

### **Digital Video Encorders**

# Video bus interface



BU9969KN No.09067EAT02

#### Description

BU9969KN is a digital video encoder IC for NTSC/PAL (ITU-R BT.601,ITU-R BT.656).

It allows captured images (e.g. downloaded or on mobile phones) to be viewed on a TV monitor. In addition, a digital filter is built in for high image quality, and both multifunction and simple types are available for greater compatibility.

#### Features

- Video Format
  - NTSC-M
  - PAL-B/D/G/H/I
- Bus Interface

• 656 input mode YCbCr 8 bit (included in EAV, SAV)

• 601 input mode YCbCr 16 bit or RGB 16 bit ( with Hsync, Vsync input )

Input Data Format

• YCbCr 4:2:2 (656 mode or 601 mode)

• RGB R: 5bit, G: 6bit, B: 5bit (601 mode)

- Input Range
  - YCbCr:

1) Y: 16-235, CbCr: 16-240 SCALE\_M\* = "1"

2) YCbCr : 1-254 SCALE\_M\* = "0" (601 mode)

\*SCALE\_M is 1st bit of Sub-Address x' 04.

- RGB: R, B: 0 31, G: 0 63
- NTSC/PAL Standard Video Output Support
- Trap Filter Built In
- x4 System Clock Over Sampling Function Built In
- 10-bit Video DAC Built In
- PLL Built In
- 2-Wire Serial Interface
- 2 Supply Voltage Operation: (DVDD = PVDD = 1.8V : Typ, IOVDD = AVDD = 3.0V : Typ)
- Package: VQFN36

#### Application

Cell Phone

### • Absolute Maximum Ratings

Table.1 Absolute Maximum Ratings

Item	Symbol	Rating	Unit
[1.8V Power Source System]			
Digital Core Power Source Voltage	DVDD	-0.2 to 2.5	V
PLL Power Source Voltage	PVDD		
[3.0V Power Source System]			
Digital I/O power source voltage	IOVDD	−0.2 to 4.5	V
DAC Power Source Voltage	AVDD		
Power Dissipation1	Pd1	450 (Note.1)	mW
Power Dissipation2	Pd2	700 (Note.2)	mW
Storage temperature range	Tstg	-25 to 125	°C

Note 1: When not mounted on any board at  $Ta = 25^{\circ}C$ .

Note 2: When mounted on 50mm\*58mm\*1.6mm glass epoxy board. In the case to use at Ta = 25°C or higher, 11.3 mW should be decreased per 1°C. This value is an actually measured value, and not a guaranteed value.

### •Recommended Operation Range

Table.2 Recommended Operation Range

Item	Symbol	Range	Unit
[1.8V Power Source System]			
Digital Core Power Source Voltage	DVDD	1.80 ± 0.1	٧
PLL Power Source Voltage	PVDD		
[3.0V Power Source System]			
Digital I/O power source voltage*	IOVDD	$3.00 \pm 0.3$	٧
DAC Power Source Voltage	AVDD		
Operation temperature range	Topr	-20 to 70	°C

<sup>\*</sup>Connect the pull-up resistance of the serial interface to the digital I/O power source voltage.

This procedure is same, when stopping to supply the power source.

<sup>\*</sup>Supply the power source voltage to all power source pins within 100  $\,\mu$  sec.

### •Recommended Operating Conditions

Table.3 Recommended Operating Conditions

(Unless otherwise specified Ta=25°C, DVDD=PVDD=1.8V, IOVDD=AVDD=3.0V, GND=0V)

Item	Symbol	Min	Тур	Max	Unit	Condition
Image data interface>						
SYSCLK frequency 1	fsysclk1	_	27	_	MHz	656 input mode
SYSCLK frequency 2	fsysclk2	_	13.5	-	MHz	601 input mode
SYSCLK frequency deviation 1	dfsysclk1	-100	-	100	ppm	27MHz at 656 input mode
SYSCLK frequency deviation 2	dfsysclk2	-100	_	100	ppm	13.5MHz at 601 input mode
SYSCLK rise time	t2r	-	-	5	ns	*1
SYSCLK fall time	t2f	-	-	5	ns	*1
SYSCLK duty	dutysclk	45	-	55	%	*1
<serial interface=""></serial>						
SCLK frequency	f <sub>SCLK</sub>	-	-	400	kHz	
SCLK rise time	t1sr	-	-	300	ns	*1
SCLK fall time	t1sf	_	_	300	ns	*1
SDI rise time	t1dr	-	-	300	ns	*1
SDI fall time	t1df	_	_	300	ns	*1
SCLK "L" pulse width	t1wl	1.3	_	-	us	*1
SCLK "H" pulse width	t1wh	0.6	_	_	us	*1

<sup>\*1</sup> Refer to Fig.5 the serial interface-timing chart on page 9.

