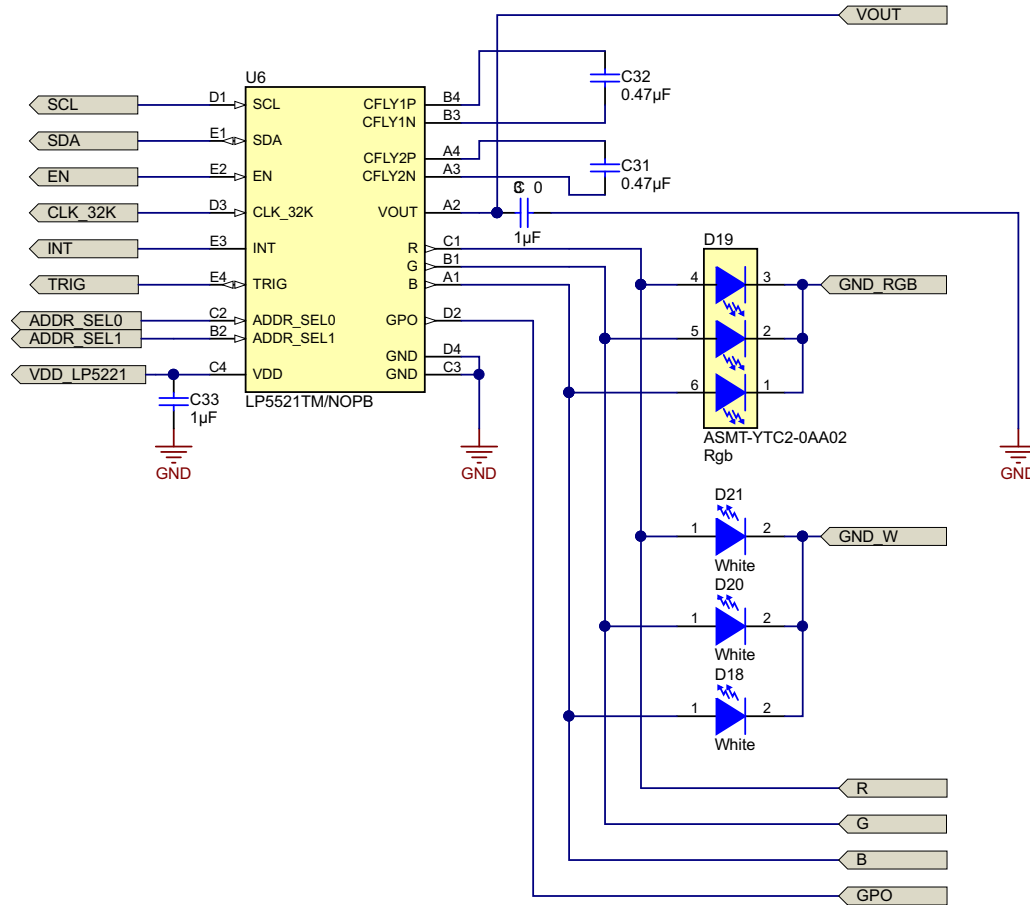


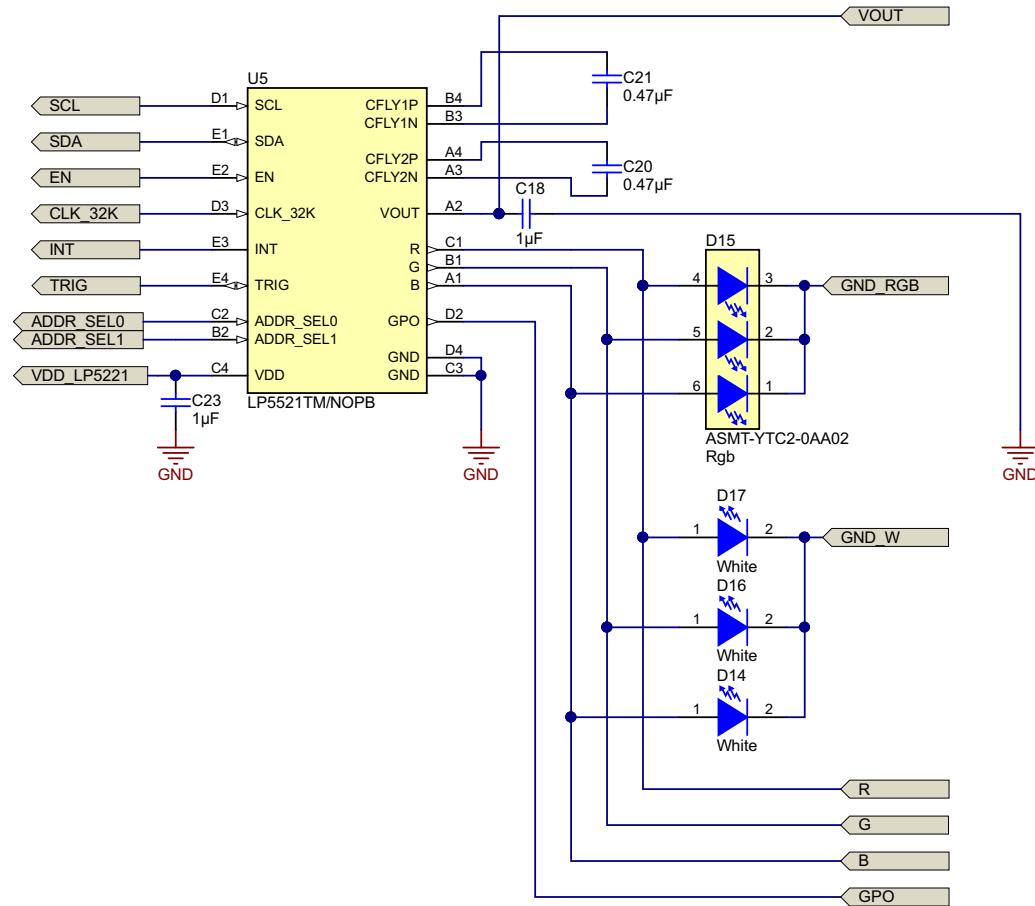
Figure 6. Microcontroller

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