General Description

The MAX1307/MAX1311/MAX1315 12-bit, analog-to-digital converters (ADCs) feature a 1075ksps sampling rate, a 20MHz input bandwidth, and three analog input ranges. The MAX1307 provides a 0 to $+5V$ input range, with $\pm 6V$ fault-tolerant inputs. The MAX1311 provides a \pm 5V input range with \pm 16.5V fault-tolerant inputs. The MAX1315 provides a \pm 10V input range with \pm 16.5V fault-tolerant inputs.

The MAX1307/MAX1311/MAX1315 include an on-chip 2.5V reference. These devices also accept an external +2V to +3V reference.

All devices operate from a +4.75 to +5.25V analog supply, and a +2.7V to +5.25V digital supply. The devices consume 36mA total supply current when fully operational. A 0.62µA shutdown mode is available to save power during idle periods.

A 20MHz, 12-bit, parallel data bus provides the conversion results. An internal 15MHz oscillator, or an externally applied clock, drives conversions.

Each device is available in a 48-pin 7mm x 7mm TQFP package and operates over the extended $(-40^{\circ}$ C to $+85^{\circ}$ C) temperature range.

Applications

Pin Configuration

Industrial Process Control and Automation Vibration and Waveform Analysis Data-Acquisition Systems

TOP VIEW CHSHDN SHDN CLK CONVST CS WR RD EOLC EOC DGND DVDD D11 하 1차 1차 1차 1차 1차 क्ष జె౹ జి। 57 मा AVDD 1 D10 36 AGND 2 D9 35 AGND 3 D8 34 AIN 4 D7 33 I.C. 5 D6 32 I*a*xi*n*i MSV 6 D5 31 MAX1307 I.C. 7 MAX1311 D4 30 I.C. 8 MAX1315 D3 29 I.C. 9 D2 28 I.C. 10 D1 27 I.C. 11 D0 26 I.C. 12 25 DVDD 의 흰. \mathbb{F} ا≅ ا: ≌ا 의 의 ଧା ଅ 지. 의 **NTCLK/EXTCLK** REFMS AGND AVDD AGND AVDD REF REF+ COM REF-AGND DGND **TQFP**

MAXM

For pricing delivery, and ordering information please contact Maxim/Dallas Direct! at 1-888-629-4642, or visit Maxim's website at www.maxim-ic.com.

Features

- ♦ **±1 LSB INL, ±0.9 LSB DNL (max)**
- ♦ **84dBc SFDR, -86dBc THD, 71dB SINAD, fIN = 500kHz at -0.4dBFS**

PERSON

- ♦ **Extended Input Ranges 0 to +5V (MAX1307) -5V to +5V (MAX1311) -10V to +10V (MAX1315)**
- ♦ **Fault-Tolerant Inputs ±6V (MAX1307) ±16.5V (MAX1311/MAX1315)**
- ♦ **Fast 0.72µs Conversion Time**
- ♦ **12-Bit, 20MHz Parallel Interface**
- ♦ **Internal or External Clock**
- ♦ **+2.5V Internal Reference or +2.0V to +3.0V External Reference**
- ♦ **+5V Analog Supply, +3V to +5V Digital Supply 36mA Analog Supply Current 1.3mA Digital Supply Current Shutdown Mode**
- ♦ **48-Pin TQFP Package (7mm x 7mm Footprint)**

Ordering Information

Selector Guide

__ Maxim Integrated Products 1

ABSOLUTE MAXIMUM RATINGS

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS

(AVDD = +5V, DVDD = +3V, AGND = DGND = 0, VREF = VREFMS = +2.5V (external reference), CREF = CREFMS = 0.1µF, CREF+ = C_{REF-} = 0.1μF, C_{REF+-to-REF-} = 2.2μF ll 0.1μF, C_{COM} = 2.2μF ll 0.1μF, C_{MSV} = 2.2μF ll 0.1μF (unipolar devices), MSV = AGND (bipo-
lar devices), f_{CLK} = 16.67MHz 50% duty cycle, INTCLK/EXTCLK = AGND (external cloc unless otherwise noted. Typical values are at T A = +25°C.) (See Figures 3 and 4)

ELECTRICAL CHARACTERISTICS (continued)