### •Electric Characteristics 1

Table 4.1 Electric Characteristics 1

(Unless otherwise specified Ta=25°C, DVDD=PVDD=1.8V, IOVDD=AVDD=3.0V, GND=0V)

Item	Symbol	Min	Тур	Max	Unit	Condition		
<pre><image data="" interface=""/></pre>	Image data interface>							
Data setup time	t2sd	5	_	ı	ns	*1		
Data hold time	t2hd	8	_	ı	ns	*1		
HS, VS setup time	t2sc	5	_	ı	ns	*1		
HS, VS hold time	t2hc	8	_	ı	ns	*1		
<serial interface=""></serial>								
Data hold time	t1h	0	_	0.9	us	*2		
Data setup time	t1s	100	_	ı	ns	*2		
Hold time (START)	t1hSTA	0.6	_	ı	us	*2		
Setup time (STOP)	t1sST0	0.6	_	ı	us	*2		
Setup time (START)	t1sSTA	0.6	_	ı	us	*2		
Bus free time Between "STOP" condition and "START" condition	tBUF	1.3	-	-	us	*2		

<sup>\*1</sup> Refer to Fig.3., the image data and synchronous signal-timing chart on page 8.

<sup>\*2</sup> Refer to Fig.5., the serial interface timing chart on page 9.

#### •Electric Characteristics 2

Table 4.2 Electric Characteristics 2

(Unless otherwise specified Ta=25°C, DVDD=PVDD=1.8V, IOVDD=AVDD=3.0V, GND=0V)

Item	Symbol	Min	Тур	Max	Unit	Condition		
<video digital="" encoder="" p="" portion.<=""></video>	(Video encoder digital portion)							
Digital core dynamic current	IDDCO	_	20	50	mA	*1		
Digital I/O dynamic current	IDDIO	_	0.5	10.0	mA			
Digital core static current	ISTDCO	_	1.5	8	uA	*2		
Digital I/O static current	ISTDIO	_	0.5	2	uA	*3		
"H" input voltage	$V_{IH}$	IOVDD	-	IOVDD	V	*4		
		*0.8		+0.2				
"L" input voltage	$V_{IL}$	-0.2	-	IOVDD	٧	*4		
				*0.2				
L input leak current 1	I <sub>ILL1</sub>	-10	_	10	uA	*5		
L input leak current 2	I <sub>ILL2</sub>							
H input leak current 1	$I_{IHL}$	-10	_	10	uA	*6		
H input leak current 2	$I_{IHT}$	10		500	uA	*7		
SDI "L" output voltage	V <sub>oL</sub>	0	_	0.5	V	*8 IOL=2mA		

- \*1 Internal Color Bar output mode at 27MHz operation.
- \*2 RESETB = Low
- \*3 RESETB = Low and All inputs pins = Low
- \*4 The following pins are applied.
  - SYSCLK, DATA[15:0], HS, VS, TEST[3:0], SCLK and SDI.
- \*5 The following pins are set to "Low". SYSCLK, DATA[15:0], HS, VS, TEST[3:0], SCLK and SDI.
  - The following pins are set to "High (IOVDD)".
  - SYSCLK, DATA[15:0], HS, VS, SCLK and SDI.
- \*7 The following pins are set to "High (IOVDD)". TEST [3:0]
- \*8 The SDI pin is applied.

### • Electric Characteristics 3

Table 4.3 Electric Characteristics 3

(Unless otherwise specified Ta=25°C, DVDD=PVDD=1.8V, IOVDD=AVDD=3.0V, GND=0V)

Item	Symbol	Min	Тур	Max	Unit	Condition
<video dac="" portion=""></video>						
Video DAC resolution	RES	-	-	10	bit	
Video DAC dynamic current	IDDV	-	40	55	mA	$R_L=37.5 \Omega$ , $R_{IREF}=1.2 k \Omega$ *1
Video DAC static current	ISTV	1	1	5	uA	RESETB=L *2
Integral linearity error	INL	1	±8.0	±15.0	LSB	$R_L=37.5 \Omega$ , $R_{IREF}=1.2 k \Omega$ *1
Differential linearity error	DNL	-	±1.0	±4.0	LSB	$R_L=37.5 \Omega$ , $R_{IREF}=1.2 k \Omega$ *1
Full scale voltage	$V_{\sf FS}$	1.1	1.25	1.4	٧	$R_L$ =37.5 $\Omega$ , $R_{IREF}$ =1.2k $\Omega$ *1
<pll portion=""></pll>						
PLL dynamic current	IDDP	-	1	2.5	mA	SYSCLK=27MHz input
PLL static current	ISTP	_	1	5	uA	*2

<sup>\*1</sup>  $R_L$ =37.5  $\Omega$  shows the value at measurement.