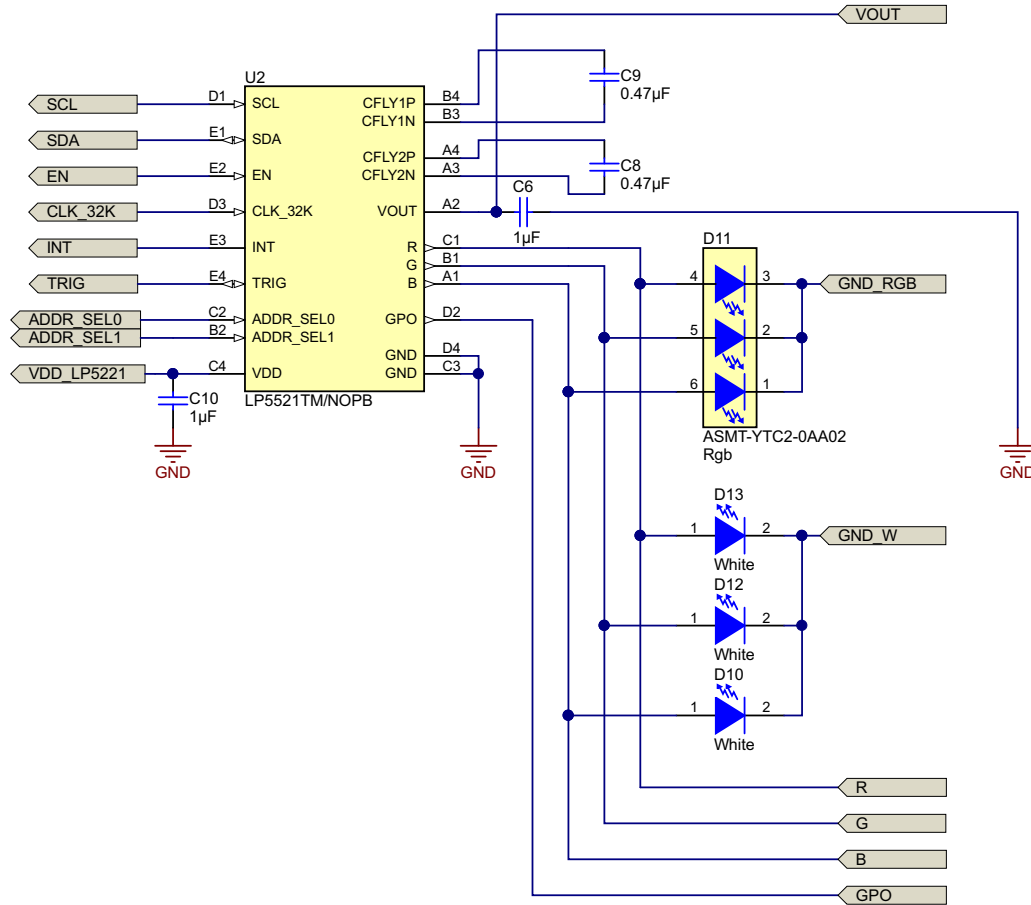
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Figure 7. LP5521 (Device 1)



