

Optical Proximity Sensor ICs

1chip Optical Proximity + Ambient Light Sensor IC



BH1772GLC No.12100EFT12

Descriptions

BH1772GLC is the IC into which optical proximity sensor and digital ambient light senor are unified. Proximity sensor part detects the human or object approach by reflection of infrared LED(IrLED) light. Ambient light sensor part can detect the wide range illuminance from the dark up to under direct sun light. The illuminant intensity of LCD display and keypad can be adjusted, so lower current consumption or higher visibility are possible.

Features

- 1) Correspond to I²C bus interface (f/s mode support)
- 2) Low Current by power down function
- 3) Correspond to 1.8V logic interface
- 4) ALS spectral responsibility is approximately human eye response (Peak wavelength : typ. 550nm)
- 5) Correspond to wide range of light intensity (1-65535 lx range)
- 6) Rejecting 50Hz/60Hz light noise (ALS function)
- 7) Built in ambient light cancelation (Proximity sensor function)
- 8) Built in configurable IrLED current driver

Applications

Mobile phone, DSC, Portable game, Camcoder, PDA, LCD display etc.

● Absolute Maximum Ratings (Ta = 25°C)

Parameter	Symbol	Ratings	Units
VCC, Supply Voltage	Vccmax	4.5	٧
SDA,SCL,GNDNC Terminal Voltage	VSDAmax, VSCLmax, VGNDNCmax	4.5	V
LEDC,INT Terminal Voltage	VLEDCmax, VINTmax	7	V
Operating Temperature	Topr	-40~85	°C
Storage Temperature	Tstg	-40~100	°C
SDA, INT Sink Current	Imax	7	mA
Power Dissipation	Pd	250*	mW

Operating Conditions

perating contained						
Parameter	Symbol		Units			
Farameter	Symbol	Min.	Тур.	Max.	Uillis	
VCC Voltage	Vcc	2.3	2.5	3.6	V	
LEDC Terminal Voltage	Vledc	0.7	2.5	5.5	V	

●Electrical characteristics (Vcc = 2.5V, Ta = 25°C, unless otherwise noted.)

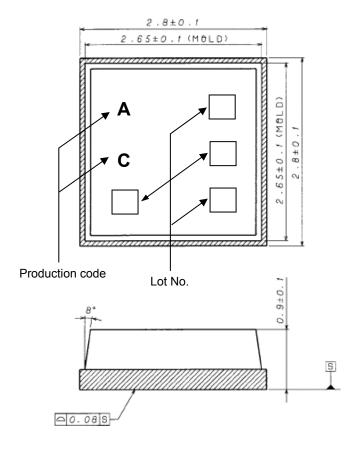
Deremeter		,	Limits		Units	Conditions
Parameter	Symbol	Min.	Тур.	Max.	Units	
Supply current for ALS	lcc1	-	90	180	μA	Ev = 100 lx **1 Average current when ALS_CONTROL register(40h) = " 03h " and the other registers are default.
Supply current for PS	lcc2	_	90	180	μA	Average current when PS_CONTROL register(41h) = " 03h " and the other registers are default.
Supply current for PS during driving LED current	Icc3	_	6.5	8.5	mA	
Standby mode current	Icc4	_	0.8	1.5	μA	ALS & PS standby No Input Light
ALS measurement time	tMALS	_	100	125	ms	H-Resolution mode
ALS measurement accuracy	S/A	0.85	1.0	1.15	Times	Sensor out / Actual Ix, Ev = 1000 Ix **1
ALS dark (0 lx) sensor out	ALS0	0	0	2	count	H-Resolution mode
PS sensor out (No proximity object)	PS0	0	0	30	count	Ambient irradiance = 0µW/cm ²
PS sensor out (Irradiance by proximity object = 324uW/cm²)	PS324u	120	128	136	count	Ambient irradiance = 0μW/cm ²
ILED pulse duration	twlLED	_	200	250	μs	
PS measurement time	tMPS	_	10	12.5	ms	
LEDC terminal sink current at LEDC terminal voltage = 1.3V	ILEDC	18	20	22	mA	ILED register(42h) [2:0] = " 010 "
INT output 'L' Voltage	VINT	0	_	0.4	V	IINT = 3mA
SCL SDA input 'H' Voltage	VIH	1.26	_	_	V	
SCL SDA input 'L' Voltage	VIL	_	_	0.54	V	
SCL SDA input 'H'/'L' Current	IIHL	-10	_	10	μA	
I ² C SDA output 'L' Voltage	VOL	0	_	0.4	V	IOL = 3mA

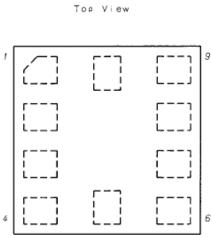
^{%1} White LED is used as optical source

●I²C bus timing characteristics (Vcc = 2.5V, Ta = 25°C, unless otherwise noted.)

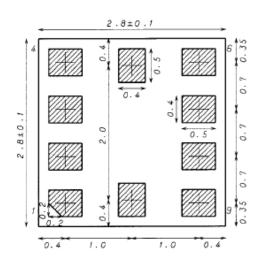
Parameter	Symb	,	Limits		Units	Conditions
Farameter	ol	Min.	Тур.	Max.	Ullits	Conditions
I ² C SCL Clock Frequency	f _{SCL}	0	_	400	kHz	
I ² C Hold Time (Repeated) START Condition	t _{HD;STA}	0.6	_	_	μs	
I ² C 'L' Period of the SCL Clock	t _{LOW}	1.3	_	_	μs	
I ² C 'H' Period of the SCL Clock	t _{HIGH}	0.6	_	_	μs	
I ² C Set up time for a Repeated START Condition	t _{SU;STA}	0.6	_	_	μs	
I ² C Data Hold Time	t _{HD;DAT}	0	_	_	μs	
I ² C Data Setup Time	t _{SU;DAT}	100	_	_	ns	
I ² C Set up Time for STOP Condition	t _{SU;STO}	0.6	_	_	μs	
I ² C Bus Free Time between a STOP and START Condition	t _{BUF}	1.3	_	_	μs	
I ² C Data Valid Time	t _{VD;DAT}	_	_	0.9	μs	
I ² C Data Valid Acknowledge Time	t _{VD;ACK}	_	_	0.9	μs	

Package outlines





Bottom View



WLGA010V28

(UNIT:mm)