<sup>\*2</sup> Set the RESETB or 1st bit of register PWD\_M to "Low".

### •Block Diagram

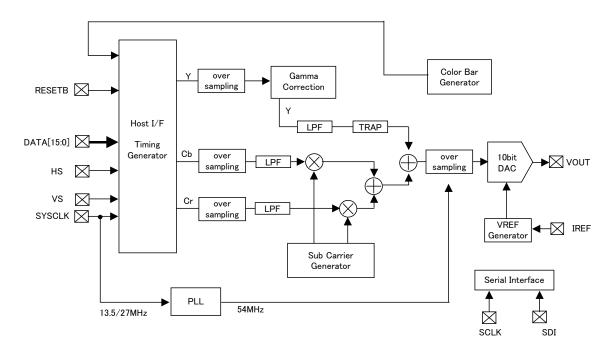


Fig.1. BU9969KN Block Diagram

#### •Terminal Functions

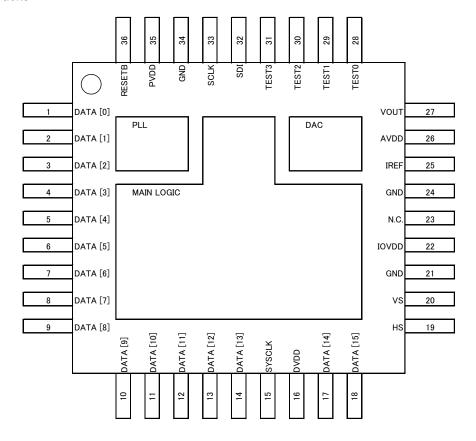


Fig 2. BU9969KN Terminal Layout

### •Terminal Functions

Table 5. BU9969KN Terminal Functions

	Tamainal		Description of terminals		1/0			
Terminal No.	Terminal name	RGB input	YCbCr input	YCbCr input	I/O *1			
	Hame	(601 input mode)	(601 input mode)	(656 input mode)	71-1			
1	DATA [0]	R[0] data	Y[0] data	YCbCr[0] data	I			
2	DATA [1]	R[1] data	Y[1] data	YCbCr[1] data	I			
3	DATA [2]	R[2] data	Y[2] data	YCbCr[2] data	I			
4	DATA [3]	R[3] data	Y[3] data	YCbCr[3] data	I			
5	DATA [4]	R[4] data	Y[4] data	YCbCr[4] data	I			
6	DATA [5]	G[0] data	Y[5] data	YCbCr[5] data	I			
7	DATA [6]	G[1] data	Y[6] data	YCbCr[6] data	I			
8	DATA [7]	G[2] data	Y[7] data	YCbCr[7] data	I			
9	DATA [8]	G[3] data	CbCr[0] data	Connected to GND	I			
10	DATA [9]	G[4] data	CbCr[1] data	Connected to GND	I			
11	DATA [10]	G[5] data	CbCr[2] data	Connected to GND	I			
12	DATA [11]	B[0] data	CbCr[3] data	Connected to GND	I			
13	DATA [12]	B[1] data	CbCr[4] data	Connected to GND	I			
14	DATA [13]	B[2] data	CbCr[5] data	Connected to GND	I			
15	SYSCLK	System clock (Image data transfer clock)						
16	DVDD	Digital core power source						
17	DATA [14]	B[3] data	CbCr[6] data	Connected to GND	I			
18	DATA [15]	B[4] data	CbCr[7] data	Connected to GND	I			
19	HS	Horizontal synchronous	signal input (To be used o	only at 16-bit input mode)	I(S)			
20	VS	Vertical synchronous signal input (To be used only at 16-bit input mode)						
21	GND	GND for I/O power sour	ce and Digital core power	source	G			
22	IOVDD	I/O power source						
23	N.C.	Non Connection						
24	GND	GND for Analog power source						
25	IREF	DAC reference current s	setting terminal		0			
26	AVDD	Analog power source			Р			
27	VOUT	Composite signal output	Composite signal output					
28	TEST0	Test terminal. It connects with GND.						
29	TEST1	Test terminal. It connect	Test terminal. It connects with GND.					
30	TEST2	Test terminal. It connects with GND.						
31	TEST3	Test terminal. It connects with GND.						
32	SDI	Serial data input						
33	SCLK	Serial clock input						
34	GND	GND for PLL power source						
35	PVDD	PLL power source						
36	RESETB	Reset input (L: reset)						

<sup>\*1</sup> ABBR:

I(S): input I/O with schmitt, I(PD): input I/O with Pull Up register, O: output, P: power source, G: ground.