(AV_{DD} = +5V, DV_{DD} = +3V, AGND = DGND = 0, V_{REF} = V_{REFMS} = +2.5V (external reference), C_{REF} = C_{REFMS} = 0.1µF, C_{REF+} = CREF- = 0.1µF, CREF+-to-REF- = 2.2µF || 0.1µF, CCOM = 2.2µF || 0.1µF, CMSV = 2.2µF || 0.1µF (unipolar devices), MSV = AGND (bipolar devices), $f_{CLK} = 16.67$ MHz 50% duty cycle, INTCLK/EXTCLK = AGND (external clock), SHDN = DGND, TA = TMIN to TMAX, unless otherwise noted. Typical values are at T_A = +25°C.) (See Figures 3 and 4)

ELECTRICAL CHARACTERISTICS (continued)

(AV_{DD} = +5V, DV_{DD} = +3V, AGND = DGND = 0, V_{REF} = V_{REFMS} = +2.5V (external reference), C_{REF} = C_{REFMS} = 0.1µF, C_{REF+} = CREF- = 0.1µF, CREF+-to-REF- = 2.2µF || 0.1µF, CCOM = 2.2µF || 0.1µF, CMSV = 2.2µF || 0.1µF (unipolar devices), MSV = AGND (bipolar devices), f_{CLK} = 16.67MHz 50% duty cycle, INTCLK/EXTCLK = AGND (external clock), SHDN = DGND, TA = T_{MIN} to T_{MAX}, unless otherwise noted. Typical values are at T_A = +25°C.) (See Figures 3 and 4)

MAXIM

ELECTRICAL CHARACTERISTICS (continued)

(AV_{DD} = +5V, DV_{DD} = +3V, AGND = DGND = 0, V_{REF} = V_{REFMS} = +2.5V (external reference), C_{REF} = C_{REFMS} = 0.1µF, C_{REF+} = CREF- = 0.1µF, CREF+-to-REF- = 2.2µF || 0.1µF, CCOM = 2.2µF || 0.1µF, CMSV = 2.2µF || 0.1µF (unipolar devices), MSV = AGND (bipolar devices), f_{CLK} = 16.67MHz 50% duty cycle, INTCLK/EXTCLK = AGND (external clock), SHDN = DGND, TA = TMIN to TMAX, unless otherwise noted. Typical values are at T_A = +25°C.) (See Figures 3 and 4)

- **Note 1:** For the MAX1307, V_{IN} = 0 to +5V. For the MAX1311, V_{IN} = -5V to +5V. For the MAX1315, V_{IN} = -10V to +10V.
- **Note 2:** The analog input resistance is terminated to an internal bias point (Figure 5). Calculate the analog input current using:

$$
I_{AIN} = \frac{V_{AIN} - V_{BIAS}}{R_{AIN}}
$$

for AIN within the input voltage range.

- **Note 3:** Throughput rate is a function of clock frequency (f_{CLK}). The external clock throughput rate is specified with f_{CLK} = 16.67MHz and the internal clock throughput rate is specified with f_{CLK} = 15MHz. See the Data Throughput section for more information. $I_{\text{AlN}} = \frac{I_{\text{AlN}}}{P_{\text{AlN}}}$
or AIN within the if
hroughput rate is
6.67MHz and the
nformation.
Neer – 2.5
- **Note 4:** The REF input resistance is terminated to an internal +2.5V bias point (Figure 2). Calculate the REF input current using:

$$
I_{REF} = \frac{V_{REF} - 2.5V}{R_{REF}}
$$

for V_{REF} within the input
The REFMS input resista

$$
V_{REFMS} - 2.5V
$$

for V_{REF} within the input voltage range.

Note 5: The REF_{MS} input resistance is terminated to an internal +2.5V bias point (Figure 2). Calculate the REF_{MS} input current using:

$$
I_{REFMS} = \frac{V_{REFMS} - 2.5V}{R_{REFMS}}
$$

for VREFMS within the input voltage range.

- **Note 6:** The analog input is driven with a -0.4dBFS 500kHz sine wave.
- **Note 7:** Shutdown current is measured with the analog input floating. The large amplitude of the maximum shutdown-current specification is due to automated test equipment limitations. IREFMS = $\frac{1.62 \times 10^{-14}}{R_{REFMS}}$
for VREFMS within the input voltage range.
The analog input is driven with a -0.4dBFS 500kHz s
Shutdown current is measured with the analog inpu
fication is due to automated test equipme
- **Note 8:** CONVST must remain low for at least the acquisition period. The maximum acquisition time is limited by internal capacitor droop.
- **Note 9:** CS to WR and CS to RD are internally AND together. Setup and hold times do not apply.
- **Note 10:** Minimum CLK frequency is limited only by the internal T/H droop rate. Limit the time between the rising edge of CONVST