Drawing No. EX812-6001

● Reference Data

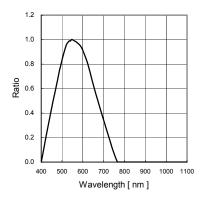


Fig.1 ALS Spectral Response

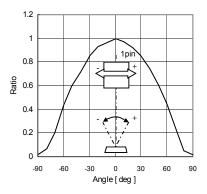


Fig.4 ALS Directional Characteristics 1

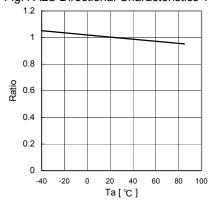


Fig.7 ALS Measurement Accuracy Temperature Dependency

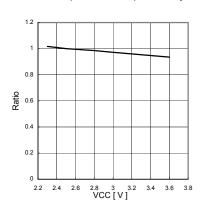


Fig.10 ALS Measurement Result VCC Dependency

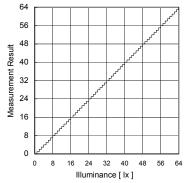


Fig.2 Illuminance - ALS Measurement Result

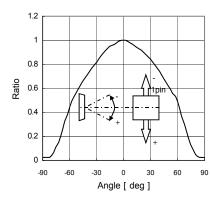


Fig.5 ALS Directional Characteristics 2

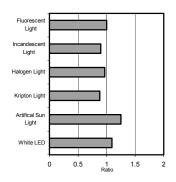


Fig.8 ALS Light Source Dependency (Fluorescent Light is set to '1')

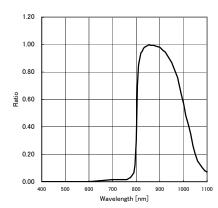


Fig.11 PS Spectral Response

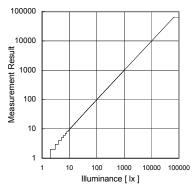


Fig.3 Illuminance - ALS Measurement Result 2

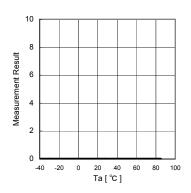


Fig.6 ALS Dark Response

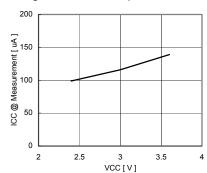


Fig.9 VCC - ICC (During ALS measurement)

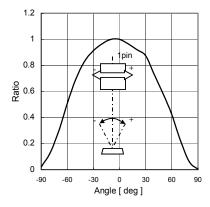
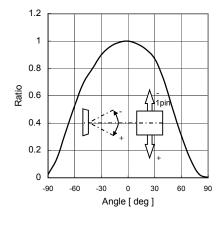
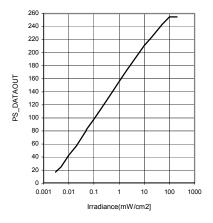


Fig.12 PS Directional Characteristics 1





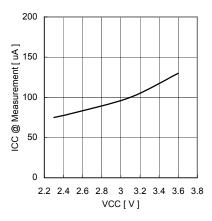
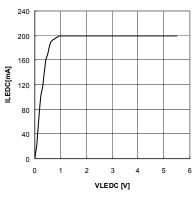
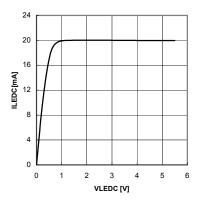


Fig.13 PS Directional Characteristics 2

Fig.14 Irradiance – PS_DATAOUT

Fig.15 VCC - ICC (During PS measurement)





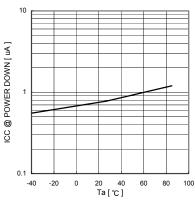
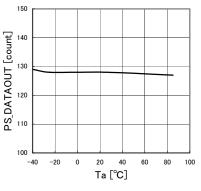
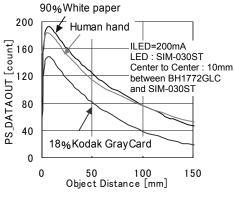


Fig.16 VLEDC – ILEDC@ ILED is set 200mA by ILED register

Fig.17 VLEDC – ILEDC@ ILED is set 20mA by ILED register

Fig.18 VCC – ICC@0 Lx (POWER DOWN)





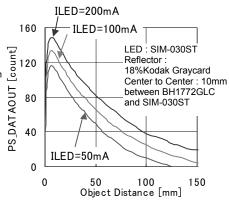
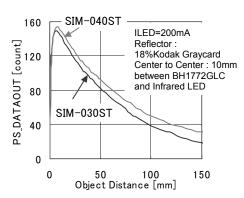


Fig.19 PS sensor out Fig.2
Temperature Dependency
(Irradiance by Proximity object = 324µW/cm²)

Fig.20 Object Distance – PS_DATAOUT of different reflector

Fig.21 Object Distance – PS_DATAOUT of different ILED



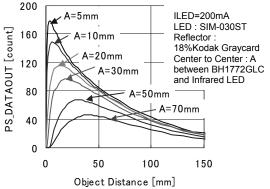


Fig.22 Object Distance – PS_DATAOUT of different Infrared LED

Fig.23 Object Distance – PS_DATAOUT of different distance between BH1772GLC and SIM-030ST

	1 ² C	hue	commi	ınica	ation
•	ı	bus	commi	JNICa	atior

- 1) Slave address "0111000"
- 2) Main write format
 - 1. Case of "Indicate register address"

ST	Slave Address 0111000	W 0	ACK	Indicate register address 010XXXXX	ACK	SP
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2. Case of "write to data register after indicating register address"

ST	Slave Address 0111000		W 0	ACK	Indicate register address 010XXXXX	ACK	
Data	a specified at register address field	ACK]	ACK	Data specified at register address field + N	ACK	SP

BH1772GLC continues to write data with address increments until master issues stop condition. Write cycle is 40h - 41h - 42h - 43h - 44h - 45h - 46h - 52h 5Dh - 5Eh - 40h

- Ex) If register address field is 45h, then BH1772GLC writes data like seeing in below. 45h - 46h -52h 5Dh – 5Eh - 40h........It is continued until master issues stop condition.
- 3) Main read format
 - 1. Case of read data after indicate register address and read data (Master issues restart condition)

ST	Slave Address 0111000		W 0	ACK	Indicate register address 010XXXXX	ACK	
ST	Slave Address 0111000		R 1	ACK	Data specified at register address field	ACK	
Data	a specified at register address field + 1	ACK		ACK	Data specified at register address field + N	NACK	SP

2. Case of read data after selecting register address

ST	Slave Address 0111000		R 1	ACK	Data specified at register address field	ACK	
Data	a specified at register address field + 1	ACK		ACK	Data specified at register address field + N	NACK	SP

 ${\tt BH1772GLC\ outputs\ data\ from\ specified\ address\ field\ until\ master\ issues\ stop\ condition}.$

Read cycle is 40h - 41h - 42h - 43h - 44h - 45h - 46h - 4Ah 5Dh - 5Eh - 40h

Ex) If register address field is 4Ch, then BH1772GLC outputs data like seeing in below.