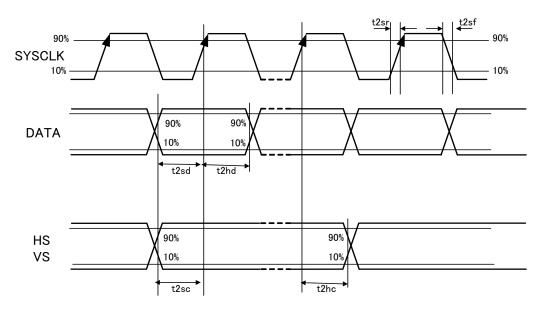
<sup>\*2</sup> At reset mode, the bidirectional I/O pin is set to the input mode.

### •Terminal Equivalent Circuit

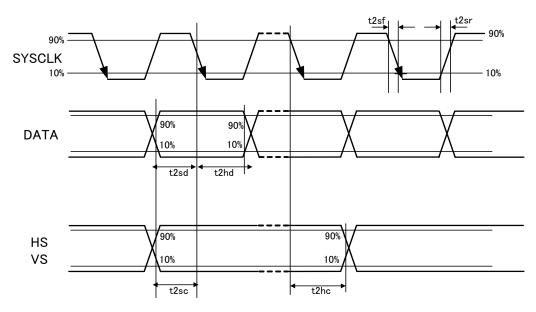
Table 6. Terminal Equivalent Circuit

Terminal name	Equivalent circuit diagram	Terminal name	Equivalent circuit diagram
DATA[15:0]	PAD W GND	IREF	AVDD PAD PAD GND
SYSCLK SCLK VS HS RESETB	PAD W GND	VOUT	AVDD PAD PAD GND
SDI	PAD W GND	DVDD PVDD	PAD PAD GND
TEST0 TEST1 TEST2 TEST3	PAD SND GND	IOVDD AVDD	PAD
		GND	IOVDD AVDD DVDD PVDD PAD

### •Input Timing Chart



Data latched by the rising edge of SYSCLK



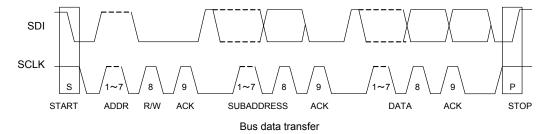
Data latched by the falling edge of SYSCLK

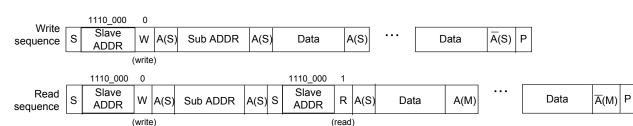
Fig.3. Image data and synchronous signal timing chart

It can be controlled by 3<sup>rd</sup> bit of register SYCPOL\_M that is latched by the rising or falling of SYSCLK.

#### Serial Interface Format

The slave address of the device is E0h.



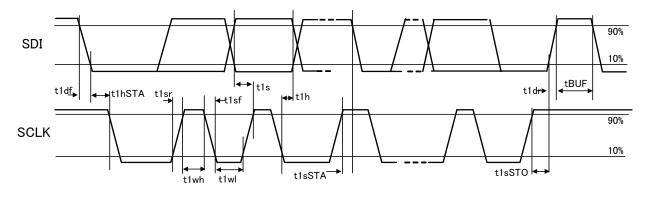


Write / read sequence

S = start bit P = stop bit A(S) = acknowledge by slave A(M) = acknowledge by master  $\overline{\underline{A}}(S)$  = no acknowledge by slave  $\overline{A}(M)$  = no acknowledge by master