/VI /IXI /VI

Typical Operating Characteristics

(AVDD = +5V, DVDD = +3V, AGND = DGND = 0, VREF = VREFMS = +2.5V (external reference), CREF = CREFMS = 0.1µF, CREF+ = CREF- = 0.1μ F, CREF+-to-REF- = 2.2μ F || 0.1μ F, CCOM = 2.2μ F || 0.1μ F, CMSV = 2.2μ F || 0.1μ F (unipolar devices), MSV = AGND (bipolar devices), fcLK = 16.67MHz 50% duty cycle, INTCLK/EXTCLK = AGND (external clock), fin = 500kHz, Ain = -0.4dBFS. TA = +25°C, unless otherwise noted.) (Figures 3 and 4)

Typical Operating Characteristics (continued)

(AV_{DD} = +5V, DV_{DD} = +3V, AGND = DGND = 0, VREF = VREFMS = +2.5V (external reference), CREF = CREFMS = 0.1µF, CREF+ = $C_{REF} = 0.1 \mu$ F, C_{REF} +to-REF- = 2.2 μ F || 0.1 μ F, C_{COM} = 2.2 μ F || 0.1 μ F, C_{MSV} = 2.2 μ F || 0.1 μ F (unipolar devices), MSV = AGND (bipolar devices), fcLK = 16.67MHz 50% duty cycle, INTCLK/EXTCLK = AGND (external clock), fin = 500kHz, AIn = -0.4dBFS. TA = +25°C, unless otherwise noted.) (Figures 3 and 4)

OUTPUT HISTOGRAM (DC INPUT)

Typical Operating Characteristics (continued)

(AV_{DD} = +5V, DV_{DD} = +3V, AGND = DGND = 0, VREF = VREFMS = +2.5V (external reference), CREF = CREFMS = 0.1µF, CREF+ = $C_{REF} = 0.1 \mu F$, C_{REF} -to-REF- = 2.2 μ F II 0.1 μ F, Ccom = 2.2 μ F II 0.1 μ F, Cmsv = 2.2 μ F II 0.1 μ F (unipolar devices), MSV = AGND (bipolar devices), fcLK = 16.67MHz 50% duty cycle, INTCLK/EXTCLK = AGND (external clock), fin = 500kHz, AIn = -0.4dBFS. TA = +25°C, unless otherwise noted.) (Figures 3 and 4)

0 5 10 15 20 25

f_{CLK} (MHz)

0 5 10 15 20 25

f_{CLK} (MHz)

60 65

-85 -80 -75 -70 THD (dBc)

> -100 -95 -90

> > */VI/IXI/VI*

Typical Operating Characteristics (continued)

(AVDD = +5V, DVDD = +3V, AGND = DGND = 0, VREF = VREFMS = +2.5V (external reference), CREF = CREFMS = 0.1µF, CREF+ = CREF- = 0.1μ F, CREF+-to-REF- = 2.2μ F || 0.1μ F, C_{COM} = 2.2μ F || 0.1μ F, C_{MSV} = 2.2μ F || 0.1μ F (unipolar devices), MSV = AGND (bipolar devices), fcLK = 16.67MHz 50% duty cycle, INTCLK/EXTCLK = AGND (external clock), fin = 500kHz, AIn = -0.4dBFS. TA = +25°C, unless otherwise noted.) (Figures 3 and 4)

VREF (V)

2.2 2.4 2.6 2.8

2.0 3.0

75

70

80

Typical Operating Characteristics (continued)

(AV_{DD} = +5V, DV_{DD} = +3V, AGND = DGND = 0, VREF = VREFMS = +2.5V (external reference), CREF = CREFMS = 0.1µF, CREF+ = $C_{REF} = 0.1 \mu F$, C_{REF} -to-REF- = 2.2 μ F II 0.1 μ F, Ccom = 2.2 μ F II 0.1 μ F, Cmsv = 2.2 μ F II 0.1 μ F (unipolar devices), MSV = AGND (bipolar devices), fcLK = 16.67MHz 50% duty cycle, INTCLK/EXTCLK = AGND (external clock), fin = 500kHz, AIn = -0.4dBFS. TA = +25°C, unless otherwise noted.) (Figures 3 and 4)

 $AV_{DD} (V)$

Typical Operating Characteristics (continued)