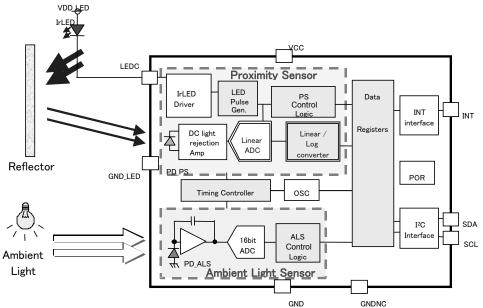
4Ch - 4Dh -4Eh 5Dh - 5Eh - 40h........It is continued until master issues stop condition.

	 <u></u>
from master to slave	from slave to maste

^{*} BH1772GLC operates as I²C bus slave device.

^{*} Please refer formality I²C bus specification of NXP semiconductors

Block diagram and block explanation



➤ I²C Interface

I²C bus interface. 1.8V logic interface is supported.

▶ POR

Power on reset function.

> OSC

Internal oscillator.

> Timing controller

Internal management block for proximity sensor and ambient light sensor.

> INT interface

INT terminal control block. Details are on Page 13 - 14

> DATA registers

Register for strage of measurement results or commands. Details are on Page 15.

> PS control logic

This block controls proximity sensor analog block

> LED Pulse Ger

LED current generator. LED current value is configurable by ILED(42h) register.

➤ IrLED Driver

IrLED driver block.

➤ PD ALS

Photo diode for ambient light sensor. Peak wavelength is approximately 550nm.

➤ 16bit ADC

AD converter for ALS.

> ALS control logic

This block controls ambient light sensor analog block.

➤ PD PS

Photo diode for proximity sensor. Peak wavelength is approximately 850nm.

> DC light rejection Amp

DC light is rejected in this block. And generated Infrared pulse is passed to linear ADC block.

Linear ADC

AD converter for proximity sensor. Detection range is very wide (1µW/cm² - 100mW/cm²).

➤ Linear/Log converter

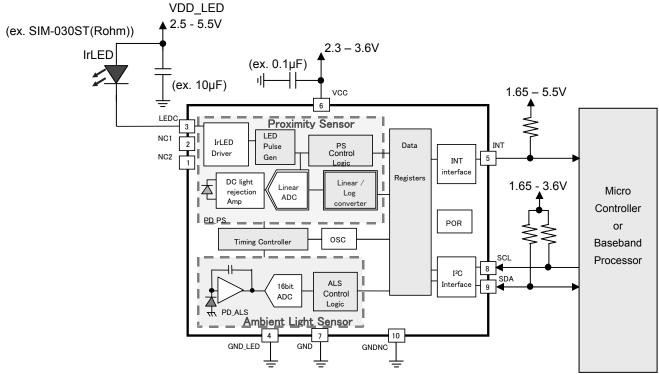
Linear to logarithm converter for proximity sensor. Output data is 8bit.

PS irradiance calculation example is on Page 23.

Example of application circuit diagram

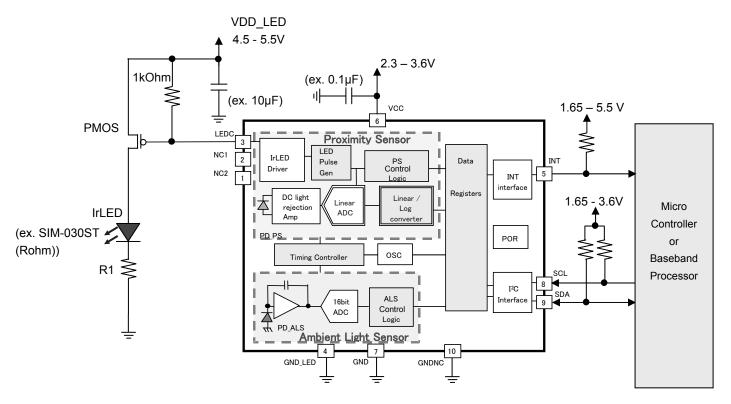
If you do not use the INT pin, please connect to GND or opening (non connect). Regarding NC1 and NC2, please connect to VDD_LED or open (non connect).

1) Standard application circuit example



2) In case of extending proximity sensor detection distance

BH1772GLC can drive maximum 200mA(Typ) current. By adding simple external circuit, it is possible to increase IrLED current and to extend detection distance. In case of driving large current for IrLED, note that the current value must not be over the absolute maximum rating for IrLED.



●Te

rminal des PIN No.	Terminal Name	Equivalent Circuit	Function
1	NC1		Terminal for internal test. Non connect or pull up to VDD_LED (external IrLED anode terminal)
2	NC2		Terminal for internal test. Non connect or pull up to VDD_LED (external IrLED anode terminal)
3	LEDC		Nch open drain LED current output terminal. LED current and emitting interval is defined by internal register. Register value is possible to configure by I ² C bus.
4	GND_LED		GND terminal for LED driver
5	INT		Nch open drain output. Interrupt setting is defined by internal register. Register value is possible to configure by I ² C bus.
6	VCC		Power supply terminal
7	GND		GND terminal
8	SCL	○	I ² C bus Interface SCL terminal
9	SDA		I ² C bus Interface SDA terminal
10	GNDNC	VCC VCC	Non connect or pull down to GND

Proximity sensor measurement sequence

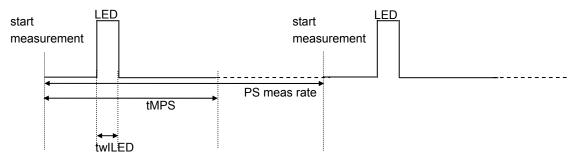
The below figure shows proximity sensor measurement sequence. First PS measurement is triggered by I^2C bus master writes measurement command to PS_CONTROL register (41h).

1. Forced mode

PS measurement is done only 1time and PS trigger bit (44h<0>) is overwritten from 'H' to 'L' after PS measurement complete. PS measurement is re-started by master writes PS trigger bit to 'H'.

2. Stand alone mode

PS measurement is continuously done until master select the other mode. Measurement interval is defined at PS MEAS RATE register (45h).



twlLED: LED current pulse duration, please refer P2 (Electrical Characteristics).

tMPS: Proximity sensor measurement time, please refer P2 (Electrical Characteristics).

Measurement result is generated in this term.

PS meas rate: In case of stand alone mode, It is defined at PS_MEAS_RATE register (45h).

In case of forced mode, it means the term until overwriting PS trigger bit to 'H'.

●Ambient light sensor measurement sequence

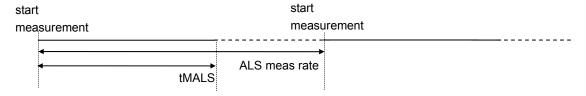
The below figure shows ambient light sensor measurement sequence. First ALS measurement is triggered by I²C bus master writing measurement command to ALS CONTROL register (40h).