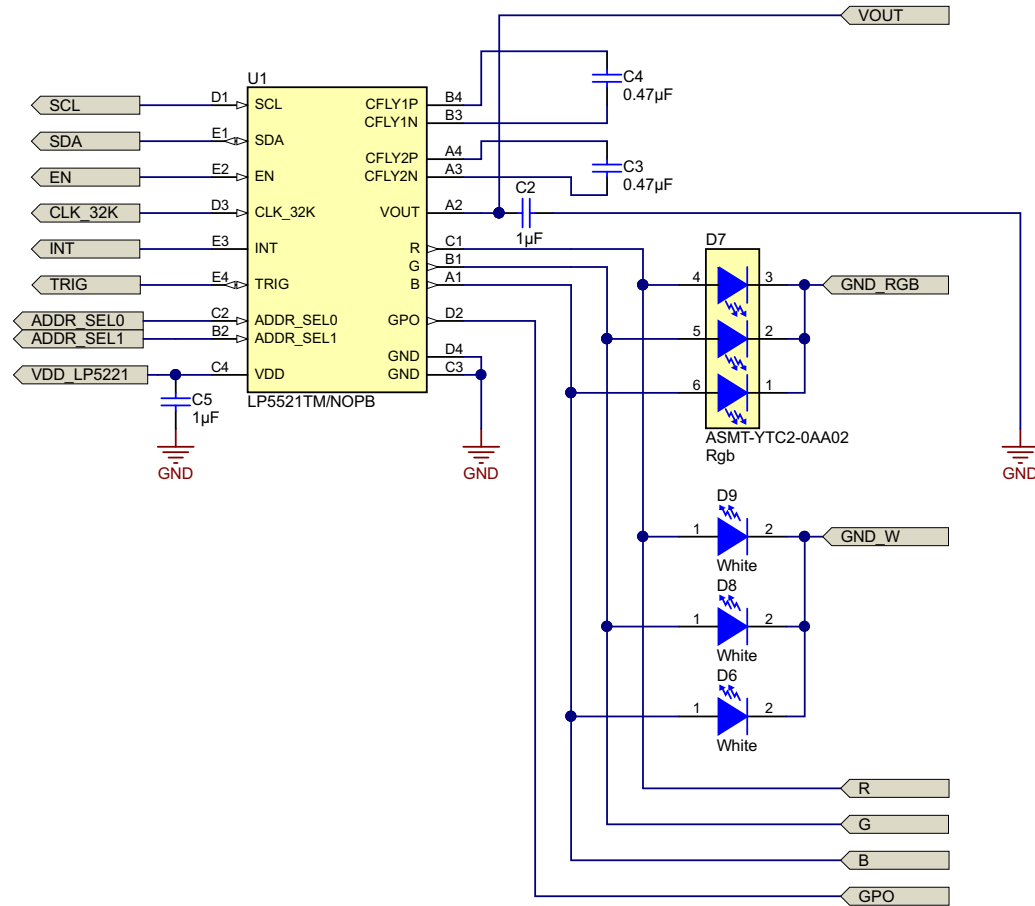
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Figure 8. LP5521 (Device 2)