(AVDD = +5V, DVDD = +3V, AGND = DGND = 0, VREF = VREFMS = +2.5V (external reference), CREF = CREFMS = 0.1µF, CREF+ = $C_{REF} = 0.1 \mu$ F, C_{REF} -to-REF- = 2.2 μ F II 0.1 μ F, C_{COM} = 2.2 μ F II 0.1 μ F, C_{MSV} = 2.2 μ F II 0.1 μ F (unipolar devices), MSV = AGND (bipolar devices), fcLK = 16.67MHz 50% duty cycle, INTCLK/EXTCLK = AGND (external clock), fin = 500kHz, AIn = -0.4dBFS. TA = +25°C, unless otherwise noted.) (Figures 3 and 4)

Pin Description

Pin Description (continued)

Detailed Description

The MAX1307/MAX1311/MAX1315 contain a 1075ksps 12 bit ADC with track and hold (T/H). Input scaling on the MAX1307/MAX1311/MAX1315 allows a 0 to +5V, ±5V, or ±10V analog input signal, respectively. Additionally, the MAX1307 features ±6V fault-tolerant inputs, while the MAX1311/MAX1315 feature ±16.5V fault-tolerant inputs. The MAX1307/MAX1311/MAX1315 include an on-chip +2.5V reference. These devices also accept an external +2V to +3V reference.

The conversion results are available in 0.72µs with a sampling rate of 1075ksps. Internal or external clock capabilities offer greater flexibility. A high-speed, 20MHz parallel interface outputs the conversion results.

Figure 1. Digital Load Test Circuit

Figure 2. Functional Diagram

Figure 3. Typical Bipolar Operating Circuit

Figure 4. Typical Unipolar Operating Circuit

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Figure 5. Equivalent Analog Input T/H Circuit

Analog Input

Track and Hold (T/H)

The input T/H circuit is controlled by the CONVST input. When CONVST is low, the T/H circuit tracks the analog input. When CONVST is high, the T/H circuit holds the analog input. The rising edge of CONVST is the analog input sampling instant. There is an aperture delay (tAD) of 8ns and a 50psRMS aperture jitter (tAJ).

To settle the charge on CSAMPLE to 12-bit accuracy, use a minimum acquisition time (t_{ACO}) of 100ns. Therefore, CONVST must be low for at least 100ns. Although longer acquisition times allow the analog input to settle to its final value more accurately, the maximum acquisition time must be limited to 1ms. Accuracy with conversion times longer than 1ms cannot be guaranteed due to capacitor droop in the input circuitry.

Due to the analog input resistive divider formed by R1 and R2 in Figure 5, any significant analog input source resistance (RSOURCE) results in gain error. Furthermore, RSOURCE causes distortion due to nonlinear analog input currents. Limit R_{SOLIRCF} to a maximum of 100 Ω.

Selecting an Input Buffer

To improve the input signal bandwidth under AC conditions, drive the input with a wideband buffer (>50MHz) that can drive the ADC's input capacitance (15pF) and settle quickly. For example, the MAX4431 or the MAX4265 can be used for 0 to +5V unipolar devices, or the MAX4350 can be used for ±5V bipolar inputs.

Most applications require an input buffer to achieve 12-bit accuracy. Although slew rate and bandwidth are important, the most critical input buffer specification is settling time. At the beginning of the acquisition, the ADC internal sampling capacitor array connects to the analog inputs, causing some disturbance. Ensure the amplifier is capable of settling to at least 12-bit accuracy during the acquisition time (t_{ACQ}). Use a low-noise, low-distortion, wideband amplifier that settles quickly and is stable with the ADC's 15pF input capacitance.

Refer to the Maxim website at www.maxim-ic.com for application notes on how to choose the optimum buffer amplifier for your ADC application.

Input Bandwidth

The input-tracking circuitry has a 20MHz small-signal bandwidth, making it possible to digitize high-spee d transient events and measure periodic signals with bandwidths exceeding the ADC's sampling rate by using undersampling techniques. To avoid high-frequency signals being aliased into the frequency band of interest, anti-alias filtering is recommended.

Input Range and Protection

The MAX1307 provides a 0 to +5V input voltage range with fault protection of ±6V. The MAX1311 provides a $±5V$ input voltage range with fault protection of $±16.5V$. The MAX1315 provides a \pm 10V input voltage range with fault protection of $\pm 16.5V$. Figure 5 shows the equivalent analog input circuit.