1. Forced mode

ALS measurement is done only 1time and ALS trigger bit(44h<1>) is overwritten from 'H' to 'L' after ALS measurement is completed. ALS measurement is re-started by master writes ALS trigger bit to 'H'.

2. Stand alone mode

ALS measurement is continuously done until master select the other mode. Measurement interval is defined at ALS_MEAS_RATE register (46h). If ALS rate disable bit (46h<7>) is 'H', there is no interval between measurement.



tMALS: Ambient light sensor measurement time, please refer P2 (Electrical Characteristics).

Measurement result is generated in this term.

ALS meas rate: In case of stand alone mode, It is defined at ALS_MEAS_RATE register (46h)

In case of forced mode, it means the term until overwriting ALS trigger bit to 'H'.

Interrupt function

Interrupt function compares ALS or PS measurement result to preset interrupt threshold level. PS uses one threshold level or two threshold level (in hysteresis mode) and ALS uses two threshold level (upper and lower).

Interrupt status is monitored by INT pin or ALS PS STATUS register (4Eh) and Interrupt function is able to be controlled by INTERRUPT register (52h). Interrupt threshold is defined at ALS TH UP and ALS TH LOW and PS TH H and

PS TH L registers (53h, 56 - 59h, 5Ch). PS TH L registers is effective when PS hysteresis bit (52h<4>) is 'H'. Interrupt persistence function is defined at PERSISTENCE register (5Bh).

INT pin is Nch open drain terminal so this terminal should be pull-up to some kind of voltage source by an external resister. Maximum sink current rating of this terminal is 7mA.

There are two output modes about interrupt function (latched mode and unlatched mode).

In case of using ALS and PS interrupt functions at the same time, latch mode is recommended.

INT terminal is high impedance when VCC is supplied.

INT terminal becomes inactive by setting INTERRUPT register (52h)[1:0] to "00". (It is not worked during power down mode. Power down mode means ALS CONTROL(40h)<1>='0' and PS CONTROL(41h)<1> = '0'.)

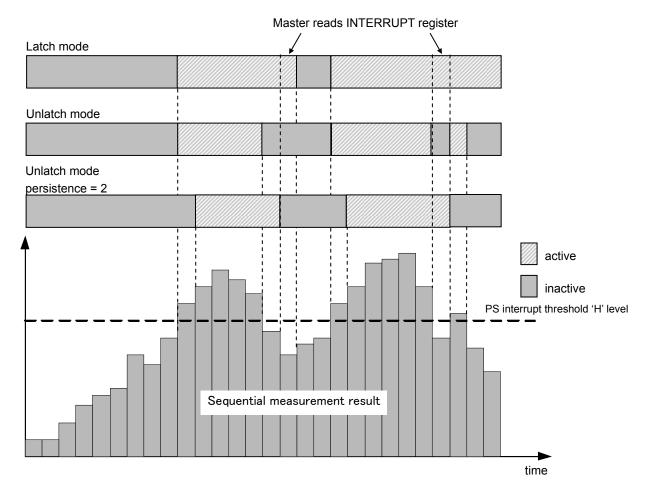
INT terminal keeps just previous state which power down command is sent. So to set INT terminal to high impedance is recommended. VCC current(approximately 25µA at VCC=2.5V) is consumed during INT terminal is 'L'. There are two method to set INT terminal to high impedance.

- Send software reset command. (Write 'H' to ALS CONTROL(40h)<2>. Software reset is also worked during power down. All registers are initialized by software reset command.)
- Write "000" to INTERRUPT register(52h)<2:0>.
- ex1) In case of using only PS 'H' threshold (INTERRUPT register 52h<4>: '0')

In case of unlatch mode if the measurement value exceeds the PS interrupt threshold 'H' value, the interrupt becomes active. And if the measurement value goes below the threshold, the interrupt becomes inactive.

In case of latch mode once the interrupt becomes active, it keeps the status until end of measurement after INTERRUPT register is read.

In case of persistence function is set to active, if the interrupt is inactive, it keeps inactive status until the measurement value is beyond the threshold 'H' value continuously. If the interrupt is active, it keeps active status until the measurement value is below threshold 'H' value continuously or until end of measurement after INTERRUPT register is read.

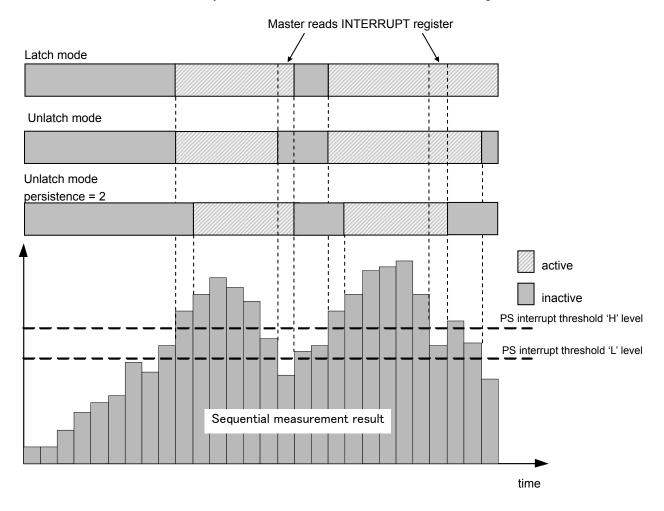


ex2) In case of using PS 'H/L' threshold (INTERRUPT register 52h<4>: '1')

In case of unlatch mode if the measurement value exceeds the PS interrupt threshold 'H' value, the interrupt becomes active. And if the measurement value goes below the threshold 'L' value, the interrupt becomes inactive.

In case of latch mode once the interrupt becomes active, it keeps the status until end of measurement after INTERRUPT register is read.

In case of persistence function is set to active, if the interrupt is inactive, it keeps inactive status until the measurement value is beyond the threshold 'H' value continuously. If the interrupt is active, it keeps active status until the measurement value is below threshold 'L' value continuously or until end of measurement after INTERRUPT register is read.