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Figure 9. LP5521 (Device 3)



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Figure 10. LP5521 (Device 4)

10 PCB Layout

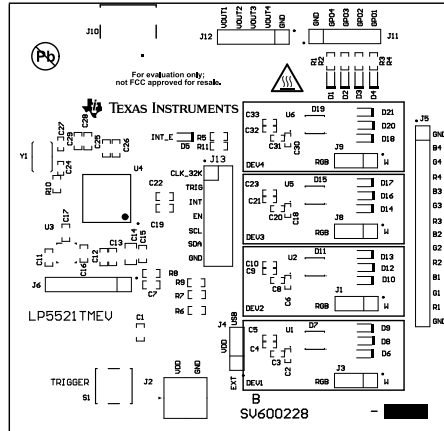


Figure 11. Top Overlay

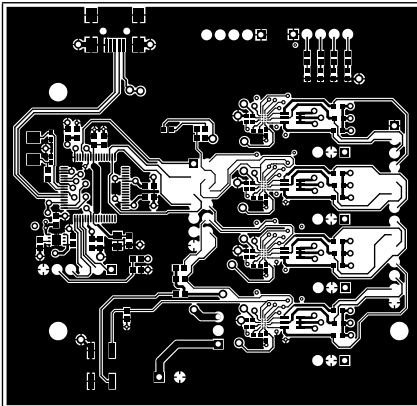


Figure 12. Layer 1 (Top, Signal)

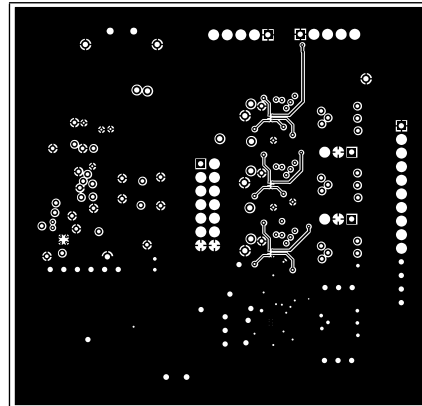


Figure 13. Layer 2 (GND)

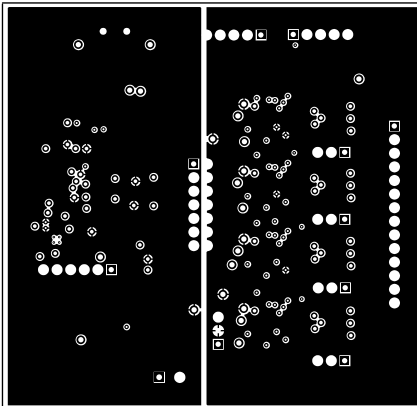


Figure 14. Layer 4 (Power)

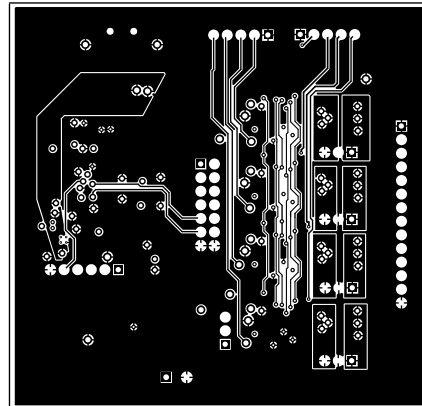


Figure 15. Layer 4 (Bottom, Signal)