Data Throughput

The data throughput (fTH) of the MAX1307/MAX1311/ MAX1315 is a function of the clock speed (f_{CLK}). In internal clock mode, $f_{CLK} = 15MHz$ (typ). In external clock mode, these devices accept an f_{CLK} between 100kHz and 20MHz. Figures 6 and 7 calculate f_{TH} as follows:

$$
f_{TH} = \frac{1}{t_{ACQ} + t_{QUIET} + \frac{13}{t_{CLK}}}
$$

where to unterprise the period of bus inactivity before the rising edge of CONVST (≥50ns). See the Starting a Conversion section for more information.

Clock Modes The MAX1307/MAX1311/MAX1315 perform conversions using either an internal clock or external clock. There are 13 clock periods per conversion.

Internal Clock Internal clock mode frees the microprocessor from the burden of running the ADC conversion clock. For internal clock operation, connect INTCLK/EXTCLK to AV_{DD} and connect CLK to DGND. Note that INTCLK/EXTCLK is referenced to AV_{DD}, not DV_{DD}.

External Clock

For external clock operation, connect INTCLK/EXTCLK to AGND and connect an external clock source to CLK. Note that INTCLK/EXTCLK is referenced to AV_{DD}, not DV_{DD}. The external clock frequency can be up to 20MHz. Linearity is not guaranteed with clock frequencies below 100kHz due to droop in the T/H circuits.

Applications Information

Digital Interface

Conversion results are available through the 12-bit digital interface (D0–D11). The interface includes the following control signals: chip select (\overline{CS}) , read (\overline{RD}) , end of conversion (EOC), end of last conversion (EOLC), conversion start (CONVST), shutdown (SHDN), internal clock select (INTCLK/EXTCLK), and external clock input (CLK). Figures 6 and 7 and the Timing Characteristics show the operation of the interface. D0–D11 go high impedanc e when $\overline{RD} = 1$ or $\overline{CS} = 1$.

Starting a Conversion

To start a conversion using internal clock mode, pull CONVST low for the acquisition time (t_{ACO}) . The T/H acquires the signal while CONVST is low, and conver sion begins on the rising edge of CONVST. The end-ofconversion (EOC) signal and end-of-last-conversion signal (EOLC) pulse low whenever a conversion result is available for reading (Figure 6).

To start a conversion using external clock mode, pull CONVST low for the acquisition time (tACQ). The T/H acquires the signal while CONVST is low. The rising edge of CONVST is the sampling instant. Apply an external clock to CLK to start the conversion. To avoid T/H droop degrading the sampled analog input signals, the first CLK pulse must occur within 10µs from the rising edge of CONVST. Additionally, the external clock frequency must be greater than 100kHz to avoid T/H droop degrading accuracy. The conversion result is available for read when EOC or ELOC goes low on the rising edge of the 13th clock cycle (Figure 7).

In both internal and external clock modes, hold CONVST high until the conversion result is read. If CONVST goes low in the middle of a conversion, the current conversion is aborted and a new conversion is initiated. Furthermore, there must be a period of bus inactivity (tQUIET) for 50ns or longer before the falling edge of CONVST for the specified ADC performance.

Reading a Conversion Result

Figures 6 and 7 show the interface signals to initiate a read operation. \overline{CS} can be low at all times, low during the RD cycles, or the same as RD.

After initiating a conversion by bringing CONVST high, wait for \overline{EOC} or \overline{EOLC} to go low. In internal clock mode, EOC or EOLC goes low within 900ns. In external clock mode, EOC or EOLC goes low on the rising edge of the 13th CLK cycle. To read the conversion result, drive $\overline{\text{CS}}$ and RD low to latch data to the parallel digital output bus. Bring RD high to release the digital bus.

Figure 6. Reading a Conversion—Internal Clock

Power-Up Reset

After applying power, allow a 1ms wake-up time to elapse and then initiate a conversion and discard the results. After the conversion is complete, accurate conversions can be obtained.

Shutdown Modes

During shutdown the internal reference and analog circuits in the device shutdown and the analog supply current drops to 0.6µA (typ). Set SHDN high to ente r shutdown mode.

EOC and EOLC are high when the MAX1307/MAX1311/ MAX1315 are shut down.

The state of the digital outputs D0–D11 is independent of the state of SHDN. If \overline{CS} and \overline{RD} are low, the digital outputs D0–D11 are active regardless of SHDN. The digital outputs only go high impedance when \overline{CS} or \overline{RD} is high. When the digital outputs are powered down, the digital supply current drops to 20nA.

Exiting shutdown (falling edge of SHDN) starts a conversion in the same way as the rising edge of CONVST. After coming out of shutdown, initiate a conversion and discard the results. Allow a 1ms wake-up time to expire before initiating the first accurate conversion.