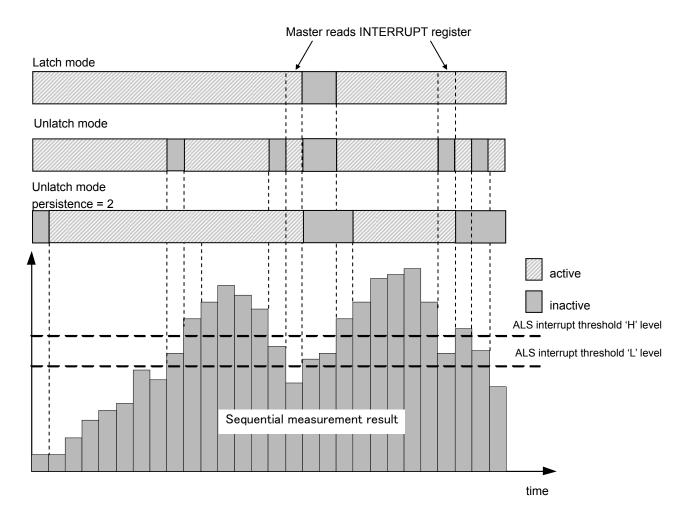


ex3) Ambient light sensor interrupt function

In case of unlatch mode if the measurement value is within the range set by ALS interrupt threshold 'H' and 'L' value, the interrupt becomes inactive. And if the measurement value is out of the range set by threshold 'H' and 'L' value, the interrupt becomes active.

In case of latch mode once the interrupt becomes active, it keeps the status until end of measurement after INTERRUPT register is read.

In case that persistence function is set to active, if the interrupt is inactive, it keeps inactive status until the measurement value is continuously out of the range set by threshold 'H' and 'L' value. If the interrupt is active, it keeps active status until the measurement value is continuously within the range set by threshold 'H' and 'L' value or until end of measurement after INTERRUPT register is read.



●Command set

Address	Туре	Register name	Register function
40h	RW	ALS_CONTROL	ALS operation mode control and SW reset
41h	RW	PS_CONTROL	PS operation mode control
42h	RW	I_LED	LED current setting
43h	RW	Reserved register 1	-
44h	RW	ALS_PS_MEAS	Forced mode trigger
45h	RW	PS_MEAS_RATE	PS measurement rate
46h	RW	ALS_MEAS_RATE	ALS measurement rate
4Ah	R	Reserved register 2	-
4Bh	R	Reserved register 3	-
4Ch	R	ALS_DATA_0	ALS data (Low Byte)
4Dh	R	ALS_DATA_1	ALS data (High Byte)
4Eh	R	ALS_PS_STATUS	Measurement data and interrupt status
4Fh	R	PS_DATA	PS data
50h	R	Reserved register 4	-
51h	R	Reserved register 5	-
52h	RW	INTERRUPT	Interrupt setting
53h	RW	PS_TH_H	PS interrupt H threshold
54h	RW	Reserved register 6	-
55h	RW	Reserved register 7	-
56h	RW	ALS_TH_UP_0	ALS upper threshold low byte
57h	RW	ALS_TH_UP_1	ALS upper threshold high byte
58h	RW	ALS_TH_LOW_0	ALS lower threshold low byte
59h	RW	ALS_TH_LOW_1	ALS lower threshold high byte
5Ah	RW	ALS_SENSITIVITY	ALS sensitivity setting
5Bh	RW	PERSISTENCE	INT pin INTERRUPT persistence setting
5Ch	RW	PS_TH_L	PS interrupt L threshold
5Dh	RW	Reserved register 8	-
5Eh	RW	Reserved register 9	-

OALS_CONTROL (40h)

7	6	5	4	3	2	1	0
RES	RES	RES	RES	ALS	SW	ALS mode	
				Resolution	Reset		

default value 00h

Field	Bit	Туре	Description		
RES	7:4	RW	Write "0000"		
ALS Resolution	2	RW	0 : H-Resolution mode, 1 lx step output		
ALS Resolution	3		1 : M-Resolution mode, 4 lx step output		
CVV recet	2	RW	0 : initial reset is not started		
SW reset			1 : initial reset is started		
			00 : Standby mode		
ALS mode	1:0	RW	01 : Don't use.		
ALS Mode	1.0	KVV	10 : Forced mode		
			11 : Stand alone mode		

OPS_CONTROL (41h)

7 6 5 4 3 2 1 0 X X X X X X X PS mode

default value 00h

Field	Bit	Туре	Description	
NA	7:2	-	Ignored	
		1:0 RW 0	00 : Standby mode	
PS mode	1 . 0		01 : Don't use.	
P3 mode	1.0		10 : Forced mode	
			11 : Stand alone mode	

OI_LED (42h)

7	6	5	4	3	2	1	0
Reserve	ed				LED curi	ent	

default value 1Bh

Field	Bit	Туре	Description
Reserved	7:3	RW	write "00011"
LED current	2:0	RW	000 : 5mA 001 : 10mA 010 : 20mA 011 : 50mA 100 : 100mA 101 : 150mA
			11X : 200mA

OReserved register 1 (43h)

7	6	5	4	3	2	1	0
Χ	Х	Χ	Χ	Χ	Reserve	d	

default value 03h

Field	Bit	Туре	Description
NA	7:3	-	Ignored
Reserved	2:0	RW	000 : 5mA

OALS_PS_MEAS (44h)

7	6	5	4	3	2	1	0
Х	Х	Χ	Х	Х	Χ	ALS	PS
						trigger	trigger

default value 00h

Field	Bit	Туре	Description		
NA	7:2	-	Ignored		
ALS trigger	1	RW	0 : Ignored 1 : Start ALS measurement at force mode ^{*2}		
PS trigger	0	RW	0 : Ignored 1 : Start PS measurement at force mode *2		

^{*2} Even if trigger is set during measurement, the measurement doesn't restart. The measurement will start, in case that It is set to forced mode by ALS_CONTROL register (40h) or PS_CONTROL register (41h) and is not during measurement.

OPS_MEAS_RATE (45h)

7	6	5	4	3	2	1	0
Χ	Χ	Χ	Χ	PS meas	rate		

default value 05h

Field	Bit	Туре	Description
NA	7:4	-	Ignored
PS meas rate	3:0	RW	0000 : 10ms 0001 : 20ms 0010 : 30ms 0011 : 50ms 0100 : 70ms 0101 : 100ms 0110 : 200ms 0111 : 500ms 1000 : 1000ms 1001 : 2000ms 101X : 2000ms 11XX : 2000ms

OALS_MEAS_RATE (46h)

7	6	5	4	3	2	1	0
ALS							
rate	Х	Х	X	Х	Al	LS meas ra	te
disable							

default value 02h

Field	Bit	Туре	Description
ALS rate disable	7	RW	0 : ALS meas rate(46h<2:0>) is active 1 : ALS meas rate(46h<2:0>) is inactive
NA	6:3	-	Ignored
ALS meas rate	2:0	RW	000 : 100ms 001 : 200ms 010 : 500ms 011 : 1000ms 1XX : 2000ms

OReserved register 2 (4Ah)