11 Bill of Materials

The following is the bill of materials for the LP5521TMEV:

| DESIGNATOR | QUANTITY | VALUE | PART NUMBER |
|---|----------|--------|----------------------|
| C1, C7, C15, C22, C25, C29 | 6 | 0.1uF | GRM188R71C104KA01D |
| C2, C5, C6, C10, C18, C23, C30, C33 | 8 | 1uF | C1005X5R1A105K050BB |
| C3, C4, C8, C9, C20, C21, C31, C32 | 8 | 0.47uF | C1005X5R1A474K050BB |
| C11, C13, C19, C28 | 4 | 0.01uF | C0603H103J3GACTU |
| C12, C16, C17, C26 | 4 | 1uF | GRM188R61A105KA61D |
| C14 | 1 | 2.2uF | EMK212B7225KG-T |
| C24, C27 | 2 | 10pF | GRM1555C1H100FA01D |
| D1, D2, D3, D4, D5 | 5 | Red | HSMC-C190 |
| D6, D8, D9, D10, D12, D13, D14, D16, D17, D18, D20, D21 | 12 | White | SML312WBCW1 |
| D7, D11, D15, D19 | 4 | Rgb | ASMT-YTC2-0AA02 |
| R1, R2, R3, R4, R5 | 5 | 300 | RC0603JR-07300RL |
| R6, R11 | 2 | 10k | RC0603JR-0710KL |
| R7, R9 | 2 | 1.5k | RC0603JR-071K5L |
| R8 | 1 | 10k | CRCW060310K0JNEA |
| R10 | 1 | 0 | CRCW06030000Z0EA |
| S1 | 1 | | B3SL-1022P |
| U1, U2, U5, U6 | 4 | | LP5521TM/NOPB |
| U3 | 1 | | TPS73633DRBR |
| U4 | 1 | | TM4C123GH6PMTR |
| Y1 | 1 | | ABM3-16.000MHZ-D2Y-T |

Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

| DATE | REVISION | NOTES |
|----------------|-----------------|----------------------------------|
| September 2016 | E | Complete re-write of user guide. |

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- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

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3.2.1 For EVMs issued with an Industry Canada Certificate of Conformance to RSS-210

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Concernant les EVMs avec appareils radio:

Le présent appareil est conforme aux CNR d'Industrie Canada applicables aux appareils radio exempts de licence. L'exploitation est autorisée aux deux conditions suivantes: (1) l'appareil ne doit pas produire de brouillage, et (2) l'utilisateur de l'appareil doit accepter tout brouillage radioélectrique subi, même si le brouillage est susceptible d'en compromettre le fonctionnement.

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Under Industry Canada regulations, this radio transmitter may only operate using an antenna of a type and maximum (or lesser) gain approved for the transmitter by Industry Canada. To reduce potential radio interference to other users, the antenna type and its gain should be so chosen that the equivalent isotropically radiated power (e.i.r.p.) is not more than that necessary for successful communication. This radio transmitter has been approved by Industry Canada to operate with the antenna types listed in the user guide with the maximum permissible gain and required antenna impedance for each antenna type indicated. Antenna types not included in this list, having a gain greater than the maximum gain indicated for that type, are strictly prohibited for use with this device.

Concernant les EVMs avec antennes détachables

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http://www.tij.co.jp/llds/ti_ja/general/eStore/notice_01.page

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2. Use EVMs only after User obtains the license of Test Radio Station as provided in Radio Law of Japan with respect to EVMs, or
3. Use of EVMs only after User obtains the Technical Regulations Conformity Certification as provided in Radio Law of Japan with respect to EVMs. Also, do not transfer EVMs, unless User gives the same notice above to the transferee. Please note that if User does not follow the instructions above, User will be subject to penalties of Radio Law of Japan.

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