Figure 7. Reading a Conversion—External Clock

MAX1307/MAX1311/MAX1315

Reference

Internal Reference

The internal reference circuits provide for analog input voltages of 0 to +5V for the unipolar MAX1307, ±5V for the bipolar MAX1311, or \pm 10V for the bipolar MAX1315. Install external capacitors for reference stability, as indicated in Table 1 and shown in Figures 3 and 4.

As illustrated in Figure 2, the internal reference voltage is 2.5V (VREF). This 2.5V is internally buffered to create the voltages at REF+ and REF-. Table 2 shows the voltages at COM, REF+, and REF-.

External Reference

External reference operation is achieved by overriding the internal reference voltage. Override the internal reference voltage by driving REF with a +2.0V to +3.0V external reference. As shown in Figure 2, the REF input impedance is 5k Ω . For more information about using external references, see the Transfer Functions section.

Midscale Voltage (MSV)

The voltage at MSV (V_{MSV}) sets the midpoint of the ADC transfer functions. For the 0 to +5V input range (unipolar devices), the midpoint of the transfer function is +2.5V. For the \pm 5V and \pm 10V input range devices, the midpoint of the transfer function is zero.

As shown in Figure 2, there is a unity-gain buffer between REF_{MS} and MSV in the unipolar MAX1307. This midscale buffer sets the midpoint of the unipolar transfer functions to either the internal +2.5V reference or an externally applied voltage at REFMS. VMSV follows VREFMS within ±3mV.

The midscale buffer is not active for the bipolar devices. For these devices, MSV must be connected t o AGND or externally driven. REF_{MS} must be bypassed with a 0.01µF capacitor to AGND.

See the Transfer Functions section for more information about MSV.

Table 1. Reference Bypass Capacitors

N/A = Not applicable. Connect MSV directly to AGND.

Table 2. Reference Voltages

Transfer Functions **Unipolar 0 to +5V Devices**

Table 3 and Figure 8 show the offset binary transfe r function for the MAX1307 with a 0 to +5V input range. The full-scale input range (FSR) is two times the voltage at REF. The internal +2.5V reference gives a +5V FSR, while an external +2V to +3V reference allows an FS R of +4V to +6V, respectively. Calculate the LSB size using:

$$
1 \text{LSB} = \frac{2 \times V_{REF}}{2^{12}}
$$

which equals 1.22mV when using a 2.5V reference.

Table 3. 0 to 5V Unipolar Code Table

The input range is centered about V_{MSV}, internally set to +2.5V. For a custom midscale voltage, drive REFMS with an external voltage source and MSV will follow REF_{MS}. Noise present on MSV or REF_{MS} directly couples into the ADC result. Use a precision, low-drift voltage reference with adequate bypassing to prevent MSV from degrading ADC performance. For maximum FSR, do not violate the absolute maximum voltage ratings of the analog inputs when choosing MSV.

Determine the input voltage as a function of VREF, VMSV, and the output code in decimal using:

 $VCH = LSB \times CODE_{10} + VMSV - 2.500V$

Figure 8. 0 to +5V Unipolar Transfer Function

Bipolar ±5V Devices

Table 4 and Figure 9 show the two's complement transfer function for the ±5V input range MAX1311. The FSR is four times the voltage at REF. The internal +2.5V reference gives a +10V FSR, while an external +2V to +3V reference allows an FSR of +8V to +12V respectively. Calculate the LSB size using:

$$
1 \text{LSB} = \frac{4 \times V_{REF}}{2^{12}}
$$

which equals 2.44mV when using a 2.5V reference.

The input range is centered about V_{MSV}. Normally, MSV = AGND, and the input is symmetrical about zero. For a custom midscale voltage, drive MSV with an external voltage source. Noise present on MSV directly couples into the ADC result. Use a precision, low-drift voltage reference with adequate bypassing to prevent MSV from degrading ADC performance. For maximum FSR, do not violate the absolute maximum voltage ratings of the analog inputs when choosing MSV.

Determine the input voltage as a function of VREF, VMSV, and the output code in decimal using:

 $VCH = LSB \times CODE_{10} + VMSV$

Figure 9. ±5V Bipolar Transfer Function

Table 4. ±5V Bipolar Code Table

Bipolar ±10V Devices

Table 5 and Figure 10 show the two's complement transfer function for the $\pm 10V$ input range MAX1315. The FSR is eight times the voltage at REF. The internal +2.5V reference gives a +20V FSR, while an external +2V to +3V reference allows an FSR of +16V to +24V, respectively. Calculate the LSB size using:

$$
1 \text{LSB} = \frac{8 \times V_{\text{REF}}}{2^{12}}
$$

which equals 4.88mV with a +2.5V internal reference.