7	6	5	4	3	2	1	0
Χ	Χ	X	Х	Х	Χ	Χ	Х

default value 93h

Field	Bit	Туре	Description
NA	7:0	R	Reserved

OReserved register 3 (4Bh)

-	7	6	5	4	3	2	1	0
)	X	Χ	Χ	Χ	Χ	Χ	Χ	Χ

default value 01h

Field	Bit	Туре	Description
NA	7:0	R	Reserved

OALS_DATA (4Ch, 4Dh)

7	6	5	4	3	2	1	0
ALS data	а						

default value 00h

Register	Address	Bit	Туре	Description
ALS data LSBs	4Ch	7:0	R	ALS data Low byte
ALS data MSBs	4Dh	7:0	R	ALS data High byte

OALS_PS_STATUS (4Eh)

7	6	5	4	3	2	1	0
ALS INT	ALS data	Reserve	ed			PS INT	PS data
status	status					status	status

default value 00h

Field	Bit	Туре	Description		
ALS INT status	7	R	0 : ALS interrupt signal inactive 1 : ALS interrupt signal active		
ALS data status	ata status 6 R		: ALS old data (data is already read) : ALS new data (data is renewed after previous reading)		
Reserved	5:2	R	-		
PS INT status	1	R	0 : PS interrupt signal inactive 1 : PS interrupt signal active		
PS data status	0	R	0 : PS old data (data is already read) 1 : PS new data (data is renewed after previous reading)		

ALS interrupt signal inactive means that ALS measurement result is within threshold level set by ALS_TH register(56h, 57h, 58h, 59h). ALS interrupt signal active means measurement result is out of threshold level set by ALS_TH register. PS interrupt signal active means PS measurement result exceeds threshold level defined by PS_TH_H register(53h). PS interrupt signal inactive means PS measurement result does not exceed threshold level set by PS_TH_H register. When PS interrupt hysteresis(INTERRUPT register 52h<4>) is 'H', if once interrupt signal becomes active, it is kept until measurement result becomes less than PS_TH_L(5Ch) register value.

OPS_DATA (4Fh)

7	6	5	4	3	2	1	0
PS data							

default value 00h

Register	Bit	Туре	Description
PS data	7:0	R	PS measurement data

OReserved register 4 (50h)

7	6	5	4	3	2	1	0
Χ	X	Χ	Χ	Х	Х	Х	Χ

default value 00h

Field	Bit	Туре	Description
Reserved	7:0	R	Reserved

OReserved register 5 (51h)

7	6	5	4	3	2	1	0
Х	Х	Х	Х	Х	Х	Χ	Χ

default value 00h

Field	Bit	Туре	Description
Reserved	7:0	R	Reserved

OINTERRUPT (52h)

7	6	5	4	3	2	1	0
Х	Х	Interru	PS	Output	Interrupt	Interrupt mode	
		pt	Interrupt	mode	polarity		
		source	hysteresis				

default value 08h

Field	Bit	Туре	Description		
NA	7:6	-	Ignored		
Interrupt source	Interrupt source 5 R		0 : First interrupt triggered by ALS		
'			1 : First interrupt triggered by PS		
PS Interrupt	4	RW	0 : Use PS_TH_H only.		
hysteresis	hysteresis 4 RVV		1 : Use PS_TH_H and PS_TH_L for hysteresis		
Output made 2	3	RW	0 : INT pin is latched until INTERRUPT register is read.		
Output mode	3		1 : INT pin is updated after each measurement.		
Interrupt polarity	2	RW	0 : INT pin is logic 'L' when interrupt signal is active		
interrupt polarity	2	KVV	1 : INT pin is logic 'L' when interrupt signal is inactive		
			00 : INT pin is inactive.		
Interrupt made	1:0	RW	01 : Triggered by only PS measurement		
Interrupt mode	1.0	KVV	10 : Triggered by only ALS measurement		
			11 : Triggered by PS and ALS measurement		

OPS_TH_H (53h)

7	6	5	4	3	2	1	0
PS H thi	reshold						

default value FFh

Register	Bit	Туре	Description
PS_TH_H	7:0	RW	PS Interrupt H threshold level

OReserved register 6 (54h)

7	6	5	4	3	2	1	0			
Reserve	Posonyod									

default value FFh

Field	Bit	Туре	Description
Reserved	7:0	RW	write "1111111"

OReserved register 7 (55h)

7	6	5	4	3	2	1	0	
Reserved								

default value FFh

Field	Bit	Туре	Description
Reserved	7:0	RW	write "11111111"

OALS_TH_UP (56h, 57h)

7	6	5	4	3	2	1	0
ALS upp	er thresh	old data					

default value FFh

Register	Address	Bit	Туре	Description
ALS TH upper LSBs	56h	7:0	RW	ALS interrupt upper threshold (Low byte)
ALS TH upper MSBs	57h	7:0	RW	ALS interrupt upper threshold (High byte)

OALS_TH_LOW (58h, 59h)

7	6	5	4	3	2	1	0
ALS lower threshold data							

default value 00h

Register	Address	Bit	Type	Description
ALS TH lower LSBs 58h 7:0		RW	ALS interrupt lower threshold	
ALS TH lower LSBS	3011	7.0	KVV	(Low byte)
ALC TH lower MCDe	ALC TILlower MCDs 50h 7.0		RW	ALS interrupt lower threshold
ALS TH lower MSBs	59h	7:0	KVV	(High byte)

OALS_SENSITIVITY (5Ah)

7	6	5	4	3	2	1	0
ALS sensitivity data							

default value 35h

Register	Bit	Type	Description
ALS sensitivity data	7:0	RW	ALS sensitivity adjustment register (refer to P24)

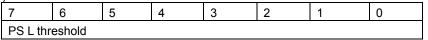
OPERSISTENCE (5Bh)

7	6	5	4	3	2	1	0
ALS per	ALS persistence				stence		

default value 11h

Field	Bit	Туре	Description
ALS persistence	7:4	RW	Persistence for ALS interrupt.
PS persistence	3:0	RW	Persistence for PS interrupt.

OPS_TH_L (5Ch)



default value 00h

Register	Bit	Туре	Description
PS_TH_L	7:0	RW	PS Interrupt L threshold level

OReserved register 8 (5Dh)

7	6	5	4	3	2	1	0
Reserved							

default value 00h

Field	Bit	Туре	Description
Reserved	7:0	RW	write "00000000"

OReserved register 9 (5Eh)

7	6	5	4	3	2	1	0
Reserved							

default value 00h

Field	Bit	Туре	Description
Reserved	7:0	RW	write "00000000"

Current consumption

BH1772GLC can operate ALS and PS individually. Average current consumption is depend on each statuses and measurement duration

(set by 45h, 46h register). Major elements which decide VCC current consumption are like following table.