Fig.4. Serial Interface Format

#### •Serial Interface Timing



t1s: DATA set-up time

t1h: DATA hold time

t1wl: SCLK "L" pulse width

t1wh: SCLK "H" pulse width

t1hSTA: Hold time START condition

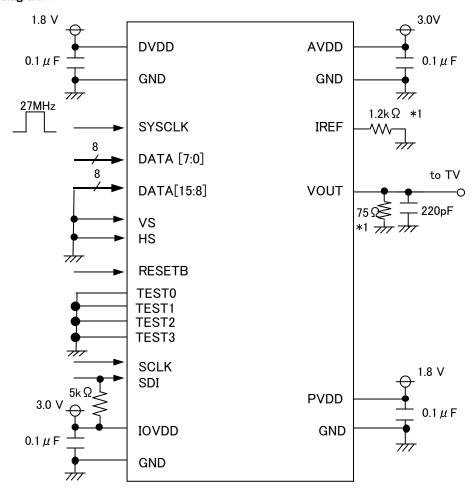
t1sSTA: Set-up time for a repeated START condition

t1sSTO: Set-up time for STOP condition

\*Please change the SDA after SCLK is stabilized in Low except the condition "START" and "STOP".

Fig.5. Serial Interface Timing Diagram

### •Application circuit diagram 1



656 input mode

Fig.6. Application Circuit Diagram Example

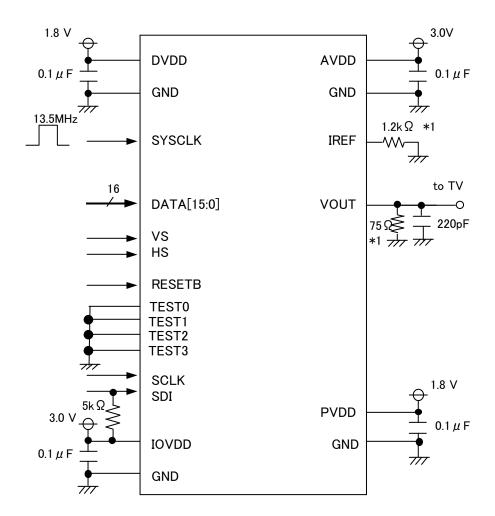
\*1 Use 75  $\Omega$  resister and 1.2k  $\Omega$  resister with precision  $\pm 1\%$ .

### Application example

The application circuit is recommended for use. Make sure to confirm the adequacy of the characteristics.

When using the circuit with changes to the external circuit constants, make sure to leave an adequate margin for external components including static and transitional characteristics as well as dispersion of the IC.

### •Application circuit diagram 2



601 input mode

Fig.7. Application Circuit Diagram Example

\*1 Use 75  $\Omega$  resister and 1.2k  $\Omega$  resister with precision  $\pm$  1%.

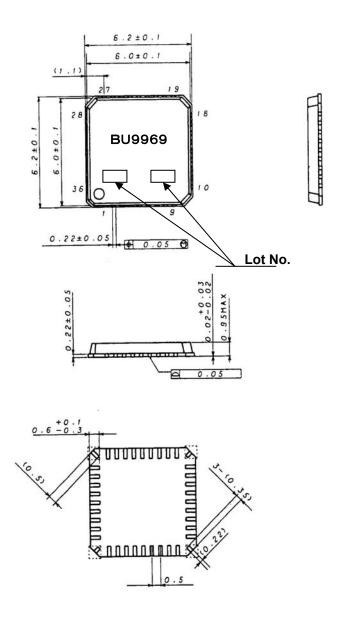
#### Application example

The application circuit is recommended for use. Make sure to confirm the adequacy of the characteristics.

When using the circuit with changes to the external circuit constants, make sure to leave an adequate margin for external components including static and transitional characteristics as well as dispersion of the IC.

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### •External Dimensional Drawing

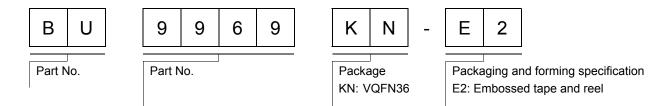


(Note) It must not be mounted at the dotted line part.

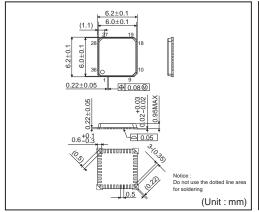
Figure number: EX346-5001-3

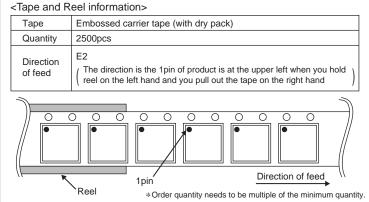
Fig.8. BU9969KN External Dimensional Drawing

### Ordering part number



### VQFN36





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