TWO's COMPLEMENT DIGITAL OUTPUT CODE	DECIMAL EQUIVALENT DIGITAL OUTPUT CODE (CODE ₁₀)	INPUT VOLTAGE (V) $($ V _{REF} = +2.5V $)$ V _{MSV} = 0
$011111111111 =$ 0x7FF	$+2047$	$+9.9976 \pm 0.5$ LSB
$011111111110 =$ 0x7FF	$+2046$	$+9.9927 \pm 0.5$ LSB
$000000000001 =$ 0x001	$+1$	$+0.0073 \pm 0.5$ LSB
$000000000000 =$ 0x000	O	0.0024 ± 0.5 LSB
1111 1111 1111 $=$ 0xFFF	-1	-0.0024 ± 0.5 LSB
$100000000001 =$ 0x801	-2047	-9.9927 ± 0.5 LSB
$10000000000 =$ 0x800	-2048	-9.9976 ± 0.5 LSB

Table 5. ±10V Bipolar Code Table

The input range is centered about V_{MSV}. Normally, MSV = AGND, and the input is symmetrical about zero. For a custom midscale voltage, drive MSV with an external voltage source. Noise present on MSV directly couples into the ADC result. Use a precision, low-drift voltage reference with adequate bypassing to preven t MSV from degrading ADC performance. For maximum FSR, do not violate the absolute maximum voltage ratings of the analog inputs when choosing MSV.

Determine the input voltage as a function of VREF, VMSV, and the output code in decimal using:

 $VCH = LSB \times CODE_{10} + VMSV$

Figure 10. ±10V Bipolar Transfer Function

ANALOG SUPPLY

+5V RETURN

OPTIONAL FERRITE BEAD

┯

av_{dd} agnd dgnd dv_{dd}

ANALOG **GROUND** POINT

MAX1307

MAXIM

DIGITAL GROUND POINT

Layout, Grounding, and Bypassing

For best performance use PC boards. Board layout must ensure that digital and analog signal lines are separated from each other. Do not run analog and digital lines parallel to one another (especially clock lines), and do not run digital lines underneath the ADC package.

Figure 11 shows the recommended system ground connections. Establish an analog ground point at AGND and a digital ground point at DGND. Connect all analog grounds to the analog ground point. Connect all digital grounds to the digital ground point. For lowest-noise operation, make the power-supply ground returns as low impedance and as short as possible. Connect the analog ground point to the digital ground point at one location.

High-frequency noise in the power supplies degrades the ADC's performance. Bypass the analog power plane to the analog ground plane with a 2.2µF capacitor within one inch of the device. Bypass each AV_{DD} to AGND pair of pins with a 0.1µF capacitor as close t o the device as possible. AV_{DD} to AGND pairs are pin 1 to pin 2, pin 14 to pin 15, and pin 16 to pin 17. Likewise, bypass the digital power plane to the digital ground plane with a 2.2µF capacitor within one inch of the device. Bypass each DV_{DD} to DGND pair of pins with a 0.1µF capacitor as close to the device as possible. DV_{DD} to DGND pairs are pin 24 to pin 25, and pin 38 to pin 39. If a supply is very noisy use a ferrite bead as a lowpass filter as shown in Figure 11.

Definitions

Integral Nonlinearity (INL)

INL is the deviation of the values on an actual transfer function from a straight line. For these devices, this straight line is drawn between the end points of th e transfer function, once offset and gain errors have been nullified.

Differential Nonlinearity (DNL)

DNL is the difference between an actual step width and the ideal value of 1 LSB. For these devices, the DNL of each digital output code is measured and the worstcase value is reported in the Electrical Characteristics table. A DNL error specification of less than ±1 LS B guarantees no missing codes and a monotonic transfer function.

DATA

DGND DV_{DD} DGND DV_{DD}

DGND

DIGITAL **CIRCUITRY**

DIGITAL SUPPLY RETURN +3V TO +5V

amount of deviation between the measured zero-scale transition point and the ideal zero-scale transition point. For the bipolar devices (MAX1311/MAX1315), the ideal midscale transition from 0xFFF to 0x000 occurs at MSV (Figures 9 and 10, Tables 4 and 5). The bipolar offset

error is the amount of deviation between the measured midscale transition point and the ideal midscale transition point.