Parameter	Symbol	Тур.	Units	Comment
ALS part's current	IccALS	140	μА	Except for ALS/PS common circuit current.
PS part's current	IccPS	250	μA	Except for ALS/PS common circuit current. Current flow for 1.4ms
PS current during driving LED	Icc3	6.5	mA	
ALS/PS common ciruit current	Icccmn	60	μΑ	

 Current consumption in case of operating only ALS VCC current consumption can calculate according to following formula.

ICC(only ALS) = IccALS * (100ms / ALS meas rate) +Icccmn

For example in case measurement rate is 500ms, the value is as following.

e. g.) ICC(onlyALS) = $140\mu A (100ms / 500ms) + 60\mu A = 88\mu A$

2) Current consumption in case of operating only PS

VCC current consumption can calculate according to following formula.

ICC(only PS) = IccPS * (1.4ms / PS meas rate) +Icccmn + Icc3 * (200µs / PS meas rate)

VDD_LED current consumption can calculate according to following formula.

IVDD LED = 200µs / PS meas rate

For example in case it drives 50mA and measurement rate is 100ms, the value is as following.

e. g.) ICC(onlyPS) =
$$250\mu A* (1.4ms / 100ms) + 60\mu A + 6.5mA* (200\mu s / 100ms) = 76.5\mu A$$
 IVDD LED = $50mA* (200\mu s / 100ms) = 100\mu A$

3) Current consumption in case of operating ALS and PS at the same time.

VCC current consumption can calculate according to following formula.

For example in case ALS measurement rate is 500ms and PS measurement rate is 100ms and it drives 50mA, the value is as following.

e.g.) ICC(ALS+PS) =
$$88\mu A + 76.5\mu A - 60\mu A = 104.5\mu A$$

VDD LED current consumption can calculate same as the case of operating only PS.

 In case of waiting trigger at forced mode ALS/PScommon cucuit current (Icccmn) is flow.

ALS Measurement mode explanation

Measurement Mode	Measurement Time	Resolution
H-Resolution mode	typ. 100ms.	1 Lx
M-Resolution mode	typ.16ms.	4 Lx

We recommend to use H-Resolution Mode.

Measurement time (integration time) of H-Resolution mode is so long that some kind of noise(including in 50Hz / 60Hz noise) is rejected. And H-Resolution mode is 1 Ix resolution so that it is suitable for darkness.

● Regarding ALS measurement result

ALS measurement result is registered as following format

ALS DATA LSB (4Ch)

7	6	5	4	3	2	1	0
2 ⁷	2 ⁶	2 ⁵	2 ⁴	2 ³	2 ²	2 ¹	2 ⁰

ALS DATA MSB (4Dh)

7	6	5	4	3	2	1	0
2 ¹⁵	2 ¹⁴	2 ¹³	2 ¹²	2 ¹¹	2 ¹⁰	2 ⁹	2 ⁸

ALS Lux calculation example

$$(2^{15} + 2^9 + 2^8 + 2^7 + 2^4) = 33680 [lx]$$

Regarding PS measurement result

PS measurement result is converted to logarithm 8bit data and is registered as following format

PS DATA (4Fh)

7	6	5	4	3	2	1	0
27	2 ⁶	2 ⁵	2 ⁴	2 ³	2 ²	2 ¹	2 ⁰

The data seeing above register is possible to change the irradiance.

Approximation formula is seeing in below.

PS irradiance calculation example

10 ^ (
$$(2^7 + 2^2 + 2^0)$$
 x 0.0197) = 10^(133 x 0.0197) \div 417 [μ W/cm^2]

ALS sensitivity adjustment function

BH1772GLC is possible to change ALS sensitivity. And it is possible to cancel the optical window influence (difference with / without optical window) by using this function. Adjustment is done by changing measurement time. For example, when transmission rate of optical window is 50% (measurement result becomes 0.5 times if optical window is set), influence of optical window is ignored by changing sensor sensitivity from default to 2 times.

Sensitivity can be adjusted by ALS_SENSITIVITY(5Ah). For example, sensitivity 2 times when the value of the register is 2 times, and the measurement time 2 times, too.

The range of adjusting ALS SENSITIVITY is below.

		Min.	Тур.	Max.
Adjustable range of	binary	0001_1000 (sensitivity: default * 0.45)	0011_0101 default	1111_1110 (sensitivity: default * 4.79)
ALS_SENSITIVITY	decimal	24	53	254
	uecimai	(sensitivity: default * 0.45)	default	(sensitivity: default * 4.79)

It is possible to detect 0.21lx by using this function at H-resolution mode.

The below formula is to calculate illuminant per 1 count.

Illuminant per 1 count (lx / count) = 1 * 53 / X

53 : Default value of ALS SENSITIVITY register (decimal)

X : ALS SENSITIVITY register value (decimal)

Illuminant per 1 count is as following within adjustable range of ALS_SENSITIVITY.

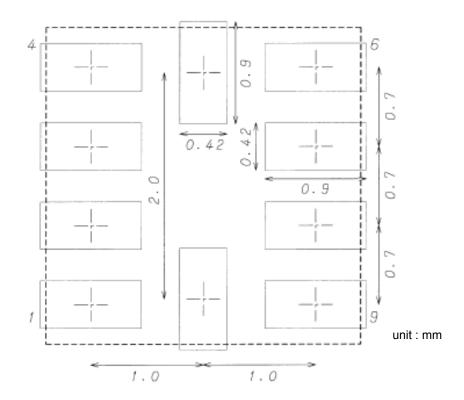
ALS_SENSITIVITY register value	Illuminant per 1count(lx / count)		
0001_1000	2.21		
0011_0101	1.00		
1111_1110	0.21		

Please input the opecode at Power Down state to change ALS_SENSITIVITY register. There is a possibility of malfunction when the opecode to change ALS_SENSITIVITY register is input while the illuminant measurement is on-going

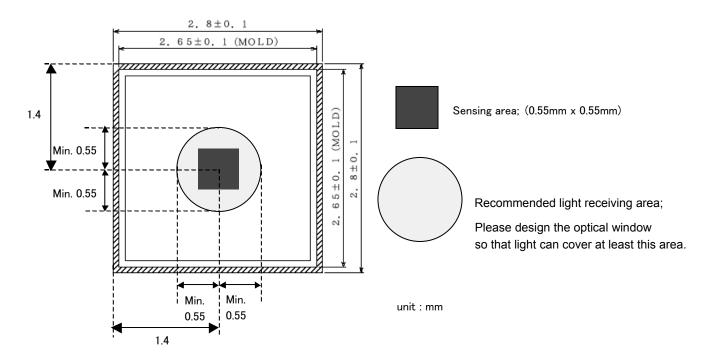
In stand alone mode, if ALS measurement time exceeds the value defined ALS_MEAS_RATE register, ALS_MEAS_RATE register value is ignored. Next measurement is started immediately after one measurement completion.