Gain Error

Gain error is a figure of merit that indicates how well the slope of the actual transfer function matches the slope of the ideal transfer function. For the MAX1307/ MAX1311/MAX1315, the gain error is the difference o f the measured full-scale and zero-scale transition points minus the difference of the ideal full-scale and zeroscale transition points.

For the unipolar devices (MAX1307), the full-scale transition point is from 0xFFE to 0xFFF and the zero-scale transition point is from 0x000 to 0x001.

For the bipolar devices (MAX1311/MAX1315), the full scale transition point is from 0x7FE to 0x7FF and the zero-scale transition point is from 0x800 to 0x801.

Signal-to-Noise Ratio (SNR)

For a waveform perfectly reconstructed from digital samples, the theoretical maximum SNR is the ratio o f the full-scale analog input (RMS value) to the RMS quantization error (residual error). The ideal, theoretical minimum analog-to-digital noise is caused by quantization error only and results directly from the ADC's resolution (N bits):

$$
SNRdB(max] = 6.02dB × N + 1.76dB
$$

In reality, there are other noise sources such as thermal noise, reference noise, and clock jitter.

For these devices, SNR is computed by taking the ratio of the RMS signal to the RMS noise. RMS noise includes all spectral components to the Nyquist fre quency excluding the fundamental, the first five harmonics, and the DC offset.

Signal-to-Noise Plus Distortion (SINAD)

SINAD is computed by taking the ratio of the RMS signal to the RMS noise plus distortion. RMS noise plus distortion includes all spectral components to the Nyquist frequency excluding the fundamental and the DC offset.

$$
SINAD(dB) = 20 \times \log \left(\frac{Signal_{RMS}}{\sqrt{Noise_{RMS}^{2} + Distortion_{RMS}^{2}}} \right)
$$

Effective Number of Bits (ENOB)

ENOB specifies the dynamic performance of an ADC at a specific input frequency and sampling rate. An ideal ADC's error consists of quantization noise only. ENOB for a full-scale sinusoidal input waveform is computed as:

$$
ENOB = \frac{SINAD - 1.76}{6.02}
$$

Total Harmonic Distortion (THD)

THD is the ratio of the RMS sum of the first five harmonics to the fundamental itself. This is expressed as:

$$
\text{THD} = 20 \times \log \left(\frac{\sqrt{V_2^2 + V_3^2 + V_4^2 + V_5^2 + V_6^2}}{V_1} \right)
$$

where V 1 is the fundamental amplitude, and V 2 through V 6 are the amplitudes of the 2nd- through 6thorder harmonics.

Spurious-Free Dynamic Range (SFDR)

SFDR is the ratio of the RMS amplitude of the fundamental (maximum signal component) to the RMS value of the next-largest spurious component, excluding DC offset. SFDR is specified in decibels relative to the carrier (dBc).

Aperture Delay

Aperture delay (t_{AD}) is the time delay from the CONVST rising edge to the instant when an actual sample is taken.

Aperture Jitter

Aperture jitter $(t_{A,J})$ is the sample-to-sample variation in aperture delay.

Jitter is a concern when considering an ADC's dynamic performance, e.g., SNR. To reconstruct an analog input from the ADC digital outputs, it is critical to know the time at which each sample was taken. Typical applications use an accurate sampling clock signal that has low jitter from sampling edge to sampling edge. For a system with a perfect sampling clock signal, with no clock jitter, the SNR performance of an ADC is limited by the ADC's internal aperture jitter as follows:

$$
SNR = 20 \times \log \left(\frac{1}{2 \times \pi \times f_{\text{IN}} \times t_{\text{AJ}}} \right)
$$

where f_{IN} represents the analog input frequency and tAJ is the time of the aperture jitter.

Small-Signal Bandwidth

A small -20dBFS analog input signal is applied to a n ADC so that the signal's slew rate does not limit the ADC's performance. The input frequency is then swep t up to the point where the amplitude of the digitize d conversion result has decreased by -3dB.

Full-Power Bandwidth

A large, -0.5dBFS analog input signal is applied to an ADC, and the input frequency is swept up to the point where the amplitude of the digitized conversion result has decreased by -3dB. This point is defined as fullpower input bandwidth frequency.

DC Power-Supply Rejection (PSRR)

DC PSRR is defined as the change in the positive fullscale transfer-function point caused by a $\pm 5\%$ variation in the analog power-supply voltage (AV_{DD}) .

Chip Information

TRANSISTOR COUNT: 50,000 PROCESS: 0.6µm BiCMOS

Package Information

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to **www.maxim-ic.com/packages**.)

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