Recommended land pattern

Bottom View



Optical window design above the device

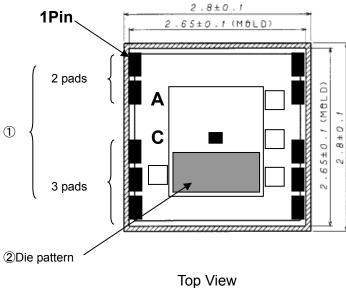


●The method of distinguishing 1pin

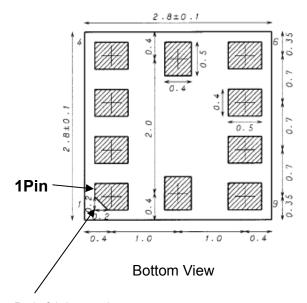
There is the following methods of distinguishing 1pin.

Distinguishing by Pad design of top side. There are 5 pads in the one side of a top side. There is a space between 2 pads and 3 pads.

Distinguishing by Die pattern.



Distinguishing by Pad design of bottom side.



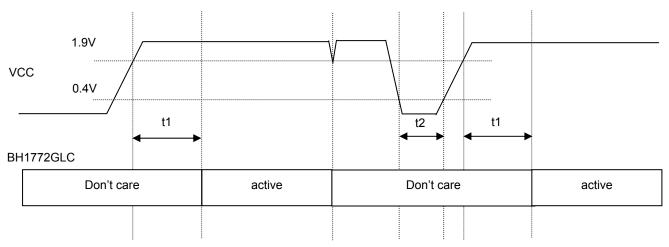
Pad of 1pin cuts the corner.

●Power on reset function

BH1772GLC has power on reset function. By operating this function, all of registers are reset when the power is supplied. Please note followings and design the application.

① Power on time: t1
BH1772GLC becomes operational after 2ms since VCC voltage crosses 1.9V from being less than 0.4V.

Power off time: t2 Before the power is supplied, VCC voltage should be less than 0.4V at least for 1ms.



^{*&}quot;active state" means that BH1772GLC is correctly operational.

INT terminal is high impedance when VCC is supplied.

Cautions on use

1) Absolute Maximum Ratings

An excess in the absolute maximum ratings, such as supply voltage (Vccmax, VSDAmax, VSCLmax, VINTmax, VGNDNCmax, VLEDCmax), temperature range of operating conditions (Topr), etc., can break down devices, thus making impossible to identify breaking mode such as a short circuit or an open circuit. If any special mode exceeding the absolute maximum ratings is assumed, consideration should be given to take physical safety measures including the use of fuses, etc.

2) GND voltage

Make setting of the potential of the GND terminal and GND_LED terminal so that they will be maintained at the minimum in any operating state. Furthermore, check to be sure no terminals are at a potential lower than the GND voltage including an actual electric transient.

3) Short circuit between terminals and erroneous mounting

In order to mount ICs on a set PCB, pay thorough attention to the direction and offset of the ICs. Erroneous mounting can break down the ICs. Furthermore, if a short circuit occurs due to foreign matters entering between terminals or between the terminal and the power supply or the GND terminal, the ICs can break down.

4) Operation in strong electromagnetic field

Be noted that using ICs in the strong electromagnetic field can malfunction them.

5) Inspection with set PCB

On the inspection with the set PCB, if a capacitor is connected to a low-impedance IC terminal, the IC can suffer stress. Therefore, be sure to discharge from the set PCB by each process. Furthermore, in order to mount or dismount the set PCB to/from the jig for the inspection process, be sure to turn OFF the power supply and then mount the set PCB to the jig. After the completion of the inspection, be sure to turn OFF the power supply and then dismount it from the jig. In addition, for protection against static electricity, establish a ground for the assembly process and pay thorough attention to the transportation and the storage of the set PCB.

6) Input terminals

In terms of the construction of IC, parasitic elements are inevitably formed in relation to potential. The operation of the parasitic element can cause interference with circuit operation, thus resulting in a malfunction and then breakdown of the input terminal. Therefore, pay thorough attention not to handle the input terminals; such as to apply to the input terminals a voltage lower than the GND respectively, so that any parasitic element will operate. In addition, apply to the input terminals a voltage within the guaranteed value of electrical characteristics.

7) Thermal design

Perform thermal design in which there are adequate margins by taking into account the power dissipation (Pd) in actual states of use.

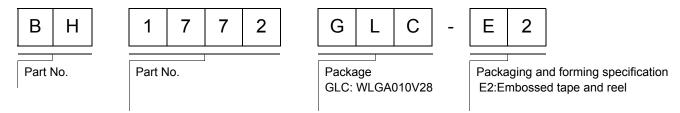
8) Treatment of package

Dusts or scratch on the photo detector may affect the optical characteristics. Please handle it with care.

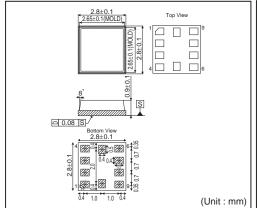
9) RUSH current

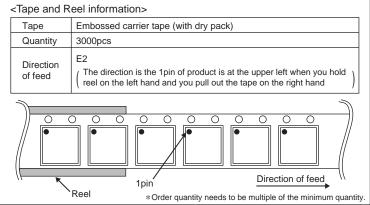
When power is first supplied to the CMOS IC, it is possible that the internal logic may be unstable and rush current may flow instantaneously. Therefore, give special consideration to power coupling capacitance, power wiring, width of GND wiring, and routing of connections.

Ordering part number



WLGA010V28





Notice

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JÁF	PAN	USA	EU	CHINA	
CLA	SSⅢ	CLACCIII	CLASS II b	CLASSIII	
CLA	SSIV	CLASSⅢ	CLASSIII	CLASSⅢ	

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 - [e] Use of our Products in proximity to heat-producing components, plastic cords, or other flammable items
 - [f] Sealing or coating our Products with resin or other coating materials
 - [g] Use of our Products without cleaning residue of flux (even if you use no-clean type fluxes, cleaning residue of flux is recommended); or Washing our Products by using water or water-soluble cleaning agents for cleaning residue after soldering
 - [h] Use of the Products in places subject to dew condensation
- 4. The Products are not subject to radiation-proof design.
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- 8. Confirm that operation temperature is within the specified range described in the product specification.
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For details, please refer to ROHM Mounting specification

Precautions Regarding Application Examples and External Circuits

- If change is made to the constant of an external circuit, please allow a sufficient margin considering variations of the characteristics of the Products and external components, including transient characteristics, as well as static characteristics.
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